

Solving ODEs Symbolically

Ordinary Differential Equations

ODE = equation describing a relationship between a function and its derivatives

- show up in dynamic systems -- systems that change with respect to time
- know the rate of change without know the underlying function

initial value problem (IVP) =

ordinary

vs

partial

first-order = only unknown function, 1st derivative of function, & independent variable show up in ODE

Solving an ODE

solving an ODE = finding the underlying function $y(t) = \dots$

Example: show that $y(t) = 10 e^{-2t}$ is the solution to $\frac{d y(t)}{d t} = -2 y(t)$ with initial condition

$$y(0) = 10$$

Check differential equation:

Check initial condition:

Steady-state of an ODE

steady-state = solution when things stop changing

To find the steady-state:

Example: find the steady-state of $\frac{d y(t)}{d t} = A \cdot y(t) + B$

Solving first-order ODEs symbolically using Maple

- construct and enter the ODE symbolically
- use `dsolve` to solve the ODE symbolically
- substitute values for symbolic constants
- explicitly plot the solution function

```
> restart
```

Equation for a linear first-order ordinary differential equation

```
> ode := diff(y(t), t) = A·y(t) + B
```

Find the steady-state solution

```
> steady := solve(rhs(ode) = 0, y(t))
```

Solve the ODE symbolically

With no initial condition:

```
> soln := dsolve(ode, y(t))
```

With a symbolic initial condition:

```
> solnWinitCond := dsolve({ode, y(0) = y0}, y(t))
```

Note: If you have an initial condition, you should use it in *desolve*

Plot the solution function

First, substitute values for symbolic constants

```
> subVals := A = - 2/5, B = 1/5, y0 = 3
```

```
> solnSub := subs(subVals, solnWinitCond)
```

```
> plot(rhs(solnSub), t = 0 .. 15)
```

```
> steadySub := subs(subVals, steady)
```

> restart

Equation for a non-linear first-order ordinary differential equation

> $ode := \text{diff}(y(t), t) = \alpha \cdot y(t) - \gamma \cdot y(t)^2$

Solve symbolically

> $soln := \text{dsolve}(\{ode, y(0) = y0\}, y(t))$

Plot the solution

First, substitute values for symbolic constants

> $subVals := \alpha = \frac{2}{3}, \gamma = \frac{1}{10}, y0 = 5$

> $solnSub := \text{subs}(subVals, soln)$

See if Maple can simplify the equation

> $solnSub := \text{simplify}(solnSub)$

> $\text{plot}(rhs(solnSub), t = 0..10)$

Find the steady-state solution

> $steady := \text{solve}(rhs(ode) = 0, y(t))$

> $steadySub := \text{subs}(subVals, \{steady\})$

> $\text{evalf}(steadySub)$

Plot the solution for a different set of values for the symbolic constants

> $subVals := \alpha = -\frac{2}{3}, \gamma = \frac{1}{10}, y0 = 5$

> $solnSub := \text{simplify}(\text{subs}(subVals, soln))$

> $\text{plot}(rhs(solnSub), t = 0..10)$

Solving Systems of ODEs

> *restart*

Equations for a system of first-order ODEs

> *ode1* := *diff*(*x1*(*t*), *t*) = *x1*(*t*) - 2·*x2*(*t*)

> *ode2* := *diff*(*x2*(*t*), *t*) = 3·*x1*(*t*) - 2·*x2*(*t*)

Solve the system of ODEs symbolically

> *initCond* := *x1*(0) = *x1_0*, *x2*(0) = *x2_0*

> *odeSymSoln* := *dsolve*({*ode1*, *ode2*, *initCond*}, {*x1*(*t*), *x2*(*t*) }

Solving a system of equations

vs

Solving a system of ODEs

Plot the solutions

> *constants* := *x1_0* = 4, *x2_0* = 1

> *odeSoln* := *subs*(*constants*, *odeSymSoln*)

> *plot*([*rhs*(*odeSoln*[1]), *rhs*(*odeSoln*[2])], *t* = 0 .. 8, *color* = [*black*, *red*])

Solving Higher-Order ODEs in Maple

higher-order ODE : equation describing a relationship between 2nd (or 3rd or higher-order) derivative & the function

- may (or may not) have lower-order derivatives in the equation

Example: $\frac{d^2 y(t)}{d t^2} = -\frac{G}{L} y(t)$

> *restart*

To solve one (or more) higher order ODEs, treat it as a *system* of ODEs consisting of:

- one (or more) ODEs
- one initial condition for each order of each ODE

1 1st order ODE $\Rightarrow$

2 1st order ODEs $\Rightarrow$

1 2nd order ODE $\Rightarrow$

2 2nd order ODEs $\Rightarrow$

1 3rd order ODE $\Rightarrow$

Higher-order ODE is implicitly a system of ODEs:

Specifying initial conditions:

function:

1st derivative:

2nd derivative:

Equation for a second-order ODE

> $ode2 := \text{diff}(y(t), t\$2) = -\frac{G}{L} \cdot y(t)$

Solve the second-order ODE

Second-order ODE requires 2 initial conditions, one for $y(t)$ and one for $\frac{dy(t)}{dt}$

> $initCond := y(0) = y_0, D(y)(0) = 0$

Solve it symbolically

> $odeSymSoln := \text{dsolve}(\{ode2, initCond\}, y(t))$

>