### Humans Perform Semi-Supervised Classification Too

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Zhu, Rogers, Qian, Kalish (Wisconsin) Human Semi-Supervised Learning

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Zhu, Rogers, Qian, Kalish (Wisconsin) Human Semi-Supervised



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## The semi-supervised learning task



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 Assuming each class is a coherent group (e.g. Gaussian), semi-supervised machine learning predicts decision boundary shift.

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• Do we humans shift decision boundary too?

Human learning: a behavioral experiment

#### Goal

Determine human decision boundaries for:

- labeled data only vs. labeled and unlabeled data
- same labeled data, different unlabeled data

#### • 22 University of Wisconsin students

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- Press B or N to classify
- Label: audio feedback
- No audio feedback for unlabeled data

## Visual stimuli

Stimuli parameterized by a continuous variable x.



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- Order within each block randomized
- Record their decisions and response times



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• (labeled) 10 (x = 1, B), 10 (x = -1, N). The only labeled block.

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**2** (test-1) 
$$x = -1, -0.9, \dots, 0.9, 1$$

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- $\label{eq:constraint} \bigcirc \ \ (unlabeled-1)\ 230\ stimuli \sim \\ offset\ 2\ Gaussian,\ left-\ or \\ right-shifted.\ 21\ range\ stimuli \\ evenly\ in\ [-2.5,2.5] \\ \end{matrix}$

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**(test-2)**  $x = -1, -0.9, \dots, 0.9, 1$ 

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Decision boundary:

- after labeled data (test-1): x = 0.11
- after labeled and unlabeled data (test-2):
   L-subjects x = -0.10, R-subjects x = 0.48

### Observation 2: Reaction time reflects boundary shift



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- $\bullet$  Longer reaction time  $\rightarrow$  closer to decision boundary
- Test-2 overall faster, familiarity with experiment
- L-, R-reaction time further support decision boundary shift

## Machine learning model

We can explain the human experiment with a 2-component Gaussian Mixture Model (GMM).

The GMM:

$$w_1 N(\mu_1, \sigma_1^2) + w_2 N(\mu_2, \sigma_2^2)$$
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Prior on parameters  $\theta$ :

$$w_k \sim \text{Uniform}[0,1], \mu_k \sim \mathcal{N}(0,\infty), \sigma_k^2 \sim \text{Inv} - \chi^2(\nu, s^2), k = 1, 2$$

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We fit the GMM with the Expectation-Maximization (EM) algorithm on blocks 1,2 vs. on all blocks.

### EΜ

Maximize the objective ( $\lambda \leq 1$  weight on unlabeled example)

$$\log p(\theta) + \sum_{i=1}^{l} \log p(x_i, y_i | \theta) + \lambda \sum_{i=l+1}^{n} \log p(x_i | \theta)$$

#### E-step

$$q_i(k) \propto w_k \mathcal{N}(x_i; \mu_k, \sigma_k^2), \quad i = l+1, \dots, n; k = 1, 2$$

M-step

$$\mu_{k} = \frac{\sum_{i=1}^{l} \delta(y_{i}, k) x_{i} + \lambda \sum_{i=l+1}^{n} q_{i}(k) x_{i}}{\sum_{i=1}^{l} \delta(y_{i}, k) + \lambda \sum_{i=l+1}^{n} q_{i}(k)}$$
  

$$\sigma_{k}^{2} = \frac{\nu s^{2} + \sum_{i=1}^{l} \delta(y_{i}, k) e_{ik} + \lambda \sum_{i=l+1}^{n} q_{i}(k) e_{ik}}{\nu + 2 + \sum_{i=1}^{l} \delta(y_{i}, k) + \lambda \sum_{i=l+1}^{n} q_{i}(k)}$$
  

$$w_{k} = \frac{\sum_{i=1}^{l} \delta(y_{i}, k) + \lambda \sum_{i=l+1}^{n} q_{i}(k)}{l + \lambda(n-l)}$$

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# Model fitting result 1



The GMM predicts the decision boundary shift:

## Model fitting result 2





## Model fitting result 3



The GMM also explains reaction time:

t = aH(x) + b, H(x) the entropy of label prediction

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- Flatness on [test-2] not well explained.
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- Further study may lead to new learning algorithms.