## Vandermonde Decomposition of the Prony Hankel Matrix

Badri Narayan Bhaskar

February 4, 2010

Let  $S = \{n_1, ..., n_s\}$  be the indices of x corresponding to nonzero values so that  $x_S := \{x_{n_1}, ..., x_{n_s}\}$  is the support of x. Then, the DFT coefficients are given by

$$\hat{x}_{k} = \sum_{n \in S} x_{n} \omega_{D}^{nk}$$

$$= \sum_{l=1}^{s} h_{l} t_{l}^{D} \qquad \text{where } h_{l} := x_{n_{l}} \neq 0 \text{ and } t_{l} := \omega_{D}^{n_{l}}$$

$$(1)$$

$$h_l t_l^D$$
 where  $h_l := x_{n_l} \neq 0$  and  $t_l := \omega_D^{n_l}$  (2)

so that

$$\hat{x}_{m+k} = (h_1 t_1^m) t_1^k + \dots + (h_s t_s^m) t_s^k$$

Then the (m+1)th column in the "Prony" Hankel matrix can be written as

$$\begin{pmatrix} \hat{x}_{m} \\ \vdots \\ \hat{x}_{m+k} \\ \vdots \\ \hat{x}_{m+s-1} \end{pmatrix} = \begin{pmatrix} 1 & 1 & \dots & 1 \\ t_{1} & t_{2} & \dots & t_{s} \\ \vdots & \vdots & \dots & \vdots \\ t_{1}^{k} & t_{2}^{k} & \dots & t_{s}^{k} \\ \vdots & \vdots & \dots & \vdots \\ t_{1}^{s-1} & t_{2}^{s-1} & \dots & t_{s}^{s-1} \end{pmatrix} \begin{pmatrix} h_{1}t_{1}^{m} \\ \vdots \\ h_{k}t_{k}^{m} \\ \vdots \\ h_{s}t_{s}^{m} \end{pmatrix}.$$
(3)

Thus the Prony Matrix can be written as

$$\begin{pmatrix} \hat{x}_{0} & \dots & \hat{x}_{m} & \dots & \hat{x}_{s-1} \\ \vdots & \vdots & \vdots & \vdots \\ \hat{x}_{k} & \dots & \hat{x}_{m+k} & \dots & \hat{x}_{k+s-1} \\ \vdots & \vdots & \vdots & \vdots \\ \hat{x}_{s-1} & \dots & \hat{x}_{s+k-1} & \dots & \hat{x}_{2s-2} \end{pmatrix} = \begin{pmatrix} 1 & 1 & \dots & 1 \\ t_{1} & t_{2} & \dots & t_{s} \\ \vdots & \vdots & \dots & \vdots \\ t_{1}^{k} & t_{2}^{k} & \dots & t_{s}^{k} \\ \vdots & \vdots & \dots & \vdots \\ t_{1}^{s-1} & t_{2}^{s-1} & \dots & t_{s}^{s-1} \end{pmatrix} \begin{pmatrix} h_{1} & \dots & h_{1}t_{1}^{m} & \dots & h_{1}t_{1}^{s-1} \\ \vdots & \vdots & \ddots & \vdots \\ h_{k} & \dots & h_{k}t_{k}^{m} & \dots & h_{k}t_{k}^{s-1} \\ \vdots & \vdots & \vdots & \vdots \\ h_{s} & \dots & h_{s}t_{s}^{m} & \dots & h_{s}t_{s}^{s-1} \end{pmatrix}$$

$$= VDV^{T}$$

$$(4)$$

where V is the Vandermonde matrix given by

$$V = \begin{pmatrix} 1 & 1 & \dots & 1 \\ t_1 & t_2 & \dots & t_s \\ \vdots & \vdots & \dots & \vdots \\ t_1^k & t_2^k & \dots & t_s^k \\ \vdots & \vdots & \dots & \vdots \\ t_1^{s-1} & t_2^{s-1} & \dots & t_s^{s-1} \end{pmatrix}$$

and D is a diagonal matrix with  $(h_1, \ldots, h_s)$  along the main diagonal. Now, note that the Prony matrix will be full ranked if x has *exactly* s non-zero elements.

## Motivation for Prony's method

To students familiar with the theory of difference equations, the form in equation (2) is readily recognizable as a solution of a difference equation of order s. This observation was made in [1]. Thus,  $\hat{x}$  should satisfy the difference equation

$$\hat{x}_k + \lambda_1 \hat{x}_{k-1} + \dots + \lambda_s \hat{x}_{k-s} = 0 \tag{6}$$

where the corresponding generating polynomial

$$G(z) = 1 + \sum_{k=1}^{s} \lambda_k z^k,\tag{7}$$

must have roots at  $t_1, \ldots, t_s$ . Writing (6) in vector form we have

$$\begin{pmatrix} x_s \\ \vdots \\ x_{s+k} \\ \vdots \\ x_{2s-1} \end{pmatrix} + \begin{pmatrix} \hat{x}_0 & \dots & \hat{x}_m & \dots & \hat{x}_{s-1} \\ \vdots & \vdots & & \vdots \\ \hat{x}_k & \dots & \hat{x}_{m+k} & \dots & \hat{x}_{k+s-1} \\ \vdots & & \vdots & & \vdots \\ \hat{x}_{s-1} & \dots & \hat{x}_{s+k-1} & \dots & \hat{x}_{2s-2} \end{pmatrix} \begin{pmatrix} \lambda_1 \\ \vdots \\ \lambda_s \end{pmatrix} = 0$$
(8)

When the sparsity of x is exactly s, we have established via the Vandermonde Factorization that the matrix in the above equation is invertible. Thus the  $\lambda_k$ s and hence  $t_k$ s can be found. By solving a linear system of equations, the  $h_k$ s can also be found.

## References

 A Novel Interpretation of Prony's Method, Pitstick et al. 1998 Proceedings of the IEEE, Vol 76 Issue 8 pp. 1052-1053