

# Advanced Search

## Hill climbing

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[Based on slides from Jerry Zhu, Andrew Moore <http://www.cs.cmu.edu/~awm/tutorials> ]

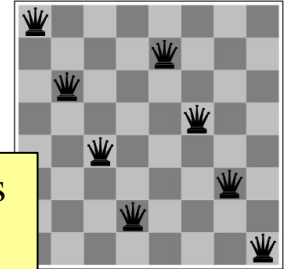
# Optimization problems

- Previously we want a **path** from start to goal
  - **Uninformed search**:  $g(s)$ : Iterative Deepening
  - **Informed search**:  $g(s)+h(s)$ : A\*
- **Now a different setting**:
  - Each state  $s$  has a **score**  $f(s)$  that we can compute
  - The goal is to find the state with the **highest score**, or a **reasonably high score**
  - Do not care about the path
  - This is an **optimization problem**
  - Enumerating the states is intractable
  - Even previous search algorithms are too expensive

# Examples

- N-queen:  $f(s)$  = number of conflicting queens in state  $s$

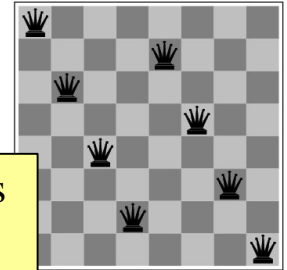
Note we want  $s$  with the lowest score  $f(s)=0$ . The techniques are the same. Low or high should be obvious from context.



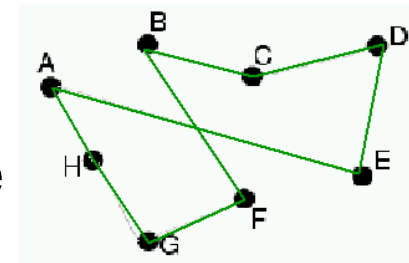
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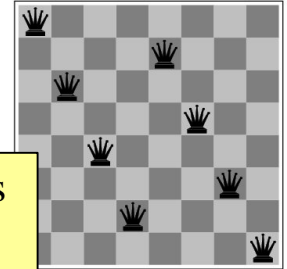
- Traveling salesperson problem (TSP)
  - Visit each city once, return to first city
  - State = order of cities,  $f(s)$  = total mileage



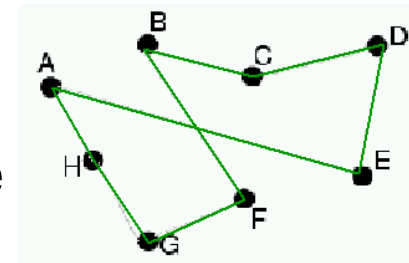
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- Traveling salesperson problem (TSP)
  - Visit each city once, return to first city
  - State = order of cities,  $f(s)$  = total mileage
- Boolean satisfiability (e.g., 3-SAT)
  - State = assignment to variables
  - $f(s)$  = # satisfied clauses



$A \vee \neg B \vee C$   
 $\neg A \vee C \vee D$   
 $B \vee D \vee \neg E$   
 $\neg C \vee \neg D \vee \neg E$   
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# 1. HILL CLIMBING

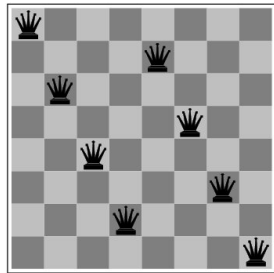


# Hill climbing

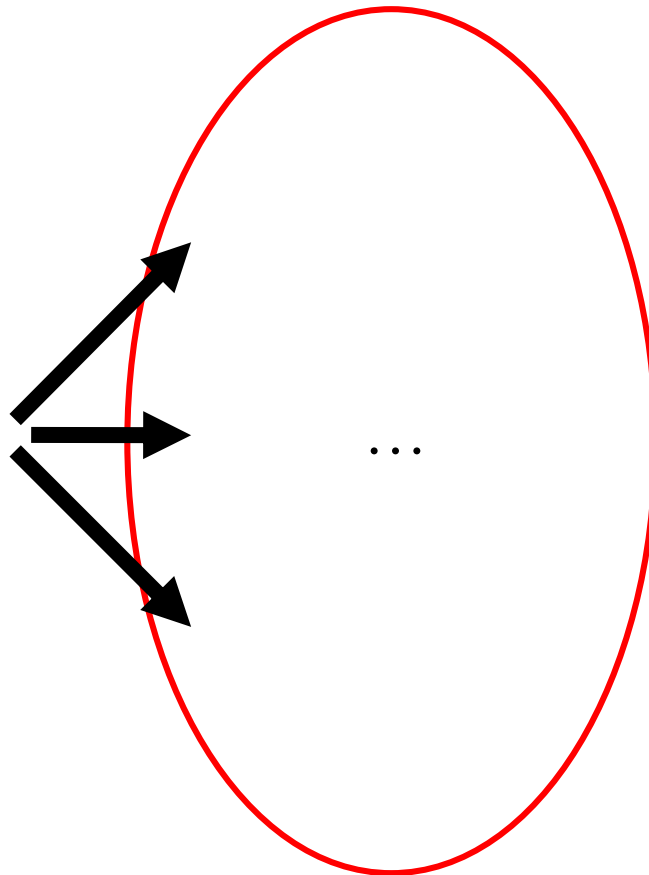
- Very simple idea: Start from some state  $s$ ,
  - Move to a neighbor  $t$  with better score. Repeat.
- **Question:** what's a neighbor?
  - You have to define that!
  - The **neighborhood** of a state is the set of neighbors
  - Also called 'move set'
  - Similar to successor function

# Neighbors: N-queen

- Example: N-queen (one queen per column). One possibility:



$s$   
 $f(s)=1$

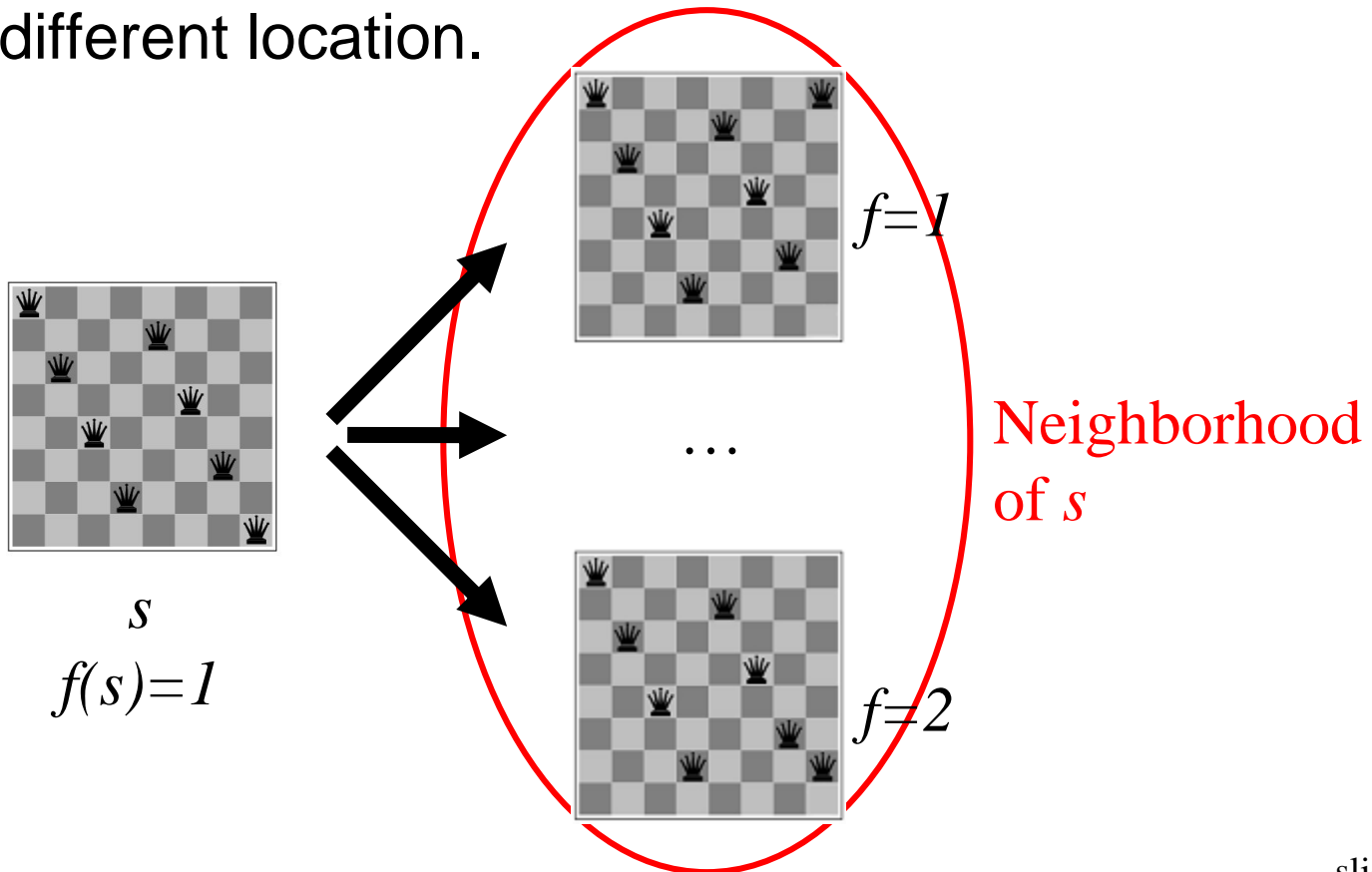


Neighborhood  
of  $s$



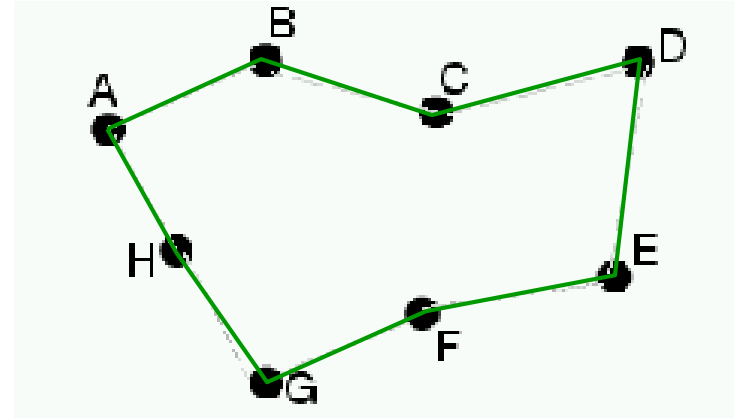
# Neighbors: N-queen

- Example: N-queen (one queen per column). One possibility: tie breaking more promising?
  - Pick the right-most most-conflicting column;
  - Move the queen in that column vertically to a different location.



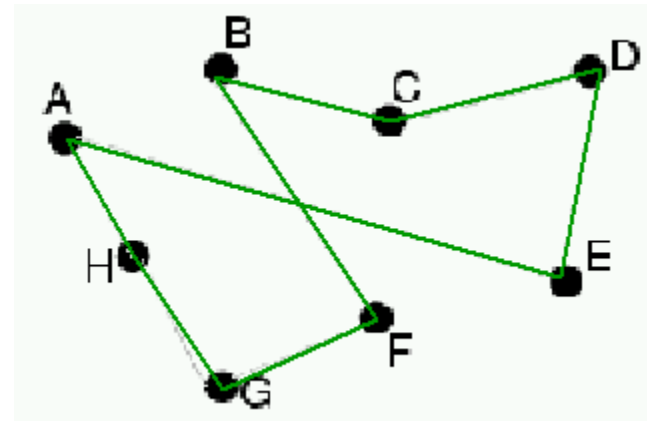
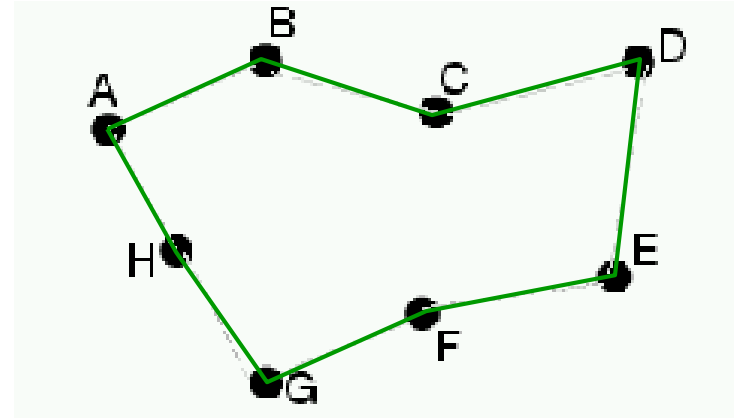
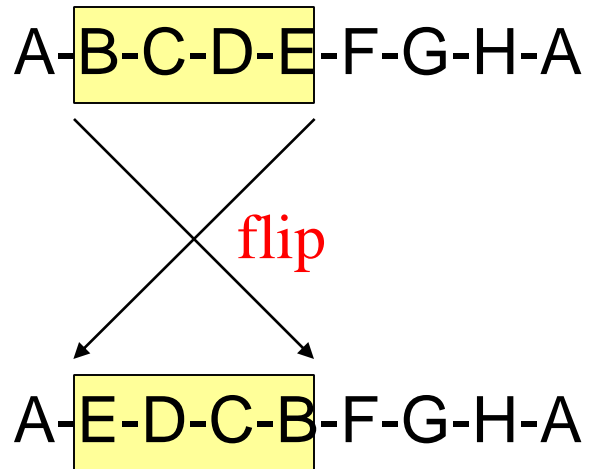
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- state: A-B-C-D-E-F-G-H-A
- $f$  = length of tour



# Neighbors: TSP

- state: A-B-C-D-E-F-G-H-A
- $f$  = length of tour
- One possibility: 2-change



# Neighbors: SAT

- State: (A=T, B=F, C=T, D=T, E=T)
- $f$  = number of satisfied clauses
- Neighbor:

$$A \vee \neg B \vee C$$

$$\neg A \vee C \vee D$$

$$B \vee D \vee \neg E$$

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# Neighbors: SAT

- State: (A=T, B=F, C=T, D=T, E=T)
- $f$  = number of satisfied clauses
- Neighbor: flip the assignment of one variable

(A=**F**, B=F, C=T, D=T, E=T)

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# Hill climbing

- **Question:** What's a neighbor?
  - (vaguely) Problems tend to have structures. A small change produces a neighboring state.
  - The neighborhood must be small enough for efficiency
  - **Designing the neighborhood is critical. This is the real ingenuity – not the decision to use hill climbing.**
- **Question:** Pick which neighbor?
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- **Question:** Pick which neighbor? **The best one (greedy)**
- **Question:** What if no neighbor is better than the current state? **Stop. (Doh!)**

# Hill climbing algorithm

1. Pick initial state  $s$
2. Pick  $t$  in neighbors( $s$ ) with the largest  $f(t)$
3. IF  $f(t) \leq f(s)$  THEN stop, return  $s$
4.  $s = t$ . GOTO 2.

- Not the most sophisticated algorithm in the world.
- Very greedy.
- Easily stuck.



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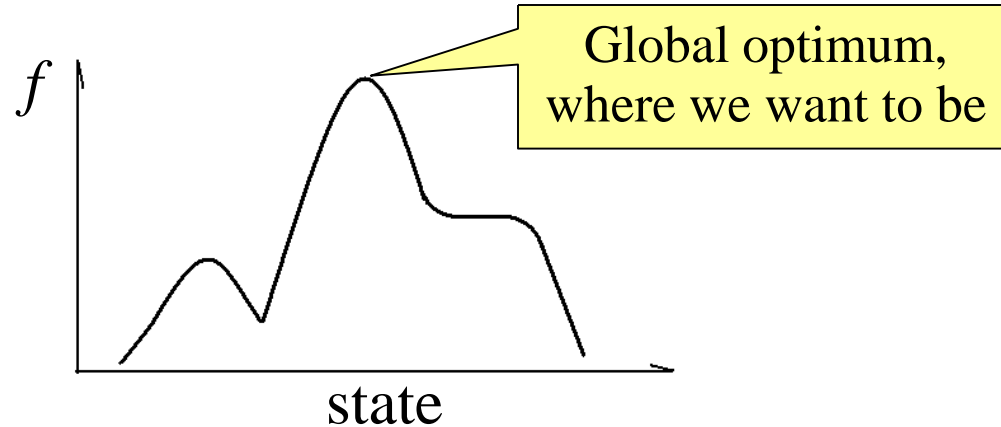
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your enemy:

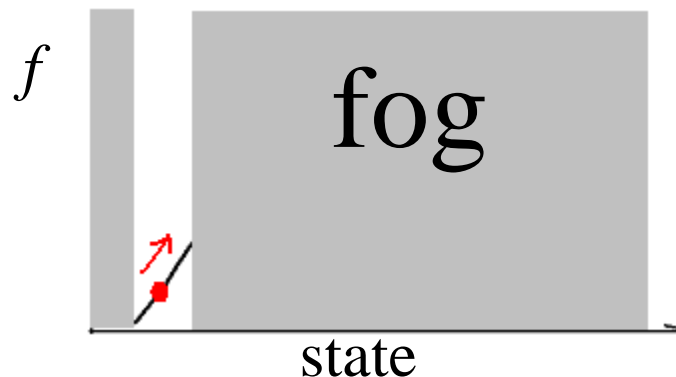
**local  
optima**

# Local optima in hill climbing

- Useful conceptual picture:  $f$  surface = 'hills' in state space

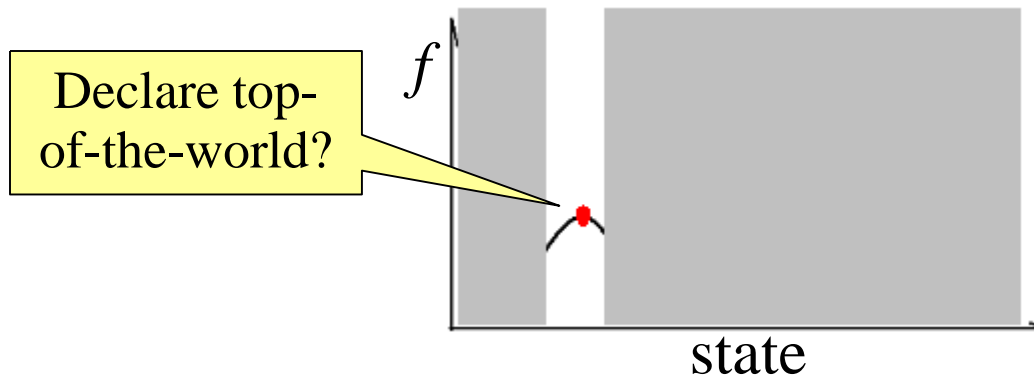


- But we can't see the landscape all at once. Only see the neighborhood. Climb in fog.

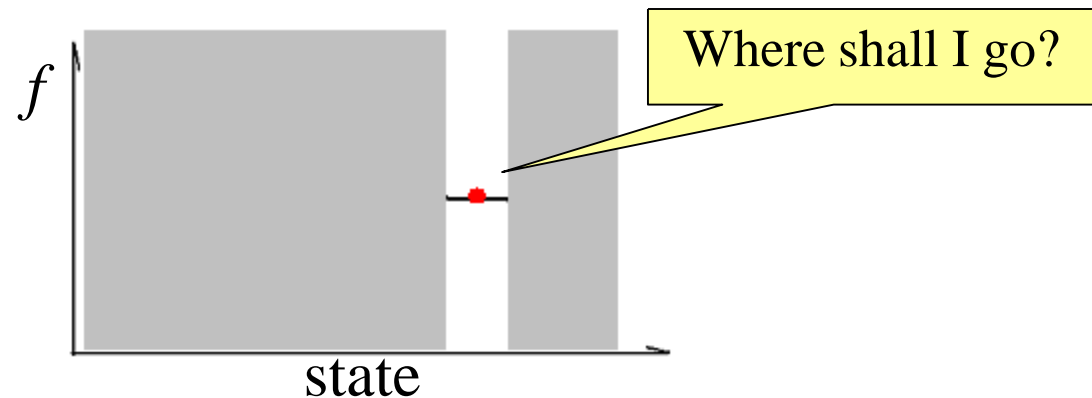


# Local optima in hill climbing

- Local optima (there can be many!)



- Plateaux



# Local optima in hill climbing

- Local optima (there can be many)

Declare the  
the world

The rest of the lecture is  
about

**Escaping  
local optima**

- Plateaus

Where shall I go?

# Not every local minimum should be escaped



# Repeated hill climbing with random restarts

- Very simple modification
  1. When stuck, pick a random new start, run basic hill climbing from there.
  2. Repeat this  $k$  times.
  3. Return the best of the  $k$  local optima.
- Can be very effective
- Should be tried whenever hill climbing is used

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- **Question:** What if the neighborhood is too large to enumerate? (e.g. N-queen if we need to pick both the column and the move within it)
  - First-choice hill climbing
    - Randomly generate neighbors, one at a time
    - If better, take the move
    - Pros / cons compared with basic hill climbing?

# Variations of hill climbing

- We are still greedy! Only willing to move upwards.
- Important observation in life:

Sometimes one needs to temporarily step back in order to move forward.

=

Sometimes one needs to move to an inferior neighbor in order to escape a local optimum.

# Variations of hill climbing

## WALKSAT [Selman]

- Pick a random unsatisfied clause
- Consider 3 neighbors: flip each variable
- If any improves  $f$ , accept the best
- If none improves  $f$ :
  - 50% of the time pick the least bad neighbor
  - 50% of the time pick a random neighbor

This is the best known algorithm for satisfying Boolean formulae.

$$\begin{array}{l} A \vee \neg B \vee C \\ \neg A \vee C \vee D \\ B \vee D \vee \neg E \\ \neg C \vee \neg D \vee \neg E \\ \neg A \vee \neg C \vee E \end{array}$$