

Nondeterminism and Epsilon Transitions

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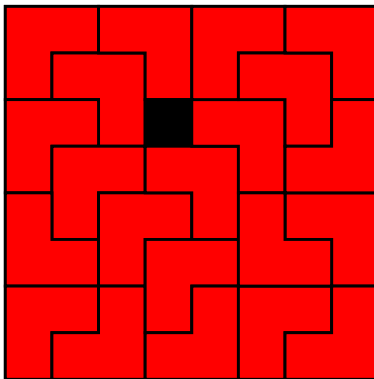
Stanford University

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Challenge Problem

Question

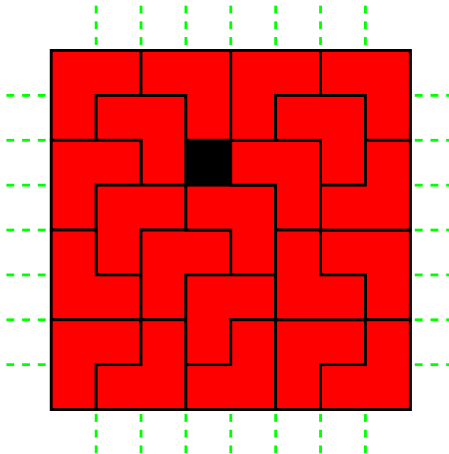
Prove that any square with side length a power of 2, and one square removed, is tileable with L's.



Something to think about ...

Question

Are such tilings always possible?



Recap: Deterministic Finite Automata

Definition

A DFA is a 5-tuple $(Q, \Sigma, \delta_D, q_0, F)$ consisting of:

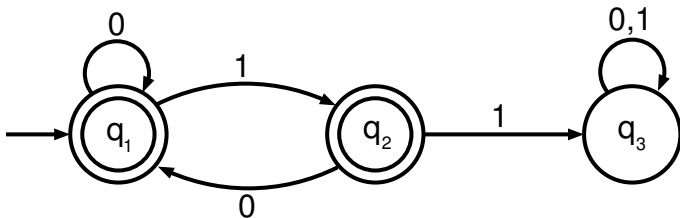
- A finite set of states Q ,
- A set of input alphabets Σ ,
- A transition function $\delta_D : Q \times \Sigma \rightarrow Q$,
- A start state q_0 , and
- A set of accept states $F \subseteq Q$.

The transition function δ_D :

- Takes two arguments, a state q and an alphabet a .
- $\delta_D(q, a)$ = the state the DFA goes to when it is in state q and the alphabet a is received.

Recap: Graph representation of DFA's

- Nodes correspond to states.
- Arcs represent transition function.
 - Arc from state p to state q labeled by **all** those input symbols that have transitions from p to q .
- Incoming arrow from outside denotes **start** state.
- Accept states indicated by **double** circles.



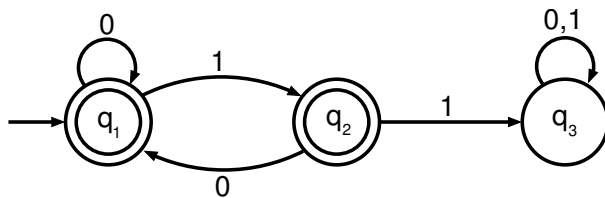
- Accepts all binary strings **without** two consecutive 1's.

Recap: Transition table for DFA's

→

	0	1
q_1^*	q_1	q_2
q_2^*	q_1	q_3
q_3	q_3	q_3

- A row for each **state**, a column for each **alphabet**.
- Accept states are **starred**.
- Arrow for the start state.



Recap: Regular languages

Definition

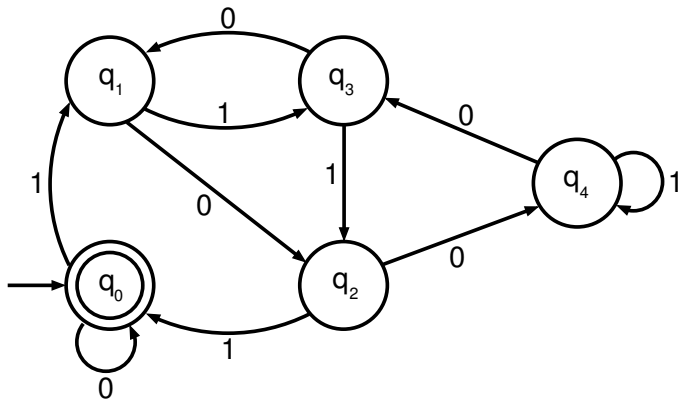
A DFA $M = (Q, \Sigma, \delta_D, q_0, F)$ **accepts** w if there exists a sequence of states r_0, r_1, \dots, r_n in Q with three conditions:

- $r_0 = q_0$
 - $\delta_D(r_i, w_{i+1}) = r_{i+1}$ for $i = 0, \dots, n - 1$, and
 - $r_n \in F$
-
- Condition 1 says that M starts in the start state q_0 .
 - Condition 2 says that M follows δ_D between two states.
 - Condition 3 says that last state is an **accept** state.
 - We say that M **recognizes** L if $L = \{w \mid M \text{ accepts } w\}$.

Regular Languages: Examples

Example

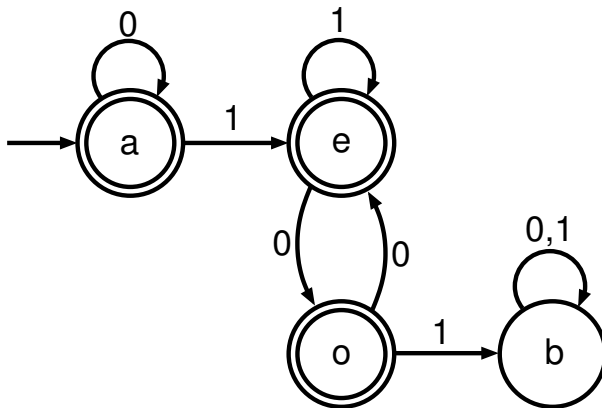
Let $L = \{w \mid w \in \{0,1\}^* \text{ and } w, \text{ viewed as a binary integer, is divisible by } 5.\}$



Regular Languages: Examples

Example

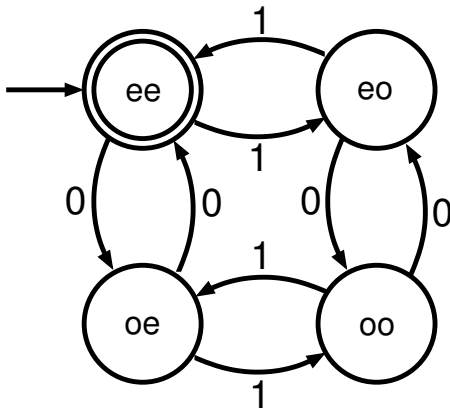
Show that the language of all strings over $\{0, 1\}$ that do not contain a pair of 1's that are separated by an odd number of 0's is regular.



Regular Languages: Examples

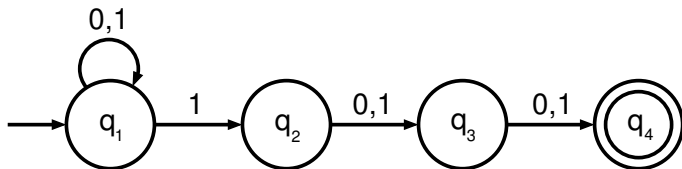
Example

Show that the language of all strings over $\{0,1\}$ that contain an even number of 0's and 1's is regular.



Nondeterminism

- **Deterministic** finite automata can only be in **one** state at any point in time.
 - Recall the definition of the transition function δ_D .
- In contrast, **nondeterministic** finite automata (NFA's) can be in **several** states at once!
 - The transition function δ_N is a **one-to-many** function.

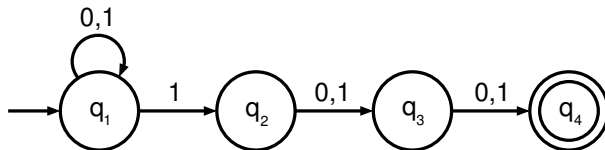


- This NFA recognizes strings in $\{0,1\}^*$ containing a **1** in the **third** position from the **end**.

Transition table

	0	1
\rightarrow q_1	q_1	q_1, q_2
q_2	q_3	q_3
q_3	q_4	q_4
q_4^*	q_4	q_4

- q_1 is a **nondeterministic** state with a **one-many** transition on **1**.

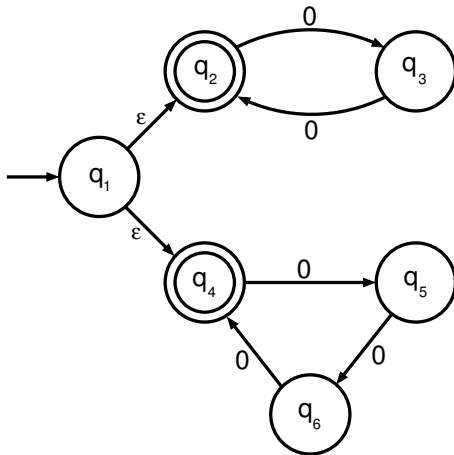


- Intuitively, the NFA always **guesses right**.

Nondeterministic Finite Automata

Example

An NFA that accepts all strings of the form 0^k where k is a multiple of 2 or 3.



Definition

An NFA is a 5-tuple $(Q, \Sigma, \delta_N, q_0, F)$ consisting of:

- A finite set of states Q ,
- A set of input alphabets Σ ,
- A transition function $\delta_N : Q \times \Sigma_\epsilon \rightarrow \mathcal{P}(Q)$,
- A start state q_0 , and
- A set of accept states $F \subseteq Q$.

- Here, Σ_ϵ denotes the set $\Sigma \cup \{\epsilon\}$.
- $\mathcal{P}(Q)$ denotes the power set of Q .

Transition function of an NFA

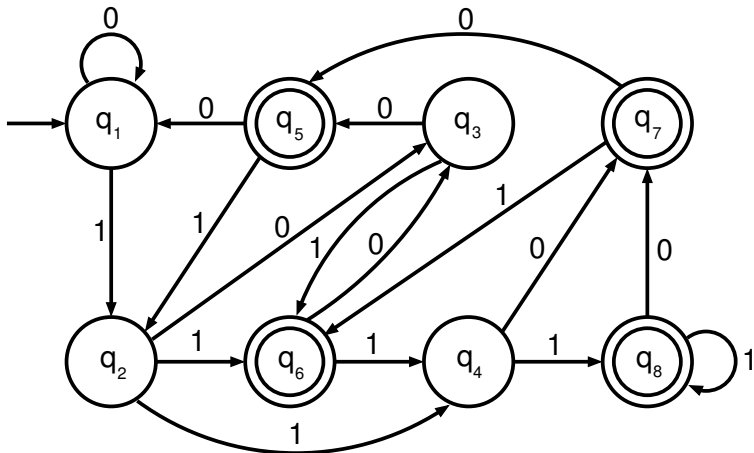
- $\delta_N(q, a)$ is a set of states.
- Extend to strings as follows:
 - **Basis:** $\delta_N(q, \epsilon) = q$
 - **Induction:** $\delta_N(q, wa) =$ the union over all states of $\delta_N(p, a)$, where $p \in \delta_N(q, w)$.
- A string is **accepted** by an NFA if $\delta_N(q_0, w)$ contains **at least** one state $p \subseteq F$.
- The language of an NFA is the set of strings it accepts.

Equivalence of DFA's and NFA's

- **Every** DFA is **also** an NFA by definition.
 - There is simply **no** nondeterminism.
- Surprisingly, for **every** NFA, there is also an **equivalent** DFA!
 - Two equivalent machines recognize the **same** language.
 - **Nonintuitive**, as we'd expect NFA's to be **more** powerful.
 - **Useful**, as describing an NFA is much simpler.
- Proof is the **subset construction**.
- The number of states of the DFA can be **exponential** in the number of states of the NFA.
- Thus, NFA's accept **exactly** the regular languages.

Equivalence of DFA's and NFA's

- DFA for recognizing strings with a **1** in the **third last** position.



Subset construction

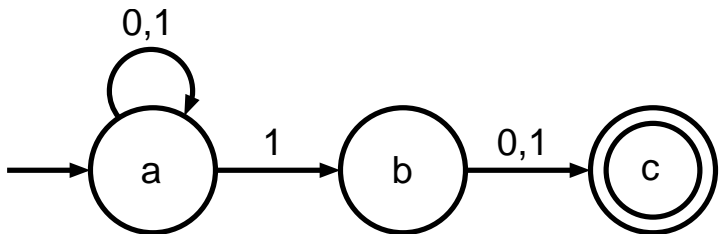
- Given an NFA $(Q, \Sigma, \delta_N, q_0, F)$, construct equivalent DFA with:
 - States $\mathcal{P}(Q)$ (set of subsets of Q).
 - Inputs Σ .
 - Start state $\{q_0\}$.
 - Final states = all those with a member of F .

Note:

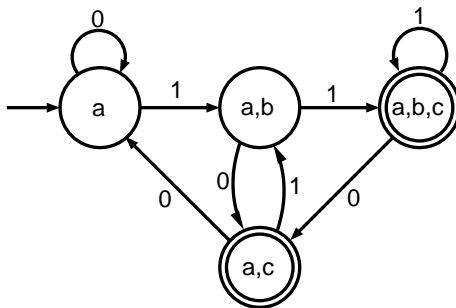
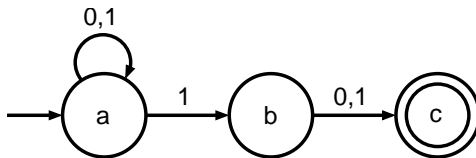
- The DFA states have **names** that are **sets** of NFA states.
- But as a DFA state, an expression like $\{p, q\}$ must be read as a **single** symbol.

Subset construction

- **Example:** We'll construct the DFA for the following NFA which recognizes strings in $\{0,1\}^*$ containing a **1** in the **second** position from the end.



Subset construction

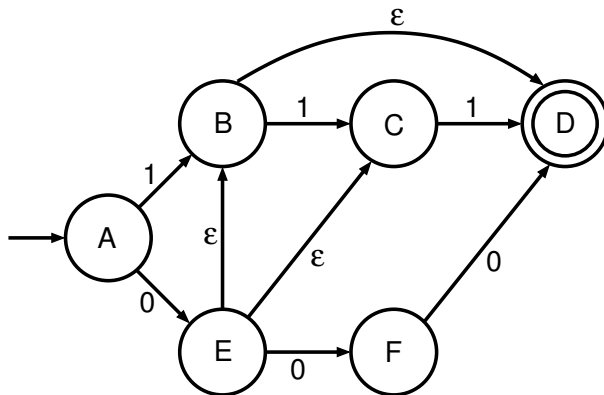


Proof of equivalence: subset construction

- Show by **induction** on length of w that $\delta_N(q_0, w) = \delta_D(\{q_0\}, w)$
- **Basis:** $w = \varepsilon$. $\delta_N(q_0, \varepsilon) = \delta_D(\{q_0\}, \varepsilon) = \{q_0\}$.
- **Inductive step:** Assume **IH** is true for all strings shorter than w . Let $w = xa$, then **IH** is true for x .
 - Let $\delta_N(q_0, x) = \delta_D(\{q_0\}, x) = S$.
 - Let $T =$ the union over all states p in S of $\delta_N(p, a)$.
 - Then $\delta_N(q_0, w) = \delta_D(\{q_0\}, w) = T$ (by definition).

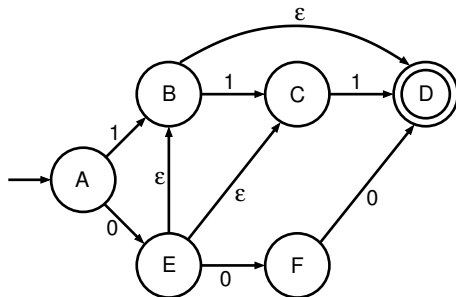
NFA's with ϵ -transitions

- State-to-state transitions on ϵ input.
- These transitions are **spontaneous**, and do not consider the input string.



Closure of States

- $CL(q)$ = set of states that can be reached from state q following only arcs labeled ϵ .

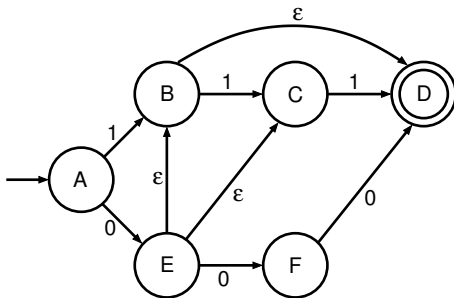


- $CL(A) = \{A\}$, $CL(E) = \{B, C, D, E\}$.
- Closure of set of states = union of closure of each state.

Extended transition function

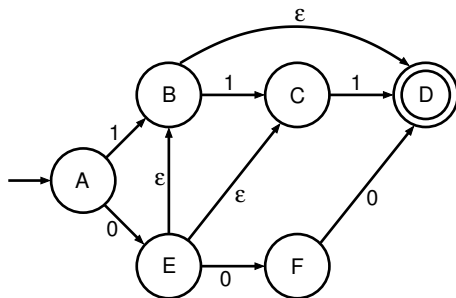
- **Basis:** $\delta_E(q, \varepsilon) = \text{CL}(q)$.
- **Induction:** $\delta_E(q, xa)$ is computed as follows:
 - ① Start with $\delta_E(q, x) = S$.
 - ② Take the union of $\text{CL}(\delta(p, a))$ for all p in S .
- **Intuition:** $\delta_E(q, w)$ is the set of states you can reach from q following a path labeled w with ε 's in between.

Example: Extended transition function



- $\delta_E(A, \varepsilon) = \text{CL}(A) = \{A\}$.
- $\delta_E(A, 0) = \text{CL}(E) = \{B, C, D, E\}$.
- $\delta_E(A, 01) = \text{CL}(C, D) = \{C, D\}$.

Example: Extended transition function



- **Language** of an ϵ -NFA is the set of strings **w** such that $\delta_E(q_0, w)$ contains a **final** state.

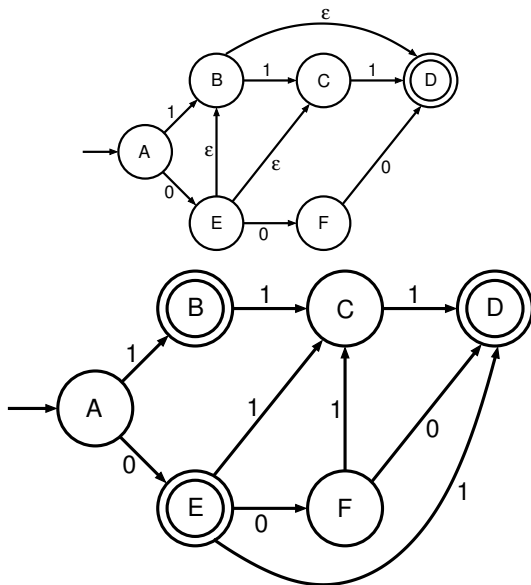
Equivalence of NFA, ε -NFA

- Every NFA **is** an ε -NFA.
 - It just has **no** ε -transitions.
- Converse requires us to take an ε -NFA and construct an NFA that accepts the **same** language.
- This is done by combining ε -transitions with the **next** transition on a **real** input.
- Start with an ε -NFA $(Q, \Sigma, q_0, F, \delta_E)$ and construct an **ordinary** NFA $(Q, \Sigma, q_0, F', \delta_N)$.

Equivalence of NFA, ε -NFA

- Compute $\delta_N(\mathbf{q}, \mathbf{a})$ as follows:
 - Let $S = \text{CL}(\mathbf{q})$.
 - $\delta_N(\mathbf{q}, \mathbf{a})$ is the union over all \mathbf{p} in S of $\delta_E(\mathbf{p}, \mathbf{a})$.
- F' = set of states \mathbf{q} such that $\text{CL}(\mathbf{q})$ contains a state of F .
- **Intuition:** δ_N incorporates ε -transitions **before** using \mathbf{a} .
- Proof of equivalence is by induction on $|\mathbf{w}|$ that $\text{CL}(\delta_N(\mathbf{q}_0, \mathbf{w})) = \delta_E(\mathbf{q}_0, \mathbf{w})$.
- **Basis:** $\text{CL}(\delta_N(\mathbf{q}_0, \varepsilon)) = \text{CL}(\mathbf{q}_0) = \delta_E(\mathbf{q}_0, \varepsilon)$.
- **Inductive step:** Assume **IH** is true for all \mathbf{x} shorter than \mathbf{w} .
Let $\mathbf{w} = \mathbf{x}\mathbf{a}$.
 - Then $\text{CL}(\delta_N(\mathbf{q}_0, \mathbf{x}\mathbf{a})) = \text{CL}(\delta_E(\text{CL}(\delta_N(\mathbf{q}_0, \mathbf{x})), \mathbf{a}))$ (by definition).
 - But from **IH**, $\text{CL}(\delta_N(\mathbf{q}_0, \mathbf{x})) = \delta_E(\mathbf{q}_0, \mathbf{x})$.
 - Hence, $\text{CL}(\delta_N(\mathbf{q}_0, \mathbf{w})) = \text{CL}(\delta_E(\delta_E(\mathbf{q}_0, \mathbf{x}), \mathbf{a})) = \delta_E(\mathbf{q}_0, \mathbf{w})$.

Example



Summary

- DFA's, NFA's and ε -NFA's all accept **exactly** the same set of languages: the **regular** languages.
- NFA types are easier to design and may have **exponentially fewer** states than a DFA.
- But only a DFA can be **implemented**!