

# CliqueMap: Productionizing an RMA-Based Distributed Caching System

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# Introduction / Summary

In-memory key-value caching/serving systems are crucial building blocks of user-facing services throughout the industry (Twemcache<sub>(osdi20)</sub>, CacheLib<sub>(osdi20)</sub> ....)



## Remote Memory Access (RMA):

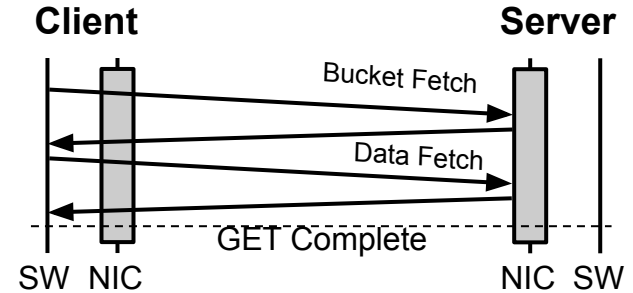
- Benefits: Performance/efficiency benefits
- Downsides: Limited programmability/narrow primitives
- *Production Challenges*
  - Delivering high availability and low cost
  - Balancing CPU- and RAM-efficiency
  - Evolving the system over time
  - Multi-language serving ecosystems
  - Navigating heterogeneous datacenters

**How do we  
productionize an  
RMA-based  
distributed caching  
system?**

# CliqueMap: Productionized RMA-Based Caching System

Hybrid RMA+RPC caching system in production use at Google 3+ years.

- Serves >1PB DRAM, >150M QPS
- RMAs on the critical serving path
- RPCs for mutations & other functions
- Simple “2xR” lookup protocol amenable to different underlying RMA technologies (RDMA, PonyExpress, 1RMA)



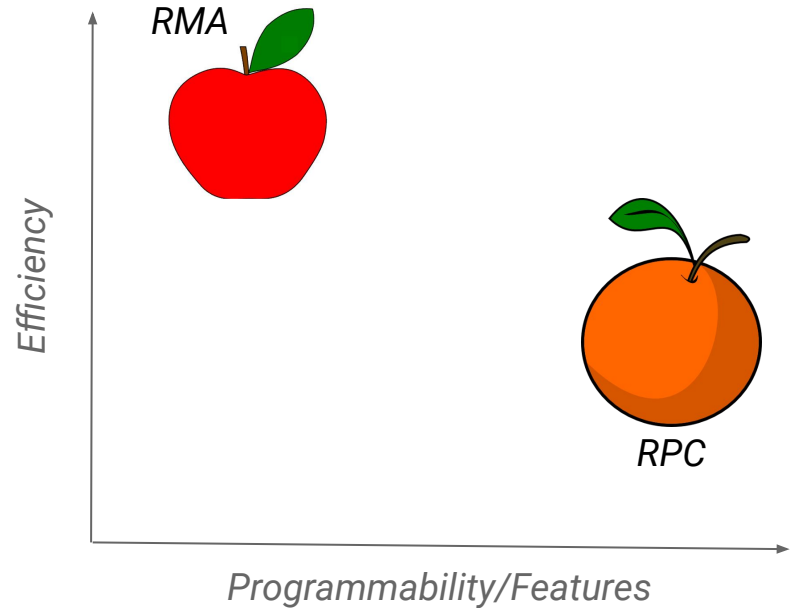
A 2xR-style R=1 Lookup operation using RMA primitives. A first operation to a predictable location *finds* the datum in an index. A second, dependent operation *retrieves* the datum.

# RPC or RMA? False dichotomy.

**RMAs** [*No application code runs on target*] offer narrow but efficient primitives.

**RPCs** [*Wherein arbitrary application code runs/responds on target*] offer easier productionization and high flexibility.

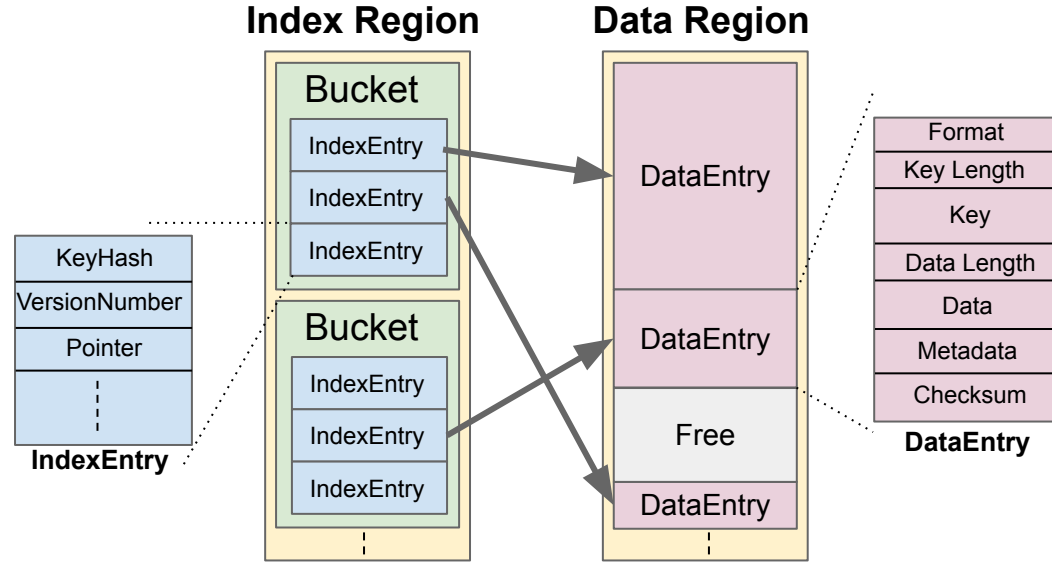
Hybrids like CliqueMap leverage the strengths of **both**: RMA for most/important operations to gain efficiency, RPC when programmability is needed.



# CliqueMap Approach and Building Blocks

**Self-verification:** A lookup self-verifies its outcome by strongly checksumming data, key, and metadata.

**Retry at the Right Layer of the Stack:** E.g., checksum failures repeat the lookup. Metadata inconsistencies (e.g., during a rollout) reload configuration.

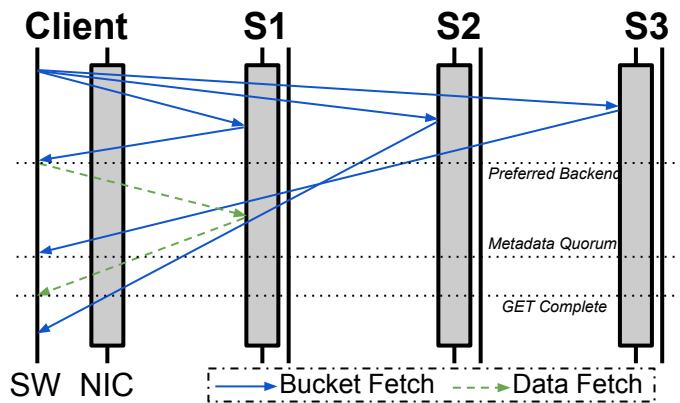


# Challenge: Availability/Cost Tradeoffs

**Tension with RMA:** Synchronizing RMAs, tolerating failures.

## **CliqueMap's Approach:**

- Modes for  $R=1$ ,  $R=2$ ,  $R=3.2$  for tuning availability/cost tradeoffs
- RPCs for mutations; RMAs are self-verifying
- Data migration for maintenance events
- Tunable on demand repair



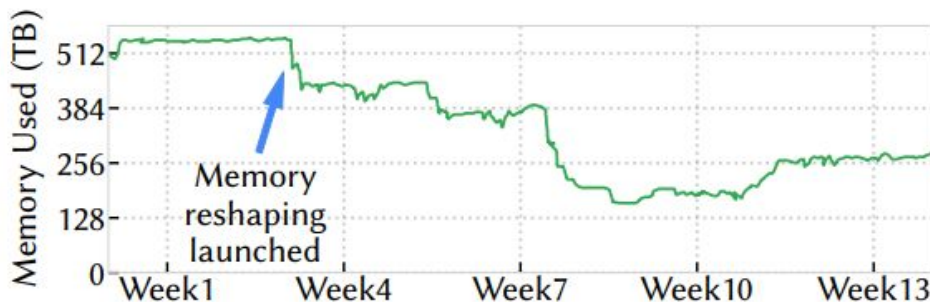
A 2xR-style  $R=3.2$  Quorummed Lookup operation. By establishing a quorum (majority vote) on metadata, a slow, absent, or inconsistent replica can be tolerated.

# Challenge: Memory & CPU Efficiency

**Tension with RMA:** Memory registration is expensive/subtle; needs to be done off the critical path.

## **CliqueMap's Approach:** *Dynamic Backend Scaling*

- Start expanding memory when usage above watermark (RPC-triggered)
- Clients can discover new backend geometries lazily, refresh metadata

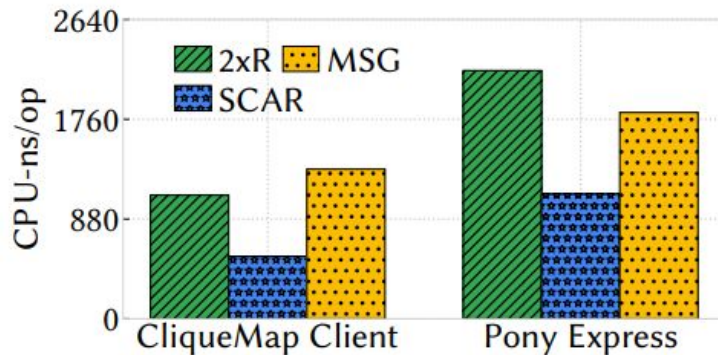


Plot of memory usage over time after *Dynamic Backend Scaling*'s initial rollout. Initially, capacity was simply slightly overprovisioned - this memory could be released. At ~Week 8, demand on corpus fell and more memory could be safely refunded.

# Challenge: Evolution over Time

***Tension with RMA:*** RMA exposes in-memory binary formats, making iteration difficult.

***CliqueMap's Approach:*** Metadata verification during checksumming enables protocol versioning. Entirely new primitives can be introduced.



SCAR was a major feature introduction that occurred post-productionization; evolution-friendly retry-based design enabled a transition wherein the logical 2xR lookup strategy could be flattened to a single round-trip, leading to efficiency improvements across all layers of infrastructure.

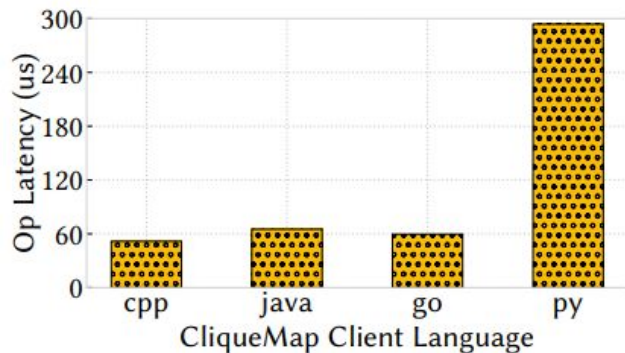
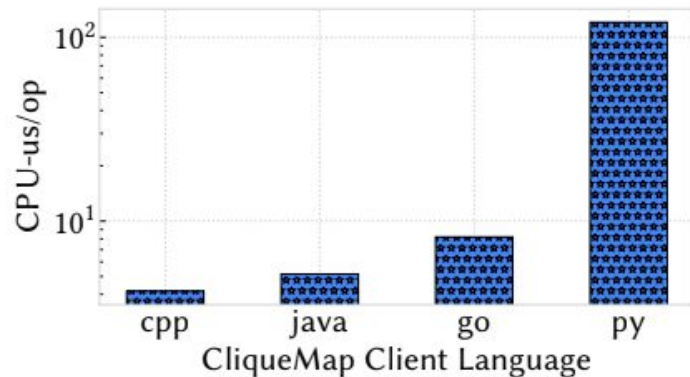


# Challenge: Language Interoperability

***Tension with RMA:*** C/C++ predominance

## ***CliqueMap's Approach:***

- Launch a subprocess containing the normal C++ CliqueMap libraries
  - IPC solutions per target language
    - Go, Python → Named Pipes
    - Java → Shared Memory
- Enables established, large-scale infrastructure with substantial non-C++ components to adopt CliqueMap.

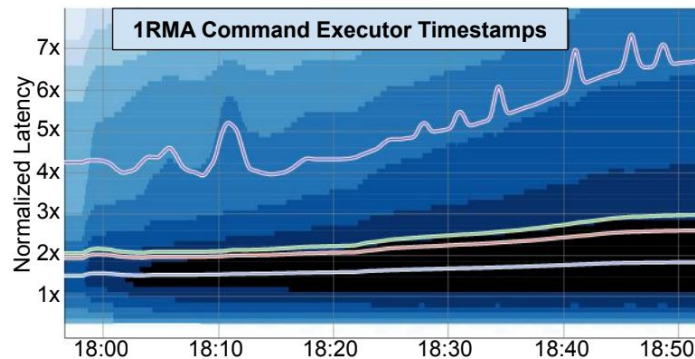
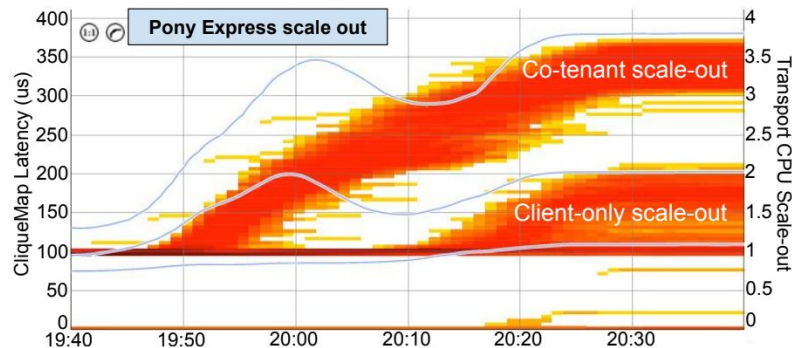


# Challenge: Hardware heterogeneity

***Tension with RMA:*** Wire Interoperability, performance expectations, mixed-age hardware

## ***CliqueMap's Approach:***

- Resilient, generic high-level protocols (2xR) suitable to different underlying RMA implementations (e.g., SCAR)
- Evolve over time, embrasure of programmable NICs



# Coming up

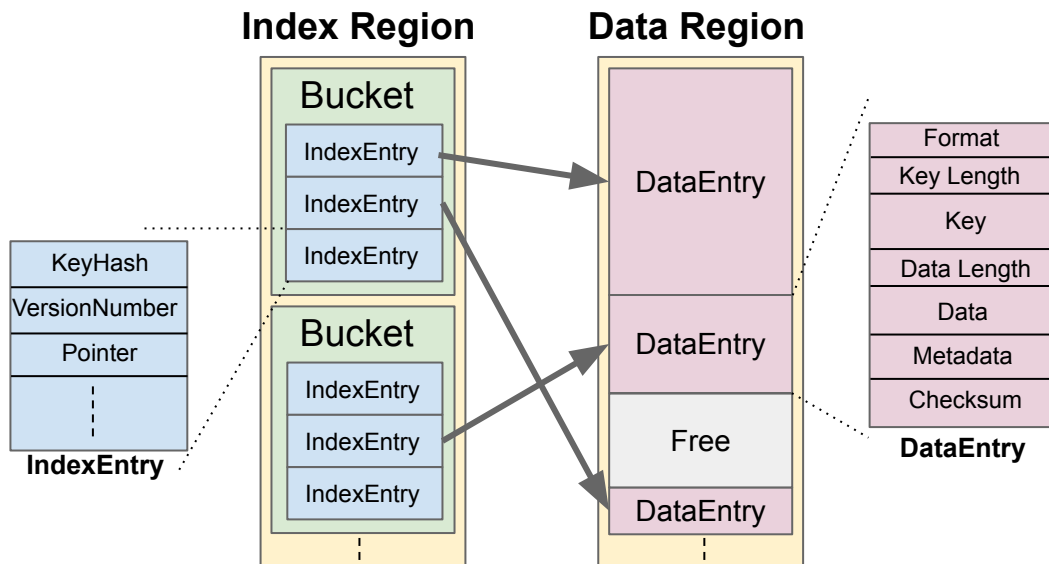
## A Deeper look at R=3.2

- Backend Memory Layout in Detail

- 2xR GET/SET Example

- Enduring Failures

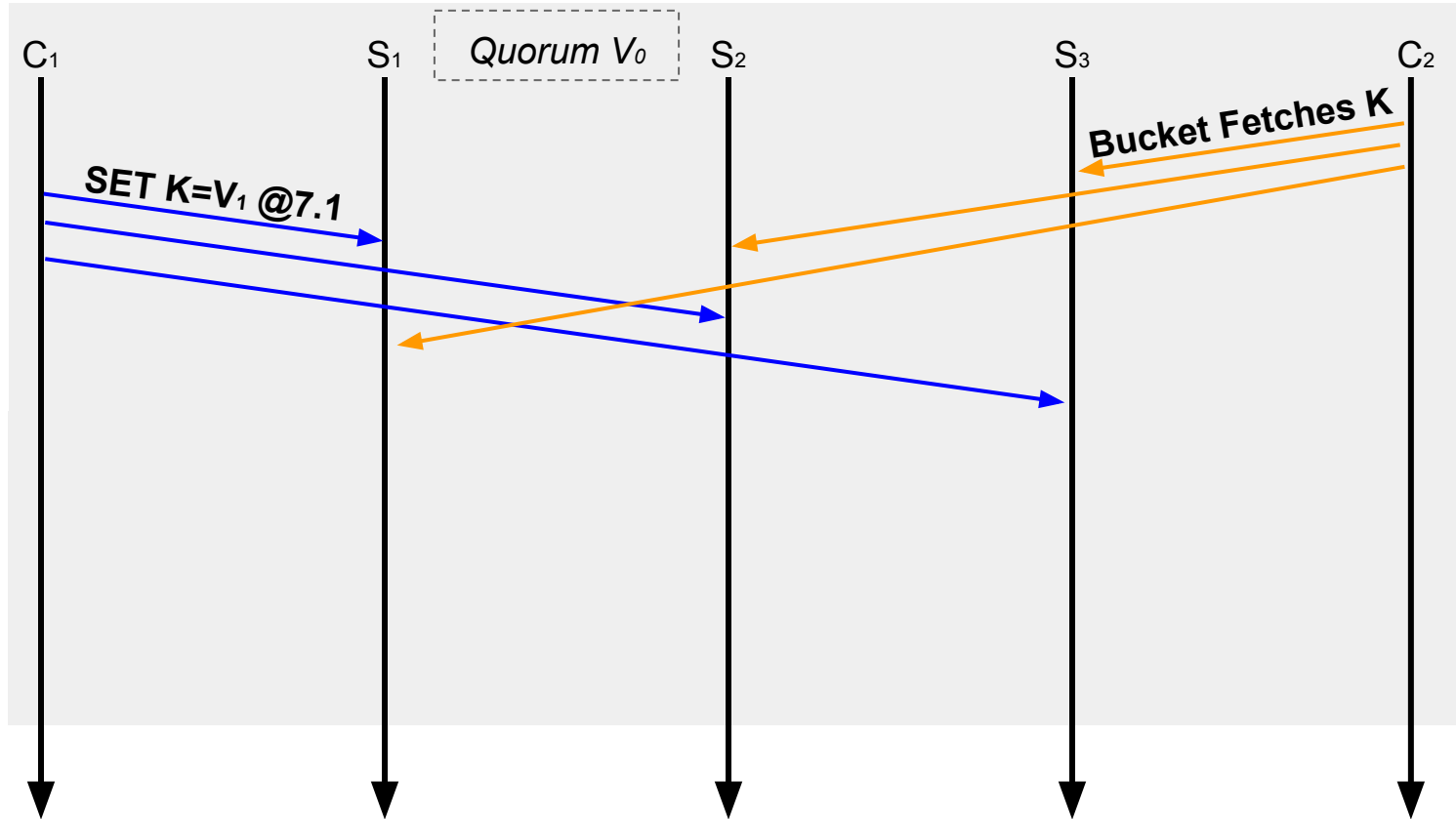
# CliqueMap Backend Memory Layout



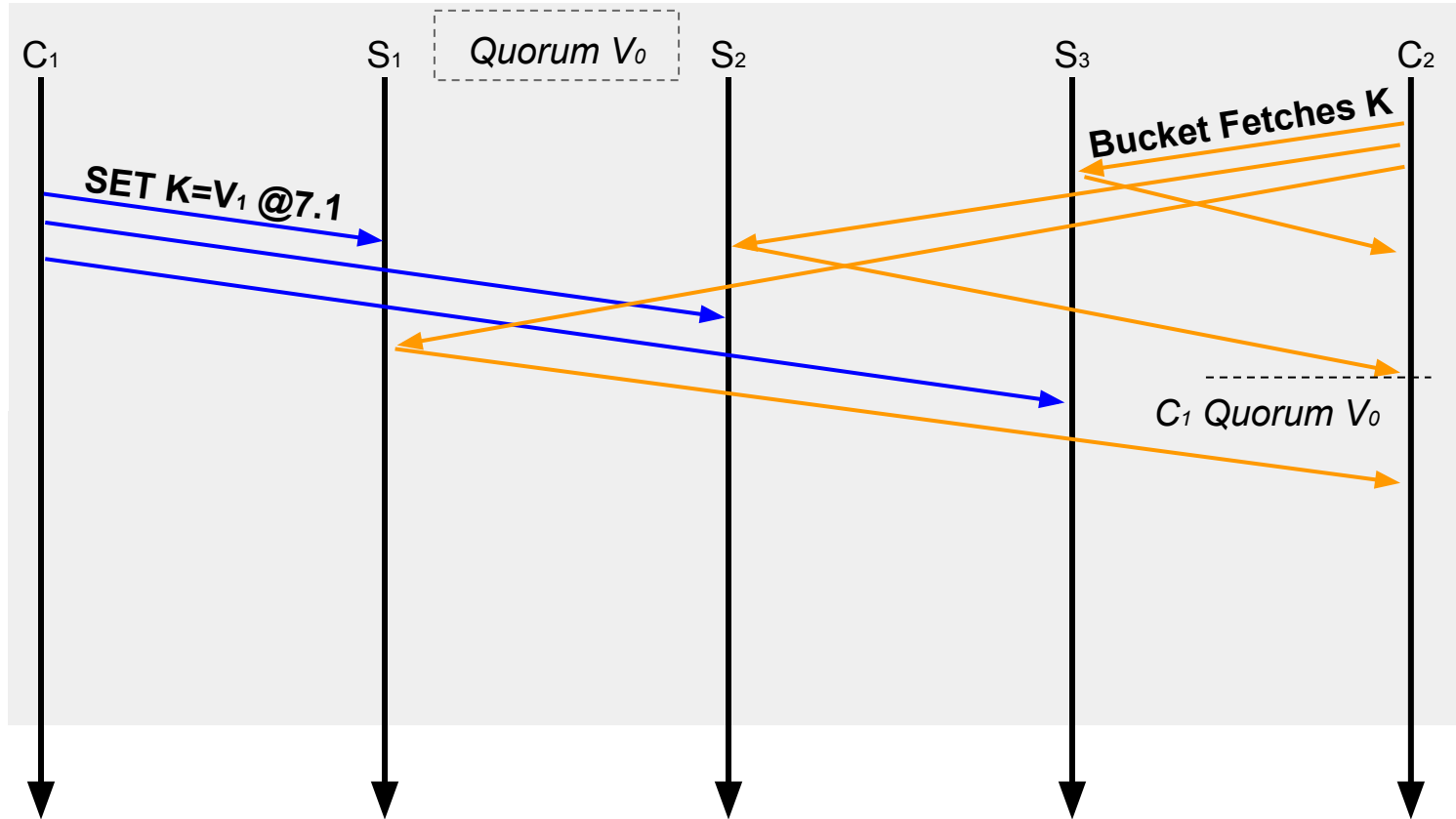
Backend hashtable layout chosen to be amenable to self-verification, retries, and evolution.

- Backend can relocate **DataEntires**, e.g., to defrag
- Checksum covers index and data end-to-end (client can detect inconsistencies and retry)
- Fields include enough metadata to hint at the right kind of retry

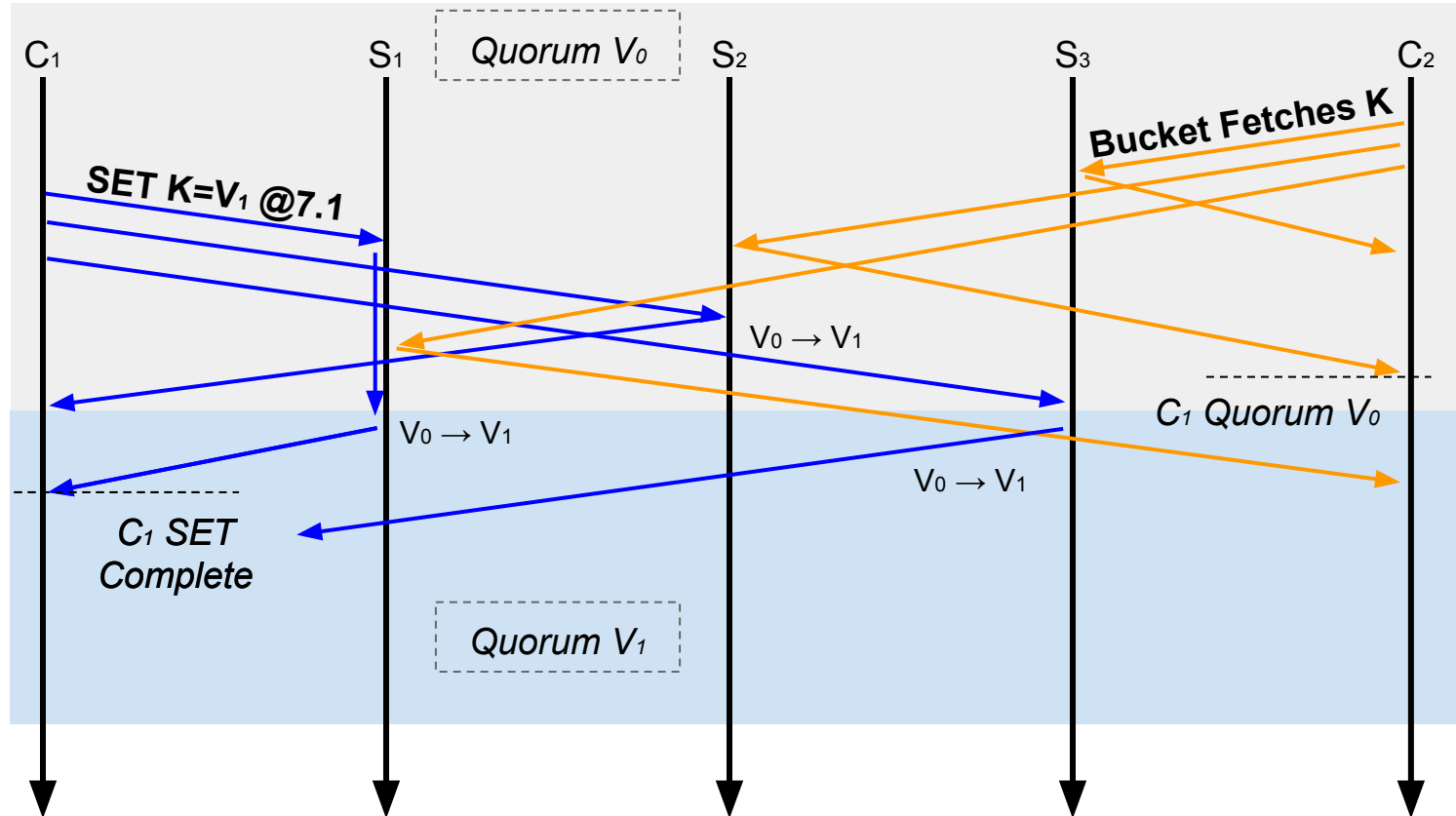
## R=3.2: Quoruming and Versioning



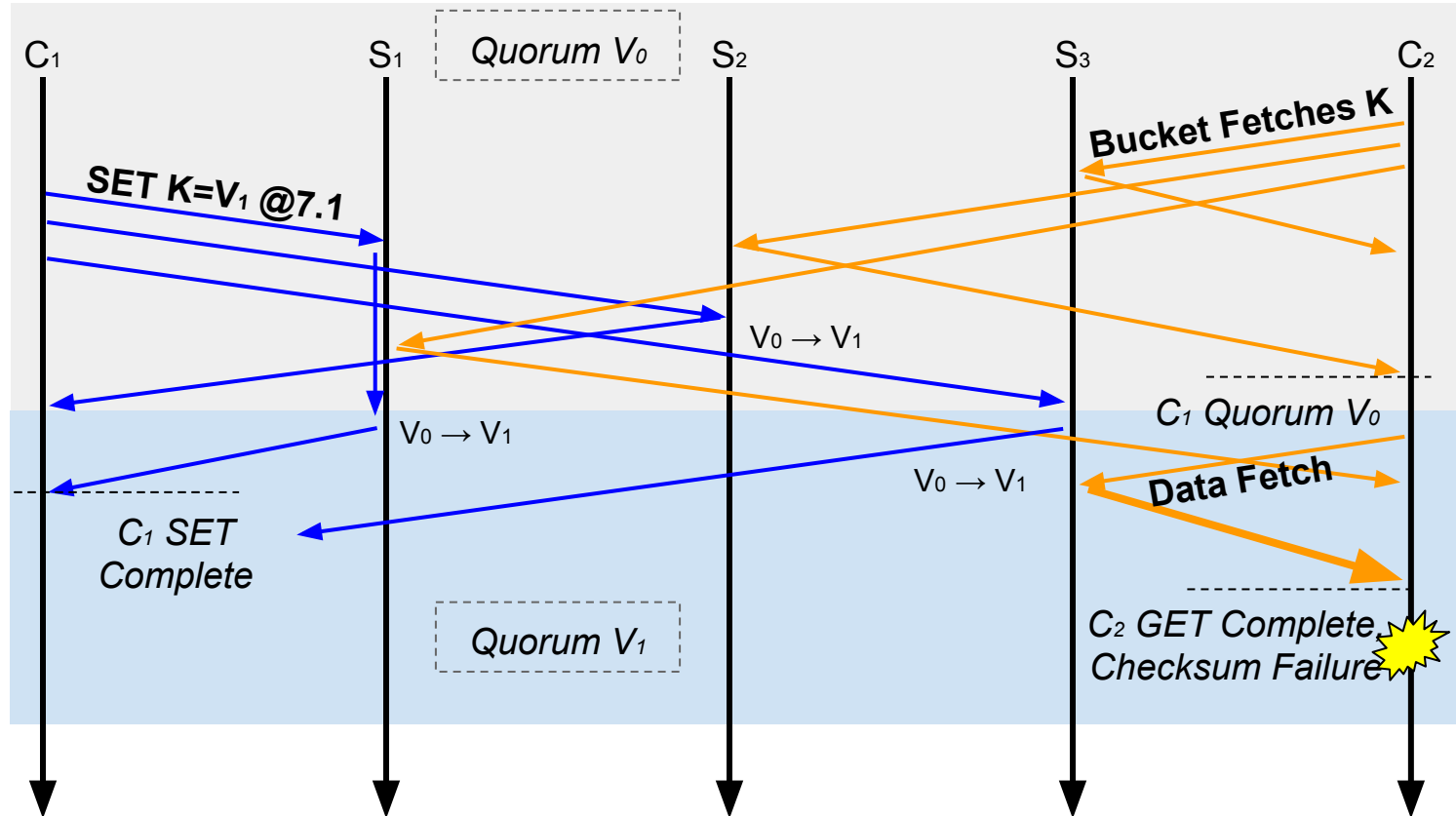
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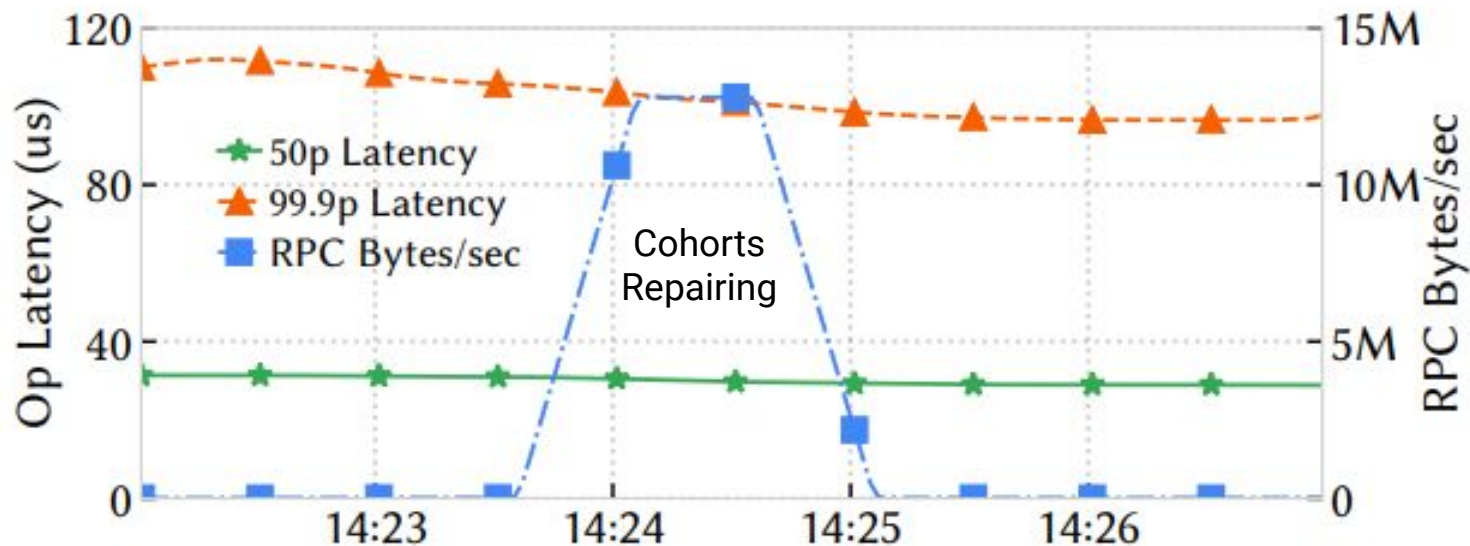


## R=3.2: Quorumming and Versioning



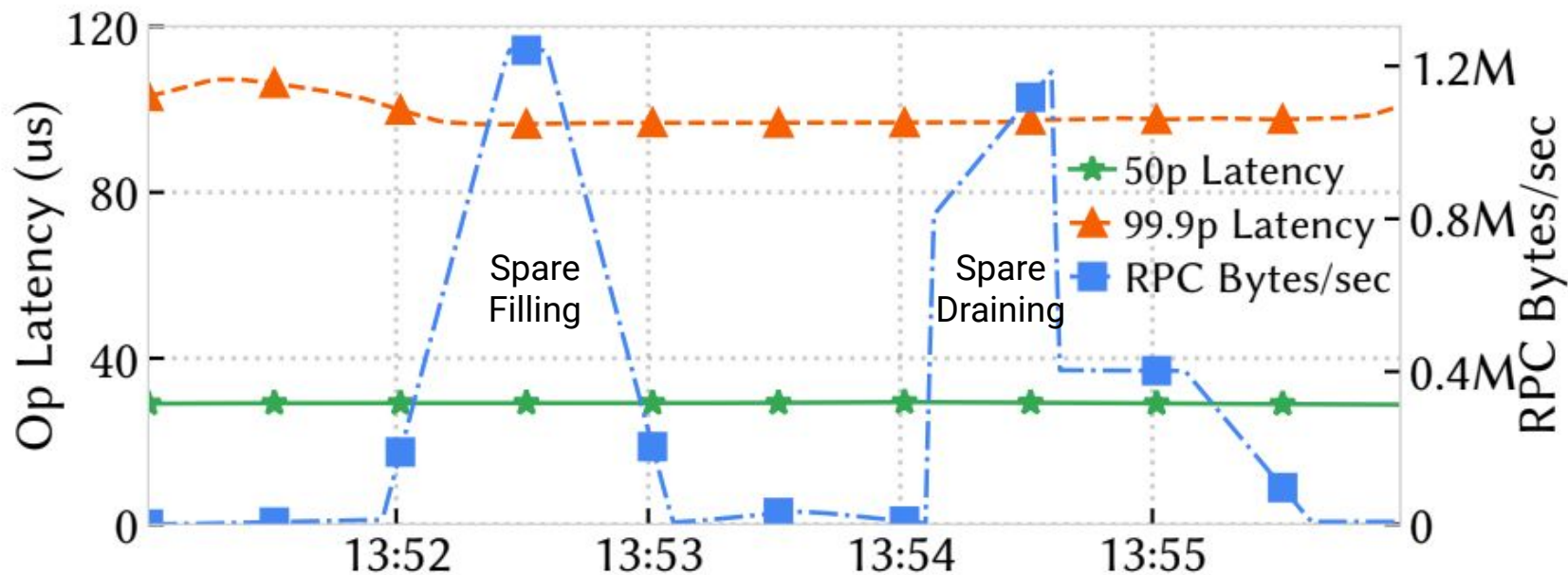


## R=3.2 with Unplanned Failures



*R=3.2 with repair preserves performance across single unplanned failures.*

## R=3.2 with Planned Maintenance/Upgrades



*R=3.2 with warm sparing maintains a clean quorum during planned maintenance events.*

# Closing Remarks

Leverage RPC, in composition with RMA, to maintain post-deployment agility

Enable multi-language software ecosystems

Don't compromise memory efficiency

Simply design with self-validating server responses and client retries

Programmable NICs offer advantages through specialization

See the paper for many more details!

Thank you!

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