A class of anisotropic multiple multiresolution analysis

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Jointly with: Mira Bozzini, Milvia Rossini, Tomas Sauer

• Description of expanding matrices and related objects



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- Inside filterbanks and subdivisions



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- Remarks of their multiple counterparts



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Expanding matrices

Let $M \in \mathbb{Z}^{s \times s}$ be an expanding matrix, i.e.

• all its its eigenvalues are larger than one in modulus

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• $\|M^{-n}\| \to 0$

as n increases, $M^{-n}\mathbb{Z}^s \to \mathbb{R}^s$

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- *M* defines a sampling lattice
- $d = |\det(M)|$ is the number of cosets

The cosets have the form

$$M\mathbb{Z}^s + \xi_j, \quad j = 0, \dots, d-1$$

where

$$\xi_j \in M[0,1)^s igcap \mathbb{Z}^s$$

are the coset representatives.

It is well known that

$$\mathbb{Z}^s = igcup_{j=0}^{d-1}(\xi_j + M\mathbb{Z}^s)$$

Separable/Nonseparable



Isotropy/Anisotropy



Down/upsampling

Let $c \in \ell(\mathbb{Z}^s)$ be a given signal.

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• Upsampling operator \uparrow_M associated to *M*:

$$\uparrow_{M} c(\alpha) = \begin{cases} c(M^{-1}\alpha) & \text{if } \alpha \in M\mathbb{Z}^{s} \\ 0 & \text{otherwise} \end{cases}$$

Filtering

• Filter operator *F*:

.

$$\mathsf{Fc} = f * \mathsf{c} = \sum_{\alpha \in \mathbb{Z}^s} f(\cdot - \alpha) \mathsf{c}(\alpha)$$

where $f = F\delta = (f(\alpha) : \alpha \in \mathbb{Z}^s)$ is the impulse response of *F*

Critically sampled: $d = |\det M|$

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• Analysis filter:

$$F: \ell(\mathbb{Z}^s) \to \ell^d(\mathbb{Z}^s)$$
$$Fc = [\downarrow_M F_j c : j = 0, \dots, d-1]$$

• Synthesis filter:

$$egin{aligned} G:\ell^d(\mathbb{Z}^s) &
ightarrow \ell(\mathbb{Z}^s) \ G\left[c_j \ : \ j=0,\ldots,d-1
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Perfect reconstruction:

$$GF = I$$

By perfect reconstruction:

$$c \stackrel{F}{\rightarrow} \begin{bmatrix} c_0^1 \\ c_1^1 \\ \vdots \\ c_{d-1}^1 \end{bmatrix} = \begin{bmatrix} c^1 \\ d^1 \end{bmatrix} \stackrel{G}{\rightarrow} c$$

 $\begin{array}{ll} F_0,\,G_0 \longrightarrow \text{low-pass} \\ F_j,\,G_j, \quad j > 0 \longrightarrow \text{high-pass} \end{array}$

Multiresolution decomposition ...

Iterated filter bank

MRA structure...



Observe that

.

$$G_j \uparrow c = g_j * \uparrow_M c = \sum_{\alpha \in \mathbb{Z}^s} g_j(\cdot - M\alpha) c(\alpha),$$

i.e. all reconstruction filters act as stationary subdivision operators with dilation matrix *M*.

Stationary subdivision

Subdivision operator:

$$S := S_{\mathsf{a},\mathsf{M}} \colon \ell(\mathbb{Z}^s) \to \ell(\mathbb{Z}^s)$$

defined by

$$c^{(n+1)} := Sc^{(n)} = \sum_{\alpha \in \mathbb{Z}^s} a(\cdot - M\alpha)c^{(n)}(\alpha)$$

where $M \in \mathbb{Z}^{s \times s}$ is expanding

Consider a set of a finite number of dilation matrices

$$(M_j : j \in \mathbb{Z}_m)$$

where $\mathbb{Z}_m = \{0, \ldots, m-1\}$ for $m \in \mathbb{N}$.



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Together, a_j and M_j define m stationary subdivision operators

$$S_j := S_{a_j,M_j}$$

Call

$$\epsilon = (\epsilon_1, \ldots, \epsilon_n) \in \mathbb{Z}_m^n$$

a digit sequence of length $n =: |\epsilon|$.

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We collect all finite digit sequences in

$$\mathbb{Z}_m^* := \bigcup_{n \in \mathbb{N}} \mathbb{Z}_m^n$$

and extend $|\epsilon|$ canonically to $\epsilon \in \mathbb{Z}_m^*$.

Consider the subdivision operator:

$$S_{\epsilon} = S_{\epsilon_n} \cdots S_{\epsilon_1}.$$

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For any $\epsilon \in \mathbb{Z}_m^*$ there exists a mask

$$a_{\epsilon} = S_{\epsilon}\delta$$

such that

$$S_{\epsilon}c = \sum_{lpha \in \mathbb{Z}^{s}} a_{\epsilon} \left(\cdot - M_{\epsilon} lpha
ight) c(lpha), \qquad c \in \ell(\mathbb{Z}^{s}),$$

where

$$M_{\epsilon} := M_{\epsilon_n} \cdots M_{\epsilon_1}, \qquad n = |\epsilon|.$$

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- all the matrices M_ϵ must be expanding

The matrices M_{ϵ} must all be jointly expanding i.e.

$$\lim_{|\epsilon|\to\infty} \left\| M_{\epsilon}^{-1} \right\| = 0, \tag{1}$$

or, equivalently,

$$\rho\left(M_{j}^{-1} : j \in \mathbb{Z}_{m}\right) < 1$$

 \downarrow

(joint spectral radius condition)

Example: adaptive subdivision/discrete shearlets

Based on:

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Multiple subdivision

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• parabolic scaling
$$\begin{bmatrix} 2 \\ 4 \end{bmatrix}$$

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What about other choices? Case study ...

Multiple *d*-channel filter bank

For each $k \in \mathbb{Z}_m$

• Analysis filters: $F_k : \ell(\mathbb{Z}^s) \to \ell^d(\mathbb{Z}^s)$ acting as

$$F_k c = [\downarrow_{M_k} F_{k,j} c : j = 0, \dots, d-1]$$

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Perfect reconstruction:

$$G_k F_k = I, \quad k \in \mathbb{Z}_m$$



Symbol notation

Given a finitely supported a

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• Subsymbols:

$$a_{\xi_j}^\sharp(z):=\sum_{lpha\in\mathbb{Z}^{\mathbf{s}}} a(Mlpha+\xi_j) z^lpha, \quad j=0,\ldots,d-1$$

Start from the **lowpass** reconstruction filter G_0 associated to a mask *a*.

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- simple for interpolatory schemes

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In 1D $\longrightarrow a^{\sharp}(z)$ and $a^{\sharp}(-z)$ have no common zeros.

Simplest filter bank \rightarrow lazy filters: translation operators

$$au_{\xi_i}, \quad i=0,\ldots,d-1$$

In fact

$$I = \sum_{i=0}^{d-1} \tau_{\xi_i} \uparrow \downarrow \tau_{-\xi_i},$$

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In fact

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It:

- decomposes a signal modulo *M* in the analysis
- recombines the components in the synthesis

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A subdivision operator S_a with dilation matrix M is called **interpolatory** if

 $S_{a}c(M \cdot) = c$, for any $c \in \ell(\mathbb{Z}^{s})$

Prediction-correction scheme

The completion of an interpolatory *a* yields the prediction–correction scheme

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• Analysis part:

$$F_0 = I, \qquad F_j = \tau_{-\xi_j} \left(I - S_a \downarrow_M \right), \quad j = 1, \dots, d-1,$$

• Synthesis part:

$$G_0$$
 and $G_j = \tau_{\xi_j}, \quad j = 1, \dots, d - 1.$

Prediction-correction scheme

In terms of symbols:

$$egin{aligned} &\mathcal{F}_0^{\sharp}(z) = 1, & \mathcal{F}_j^{\sharp}(z) = z^{\xi_j} - a_{\xi_j}^{\sharp}(z^{-M}), & j = 1, \dots, d-1 \ & \mathcal{G}_0^{\sharp}(z) = a^{\sharp}(z), & \mathcal{F}_j^{\sharp}(z) = z^{\xi_j}, & j = 1, \dots, d-1 \end{aligned}$$

Let

$$M = \Theta \Sigma \Theta'$$

be a Smith factorization of the expanding matrix *M*, where

 $\Sigma = \begin{bmatrix} \sigma_1 & & & \\ & \sigma_2 & & \\ & & \ddots & \\ & & & \sigma_s \end{bmatrix}$

and Θ , Θ' unimodular

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with scaling factors or "arity" σ_j ; 2 Consider the tensor product

$$b_{\Sigma} := \bigotimes_{j=1}^{s} b_j, \qquad b_{\Sigma}(\alpha) = \prod_{j=1}^{s} b_j(\alpha_j), \quad \alpha \in \mathbb{Z}^{s},$$

which is an interpolatory subdivision scheme for the diagonal scaling matrix Σ , i.e.

$$b_{\Sigma}(\Sigma \cdot) = \delta$$

Set

 $b_M := b_{\Sigma}(\Theta^{-1} \cdot)$

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In terms of symbols:

$$b^{\sharp}_{M}(z) = b^{\sharp}_{\Sigma}\left(z^{\Theta}
ight)$$

We are considering the matrices

$$egin{aligned} M_0 &:= \left[egin{array}{cc} 1 & 1 \ 1 & -2 \end{array}
ight] \ M_1 &:= S_1 M_0 &= \left[egin{array}{cc} 2 & -1 \ 1 & -2 \end{array}
ight], \end{aligned}$$

where we make use of the shear matrices

$$S_j := \begin{bmatrix} 1 & j \\ 0 & 1 \end{bmatrix}, \qquad j \in \mathbb{Z}.$$

It is easily verified that

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- M_0 is anisotropic (eigenvalues: $\frac{1}{2}(1 \pm \sqrt{13})$
- M_1 is isotropic (eigenvalues: $\pm\sqrt{3}$)
- M_0 and M_1 are jointly expanding so they define a reasonable subdivision scheme.

Coset representation: *M*₀



Coset representation: M_1



Sequence 0 0 0 0 0 0

Initial data



Sequence 1 1 1 1 1 1

Initial data



Sequence 0 1 0 1 0 1

Initial data



Sequence 1 0 1 0 1 0

Initial data


$$\phi_{\eta}(M_{\epsilon}\cdot-\alpha), \qquad \alpha\in\mathbb{Z}^{s}.$$

Multiple multiresolution analysis

.

$$\phi_{\eta}(M_{\epsilon}\cdot-lpha), \qquad lpha\in\mathbb{Z}^{s}.$$

• ϕ_{η} : limit function of subdivision

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Can we get "all rotations" by appropriate ϵ ?

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 \rightarrow Slope resolution

Multiple multiresolution analysis

Action of:

 M_1M_1 (blue), M_0M_1 (red), M_1M_0 (green), M_0M_0 (cyan) on the unit vectors



Action of:

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on the unit vectors





Can all directions, i.e., all lines through the origin, be generated by applying an appropriate M_{ϵ} to a given reference line?



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Given the reference line

$$L_x := \mathbb{R} x, \quad x \in \mathbb{R}^2$$

and a target line

$$L_y := \mathbb{R} y, \quad y \in \mathbb{R}^2$$

we ask whether there exists $\epsilon \in \mathbb{Z}_m^*$ such that

 $L_y \sim M_\epsilon L_x.$

Multiple multiresolution analysis

.

We represent lines by means of slopes, setting

$$L(s) := \mathbb{R} \begin{bmatrix} 1 \\ s \end{bmatrix}, \qquad s \in \mathbb{R} \cup \{\pm \infty\},$$

where $s = \pm \infty$ corresponds to (the same) vertical line.



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Theorem

For each $s \in (0, \frac{1}{2})$, any $s' \in \mathbb{R}$ and any $\delta > 0$ there exists $\epsilon \in \mathbb{Z}_m^*$ such that

$$|s'-s_{\epsilon}| < \delta, \qquad L(s_{\epsilon}) = M_{\epsilon}L_s.$$

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Indeed even combinations of $M_{01} = M_0 M_1$ and $M_{01} = M_1 M_0$ are sufficient to satisfy the claim of the theorem.

Smith factorizations of M_0 , M_1 :

$$\begin{split} M_0 &= \begin{bmatrix} 4 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & \\ & 3 \end{bmatrix} \begin{bmatrix} 1 & -2 \\ -1 & 3 \end{bmatrix}, \\ M_1 &= \begin{bmatrix} 5 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & \\ & 3 \end{bmatrix} \begin{bmatrix} 1 & -2 \\ -1 & 3 \end{bmatrix}. \end{split}$$

Multiple multiresolution analysis

Possible choices for the ternary interpolatory schemes

• piecewise linear interpolant:

$$b_2 = \frac{1}{3} (\dots, 0, 1, 2, 3, 2, 1, 0, \dots)$$

Multiple multiresolution analysis

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four point scheme based on local cubic interpolation

$$b_2 = \frac{1}{81} (\dots, 0, -4, -5, 0, 30, 60, 81, 60, 30, 0, -5, -4, 0, \dots)$$

The schemes are obtained from

$$b^{\sharp}_{M}(z) = b^{\sharp}_{\Sigma}\left(z^{\Theta}
ight)$$

which result in the following two symbols

$$A_1^{\sharp}(z_1, z_2) = rac{z_1^{-2}}{3} \left(1 + z_1 + z_1^2\right)^2,$$

$$egin{split} {\mathcal A}_2^{\sharp}(z_1,z_2) = -rac{z_1^{-5}}{81} \left(1+z_1+z_1^2
ight)^4 \ \left(4z_1^2-11z_1+4
ight), \end{split}$$

Theorem *Suppose:*

- b_j , j = 1, ..., s define univariate subdivision schemes with scaling factors $\sigma_j \ge 1$
- $S_{b_j} 1 = 1.$

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- b_j , j = 1, ..., s define univariate subdivision schemes with scaling factors $\sigma_j \ge 1$
- $S_{b_j} 1 = 1.$

Then b_M is a convergent subdivision scheme with dilation matrix M iff the vector scheme $S_{B_{\Sigma}}$ defined by $\nabla D_{(\Theta'\Theta)^{-1}}S_{b_{\Sigma}} = S_{B_{\Sigma}}\nabla$ satisfies

$$1 > \rho_{\infty} \left(S_{B_{\Sigma}} \mid \nabla \right) := \lim_{n \to \infty} \sup_{\|\nabla c\| \le 1} \left\| S_{B_{\Sigma}}^{n} \nabla c \right\|^{1/n}$$

where

- D_{Λ} is the dilation operator $D_{\Lambda}c = c(\Lambda \cdot)$
- ∇ is the forward difference operator $\nabla c = [c(\cdot + \epsilon_j) - c : j = 1, ..., s]$









Filter bank associated to *M*₀

$$\begin{array}{c} A_{1}^{\sharp}(z_{1},z_{2}) = \frac{z_{1}^{-2}}{3} \left(1 + z_{1} + z_{1}^{2}\right)^{2} \text{ and } M_{0} \\ \begin{array}{c} \text{Analysis} \\ F_{0} & F_{1} & F_{2} \\ \left[\begin{array}{ccc} 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array}\right] & \left[\begin{array}{ccc} 0 & 0 & 0 & 0 & 0 \\ 0 & -\frac{2}{3} & 1 & 0 & -\frac{1}{3} \\ 0 & 0 & 0 & 0 & 0 \end{array}\right] & \left[\begin{array}{ccc} 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ -\frac{1}{3} & 0 & 1 & -\frac{2}{3} & 0 \end{array}\right]$$

Filter bank associated to *M*₁

$$A_{1}^{\sharp}(z_{1}, z_{2}) = \frac{z_{1}^{-2}}{3} (1 + z_{1} + z_{1}^{2})^{2} \text{ and } M_{1}$$
Analysis
$$F_{0} \qquad F_{1} \qquad F_{2}$$

$$\begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ -\frac{1}{3} & 0 & 1 & -\frac{2}{3} & 0 \end{bmatrix} \begin{bmatrix} 0 & -\frac{2}{3} & 1 & 0 & -\frac{1}{3} \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

































































Grazie!