

# **Efficient Data Collection Requires Incentives**

**MADLab 2022 Summer Workshop**

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# A Fishy Tale

*Rob*

$N(\mu, 1)$



# Single Agent Data Collection: Payoff Maximization

- Collect  $n$  data points  $x_1, \dots, x_n \sim N(\mu, 1)$
- Maximum Likelihood Estimate  $\hat{\mu} = \frac{1}{n} \sum_{j=1}^n x_j$
- Variance  $V(\hat{\mu}) = \frac{1}{n}$
- Key assumption: Agents collect data for economic reasons

# Single Agent Data Collection: Payoff Maximization

- Benefit to the agent:  $b(n)$  concave in  $n$  (diminishing return)
  - Example:  $b(n) = \sqrt{1/V(\hat{\mu})} = \sqrt{n}$
- Cost to the agent:  $c(n)$ 
  - Example:  $c(n) = \alpha n$ ,  $\alpha$  is unit data collection cost
- Payoff to agent  $u(n) = b(n) - c(n)$

# Single Agent Data Collection: Payoff Maximization

- How many fish would Rob want to measure?

$$\max_n u(n) = \sqrt{n} - \alpha n$$

$$\frac{1}{2\sqrt{n}} - \alpha = 0$$

$$n = \frac{1}{4\alpha^2}$$

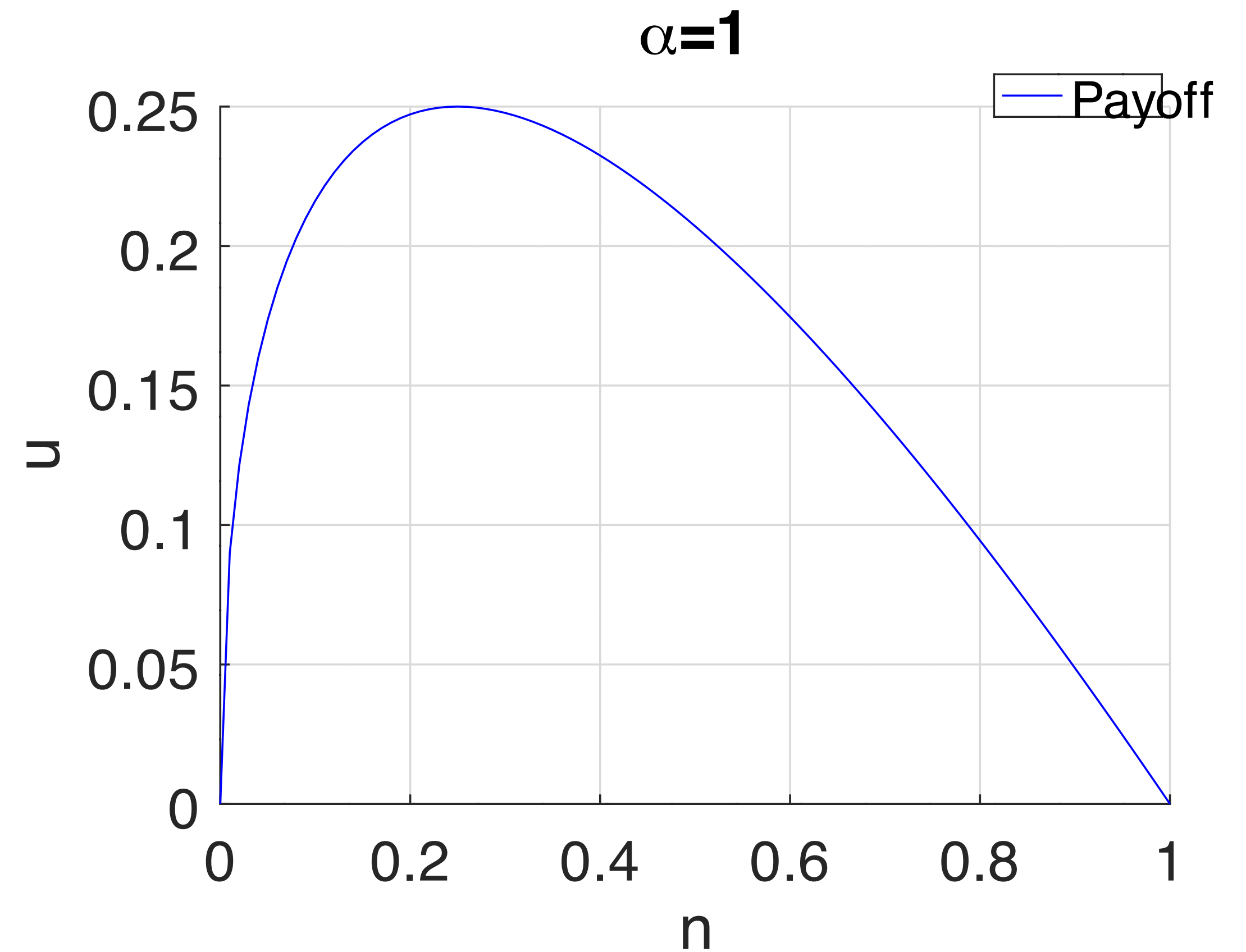
# Single Agent Data Collection: Payoff Maximization

$$n = \frac{1}{4\alpha^2}$$

“Continuous fish”



$$u(n) = \frac{1}{4\alpha}$$



# Let's All Measure Fish

- $m$  autonomous agents, each collecting  $n_1, \dots, n_m$  iid points from  $N(\mu, 1)$

- We will share our data

- $$V(\hat{\mu}) = \frac{1}{\sum_{i=1}^m n_i}$$

- Payoff to agent  $i$ :

$$u_i(n_1, \dots, n_i, \dots, n_m) = \sqrt{\sum_{j=1}^m n_j} - \alpha n_i$$

# Rationality

- Agent  $i$  action space  $n_i \in \mathbb{R}_{\geq 0}$
- The Best Response to other agents who play  $n_{-i} = (n_1, \dots, n_{i-1}, n_{i+1}, \dots, n_m)$ :

$$n_i^{BR} \in \arg \max_{n_i} u_i(n_i, n_{-i})$$

- “If others play  $n_{-i}$ , I do not want to deviate from  $n_i^{BR}$ .”
- But what *will* others play?



# Nash Equilibrium

- $(n_1^*, \dots, n_m^*)$  is a Nash equilibrium if the components are BR to each other:

$$n_i^* \in \arg \max_{n_i} u_i(n_i, n_{-i}^*), \forall i \in [m]$$

- Our problem is symmetric
- *Assume* a symmetric NE  $(n^*, \dots, n^*)$

# Multi-Agent Rational Data Collection

$$n_i^* \in \arg \max_{n_i} u_i(n_i, n_{-i}^*), \forall i \in [m]$$

$$\frac{\partial u_i(n_i, n_{-i} = n^*)}{\partial n_i} \Bigg|_{n_i = n^*} = 0$$

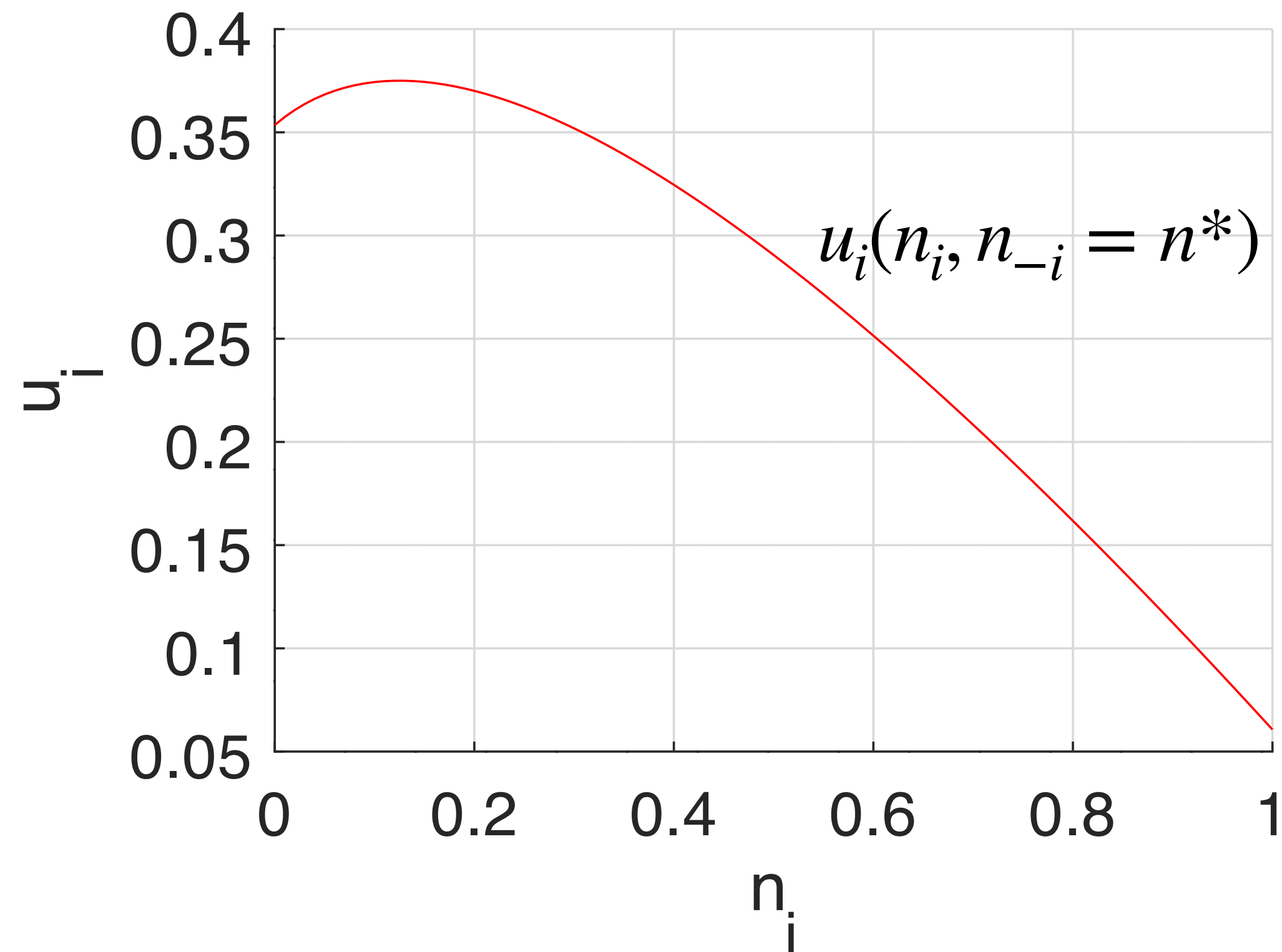
$$n^* = \frac{1}{4\alpha^2 m}$$

# Multi-Agent Rational Data Collection

$$n^* = \frac{1}{4\alpha^2 m}$$

$$u_i(n^*, \dots, n^*) = \frac{1}{2\alpha} - \frac{1}{4\alpha m}, \forall i \in [m]$$

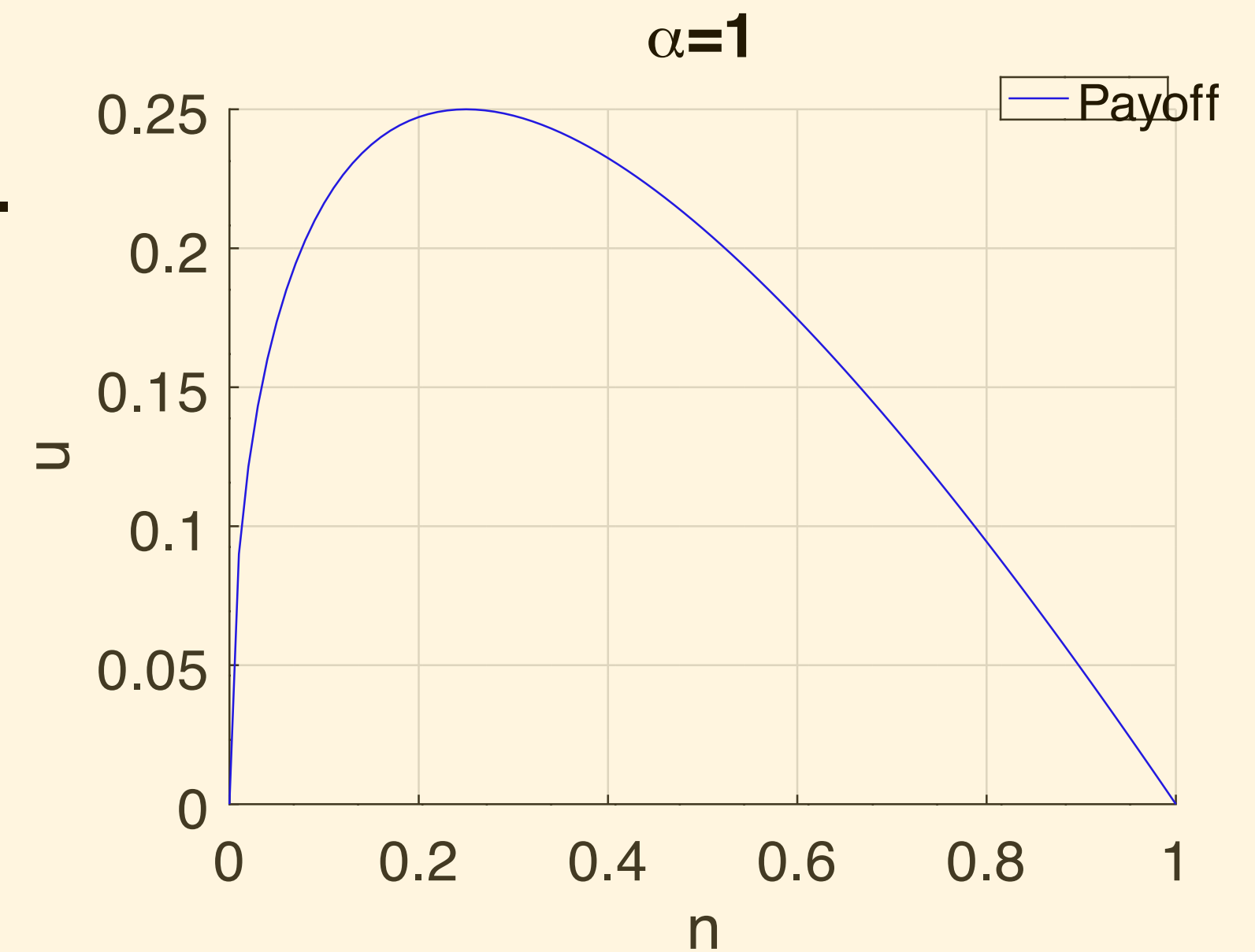
**m=2**



Compared to Rob alone

$$n = \frac{1}{4\alpha^2}$$

$$u(n) = \frac{1}{4\alpha}$$



# Tragedy of the Data Scientists

- But each of us could have done much better!
- Let's each collect  $n^\dagger$  points

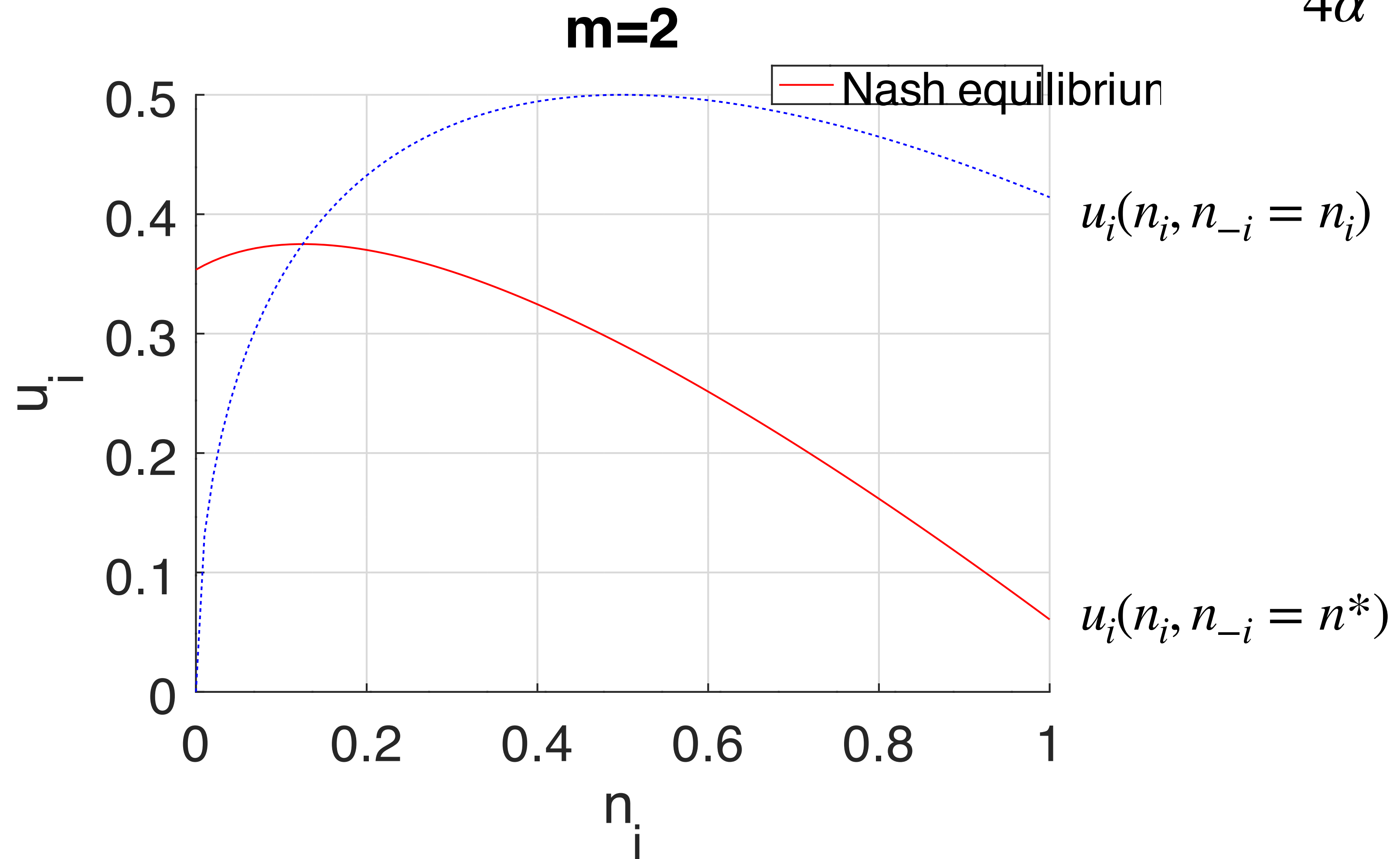
$$u_i(n_i = n^\dagger, n_{-i} = n^\dagger) = \sqrt{mn^\dagger} - \alpha n^\dagger$$

$$\frac{du_i(n_i = n^\dagger, n_{-i} = n^\dagger)}{dn^\dagger} = 0$$

$$n^\dagger = \frac{m}{4\alpha^2}$$

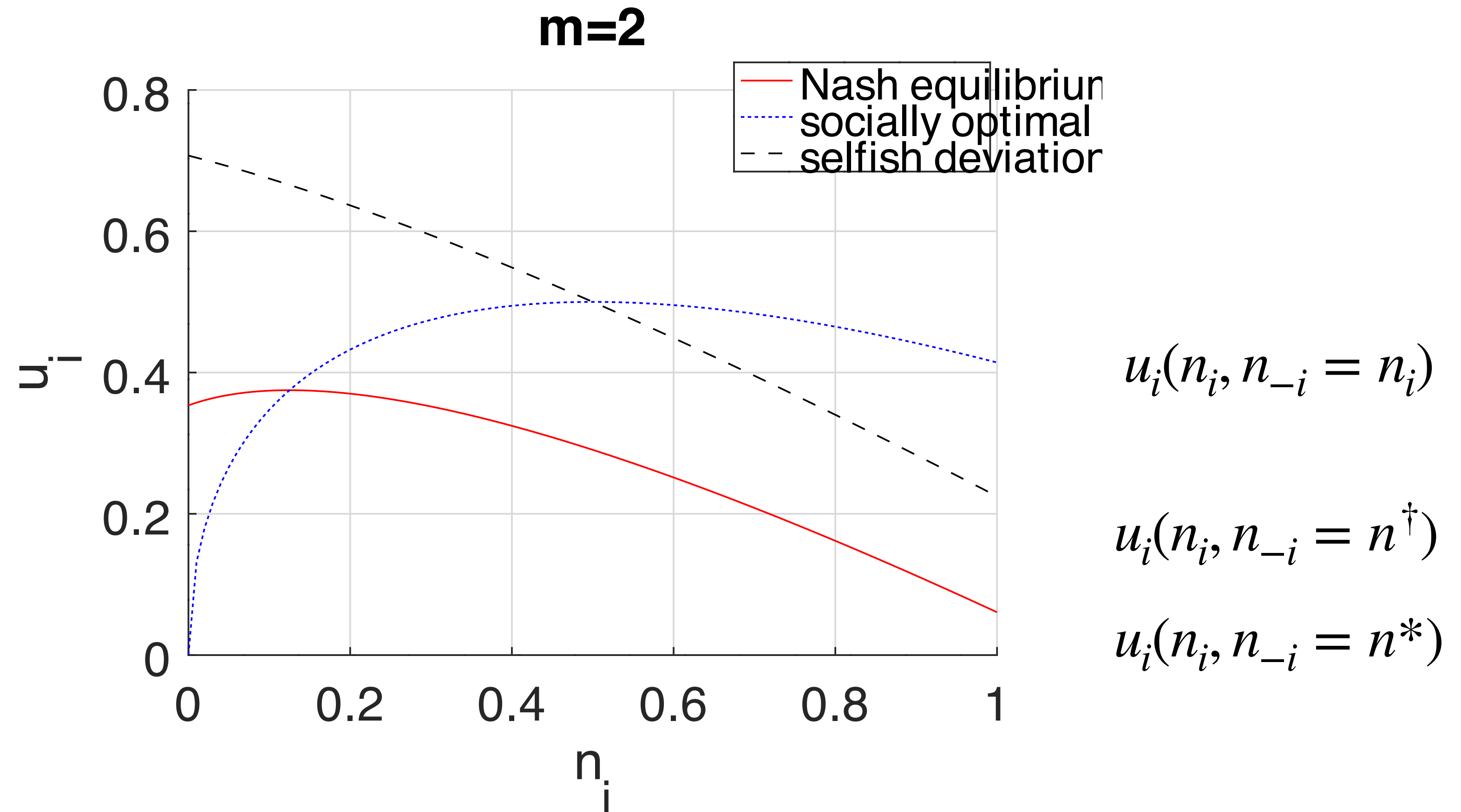
# Tragedy of the Data Scientists

- $n^\dagger = \frac{m}{4\alpha^2}$  is the socially optimal fair assignment (SOFA),  $u_i(n^\dagger \dots n^\dagger) = \frac{m}{4\alpha}$



# Tragedy of the Data Scientists

- The tragedy: no one will play SOFA.
- If others collect  $n^\dagger$ , I want to cheat and collect *no data*



# More than Fish

## Another example: multi-armed bandit

- Two Gaussian arms  $\Delta = \mu_2 - \mu_1 > 0$
- $m$  agents running the ETC algorithm
- Agent  $j$  pulls arm 1  $T_j/2$  time and arm 2  $T_j/2$  times (each pull costs  $\alpha$ )
- Agents pool data together to find the best empirical arm  $\hat{a} \in \{1,2\}$
- Each agent commits to  $\hat{a}$  for  $T'$  deployment rounds

$$u_j(T_1, \dots, T_m) = \frac{T_j}{2}(\mu_1 - \alpha) + \frac{T_j}{2}(\mu_2 - \alpha) + T'(E[\mu_{\hat{a}}] - \alpha)$$

# More than Fish

Another example: multi-armed bandit

- Nash equilibrium

$$T^* = \frac{4}{\Delta^2 m} W \left( \frac{T'^2 \Delta^6}{32\pi(2\alpha - \mu_1 - \mu_2)^2} \right)$$

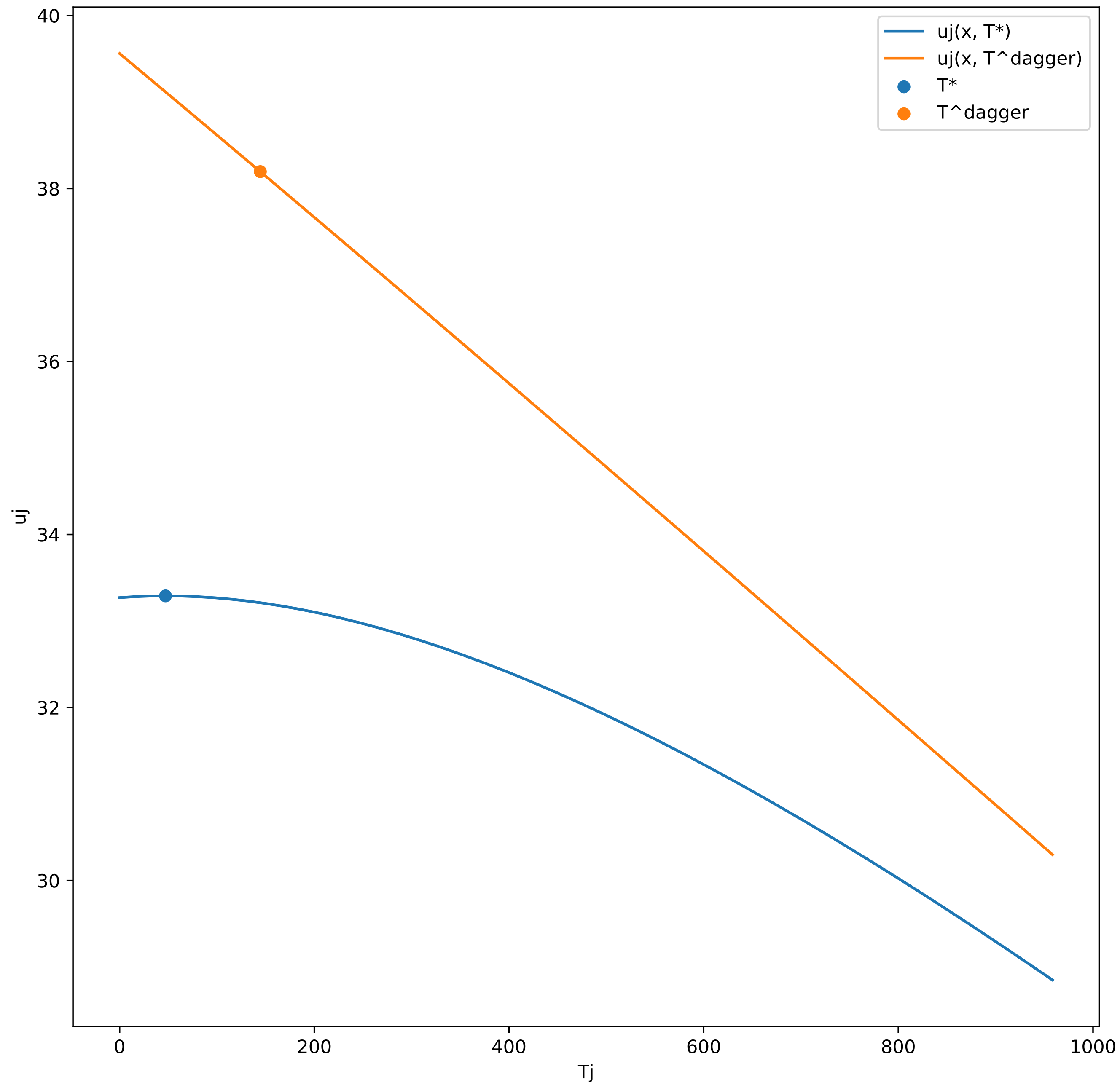
- SOFA

$$T^\dagger = \frac{4}{\Delta^2 m} W \left( \frac{m^2 T'^2 \Delta^6}{32\pi(2\alpha - \mu_1 - \mu_2)^2} \right)$$

Lambert W function:  $xe^x = z \Rightarrow x = W(z)$



mu1 = 0, mu2 = 0.1, c = 0.06, T' = 1000, m = 20



$$u_i(T_i, T_{-i} = T^\dagger)$$

$$u_i(T_i, T_{-i} = T^*)$$

# Data Collection Inefficiency in General

- Recall payoff = benefit - cost

$$u_i(n_1, \dots, n_m) := b \left( \sum_{j=1}^m n_j \right) - c(n_i)$$

- Nash is the solution to  $b'(mn^*) - c'(n^*) = 0$
- SOFA is the solution to  $mb'(mn^\dagger) - c'(n^\dagger) = 0$

# A Sufficient Condition for Tragedy

$$u_i(n_1, \dots, n_m) := b \left( \sum_{j=1}^m n_j \right) - c(n_i)$$

If:

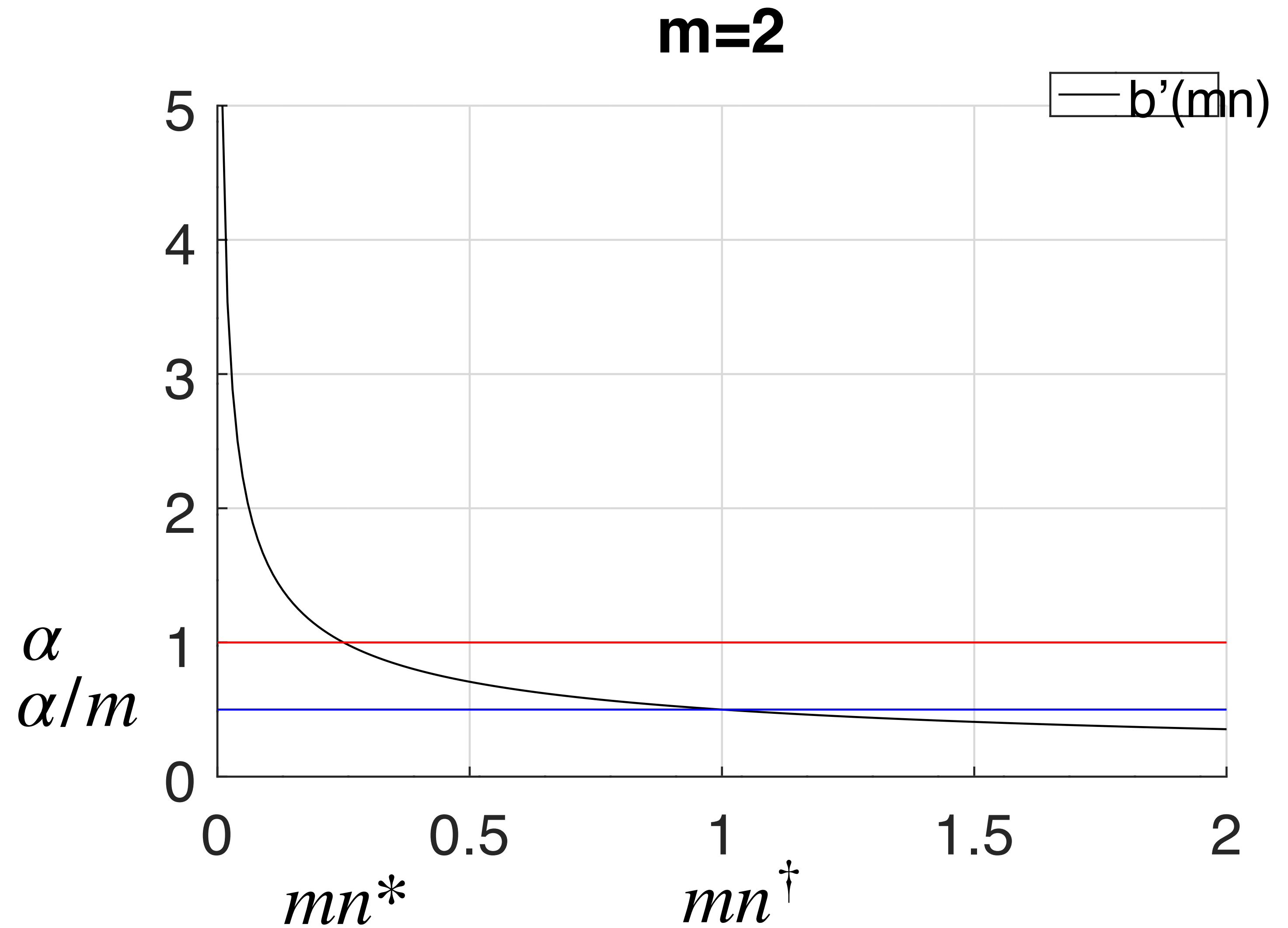
- $b$  strictly concave and non-decreasing (diminishing return)
- $c = \alpha n_i$  linear (unit cost)

then

$$n^* < n^\dagger$$

# Proof by Picture

- Nash:  $b'(mn^*) = \alpha$
- SOFA:  $b'(mn^\dagger) = \frac{\alpha}{m}$



# Efficient Data Collection Requires ~~Incentives~~ Coercion

- Paying them a unit price  $p$  is not a solution: merely changes  $\alpha$  into  $\alpha - p$
- Server: takes all data, learn, sends model to agent  $i$  only if  $n_i = n^\dagger$ 
  - Changes payoff  $u_i(n_1, \dots, n_m) = b(\sum n_j) \mathbf{1}[n_i = n^\dagger] - c(n_i)$
  - $(n^\dagger, \dots, n^\dagger)$  now a Nash equilibrium
- Tyranny of the server: enslaves the agents by pushing  $n^\dagger$  toward the solution to  $u_i = b(mn^\dagger) - c(n^\dagger) \downarrow 0$
- What if agents fake data?