
Generalized B-splines and local refinements

Carla Manni

Department of Mathematics, University of Roma “Tor Vergata”

collaboration with

P. Costantini, F. Pelosi, H. Speleers

11-th MAIA Conference

September 25–30, 2013

“Ettore Majorana” Foundation and Centre, Erice

Outline

Outline

- Bernstein-like representations

Outline

- Bernstein-like representations
- Generalized B-splines

Outline

- Bernstein-like representations
- Generalized B-splines
- Local refinements

Outline

- Bernstein-like representations
- Generalized B-splines
- Local refinements
 - Hierarchical bases for Generalized B-splines

Outline

- Bernstein-like representations
- Generalized B-splines
- Local refinements
 - Hierarchical bases for Generalized B-splines
 - Generalized B-splines over T-meshes

Outline

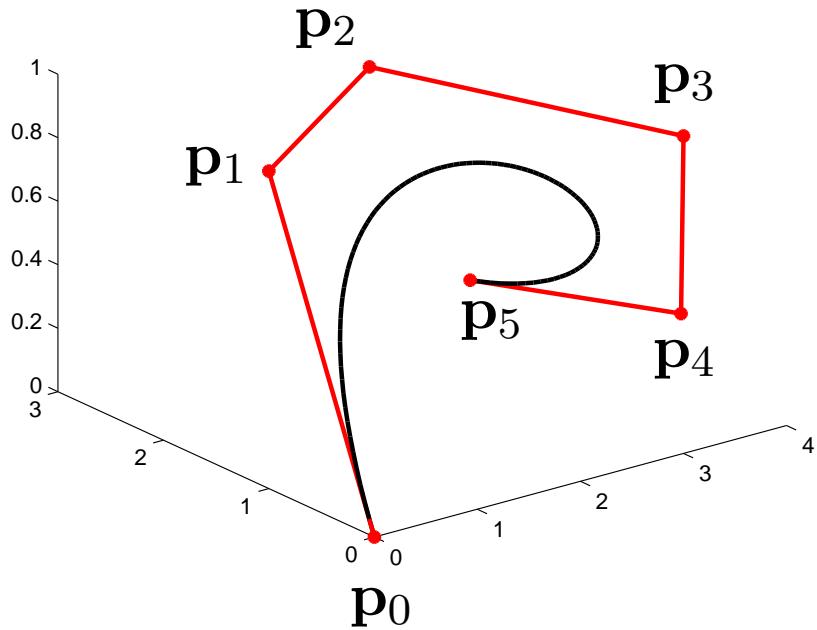
- Bernstein-like representations
- Generalized B-splines
- Local refinements
 - Hierarchical bases for Generalized B-splines
 - Generalized B-splines over T-meshes
 - Generalized B-splines over triangles

Outline

- Bernstein-like representations Ariadne's thread
- Generalized B-splines
- Local refinements
 - Hierarchical bases for Generalized B-splines
 - Generalized B-splines over T-meshes
 - Generalized B-splines over triangles

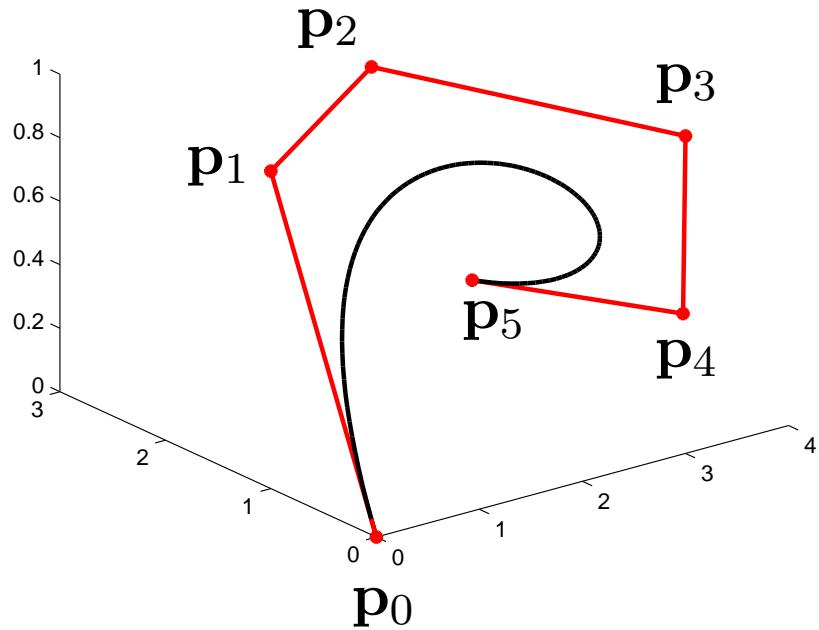
CAGD: Bézier forms

$$\sum_{i=0}^p \mathbf{p}_i \binom{p}{i} t^i (1-t)^{p-i}, \quad t \in [0, 1], \quad \mathbf{p}_i \in \mathbb{R}^d$$



CAGD: Bézier forms

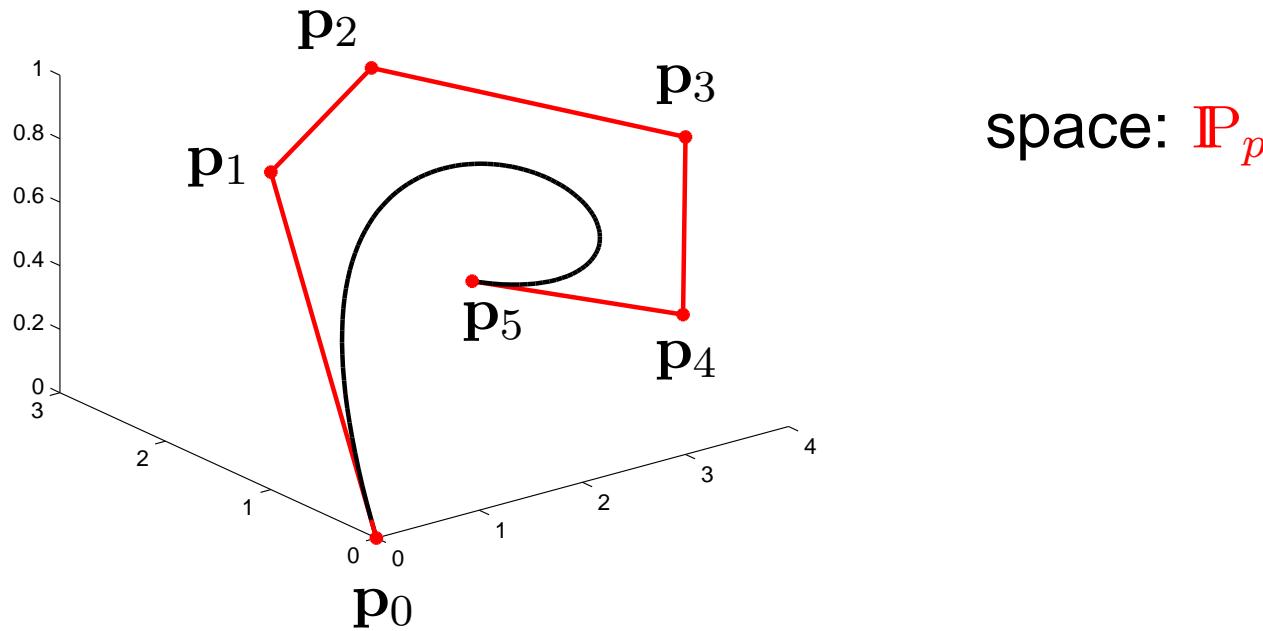
$$\sum_{i=0}^p \mathbf{p}_i \binom{p}{i} t^i (1-t)^{p-i}, \quad t \in [0, 1], \quad \mathbf{p}_i \in \mathbb{R}^d$$



BÉZIER CURVE

CAGD: Bézier forms

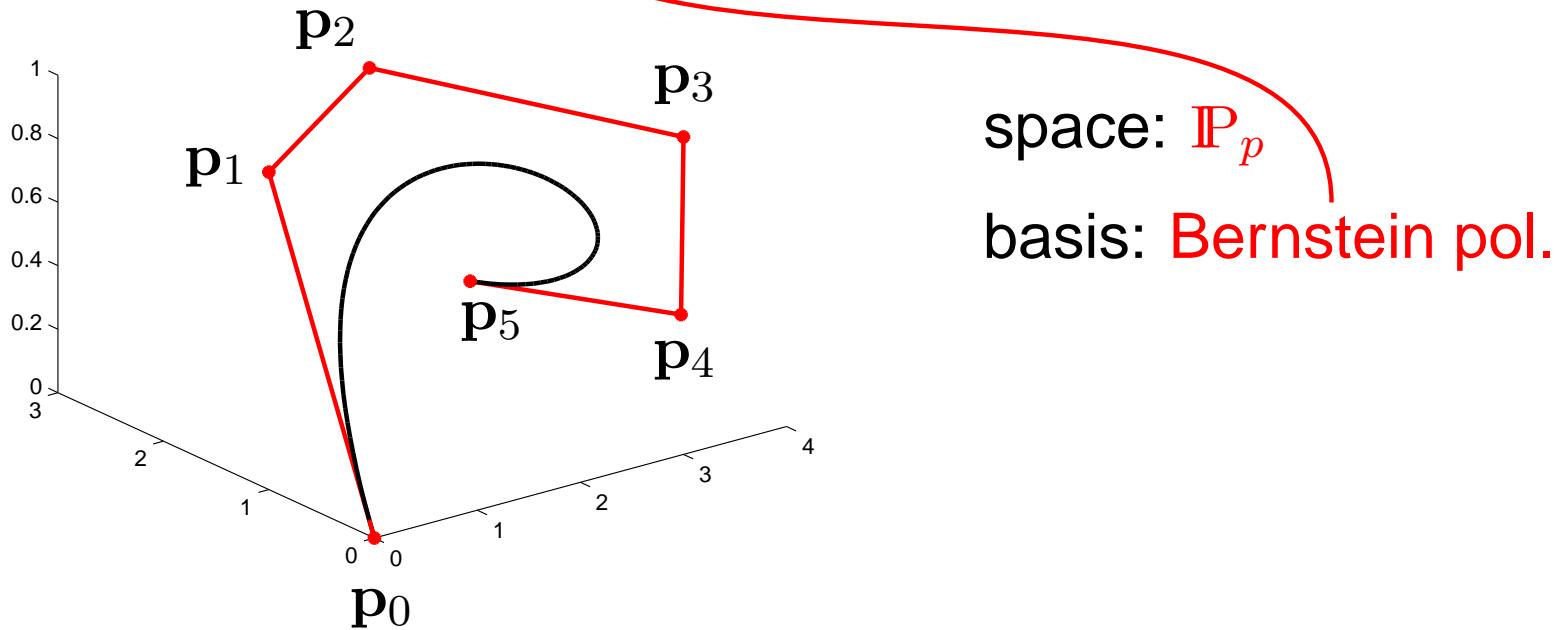
$$\sum_{i=0}^p \mathbf{p}_i \binom{p}{i} t^i (1-t)^{p-i}, \quad t \in [0, 1], \quad \mathbf{p}_i \in \mathbb{R}^d$$



BÉZIER CURVE

CAGD: Bézier forms

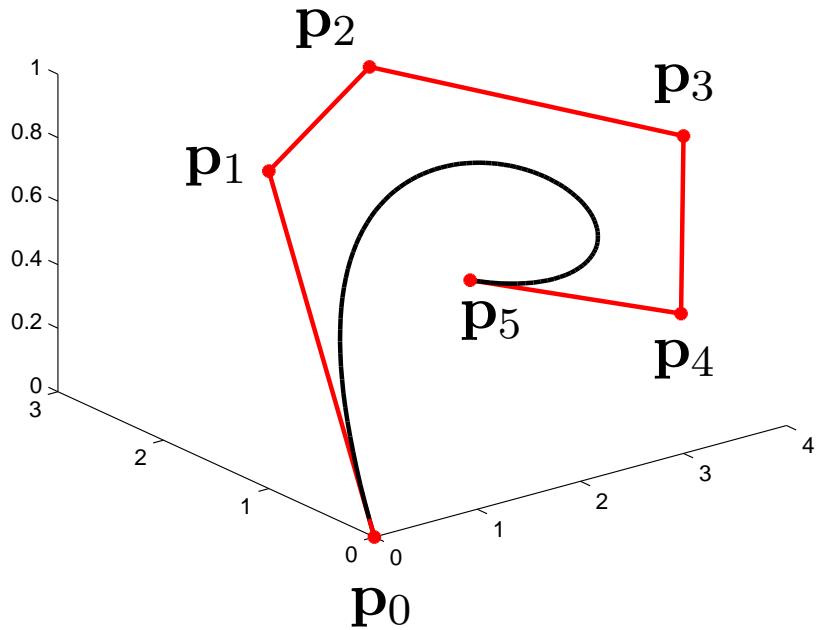
$$\sum_{i=0}^p \mathbf{p}_i \binom{p}{i} t^i (1-t)^{p-i}, \quad t \in [0, 1], \quad \mathbf{p}_i \in \mathbb{R}^d$$



BÉZIER CURVE

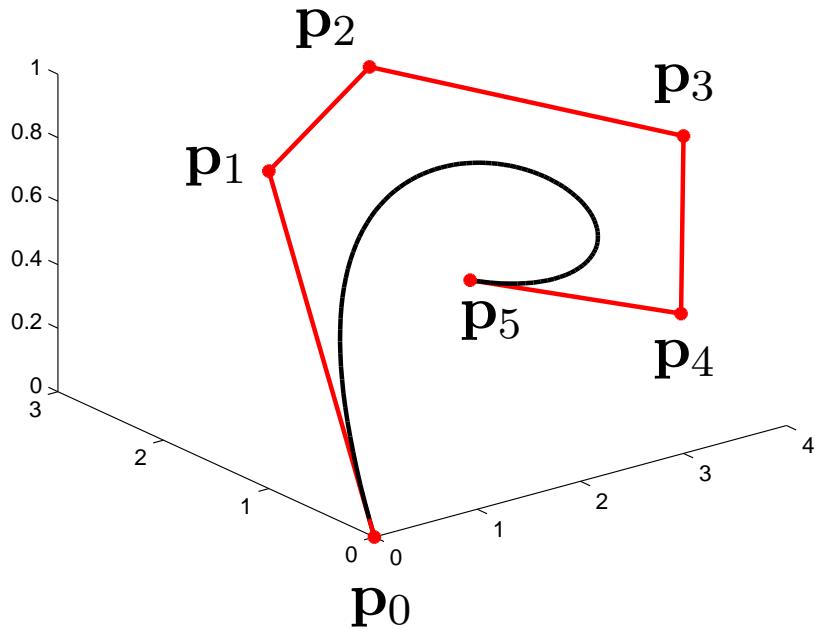
CAGD: Bernstein like representation

$$\sum_{i=0}^p \mathbf{p}_i B_i(t), \quad t \in [a, b] \quad \mathbf{p}_i \in \mathbb{R}^d$$



CAGD: Bernstein like representation

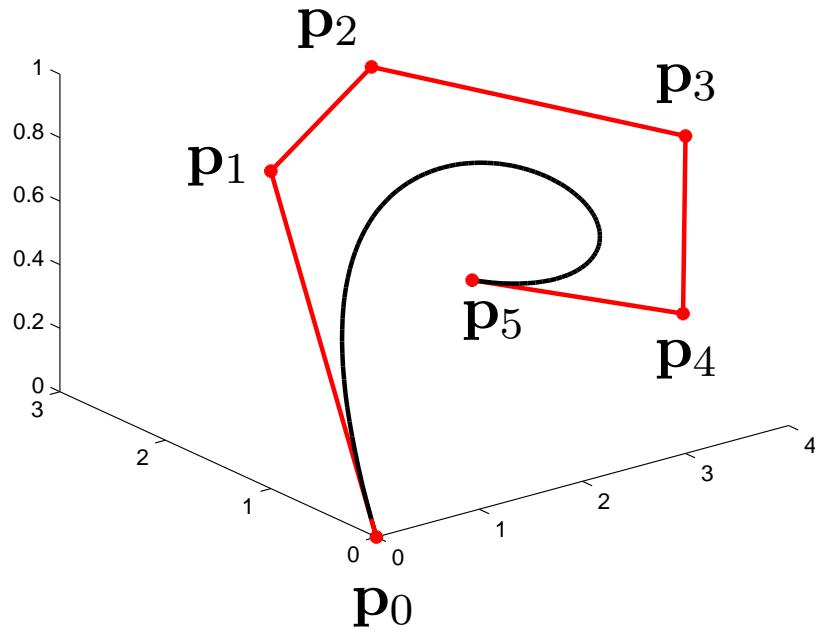
$$\sum_{i=0}^p \mathbf{p}_i B_i(t), \quad t \in [a, b] \quad \mathbf{p}_i \in \mathbb{R}^d$$



Bernstein-like representation

CAGD: Bernstein like representation

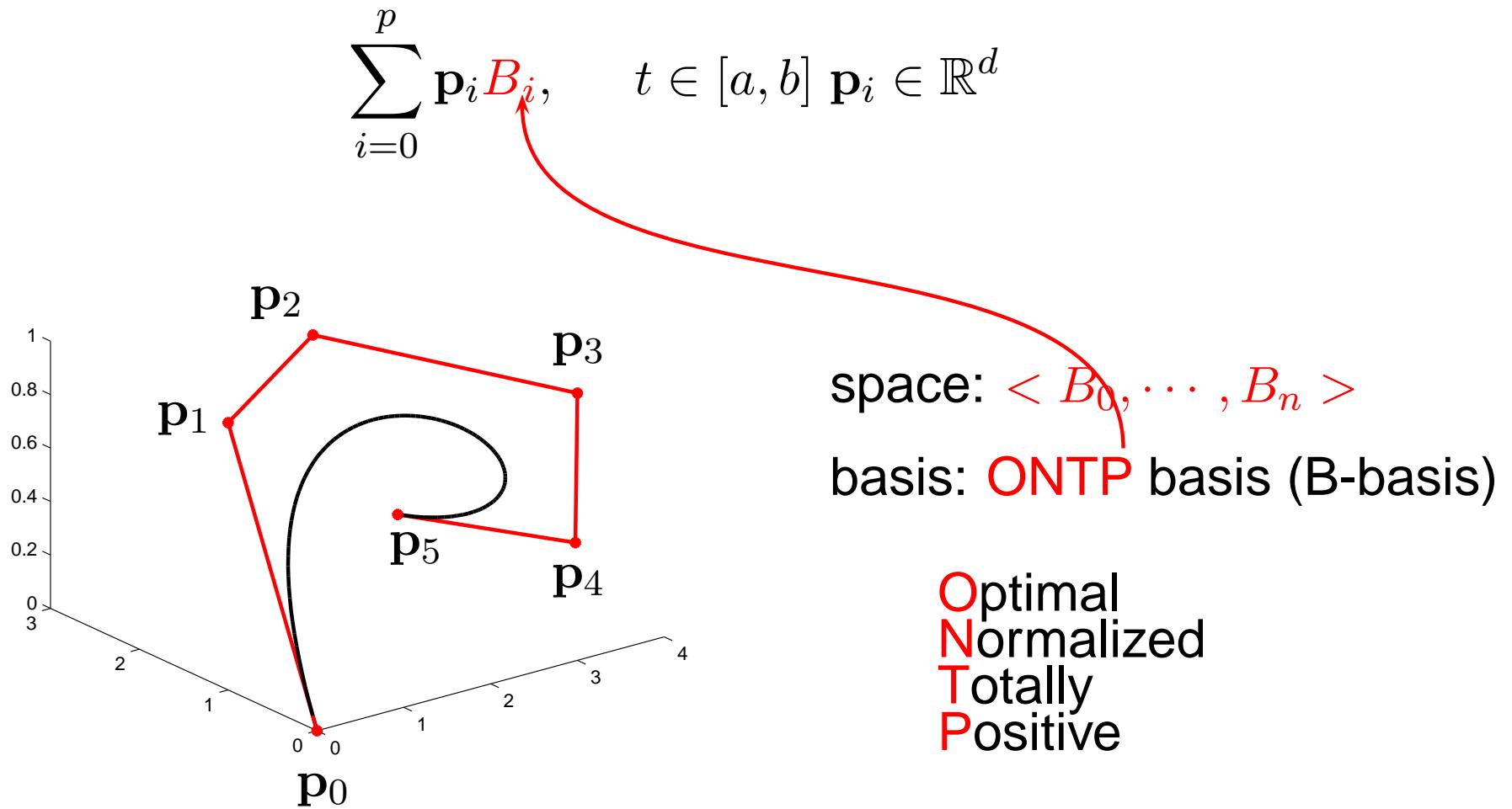
$$\sum_{i=0}^p \mathbf{p}_i B_i(t), \quad t \in [a, b] \quad \mathbf{p}_i \in \mathbb{R}^d$$



space: $\langle B_0, \dots, B_n \rangle$

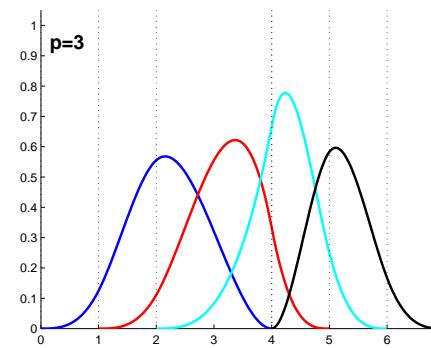
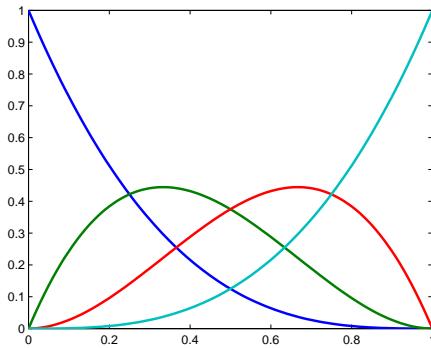
Bernstein-like representation

CAGD: Bernstein like representation



Bernstein-like representation

Bernstein/B-splines \Rightarrow Optimal NTP bases

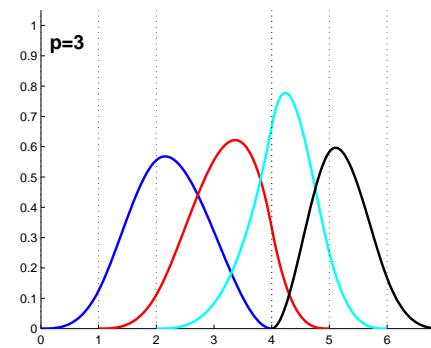
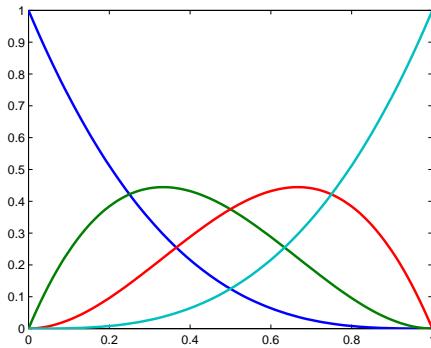


- Bernstein/B-splines bases are **the** ONTP bases for polynomials/piecewise polynomials



- optimal from a **geometric** point of view
- optimal from a **computational** point of view

Bernstein/B-splines \Rightarrow Optimal NTP bases



- Bernstein/B-splines bases are **the** ONTP bases for polynomials/piecewise polynomials



- optimal from a **geometric** point of view
- optimal from a **computational** point of view

Beyond polynomials: constrained curves/surfaces

- in CAGD curves/surfaces are often subjected to constraints

Beyond polynomials: constrained curves/surfaces

- in CAGD curves/surfaces are often subjected to constraints
 - reproduction constraints
exact reproduction of main curves/surfaces (**conic sections, ...**)
 - shape constraints
curvature orientation, torsion signs,...
 - tolerance constraints
offset constraints,...
 - ...

Beyond polynomials: constrained curves/surfaces

- in CAGD curves/surfaces are often subjected to constraints
 - reproduction constraints
exact reproduction of main curves/surfaces (**conic sections, ...**)
 - shape constraints
curvature orientation, torsion signs,...
 - tolerance constraints
offset constraints,...
 - ...
- polynomials/ piecewise polynomials (B-splines) **are not sufficient**

Reproducing conic sections, cycloids

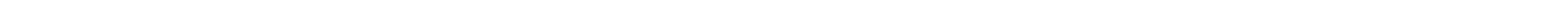
- exponentials $< 1, t, e^{\omega t}, e^{-\omega t} >$

Reproducing conic sections, cycloids

- exponentials $< 1, t, e^{\omega t}, e^{-\omega t} >$
 - ω : shape parameter
 - cubic as $\omega \rightarrow 0$
 - linear as $\omega \rightarrow +\infty$

Reproducing conic sections, cycloids

- exponentials $< 1, t, e^{\omega t}, e^{-\omega t} >$
 - ω : shape parameter
 - cubic as $\omega \rightarrow 0$
 - linear as $\omega \rightarrow +\infty$
- trigonometrics $< 1, t, \cos(\omega t), \sin(\omega t) >$



Reproducing conic sections, cycloids

- exponentials $< 1, t, e^{\omega t}, e^{-\omega t} >$
 - ω : shape parameter
 - cubic as $\omega \rightarrow 0$
 - linear as $\omega \rightarrow +\infty$
- trigonometrics $< 1, t, \cos(\omega t), \sin(\omega t) >$
 - ω : shape parameter
 - cubic if $\omega \rightarrow 0$

Shape constraints

- exponentials $\langle 1, t, e^{\omega t}, e^{-\omega t} \rangle$

Shape constraints

- exponentials $< 1, t, e^{\omega t}, e^{-\omega t} >$
 - ω : shape parameter
 - cubic as $\omega \rightarrow 0$
 - linear as $\omega \rightarrow +\infty$

Shape constraints

- exponentials $<1, t, e^{\omega t}, e^{-\omega t}>$
 - ω : shape parameter
 - cubic as $\omega \rightarrow 0$
 - linear as $\omega \rightarrow +\infty$
- variable degree $<1, t, t^\omega, (1-t)^\omega>$

Shape constraints

- exponentials $<1, t, e^{\omega t}, e^{-\omega t}>$
 - ω : shape parameter
 - cubic as $\omega \rightarrow 0$
 - linear as $\omega \rightarrow +\infty$

- variable degree $<1, t, t^\omega, (1-t)^\omega>$
 - ω : shape parameter
 - cubic if $\omega = 3$
 - linear as $\omega \rightarrow +\infty$

Shape constraints

- exponentials $< 1, t, e^{\omega t}, e^{-\omega t} >$
 - ω : shape parameter
 - cubic as $\omega \rightarrow 0$
 - linear as $\omega \rightarrow +\infty$
- variable degree $< 1, t, t^\omega, (1-t)^\omega >$
 - ω : shape parameter
 - cubic if $\omega = 3$
 - linear as $\omega \rightarrow +\infty$
- ...

Unifying approach:

- Ex: $\langle 1, t, u(t), v(t) \rangle$ (\simeq cubics) $u, v \in C^2$, $t \in [0, 1]$

Unifying approach: Bernstein-like basis

- Ex: $\langle 1, t, u(t), v(t) \rangle$ (\simeq cubics) $u, v \in C^2$, $t \in [0, 1]$
- ONTP/Bernstein-like basis $\{B_0, B_1, B_2, B_3\}$:

Unifying approach: Bernstein-like basis

- Ex: $\langle 1, t, u(t), v(t) \rangle$ (\simeq cubics) $u, v \in C^2$, $t \in [0, 1]$

- ONTP/Bernstein-like basis $\{B_0, B_1, B_2, B_3\}$:

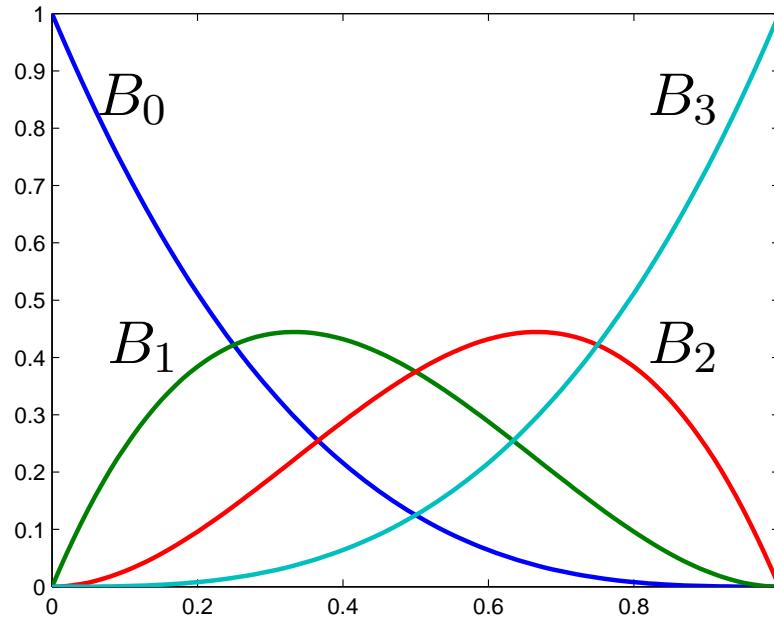
$C^2 \Rightarrow$ easy to characterize/construct

$$B_0(1) = B_0'(1) = B_0''(1) = 0$$

$$B_1(0) = B_1(1) = B_1'(1) = 0$$

$$B_2(0) = B_2'(0) = B_2(1) = 0$$

$$B_3(0) = B_3'(0) = B_3''(0) = 0$$



Unifying approach: Bernstein-like basis

- Ex: $\langle 1, t, u(t), v(t) \rangle$ (\simeq cubics) $u, v \in C^2$, $t \in [0, 1]$

- ONTP/Bernstein-like basis $\{B_0, B_1, B_2, B_3\}$:

$C^2 \Rightarrow$ easy to characterize/construct

$$B_0(1) = B_0'(1) = B_0''(1) = 0$$

$$B_1(0) = B_1(1) = B_1'(1) = 0$$

$$B_2(0) = B_2'(0) = B_2(1) = 0$$

$$B_3(0) = B_3'(0) = B_3''(0) = 0$$

- control points: $(0, b_0), (\xi, b_1), (1 - \eta, b_2), (1, b_3)$, $0 < \xi < 1 - \eta < 1$,

Unifying approach: Bernstein-like basis

- Ex: $\langle 1, t, u(t), v(t) \rangle$ (\simeq cubics) $u, v \in C^2$, $t \in [0, 1]$

- ONTP/Bernstein-like basis $\{B_0, B_1, B_2, B_3\}$:

$C^2 \Rightarrow$ easy to characterize/construct

$$B_0(1) = B_0'(1) = B_0''(1) = 0$$

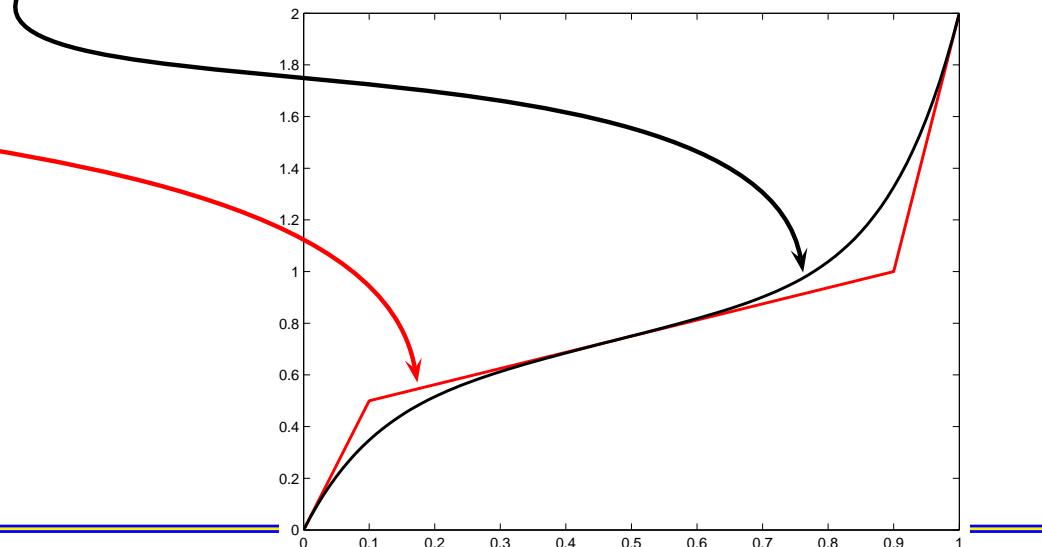
$$B_1(0) = B_1(1) = B_1'(1) = 0$$

$$B_2(0) = B_2'(0) = B_2(1) = 0$$

$$B_3(0) = B_3'(0) = B_3''(0) = 0$$

- control points: $(0, b_0), (\xi, b_1), (1 - \eta, b_2), (1, b_3)$, $0 < \xi < 1 - \eta < 1$,

- control polygon describes $s(t) = \sum_{j=0}^3 b_j B_j(t)$



Unifying approach: Bernstein-like basis

- Ex: $\langle 1, t, u(t), v(t) \rangle$ (\simeq cubics) $u, v \in C^2$, $t \in [0, 1]$
- ONTP/Bernstein-like basis $\{B_0, B_1, B_2, B_3\}$:

$C^2 \Rightarrow$ easy to characterize/construct

$$B_0(1) = B_0'(1) = B_0''(1) = 0$$

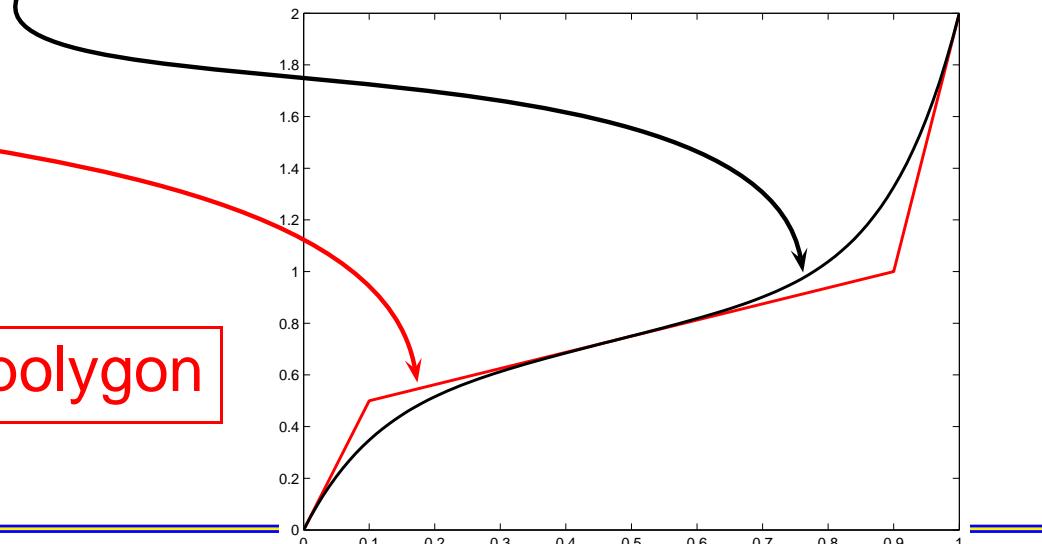
$$B_1(0) = B_1(1) = B_1'(1) = 0$$

$$B_2(0) = B_2'(0) = B_2(1) = 0$$

$$B_3(0) = B_3'(0) = B_3''(0) = 0$$

- control points: $(0, b_0), (\xi, b_1), (1 - \eta, b_2), (1, b_3)$, $0 < \xi < 1 - \eta < 1$,
- control polygon describes $s(t) = \sum_{j=0}^3 b_j B_j(t)$

properties of s by its control polygon



Unifying approach:

$$\mathbb{P}_p = \langle 1, t, \dots, t^{p-2}, t^{p-1}, t^p \rangle$$

Unifying approach:

$$\mathbb{P}_p^{u,v} := <1, t, \dots, t^{p-2}, u(t), v(t)>, \quad p \geq 2 \quad t \in [0, 1]$$

Unifying approach:

$$\mathbb{P}_p^{u,v} := \langle 1, t, \dots, t^{p-2}, u(t), v(t) \rangle, \quad p \geq 2 \quad t \in [0, 1]$$

- $\langle D^{p-1}u, D^{p-1}v \rangle$ Chebyshev in $[0, 1]$ and Extended Chebyshev in $(0, 1)$

Unifying approach: ONTP-basis

$$\mathbb{P}_p^{u,v} := \langle 1, t, \dots, t^{p-2}, u(t), v(t) \rangle, \quad p \geq 2 \quad t \in [0, 1]$$

- $\langle D^{p-1}u, D^{p-1}v \rangle$ Chebyshev in $[0, 1]$ and Extended Chebyshev in $(0, 1)$



$\mathbb{P}_p^{u,v}$ possesses a ONTP-basis

Unifying approach: ONTP-basis

$$\mathbb{P}_p^{u,v} := \langle 1, t, \dots, t^{p-2}, u(t), v(t) \rangle, \quad p \geq 2 \quad t \in [0, 1]$$

- $\langle D^{p-1}u, D^{p-1}v \rangle$ Chebyshev in $[0, 1]$ and Extended Chebyshev in $(0, 1)$



$\mathbb{P}_p^{u,v}$ possesses a ONTP-basis

- Ex:
 - u, v : trigonometric functions
 - u, v : exponential functions
 - u, v : variable degree
 -

Unifying approach: ONTP-basis

$$\mathbb{P}_p^{u,v} := \langle 1, t, \dots, t^{p-2}, u(t), v(t) \rangle, \quad p \geq 2 \quad t \in [0, 1]$$

- $\langle D^{p-1}u, D^{p-1}v \rangle$ Chebyshev in $[0, 1]$ and Extended Chebyshev in $(0, 1)$



$\mathbb{P}_p^{u,v}$ possesses a ONTP-basis

Bernstein-like representations

[Goodman, T.N.T., Mazure, M.-L., JAT, 2001]

[Mainar, E., Peña, J.M., Sánchez-Reyes, J, CAGD 2001]

[Carnicer, Mainar, Peña; CA 2004]

[Mazure, M.-L., CA, 2005]

[Costantini, P., Lyche, T., Manni, C., NM, 2005]

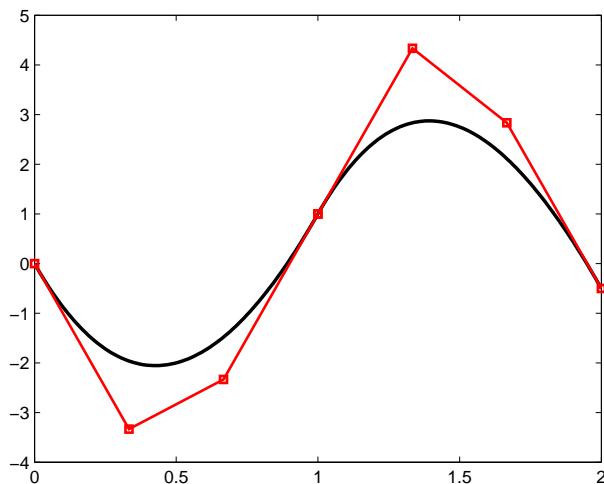
....

Unifying approach: Bernstein-like basis

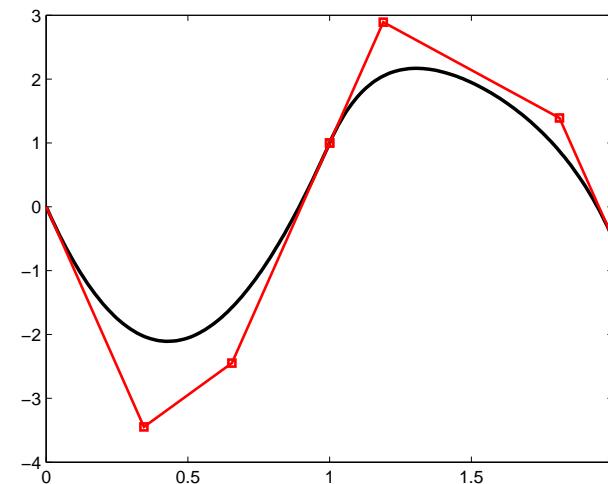
- smoothness between adjacent segments:
easily described by **control points**

Unifying approach: Bernstein-like basis

- smoothness between adjacent segments:
easily described by **control points**



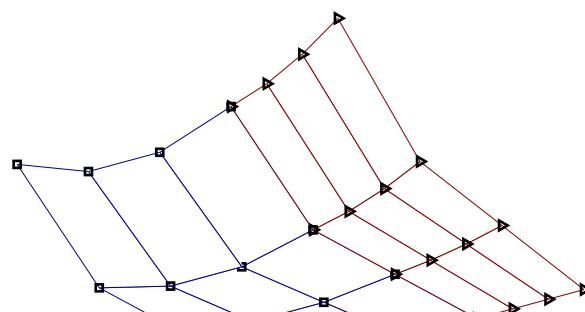
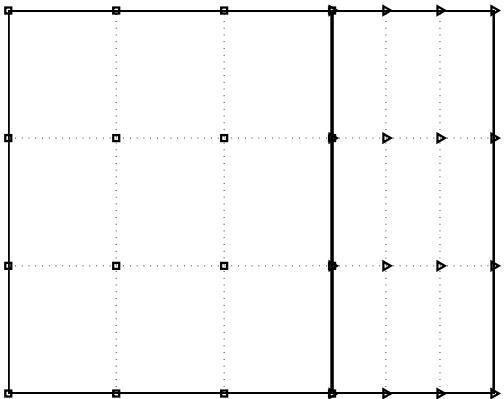
C^1 cubics



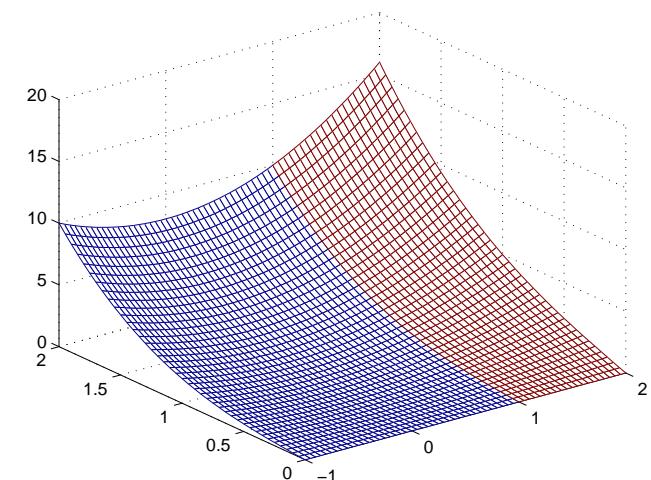
C^1 Trig/Exp

Unifying approach: Bernstein-like basis

- smoothness between adjacent segments:
easily described by **control points**

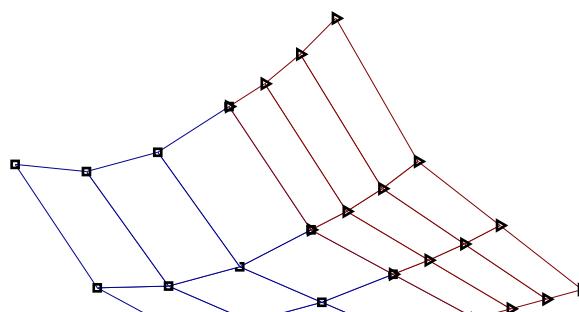
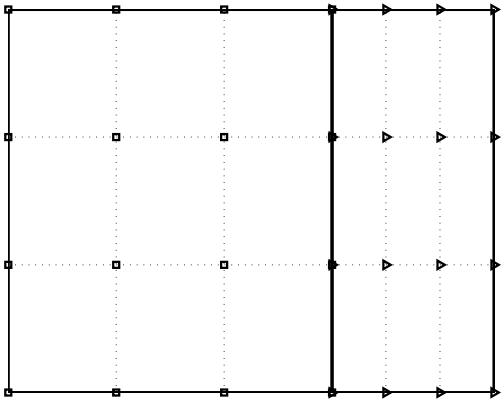


C^1 cubics

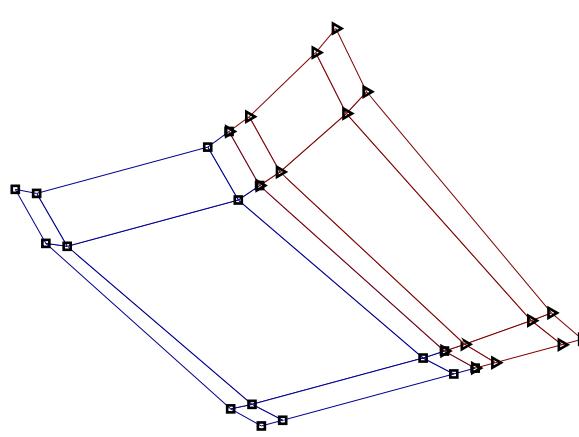
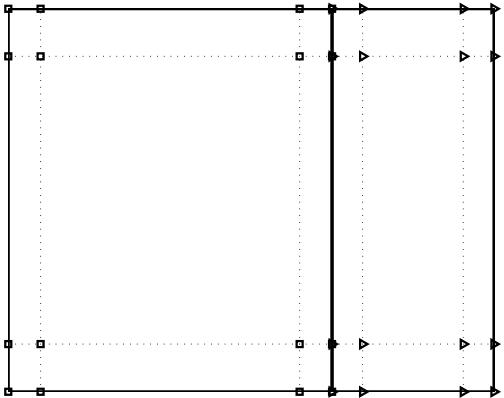


Unifying approach: Bernstein-like basis

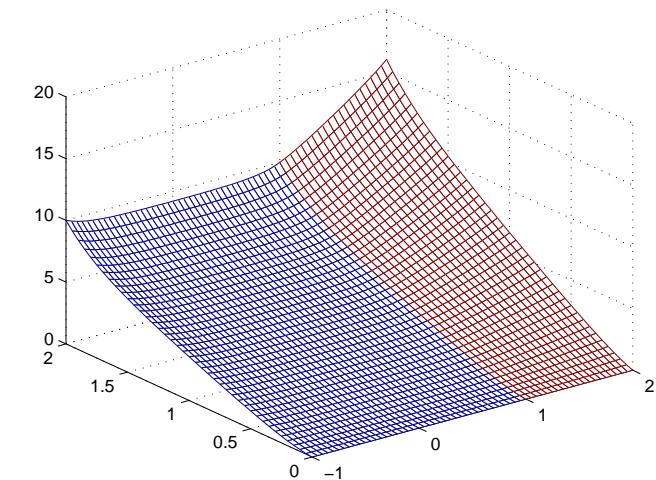
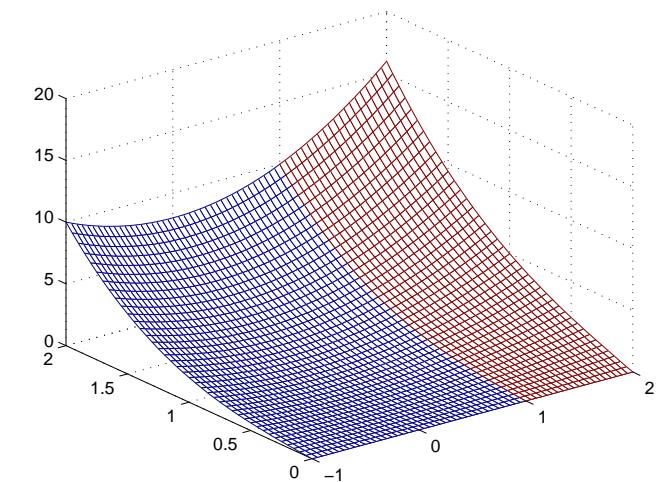
- smoothness between adjacent segments:
easily described by **control points**



C^1 cubics



C^1 exponential (cubics)



Spaces good for design

$$\mathbb{P}_p^{u,v} := <1, t, \dots, t^{p-2}, u(t), v(t)>, \quad p \geq 2 \quad t \in [0, 1]$$



Spaces good for design

$\mathbb{E} \subset C^n$: $n + 1$ dimensional **EC** space containing constants

\mathbb{E} is Extended Chebyshev (EC) in I if any non trivial element has at most n zeros in I

Spaces good for design

$\mathbb{E} \subset C^n$: $n + 1$ dimensional EC space containing constants

- B_0, \dots, B_n is a Bernstein-like basis of \mathbb{E} in $[a, b] \subset I$ if
 - B_0, \dots, B_n is NTP
 - B_k vanishes exactly k times in a and $n - k$ times in b

Spaces good for design

$\mathbb{E} \subset C^n$: $n + 1$ dimensional EC space containing constants

- B_0, \dots, B_n is a Bernstein-like basis of \mathbb{E} in $[a, b] \subset I$ if
 - B_0, \dots, B_n is NTP
 - B_k vanishes exactly k times in a and $n - k$ times in b
- A Bernstein-like basis of \mathbb{E} is the ONTP basis of \mathbb{E}

Spaces good for design

$\mathbb{E} \subset C^n$: $n + 1$ dimensional EC space containing constants

- B_0, \dots, B_n is a Bernstein-like basis of \mathbb{E} in $[a, b] \subset I$ if
 - B_0, \dots, B_n is NTP
 - B_k vanishes exactly k times in a and $n - k$ times in b
- A Bernstein-like basis of \mathbb{E} is the ONTP basis of \mathbb{E}
- \mathbb{E} possesses a Bernstein-like basis in any $[a, b] \subset I$ iff $\{f' : f \in \mathbb{E}\}$ is an Extended Chebyshev space in I

Spaces good for design

$\mathbb{E} \subset C^n$: $n + 1$ dimensional EC space containing constants

- B_0, \dots, B_n is a Bernstein-like basis of \mathbb{E} in $[a, b] \subset I$ if
 - B_0, \dots, B_n is NTP
 - B_k vanishes exactly k times in a and $n - k$ times in b
- A Bernstein-like basis of \mathbb{E} is the ONTP basis of \mathbb{E}
- \mathbb{E} possesses a Bernstein-like basis in any $[a, b] \subset I$ iff $\{f' : f \in \mathbb{E}\}$ is an Extended Chebyshev space in I
- in \mathbb{E} all classical geometric design algorithms can be developed for the Bernstein-like basis (blossoms)
 $\Rightarrow \mathbb{E}$ is good for design true under less restrictive hypotheses

[Goodman, T.N.T., Mazure, M.-L., JAT, 2001], [Carnicer, Mainar, Peña; CA 2004], [Mazure, M.-L., AiCM, 2004], [Mazure, M.-L., CA, 2005], [Costantini, P., Lyche, T., Manni, C., NM, 2005], [Mazure, M.-L., NM, 2011]

...

Alternatives to the rational model

Alternatives to the rational model

- rational model: $\mathbb{P}_p \rightarrow \text{B-splines} \rightarrow \text{NURBS}$



Alternatives to the rational model

- rational model: $\mathbb{P}_p \rightarrow \text{B-splines} \rightarrow \text{NURBS}$
- alternative: $\mathbb{P}_p = < 1, t, \dots, t^{p-2}, t^{p-1}, t^p >$
 \downarrow
 $\mathbb{P}_p^{u,v} := < 1, t, \dots, t^{p-2}, u(t), v(t) >$

Alternatives to the rational model

- rational model: $\mathbb{P}_p \rightarrow \text{B-splines} \rightarrow \text{NURBS}$
- alternative: $\mathbb{P}_p = < 1, t, \dots, t^{p-2}, t^{p-1}, t^p >$
 \downarrow
 $\mathbb{P}_p^{u,v} := < 1, t, \dots, t^{p-2}, u(t), v(t) >$
- select proper $\mathbb{P}_p^{u,v}$:
 - good approximation properties

Alternatives to the rational model

- rational model: $\mathbb{P}_p \rightarrow \text{B-splines} \rightarrow \text{NURBS}$
- alternative: $\mathbb{P}_p = < 1, t, \dots, t^{p-2}, t^{p-1}, t^p >$
 \downarrow
 $\mathbb{P}_p^{u,v} := < 1, t, \dots, t^{p-2}, u(t), v(t) >$

- select proper $\mathbb{P}_p^{u,v}$:
 - good approximation properties
 - exactly represent salient profiles

$$\mathbb{P}_p^{u,v} := < 1, t, \dots, t^{p-2}, \cos \omega t, \sin \omega t >$$

$$\mathbb{P}_p^{u,v} := < 1, t, \dots, t^{p-2}, \cosh \omega t, \sinh \omega t >$$

Alternatives to the rational model

- rational model: $\mathbb{P}_p \rightarrow \text{B-splines} \rightarrow \text{NURBS}$
- alternative: $\mathbb{P}_p = < 1, t, \dots, t^{p-2}, t^{p-1}, t^p >$
 \downarrow
 $\mathbb{P}_p^{u,v} := < 1, t, \dots, t^{p-2}, u(t), v(t) >$

- select proper $\mathbb{P}_p^{u,v}$:
 - good approximation properties
 - exactly represent salient profiles

$$\mathbb{P}_p^{u,v} := < 1, t, \dots, t^{p-2}, \cos \omega t, \sin \omega t > = \text{TRIG}$$

$$\mathbb{P}_p^{u,v} := < 1, t, \dots, t^{p-2}, \cosh \omega t, \sinh \omega t > = \text{HYP}$$

conic sections, helix, cycloid, ...

Alternatives to the rational model

- rational model: $\mathbb{P}_p \rightarrow \text{B-splines} \rightarrow \text{NURBS}$
- alternative: $\mathbb{P}_p = < 1, t, \dots, t^{p-2}, t^{p-1}, t^p >$

$$\mathbb{P}_p^{u,v} := < 1, t, \dots, t^{p-2}, u(t), v(t) >$$

\downarrow

- select proper $\mathbb{P}_p^{u,v}$:
 - good approximation properties
 - describe sharp variations

$$\mathbb{P}_p^{u,v} := < 1, t, \dots, t^{p-2}, e^{\omega t}, e^{-\omega t} >$$

$$\mathbb{P}_p^{u,v} := < 1, t, \dots, t^{p-2}, (1-t)^\omega, t^\omega >$$

Alternatives to the rational model

- rational model: $\mathbb{P}_p \rightarrow \text{B-splines} \rightarrow \text{NURBS}$
- alternative: $\mathbb{P}_p = < 1, t, \dots, t^{p-2}, t^{p-1}, t^p >$
 \downarrow
 $\mathbb{P}_p^{u,v} := < 1, t, \dots, t^{p-2}, u(t), v(t) >$

- select proper $\mathbb{P}_p^{u,v}$:
 - good approximation properties
 - describe sharp variations

$$\mathbb{P}_p^{u,v} := < 1, t, \dots, t^{p-2}, e^{\omega t}, e^{-\omega t} > = \text{EXP} = (\text{HYP})$$

$$\mathbb{P}_p^{u,v} := < 1, t, \dots, t^{p-2}, (1-t)^\omega, t^\omega > = \text{VDP}$$

Alternatives to the rational model

- rational model: $\mathbb{P}_p \rightarrow \text{B-splines} \rightarrow \text{NURBS}$
- alternative: $\mathbb{P}_p = < 1, t, \dots, t^{p-2}, t^{p-1}, t^p >$
 \downarrow
 $\mathbb{P}_p^{u,v} := < 1, t, \dots, t^{p-2}, u(t), v(t) >$

- construct/analyse spline spaces with sections in $\mathbb{P}_p^{u,v}$ with suitable bases for them (analogous to B-splines)

[Lyche, CA 1985]

[Schumaker, L.L.; 1993],

[Koch, P.E, Lyche, T.; Computing 1993],

[Marušić, M., Rogina, M.; JCAM 1995],

[Kvasov, B.I., Sattayatham, P.; JCAM 1999],

[Costantini, P.; CAGD 2000],

[Costantini, P., Manni, C.; RM 2006]

[Wang Fang; JCAM 2008],

[Kavcic, Rogina, Bosner, Math. Comput. in Simulation, 2010], ...

Generalized B-splines

$$\Xi := \{\xi_1 \leq \xi_2 \leq \cdots \leq \xi_{n+p+1}\},$$

{..., $u_i, v_i, \dots\}$, $\langle 1, t, \dots, t^{p-2}, u_i(t), v_i(t) \rangle$, $\langle D^{p-1}u_i, D^{p-1}v_i \rangle$ Chebyshev

$$D^{p-1}v_i(\xi_i) = 0, \quad D^{p-1}v_i(\xi_{i+1}) > 0, \quad D^{p-1}u_i(\xi_i) > 0, \quad D^{p-1}u_i(\xi_{i+1}) = 0,$$

Generalized B-splines

$$\Xi := \{\xi_1 \leq \xi_2 \leq \dots \leq \xi_{n+p+1}\},$$

{..., $u_i, v_i, \dots\}$, $\langle 1, t, \dots, t^{p-2}, u_i(t), v_i(t) \rangle$, $\langle D^{p-1}u_i, D^{p-1}v_i \rangle$ Chebyshev

$$D^{p-1}v_i(\xi_i) = 0, \quad D^{p-1}v_i(\xi_{i+1}) > 0, \quad D^{p-1}u_i(\xi_i) > 0, \quad D^{p-1}u_i(\xi_{i+1}) = 0,$$

$$\widehat{B}_{i,\Xi}^{(1)}(t) := \begin{cases} \frac{D^{p-1}v_i(t)}{D^{p-1}v_i(\xi_{i+1})} & t \in [\xi_i, \xi_{i+1}) \\ \frac{D^{p-1}u_{i+1}(t)}{D^{p-1}u_{i+1}(\xi_{i+1})} & t \in [\xi_{i+1}, \xi_{i+2}) \\ 0 & \text{elsewhere} \end{cases}$$

Generalized B-splines

$$\Xi := \{\xi_1 \leq \xi_2 \leq \dots \leq \xi_{n+p+1}\},$$

{..., $u_i, v_i, \dots\}$, $\langle 1, t, \dots, t^{p-2}, u_i(t), v_i(t) \rangle$, $\langle D^{p-1}u_i, D^{p-1}v_i \rangle$ Chebyshev

$$D^{p-1}v_i(\xi_i) = 0, \quad D^{p-1}v_i(\xi_{i+1}) > 0, \quad D^{p-1}u_i(\xi_i) > 0, \quad D^{p-1}u_i(\xi_{i+1}) = 0,$$

$$\widehat{B}_{i,\Xi}^{(1)}(t) := \begin{cases} \frac{D^{p-1}v_i(t)}{D^{p-1}v_i(\xi_{i+1})} & t \in [\xi_i, \xi_{i+1}) \\ \frac{D^{p-1}u_{i+1}(t)}{D^{p-1}u_{i+1}(\xi_{i+1})} & t \in [\xi_{i+1}, \xi_{i+2}) \\ 0 & \text{elsewhere} \end{cases}$$

$$\widehat{B}_{i,\Xi}^{(p)}(t) = \int_{-\infty}^t \widehat{\delta}_{i,\Xi}^{(p-1)} \widehat{B}_{i,\Xi}^{(p-1)}(s) ds - \int_{-\infty}^t \widehat{\delta}_{i+1,\Xi}^{(p-1)} \widehat{B}_{i+1,\Xi}^{(p-1)}(s) ds$$

$$\widehat{\delta}_{i,\Xi}^{(p)} := \frac{1}{\int_{-\infty}^{+\infty} \widehat{B}_{i,W,\Xi}^{(p)}(s) ds}$$

Generalized B-splines

$$\Xi := \{\xi_1 \leq \xi_2 \leq \dots \leq \xi_{n+p+1}\},$$

$\{..., u_i, v_i, ...\}, <1, t, \dots, t^{p-2}, u_i(t), v_i(t)>, <D^{p-1}u_i, D^{p-1}v_i>$ Chebyshev

$$D^{p-1}v_i(\xi_i) = 0, \quad D^{p-1}v_i(\xi_{i+1}) > 0, \quad D^{p-1}u_i(\xi_i) > 0, \quad D^{p-1}u_i(\xi_{i+1}) = 0,$$

$$\widehat{B}_{i,\Xi}^{(1)}(t) := \begin{cases} \frac{D^{p-1}v_i(t)}{D^{p-1}v_i(\xi_{i+1})} & t \in [\xi_i, \xi_{i+1}) \\ \frac{D^{p-1}u_{i+1}(t)}{D^{p-1}u_{i+1}(\xi_{i+1})} & t \in [\xi_{i+1}, \xi_{i+2}) \\ 0 & \text{elsewhere} \end{cases} \quad B_{i,\Xi}^{(1)}(t) := \begin{cases} \frac{t-\xi_i}{\xi_{i+1}-\xi_i} & t \in [\xi_i, \xi_{i+1}) \\ \frac{\xi_{i+2}-t}{\xi_{i+2}-\xi_{i+1}} & t \in [\xi_{i+1}, \xi_{i+2}) \\ 0 & \text{elsewhere} \end{cases}$$

$$\widehat{B}_{i,\Xi}^{(p)}(t) = \int_{-\infty}^t \widehat{\delta}_{i,\Xi}^{(p-1)} \widehat{B}_{i,\Xi}^{(p-1)}(s) ds - \int_{-\infty}^t \widehat{\delta}_{i+1,\Xi}^{(p-1)} \widehat{B}_{i+1,\Xi}^{(p-1)}(s) ds$$

$$\widehat{\delta}_{i,\Xi}^{(p)} := \frac{1}{\int_{-\infty}^{+\infty} \widehat{B}_{i,W,\Xi}^{(p)}(s) ds}$$

B-splines

$$B_{i,\Xi}^{(p)}(t) = \int_{-\infty}^t \delta_{i,\Xi}^{(p-1)} B_{i,\Xi}^{(p-1)}(s) ds - \int_{-\infty}^t \delta_{i+1,\Xi}^{(p-1)} B_{i+1,\Xi}^{(p-1)}(s) ds$$

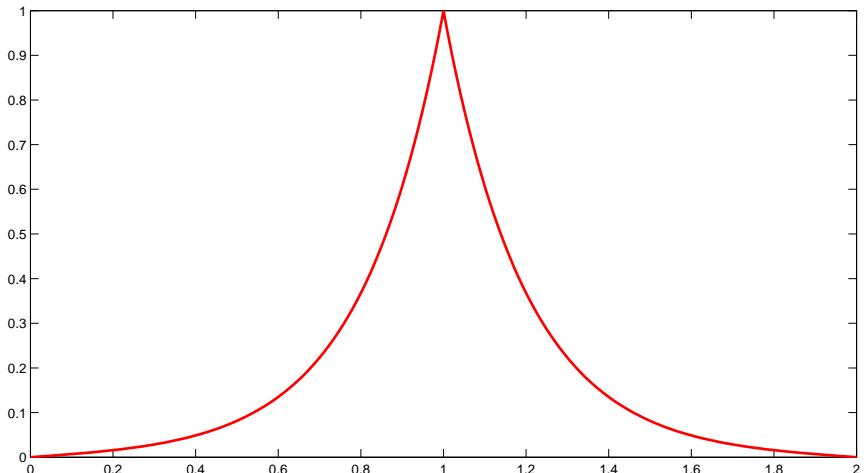
$$\delta_{i,\Xi}^{(p)} := \frac{1}{\int_{-\infty}^{+\infty} B_{i,\Xi}^{(p)}(s) ds}$$

Generalized B-splines

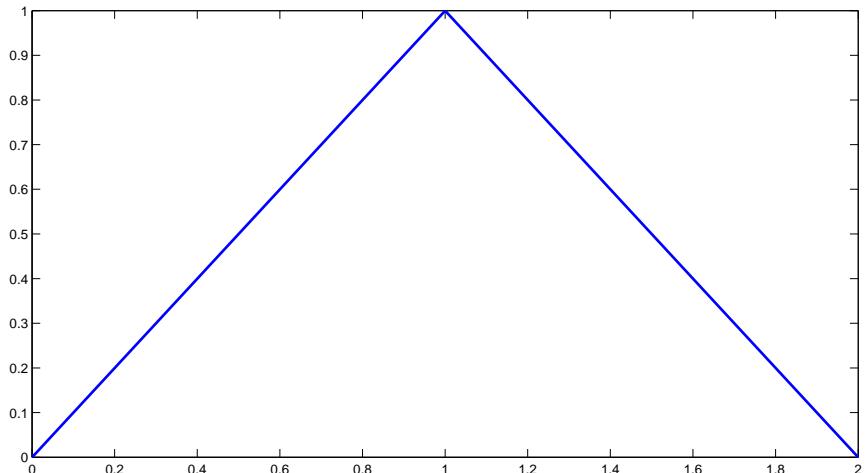
$$\Xi := \{\xi_1 \leq \xi_2 \leq \dots \leq \xi_{n+p+1}\},$$

{..., $u_i, v_i, \dots\}$, $\langle 1, t, \dots, t^{p-2}, u_i(t), v_i(t) \rangle$, $\langle D^{p-1}u_i, D^{p-1}v_i \rangle$ Chebyshev

$$D^{p-1}v_i(\xi_i) = 0, \quad D^{p-1}v_i(\xi_{i+1}) > 0, \quad D^{p-1}u_i(\xi_i) > 0, \quad D^{p-1}u_i(\xi_{i+1}) = 0,$$



$$\widehat{B}_{i,\Xi}^{(1)}$$



$$B_{i,\Xi}^{(1)}$$

- All Chebyshevian spline spaces good for design can be built by means of integral recurrence relations, [Mazure M.L., NM 2011]
-

Generalized B-splines: exponential (hyperbolic)

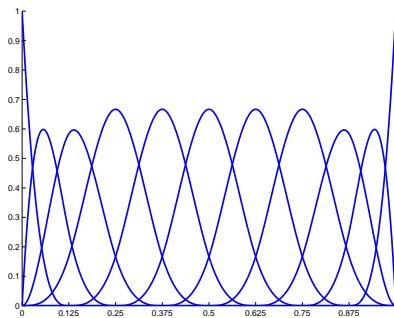
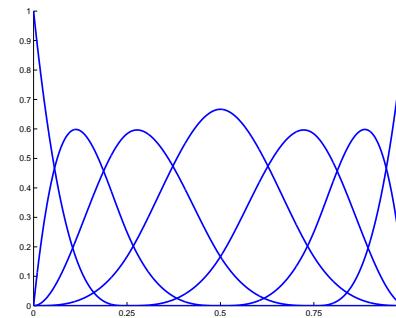
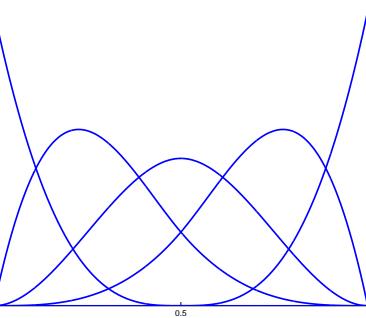
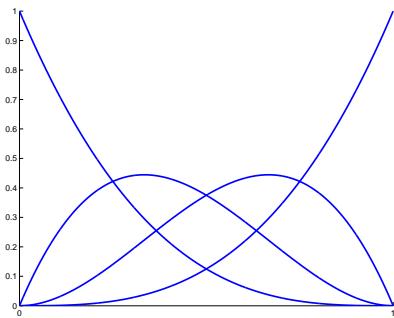
- $\Xi := \{\xi_1 \leq \xi_2 \leq \dots \leq \xi_{n+p+1}\}$: knots $W := \{\dots, \omega_i, \dots\}$: shape parameters

$$\mathbb{P}_p^{u_i, v_i} := \langle 1, t, \dots, t^{p-2}, \cosh \omega_i t, \sinh \omega_i t \rangle$$

- Exponential case: $p = 3$

$$\text{EXP}_3 = \mathbb{P}_3^{u, v} := \langle 1, t, e^{\omega t}, e^{-\omega t} \rangle \quad \text{isomorphic to } \mathbb{P}_3$$

Bernstein-like basis



$\omega \rightarrow 0:$

C^2 cubic B-splines

Generalized B-splines: exponential (hyperbolic)

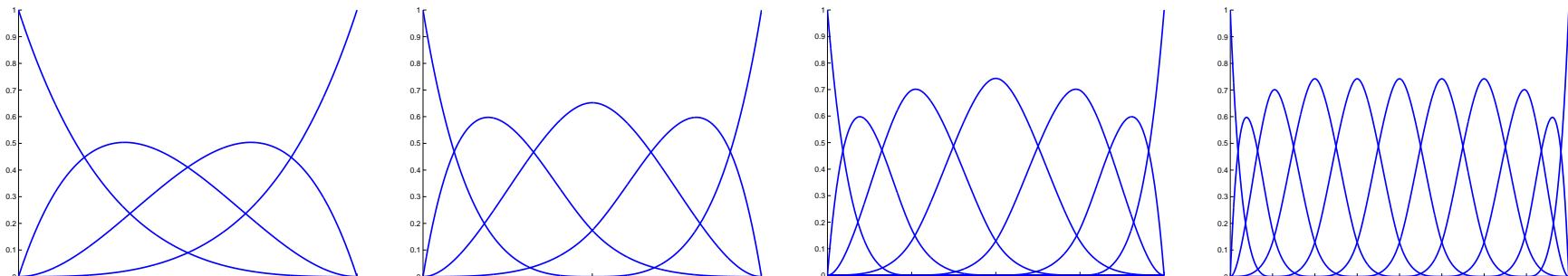
- $\Xi := \{\xi_1 \leq \xi_2 \leq \dots \leq \xi_{n+p+1}\}$: knots $W := \{..., \omega_i, ...\}$: shape parameters

$$\mathbb{P}_p^{u_i, v_i} := <1, t, \dots, t^{p-2}, \cosh \omega_i t, \sinh \omega_i t>$$

- Exponential case: $p = 3$

$$\text{EXP}_3 = \mathbb{P}_3^{u, v} := <1, t, e^{\omega t}, e^{-\omega t}> \quad \text{isomorphic to } \mathbb{P}_3$$

Bernstein-like basis



$$\omega = 3h$$

Generalized B-splines: properties

$$\{\widehat{B}_{i,\Xi}^{(p)}(t), \ i = 1, \dots\},$$

- Properties analogous to classical B-splines
 - positivity
 - partition of unity: $p \geq 2$
 - compact support
 - smoothness
 - derivatives
 - local linear independence
 - ...

Generalized B-splines: properties

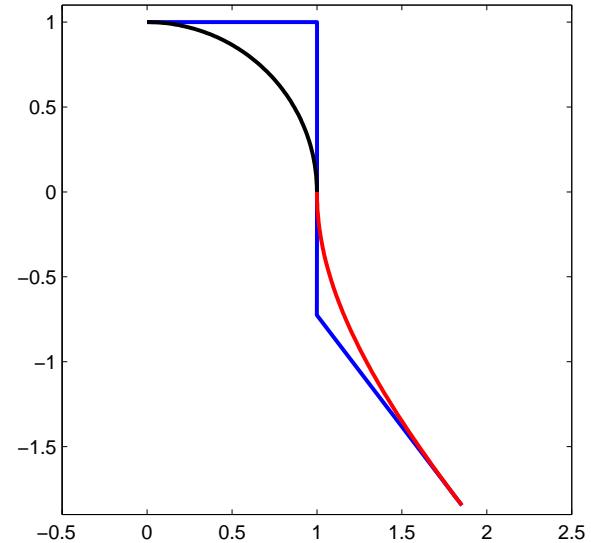
$$\{\widehat{B}_{i,\Xi}^{(p)}(t), \ i = 1, \dots\},$$

- Properties analogous to classical B-splines
 - positivity
 - partition of unity: $p \geq 2$
 - compact support
 - smoothness
 - derivatives
 - local linear independence
 - ...
 - shape properties $\{\dots, u_i, v_i, \dots\}$

Generalized B-splines: properties

$$\{\widehat{B}_{i,\Xi}^{(p)}(t), i = 1, \dots\},$$

- Properties analogous to classical B-splines
 - positivity
 - partition of unity: $p \geq 2$
 - compact support
 - smoothness
 - derivatives
 - local linear independence
 - ...
 - shape properties $\{\dots, u_i, v_i, \dots\}$
 - trig. and exp. parts can be **mixed**



Generalized B-splines: properties

$$\{\widehat{B}_{i,\Xi}^{(p)}(t), \ i = 1, \dots\},$$

- Properties analogous to classical B-splines
 - positivity
 - partition of unity: $p \geq 2$
 - compact support
 - smoothness
 - derivatives
 - local linear independence
 - ...
 - shape properties $\{\dots, u_i, v_i, \dots\}$
 - trig. and exp. parts can be **mixed**
 - straightforward multivariate extension via **tensor product**
-

Summary

Summary



$$\mathbb{P}_p = \langle 1, t, \dots, t^{p-2}, t^{p-1}, t^p \rangle$$
$$\mathbb{P}_p^{\textcolor{red}{u,v}} := \langle 1, t, \dots, t^{p-2}, \textcolor{red}{u(t)}, \textcolor{red}{v(t)} \rangle$$

\downarrow

Summary



$$\begin{aligned}\mathbb{P}_p &= \langle 1, t, \dots, t^{p-2}, t^{p-1}, t^p \rangle \\ \mathbb{P}_p^{\textcolor{red}{u,v}} &:= \langle 1, t, \dots, t^{p-2}, \textcolor{red}{u(t)}, \textcolor{red}{v(t)} \rangle\end{aligned}$$

- Bernstein like bases/control polygon

Summary



$$\begin{aligned}\mathbb{P}_p &= \langle 1, t, \dots, t^{p-2}, t^{p-1}, t^p \rangle \\ \mathbb{P}_p^{u,v} &:= \langle 1, t, \dots, t^{p-2}, u(t), v(t) \rangle\end{aligned}$$



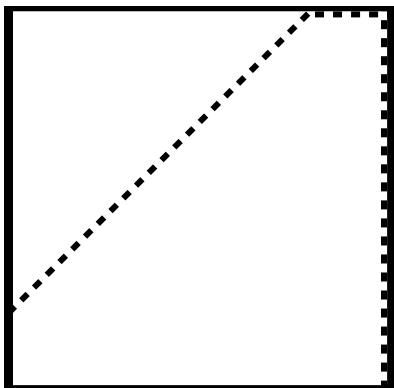
- Bernstein like bases/control polygon
- Generalized B-splines: spline spaces with sections in $\mathbb{P}_p^{u,v}$ with suitable bases for them (analogous to B-splines)

Local Refinements

- local refinements are crucial in applications (geometric modelling, simulation,...)

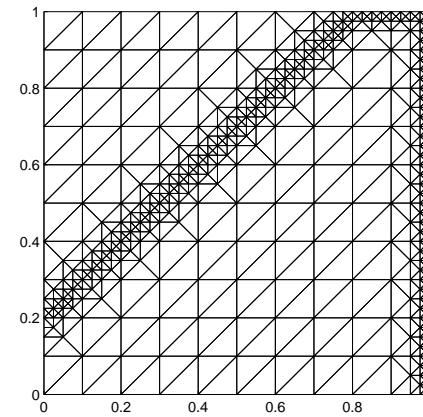
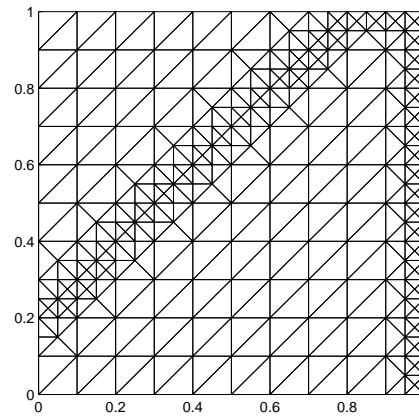
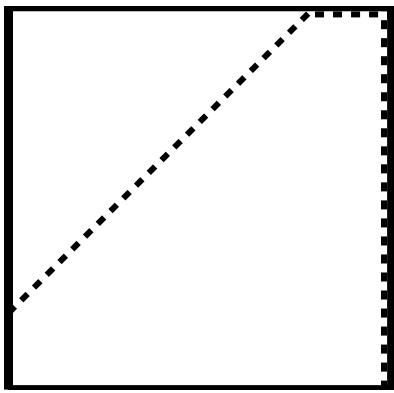
Local Refinements

- local refinements are crucial in applications (geometric modelling, simulation,...)



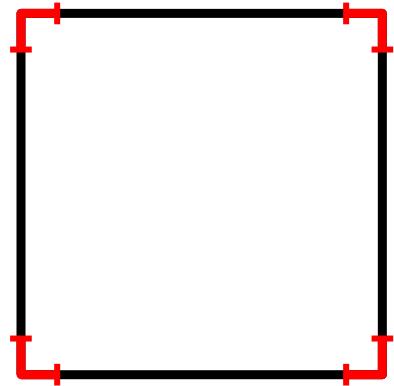
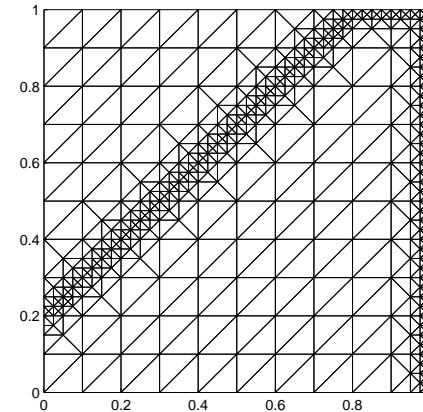
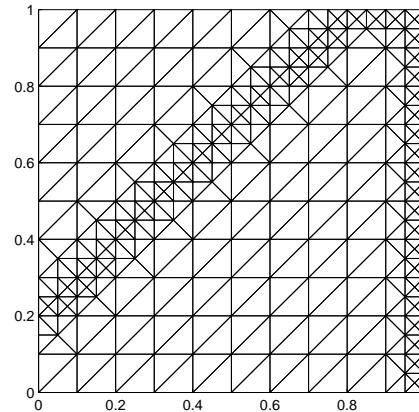
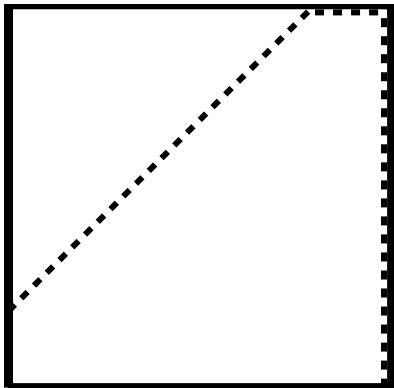
Local Refinements

- local refinements are crucial in applications (geometric modelling, simulation,...)



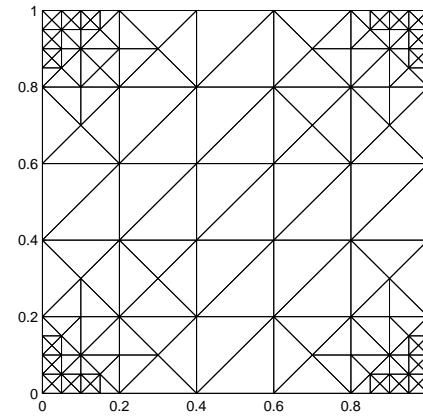
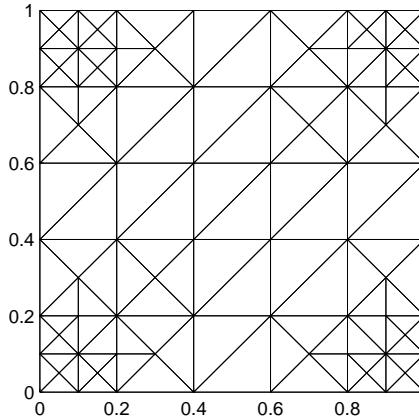
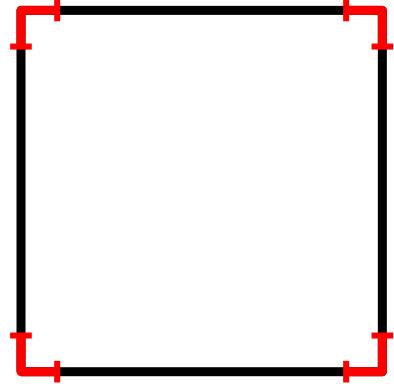
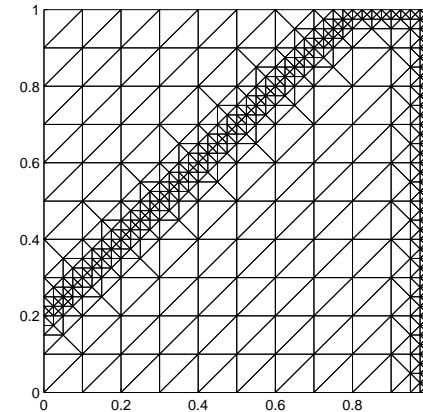
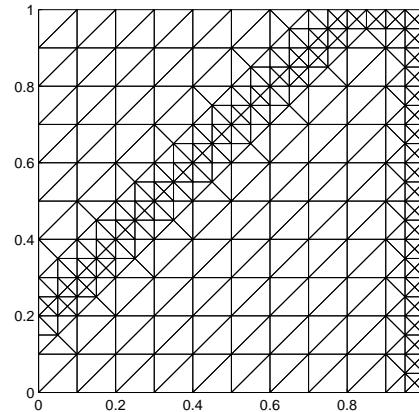
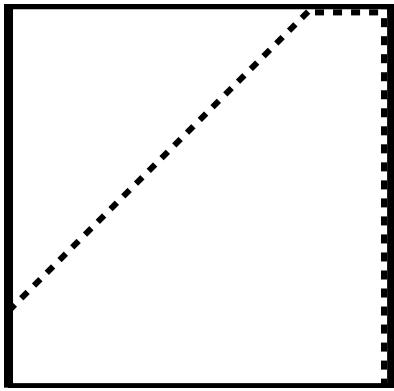
Local Refinements

- local refinements are crucial in applications (geometric modelling, simulation,...)



Local Refinements

- local refinements are crucial in applications (geometric modelling, simulation,...)



DRAWBACKS of tensor product structures

- the tensor product structure **prevents** local refinements
Alternatives (polynomial B-splines):

DRAWBACKS of tensor product structures

- the tensor product structure **prevents** local refinements
Alternatives (polynomial B-splines):
 - T-splines/Analysis-Suitable T-splines** [Bazilevs, Y., et al. CMAME 2010], [Beirão da Veiga, et al. CMAME, 2012]...

DRAWBACKS of tensor product structures

- the tensor product structure **prevents** local refinements
Alternatives (polynomial B-splines):
 - T-splines/Analysis-Suitable T-splines** [Bazilevs, Y., et al. CMAME 2010], [Beirão da Veiga, et al. CMAME, 2012]...
 - LR splines** [Dokken T., Lyche T., Pettersen K.F., CAGD 2013],

DRAWBACKS of tensor product structures

- the tensor product structure **prevents** local refinements
Alternatives (polynomial B-splines):
 - T-splines/Analysis-Suitable T-splines** [Bazilevs, Y., et al. CMAME 2010], [Beirão da Veiga, et al. CMAME, 2012]...
 - LR splines** [Dokken T., Lyche T., Pettersen K.F., CAGD 2013],
 - Hierarchical bases**

DRAWBACKS of tensor product structures

- the tensor product structure **prevents** local refinements
Alternatives (polynomial B-splines):
 - T-splines/Analysis-Suitable T-splines** [Bazilevs, Y., et al. CMAME 2010], [Beirão da Veiga, et al. CMAME, 2012]...
 - LR splines** [Dokken T., Lyche T., Pettersen K.F., CAGD 2013],
 - Hierarchical bases**
 - Splines over T-meshes**

DRAWBACKS of tensor product structures

- the tensor product structure **prevents** local refinements
- Alternatives (polynomial B-splines):
- T-splines/Analysis-Suitable T-splines** [Bazilevs, Y., et al. CMAME 2010], [Beirão da Veiga, et al. CMAME, 2012]...
 - LR splines** [Dokken T., Lyche T., Pettersen K.F., CAGD 2013],
 - Hierarchical bases**
 - Splines over T-meshes**
 - B-splines on triangulations**

Generalized Splines: local refinements?

Generalized Splines: local refinements?

- Generalized splines have **global tensor-product** structure

Generalized Splines: local refinements?

- Generalized splines have **global tensor-product** structure
- some localization techniques can be applied to (some) generalized spline spaces.
 - Hierarchical generalized splines
 - Generalized splines over T-meshes
 - Quadratic Generalized splines over triangulations

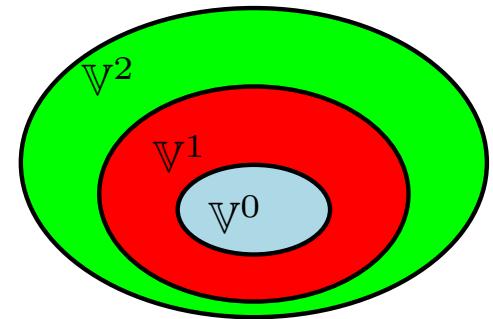
Hierarchical model

[Forsey, D.R., Bartels R.H., CG 1988], [Kraft R., Bartels R.H., Surf. Fitt. Mult. Meth. 1997], [Rabut C., 2005]

[Vuong A.-V., Giannelli C., Jüttler B., Simeon B.; CMAME 2011], [Giannelli C., Jüttler B., Speleers, H.; CAGD 2012], [Bracco C., et al., JCAM 2014]

- sequence of N nested tensor-product spline spaces

$$\mathbb{V}^0 \subset \mathbb{V}^1 \subset \dots \subset \mathbb{V}^{N-1}$$



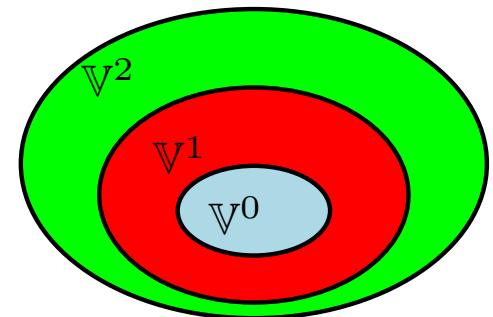
Hierarchical B-spline model

[Forsey, D.R., Bartels R.H., CG 1988], [Kraft R., Bartels R.H., Surf. Fitt. Mult. Meth. 1997], [Rabut C., 2005]

[Vuong A.-V., Giannelli C., Jüttler B., Simeon B.; CMAME 2011], [Giannelli C., Jüttler B., Speleers, H.; CAGD 2012], [Bracco C., et al., JCAM 2014]

- sequence of N nested tensor-product spline spaces

$$\mathbb{V}^0 \subset \mathbb{V}^1 \subset \dots \subset \mathbb{V}^{N-1}$$



\mathbb{V}^ℓ is spanned by a tensor-product B-spline basis \mathcal{B}^ℓ :

$$\mathcal{B}^\ell = \{\dots, B_{i,\ell}, \dots\}$$

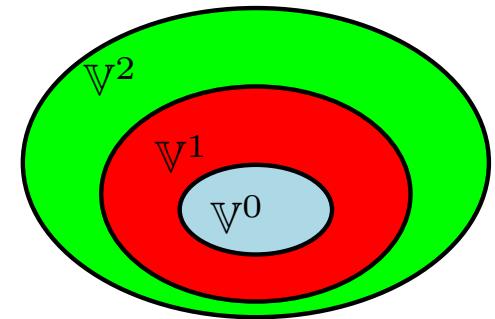
Hierarchical B-spline model

[Forsey, D.R., Bartels R.H., CG 1988], [Kraft R., Bartels R.H., Surf. Fitt. Mult. Meth. 1997], [Rabut C., 2005]

[Vuong A.-V., Giannelli C., Jüttler B., Simeon B.; CMAME 2011], [Giannelli C., Jüttler B., Speleers, H.; CAGD 2012], [Bracco C., et al., JCAM 2014]

- sequence of N nested tensor-product spline spaces

$$\mathbb{V}^0 \subset \mathbb{V}^1 \subset \dots \subset \mathbb{V}^{N-1}$$

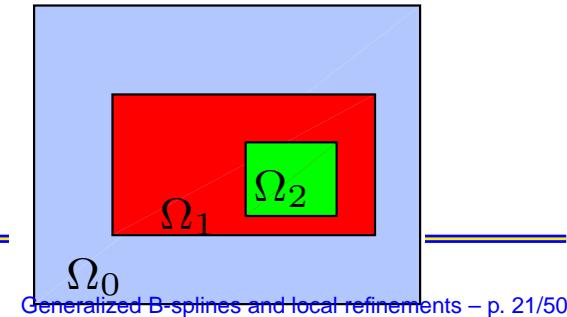


\mathbb{V}^ℓ is spanned by a tensor-product B-spline basis \mathcal{B}^ℓ :

$$\mathcal{B}^\ell = \{\dots, B_{i,\ell}, \dots\}$$

- sequence of N nested domains

$$\Omega_{N-1} \subset \Omega_{N-2} \subset \dots \subset \Omega_0, \quad \Omega_N = \emptyset$$

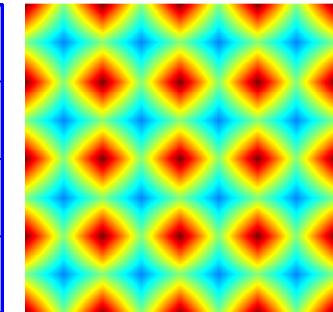
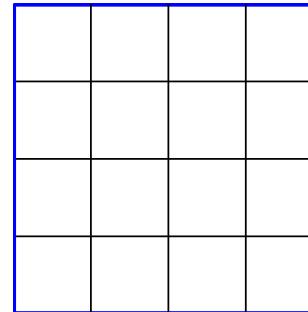


Hierarchical B-spline model

degree 1

Recursive definition

(I) Initialization: $\mathcal{H}^0 := \mathcal{B}^0$

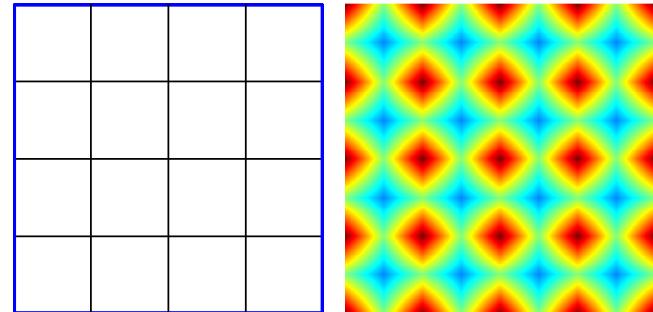


Hierarchical B-spline model

degree 1

Recursive definition

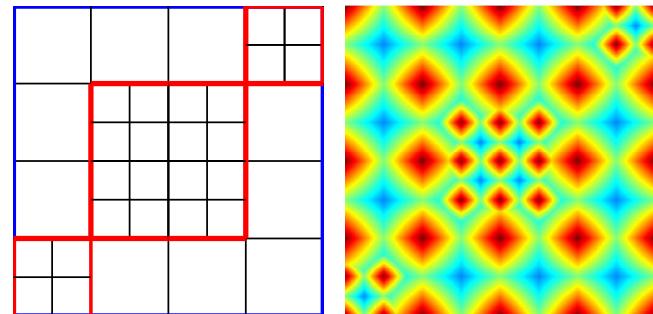
(I) Initialization: $\mathcal{H}^0 := \mathcal{B}^0$



(II) construction of $\mathcal{H}^{\ell+1}$ from \mathcal{H}^ℓ ,

$$\mathcal{H}^{\ell+1} := \mathcal{H}_C^{\ell+1} \cup \mathcal{H}_F^{\ell+1}$$

$$\ell = 0, 1, \dots, N - 1$$

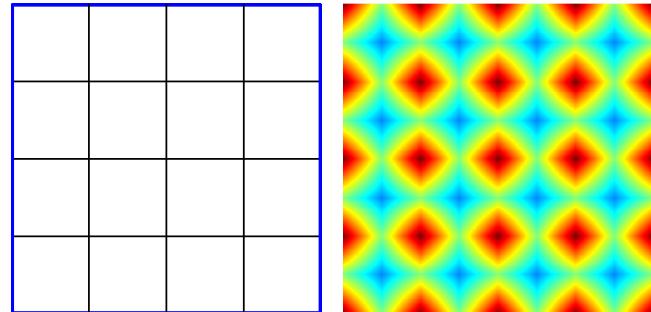


Hierarchical B-spline model

degree 1

Recursive definition

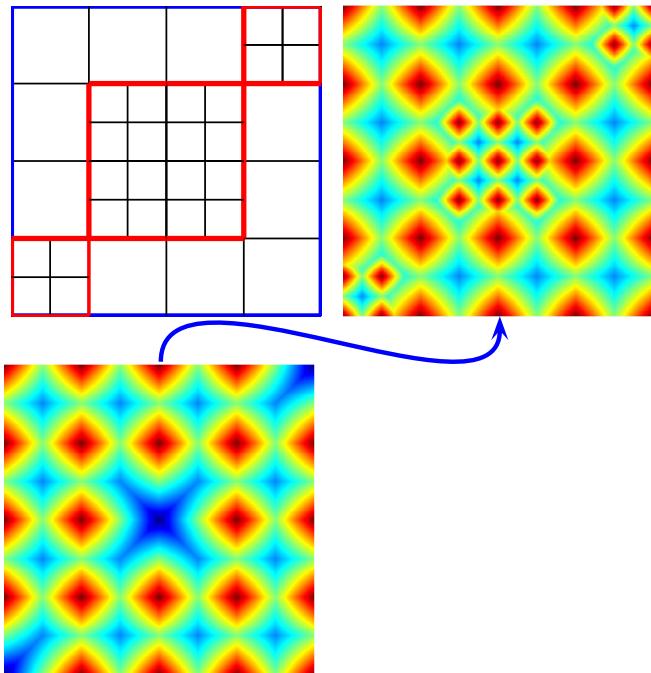
(I) Initialization: $\mathcal{H}^0 := \mathcal{B}^0$



(II) construction of $\mathcal{H}^{\ell+1}$ from \mathcal{H}^ℓ ,

$$\mathcal{H}^{\ell+1} := \mathcal{H}_C^{\ell+1} \cup \mathcal{H}_F^{\ell+1}$$

$$\ell = 0, 1, \dots, N - 1$$



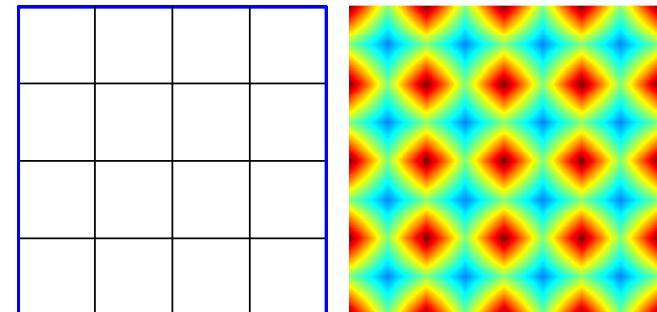
$$\mathcal{H}_C^{\ell+1} := \{B_{i,\ell} \in \mathcal{H}^\ell : \text{supp}(B_{i,\ell}) \not\subset \Omega_{\ell+1}\}$$

Hierarchical B-spline model

degree 1

Recursive definition

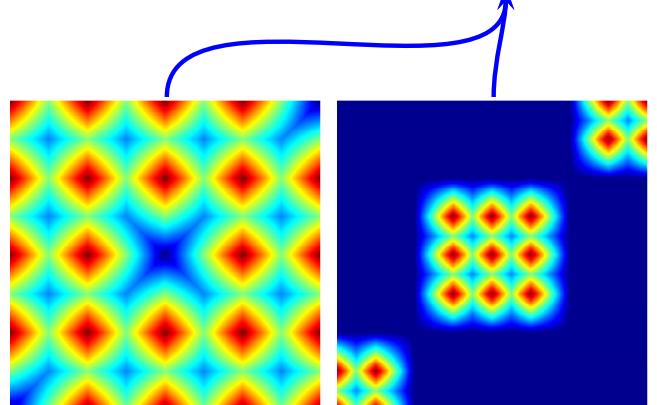
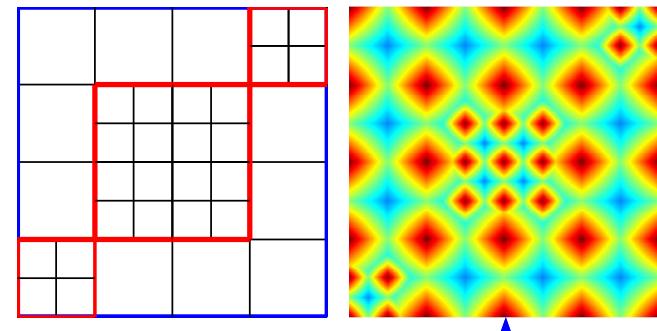
(I) Initialization: $\mathcal{H}^0 := \mathcal{B}^0$



(II) construction of $\mathcal{H}^{\ell+1}$ from \mathcal{H}^ℓ ,

$$\mathcal{H}^{\ell+1} := \mathcal{H}_C^{\ell+1} \cup \mathcal{H}_F^{\ell+1}$$

$$\ell = 0, 1, \dots, N - 1$$



$$\mathcal{H}_C^{\ell+1} := \{B_{i,\ell} \in \mathcal{H}^\ell : \text{supp}(B_{i,\ell}) \not\subset \Omega_{\ell+1}\}$$

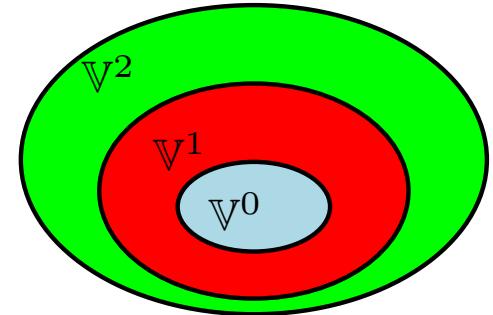
$$\mathcal{H}_F^{\ell+1} := \{B_{i,\ell+1} \in \mathcal{B}^{\ell+1} : \text{supp}(B_{i,\ell+1}) \subset \Omega_{\ell+1}\}$$

[Vuong A.-V., Giannelli C., Jüttler B., Simeon B.; CMAME 2011]

Hierarchical B-spline model

- sequence of N nested tensor-product spline spaces

$$\mathbb{V}^0 \subset \mathbb{V}^1 \subset \dots \subset \mathbb{V}^{N-1}$$

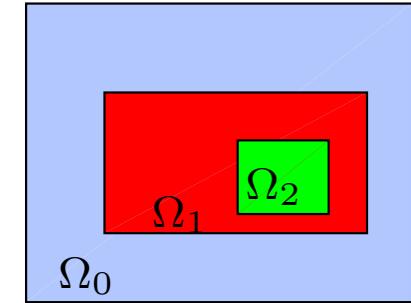


\mathbb{V}^ℓ is spanned by a tensor-product B-spline basis \mathcal{B}^ℓ :

$$\mathcal{B}^\ell = \{\dots, B_{i,\ell}, \dots\}$$

- sequence of N nested domains

$$\Omega_{N-1} \subset \Omega_{N-2} \subset \dots \subset \Omega_0, \quad \Omega_N = \emptyset$$

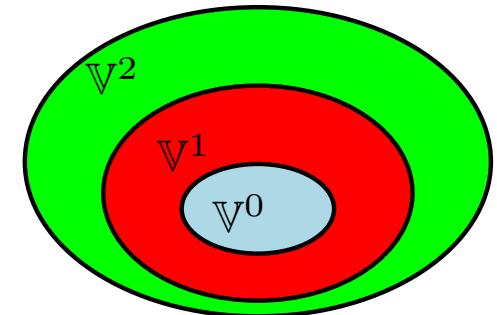


Hierarchical Generalized B-spline model

Generalized B-splines support a hierarchical refinement

- sequence of N nested tensor-product spline spaces

$$\mathbb{V}^0 \subset \mathbb{V}^1 \subset \dots \subset \mathbb{V}^{N-1}$$

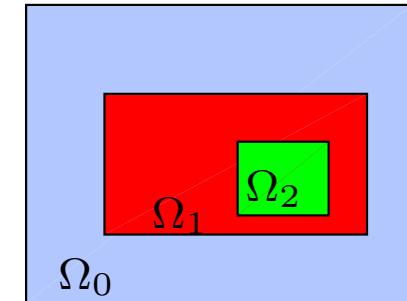


\mathbb{V}^ℓ spanned by a **tensor-product Generalized B-spline basis** $\widehat{\mathcal{B}}^\ell$:

$$\widehat{\mathcal{B}}^\ell = \{\dots, \widehat{B}_{i,\ell}, \dots\}$$

- sequence of N nested domains

$$\Omega_{N-1} \subset \Omega_{N-2} \subset \dots \subset \Omega_0, \quad \Omega_N = \emptyset$$

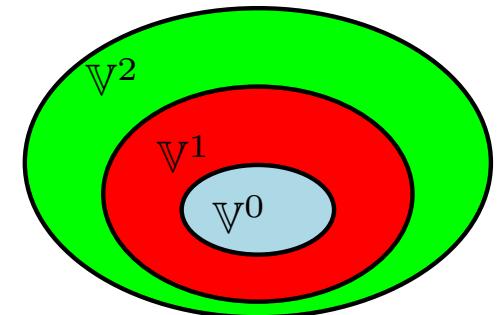


Hierarchical Generalized B-spline model

Generalized B-splines support a hierarchical refinement

- sequence of N nested tensor-product spline spaces

$$\mathbb{V}^0 \subset \mathbb{V}^1 \subset \dots \subset \mathbb{V}^{N-1}$$



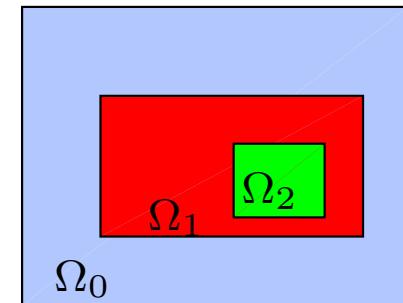
\mathbb{V}^ℓ spanned by a **tensor-product Generalized B-spline basis** $\widehat{\mathcal{B}}^\ell$:

$$\widehat{\mathcal{B}}^\ell = \{\dots, \widehat{B}_{i,\ell}, \dots\}$$

- sequence of N nested domains

$$\Omega_{N-1} \subset \Omega_{N-2} \subset \dots \subset \Omega_0, \quad \Omega_N = \emptyset$$

⇒ similar recursive definition



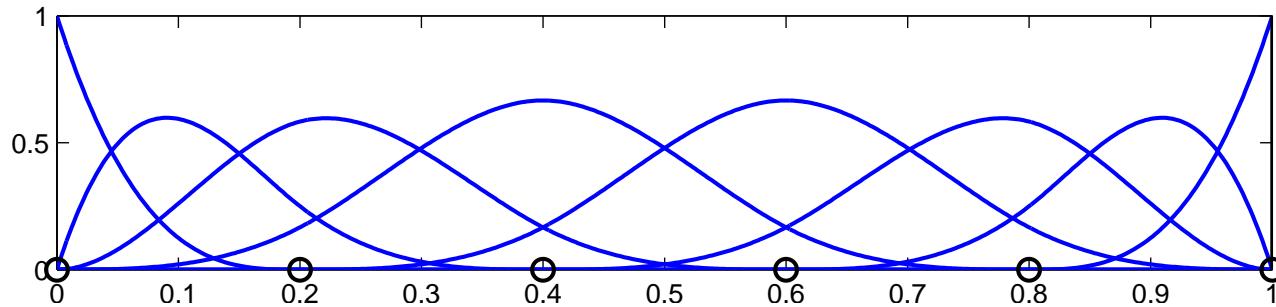
Hierarchical B-splines model

1D Example: Cubic B-spline basis

[Vuong A.-V., Giannelli C., Jüttler B., Simeon B.; CMAME 2011]

Hierarchical B-splines model

1D Example: Cubic B-spline basis

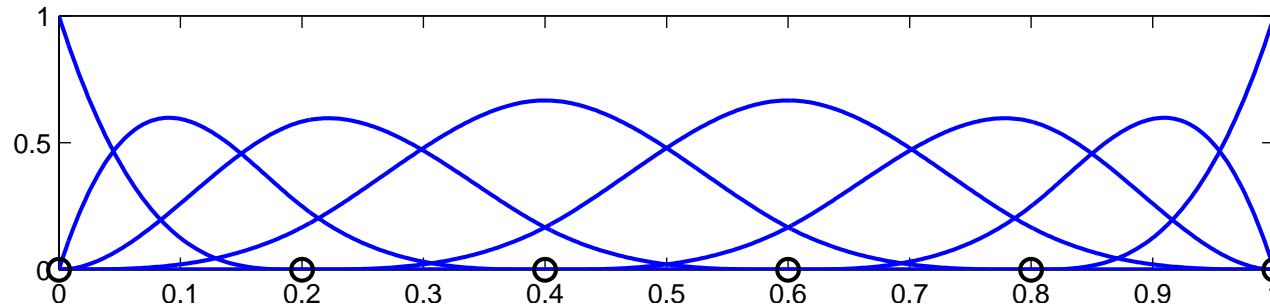


$$\mathcal{H}^0 = \mathcal{B}^0$$

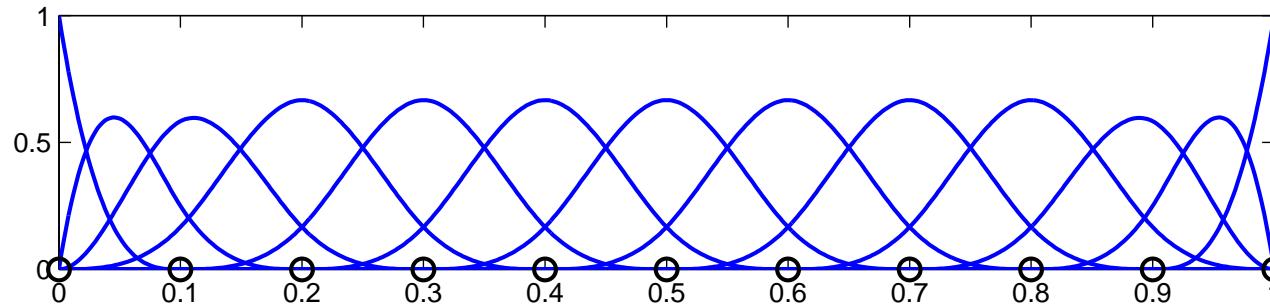
[Vuong A.-V., Giannelli C., Jüttler B., Simeon B.; CMAME 2011]

Hierarchical B-splines model

1D Example: Cubic B-spline basis



$$\mathcal{H}^0 = \mathcal{B}^0$$

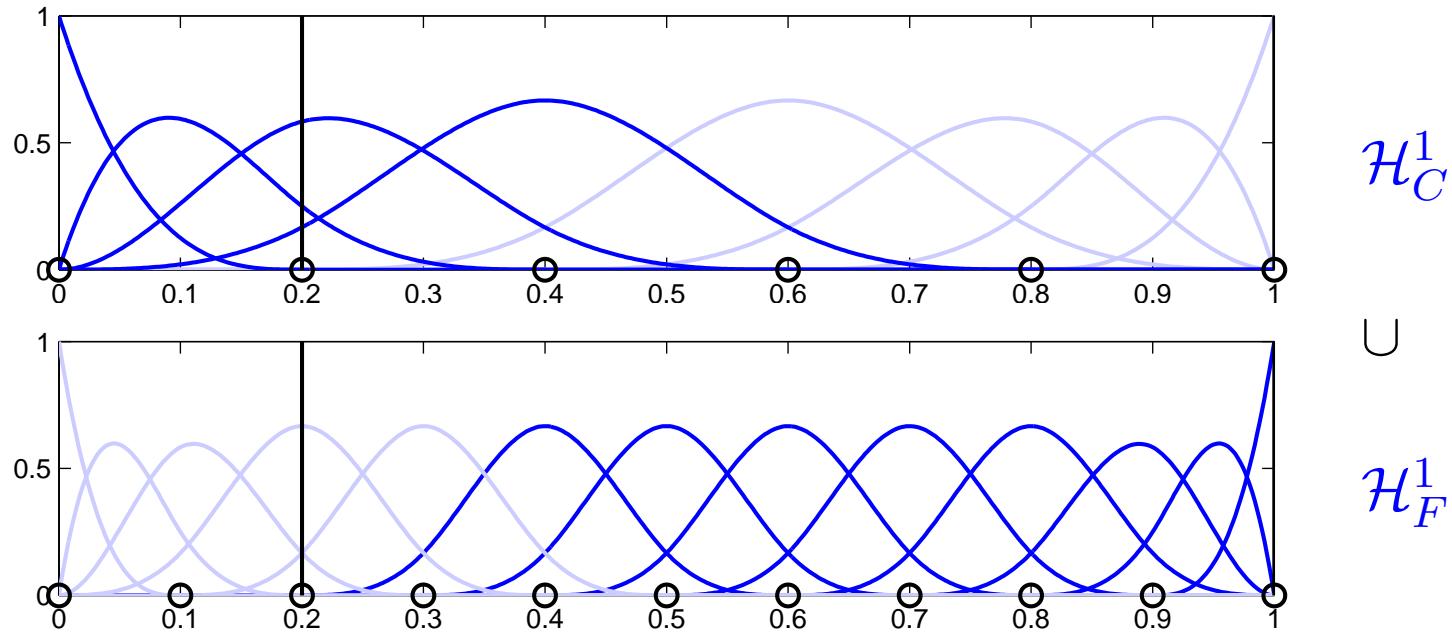


$$\mathcal{B}^1$$

[Vuong A.-V., Giannelli C., Jüttler B., Simeon B.; CMAME 2011]

Hierarchical B-splines model

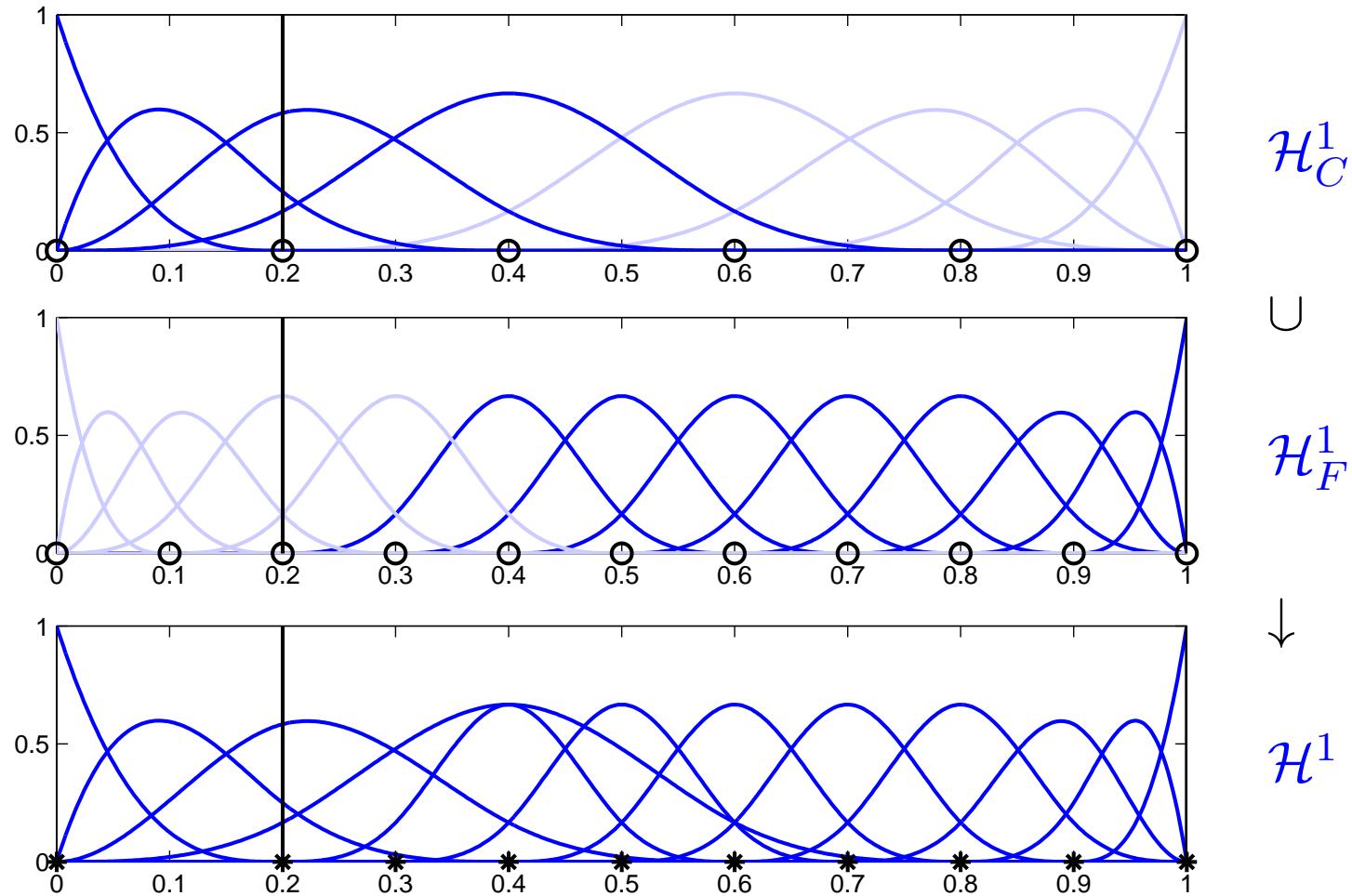
1D Example: Cubic B-spline basis



[Vuong A.-V., Giannelli C., Jüttler B., Simeon B.; CMAME 2011]

Hierarchical B-splines model

1D Example: Cubic B-spline basis



[Vuong A.-V., Giannelli C., Jüttler B., Simeon B.; CMAME 2011]

Hierarchical Generalized B-spline model

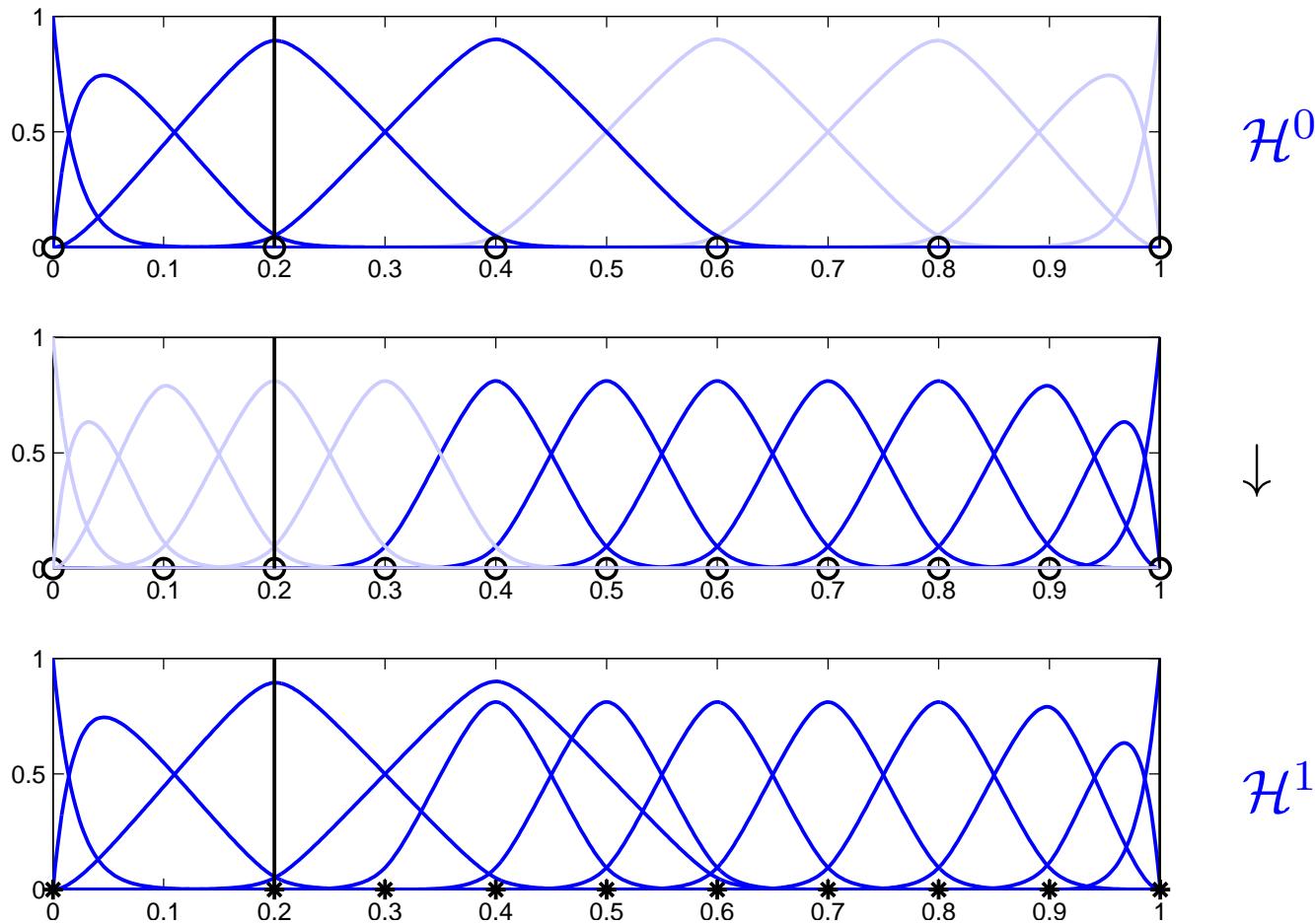
Generalized B-splines support a hierarchical refinement

1D Example: EXP₃ B-splines basis $\omega_i = 50$

Hierarchical Generalized B-spline model

Generalized B-splines support a hierarchical refinement

1D Example: EXP₃ B-splines basis $\omega_i = 50$



Hierarchical Generalized B-spline model

The main properties of Hierarchical B-splines are inherited by
Hierarchical GB-splines



Hierarchical Generalized B-spline model

The main properties of Hierarchical B-splines are inherited by Hierarchical GB-splines

- the functions in \mathcal{H}^ℓ obtained by the iterative procedure are linearly independent

Hierarchical Generalized B-spline model

The main properties of Hierarchical B-splines are inherited by Hierarchical GB-splines

- the functions in \mathcal{H}^ℓ obtained by the iterative procedure are linearly independent
- the hierarchical bases \mathcal{H}^ℓ , for each ℓ , span nested spaces:

$$\text{span}\mathcal{H}^\ell \subseteq \text{span}\mathcal{H}^{\ell+1}$$

Hierarchical Generalized B-spline model

The main properties of Hierarchical B-splines are inherited by Hierarchical GB-splines

- the functions in \mathcal{H}^ℓ obtained by the iterative procedure are linearly independent
- the hierarchical bases \mathcal{H}^ℓ , for each ℓ , span nested spaces:

$$\text{span}\mathcal{H}^\ell \subseteq \text{span}\mathcal{H}^{\ell+1}$$

- positivity

Hierarchical Generalized B-spline model

The main properties of Hierarchical B-splines are inherited by Hierarchical GB-splines

- the functions in \mathcal{H}^ℓ obtained by the iterative procedure are linearly independent
- the hierarchical bases \mathcal{H}^ℓ , for each ℓ , span nested spaces:

$$\text{span}\mathcal{H}^\ell \subseteq \text{span}\mathcal{H}^{\ell+1}$$

- positivity
- partition of unity

Hierarchical Generalized B-spline model

The main properties of Hierarchical B-splines are inherited by Hierarchical GB-splines

- the functions in \mathcal{H}^ℓ obtained by the iterative procedure are linearly independent
- the hierarchical bases \mathcal{H}^ℓ , for each ℓ , span nested spaces:

$$\text{span}\mathcal{H}^\ell \subseteq \text{span}\mathcal{H}^{\ell+1}$$

- positivity
- partition of unity
 - by using truncated bases

[Giannelli, Jüttler, Speleers; AiCM 2013]

Hierarchical Generalized B-spline model

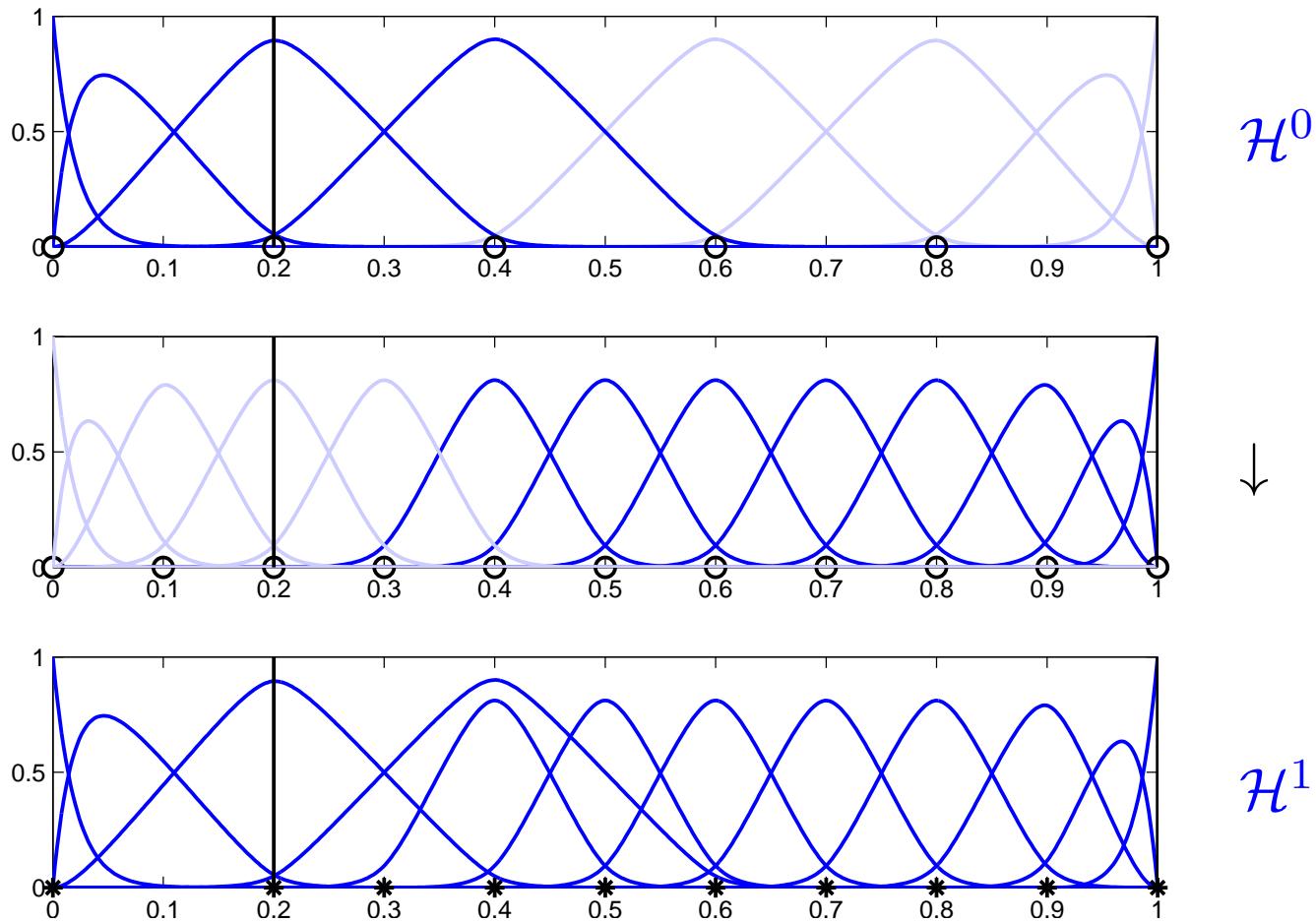
Generalized B-splines: truncated hierarchical basis

1D Example: EXP₃ B-splines basis $\omega_i = 50$

Hierarchical Generalized B-spline model

Generalized B-splines: truncated hierarchical basis

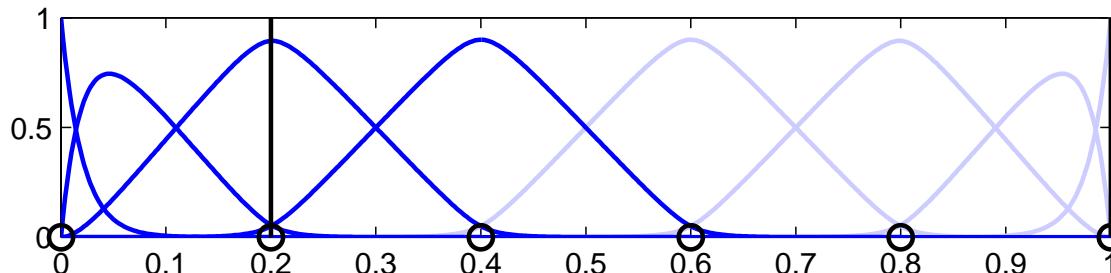
1D Example: EXP₃ B-splines basis $\omega_i = 50$



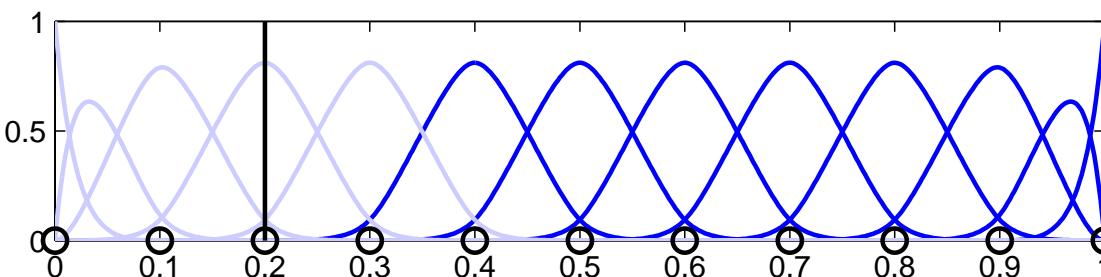
Hierarchical Generalized B-spline model

Generalized B-splines: truncated hierarchical basis

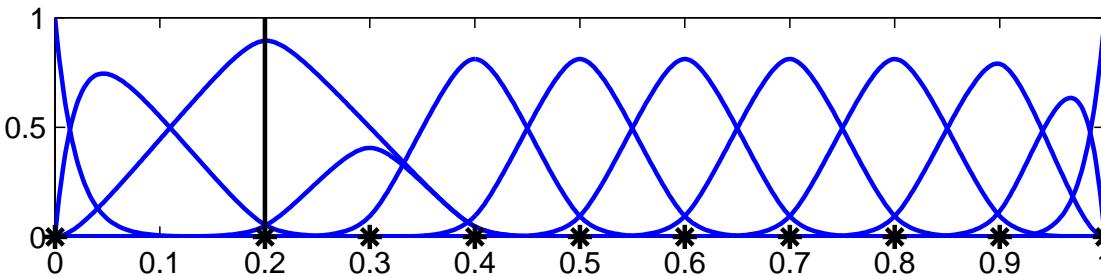
1D Example: EXP₃ B-splines basis $\omega_i = 50$



T^0



\downarrow

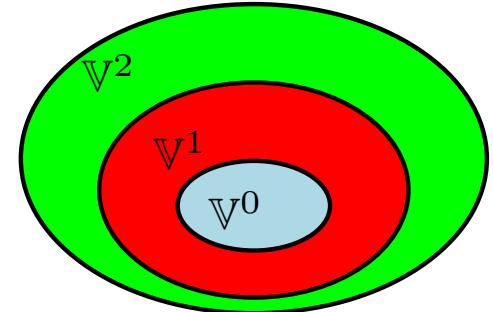


T^1

Hierarchical Generalized B-splines: space

- sequence of N nested tensor-product spline spaces

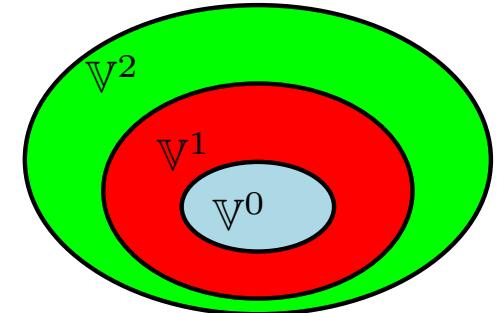
$$\mathbb{V}^0 \subset \mathbb{V}^1 \subset \dots \subset \mathbb{V}^{N-1}$$



Hierarchical Generalized B-splines: space

- sequence of N nested tensor-product spline spaces

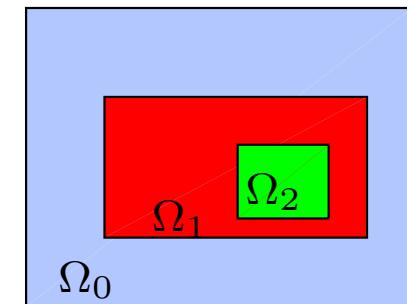
$$\mathbb{V}^0 \subset \mathbb{V}^1 \subset \dots \subset \mathbb{V}^{N-1}$$



\mathbb{V}^ℓ tensor-product (Generalized) B-splines

- sequence of N nested domains

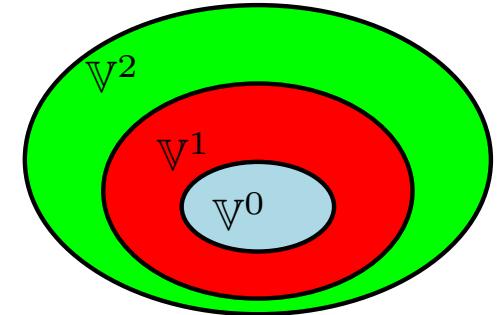
$$\Omega_{N-1} \subset \Omega_{N-2} \subset \dots \subset \Omega_0, \quad \Omega_N = \emptyset$$



Hierarchical Generalized B-splines: space

- sequence of N nested tensor-product spline spaces

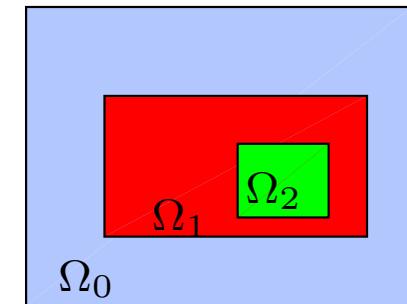
$$\mathbb{V}^0 \subset \mathbb{V}^1 \subset \dots \subset \mathbb{V}^{N-1}$$



\mathbb{V}^ℓ tensor-product (Generalized) B-splines

- sequence of N nested domains

$$\Omega_{N-1} \subset \Omega_{N-2} \subset \dots \subset \Omega_0, \quad \Omega_N = \emptyset$$



hierarchical (Generalized) B-splines span the full space

$$\{f : f|_{\Omega_0 \setminus \Omega_{\ell+1}} \in \mathbb{V}^\ell|_{\Omega_0 \setminus \Omega_{\ell+1}}, \ell = 0, \dots, N-1\}$$

[Giannelli, Jüttler; JCAM 2013], [Speleers, Manni, 2013 preprint]

Hierarchical structures: not nested spaces

the construction can be applied to a hierarchy of **not nested** spaces

$$\mathbb{V}^0, \mathbb{V}^1, \dots, \mathbb{V}^{N-1}$$

Hierarchical structures: not nested spaces

the construction can be applied to a hierarchy of **not nested** spaces

$$\mathbb{V}^0, \mathbb{V}^1, \dots, \mathbb{V}^{N-1}$$

Hierarchical structures: not nested spaces

the construction can be applied to a hierarchy of **not nested** spaces

$$\mathbb{V}^0, \mathbb{V}^1, \dots, \mathbb{V}^{N-1}$$

- great flexibility

Hierarchical structures: not nested spaces

the construction can be applied to a hierarchy of **not nested** spaces

$$\mathbb{V}^0, \mathbb{V}^1, \dots, \mathbb{V}^{N-1}$$

- great flexibility
- different section spaces at different levels



Hierarchical structures: not nested spaces

the construction can be applied to a hierarchy of **not nested** spaces

$$\mathbb{V}^0, \mathbb{V}^1, \dots, \mathbb{V}^{N-1}$$

- great flexibility
 - different section spaces at different levels
 - the functions in \mathcal{H}^ℓ obtained by the iterative procedure remain **linearly independent**
-

Hierarchical structures: not nested spaces

the construction can be applied to a hierarchy of **not nested** spaces

$$\mathbb{V}^0, \mathbb{V}^1, \dots, \mathbb{V}^{N-1}$$

- great flexibility
- different section spaces at different levels
- the functions in \mathcal{H}^ℓ obtained by the iterative procedure remain **linearly independent**
- not nested spaces span \mathcal{H}^ℓ

[Manni, Pelosi, Speleers; 2013, to appear]

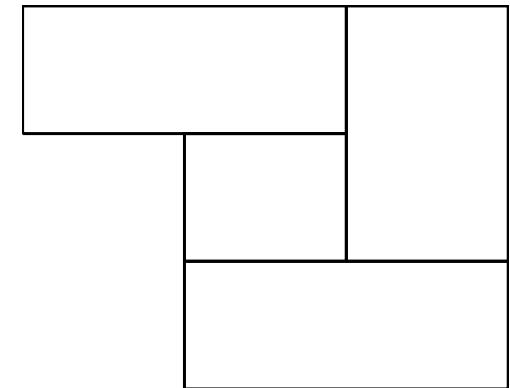
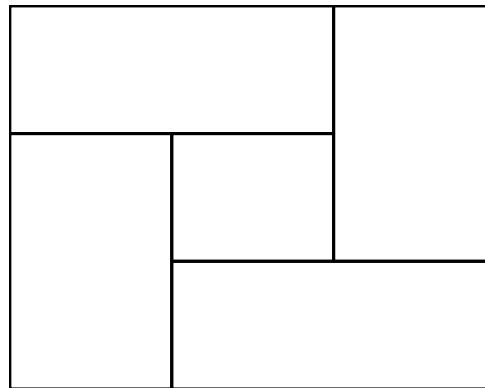
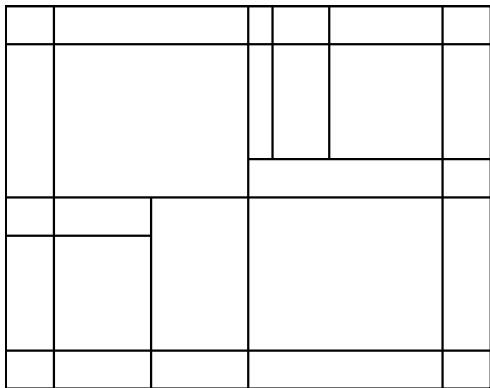
-
- Hierarchical B-splines are particular bases of particular spline spaces on special rectangular partitions

Spline spaces over T-meshes

Spline spaces over T-meshes

● T-mesh \mathcal{T}

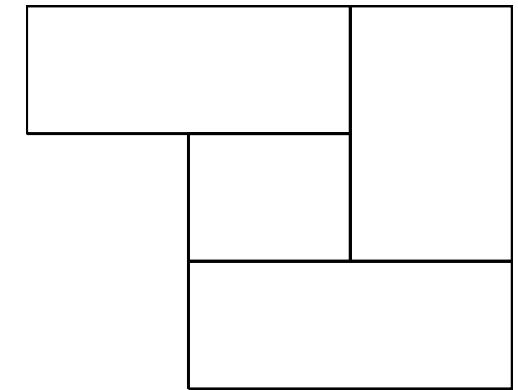
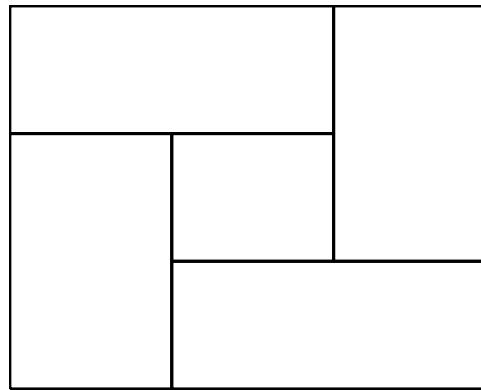
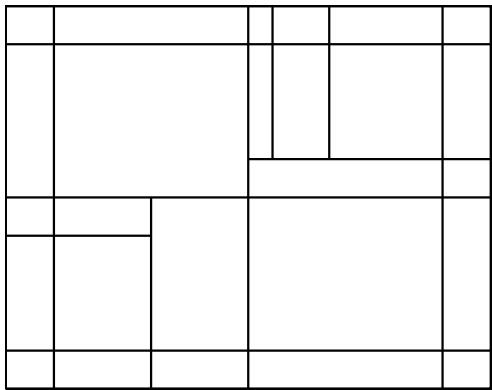
partition of a (rectangular) domain by rectangles: **T-junctions** (hanging vertices)
are allowed



Spline spaces over T-meshes

● T-mesh \mathcal{T}

partition of a (rectangular) domain by rectangles: **T-junctions** (hanging vertices) are allowed



$$\mathbb{S}_{\mathbf{d}}^{\mathbf{r}}(\mathcal{T}) := \{ s(x, y) \in C^{\mathbf{r}}, \ s(x, y)|_{\tau_i} \in \mathbb{P}_{d_1} \times \mathbb{P}_{d_2}, \ \tau_i \in \mathcal{T} \},$$

$$\mathbb{P}_d := \left\{ q(z) = \sum_{j=0}^d z^j \right\}, \ \mathbf{r} = (r_1, r_2), \ \mathbf{d} = (d_1, d_2)$$

[Deng, J.-S., Chen, F-L., Feng, Y.-Y., JCAM 2006]

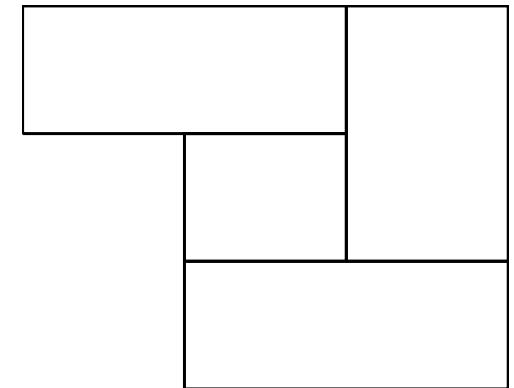
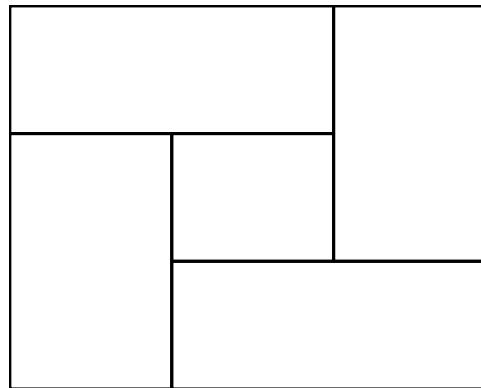
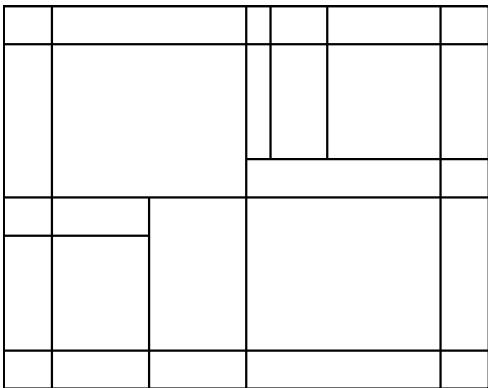
[Schumaker, L. L. and Wang, L., CAGD 2012]

[Schumaker, L. L. and Wang, L., NM 2011]

Spline spaces over T-meshes

● T-mesh \mathcal{T}

partition of a (rectangular) domain by rectangles: **T-junctions** (hanging vertices) are allowed



$$\mathbb{S}_{\mathbf{d}}^{\mathbf{r}}(\mathcal{T}) := \{ s(x, y) \in C^{\mathbf{r}}, \ s(x, y)|_{\tau_i} \in \mathbb{P}_{d_1} \times \mathbb{P}_{d_2}, \ \tau_i \in \mathcal{T} \},$$

$$\mathbb{P}_d := \left\{ q(z) = \sum_{j=0}^d z^j \right\}, \ \mathbf{r} = (r_1, r_2), \ \mathbf{d} = (d_1, d_2)$$

✓ polynomial reproduction

✗ dimension?

✗ suitable bases?

Spline spaces over T-meshes: dimension

- [Mourrain, B., Math. Comp. 2013]

$$\dim(\mathbb{S}_{\mathbf{d}}^{\mathbf{r}}(\mathcal{T})) =$$

$$F(d_1 + 1)(d_2 + 1) - E_h(d_2 + 1)(r_2 + 1) - E_v(d_1 + 1)(r_1 + 1) + V(r_1 + 1)(r_2 + 1)$$

+ homology term

$F : \#faces$, $E_h : \#hor.edges$, $E_v : \#vert.edges$, $V : \#int.vertices$

Spline spaces over T-meshes: dimension

- [Mourrain, B., Math. Comp. 2013]

$$\dim(\mathbb{S}_{\mathbf{d}}^{\mathbf{r}}(\mathcal{T})) =$$

$$F(d_1 + 1)(d_2 + 1) - E_h(d_2 + 1)(r_2 + 1) - E_v(d_1 + 1)(r_1 + 1) + V(r_1 + 1)(r_2 + 1)$$

+ homology term

F : #faces, E_h : #hor.edges, E_v : #vert.edges, V : #int.vertices

- $\mathbf{d} \geq 2\mathbf{r} + 1$,

$$\dim(\mathbb{S}_{\mathbf{d}}^{\mathbf{r}}(\mathcal{T})) =$$

$$F(d_1 + 1)(d_2 + 1) - E_h(d_2 + 1)(r_2 + 1) - E_v(d_1 + 1)(r_1 + 1) + V(r_1 + 1)(r_2 + 1)$$

[Deng, J.-S., Chen, F-L., Feng, Y.-Y. , JCAM 2006]

[Schumaker, L. L. and Wang, L., 2011, CAGD 2012]

[Schumaker, L. L. and Wang, L., NM 2011]

Spline spaces over T-meshes: dimension

- [Mourrain, B., Math. Comp. 2013]

$$\dim(\mathbb{S}_{\mathbf{d}}^{\mathbf{r}}(\mathcal{T})) =$$

$$F(d_1 + 1)(d_2 + 1) - E_h(d_2 + 1)(r_2 + 1) - E_v(d_1 + 1)(r_1 + 1) + V(r_1 + 1)(r_2 + 1)$$

+ homology term

$F : \#faces$, $E_h : \#hor.edges$, $E_v : \#vert.edges$, $V : \#int.vertices$

- $\mathbf{d} \geq 2\mathbf{r} + 1$,

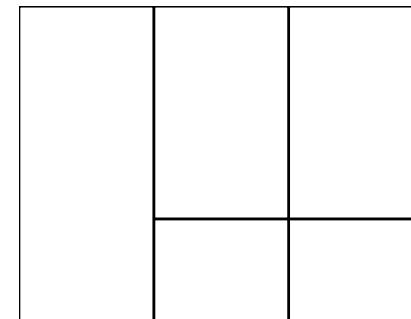
$$\dim(\mathbb{S}_{\mathbf{d}}^{\mathbf{r}}(\mathcal{T})) =$$

$$F(d_1 + 1)(d_2 + 1) - E_h(d_2 + 1)(r_2 + 1) - E_v(d_1 + 1)(r_1 + 1) + V(r_1 + 1)(r_2 + 1)$$

- C^1 cubics: $\dim(\mathbb{S}_3^1(\mathcal{T})) = 4(V_b + V_+)$

$V_b : \#b. vertices$, $V_+ : \#cross. vertices$

Ex: $\dim(\mathbb{S}_3^1(\mathcal{T})) = 4(9 + 1)$



Splines over T-meshes: dimension

- $d \geq 2r + 1$, rectangular domains: results based on
 - Bernstein representation
 - minimal determining sets

[Alfeld, P., Schumaker, L.L., CA 1987]

[Alfeld P., JCAM 2000]

[Deng, J.-S., Chen, F-L., Feng, Y.-Y., JCAM 2006]

[Schumaker, L. L. and Wang, L., 2011, preprint]

[Schumaker, L. L. and Wang, L., NM 2011]

Splines over T-meshes: dimension

- $d \geq 2r + 1$, rectangular domains: results based on
 - Bernstein representation
 - minimal determining sets

[Alfeld, P., Schumaker, L.L., CA 1987]

[Alfeld P., JCAM 2000]

[Deng, J.-S., Chen, F-L., Feng, Y.-Y., JCAM 2006]

[Schumaker, L. L. and Wang, L., 2011, preprint]

[Schumaker, L. L. and Wang, L., NM 2011]

- smoothing cofactors

[Wang, R.-H., 2001]

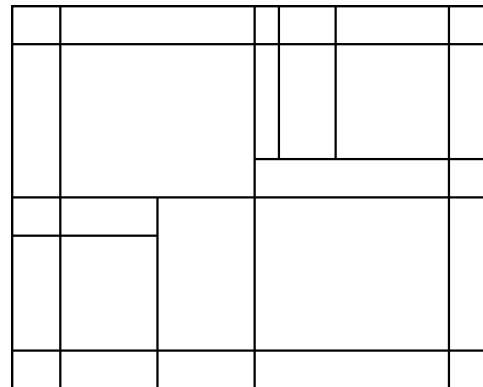
[Huang, Z.-J., Deng J.-S. Feng, Y.-Y., Chen, F.-L., JCM 2006]

Generalized Splines over T-meshes

- **T-mesh: \mathcal{T}**

partition of a (rectangular) domain by rectangles

so that **T-junctions** (hanging vertices) are allowed

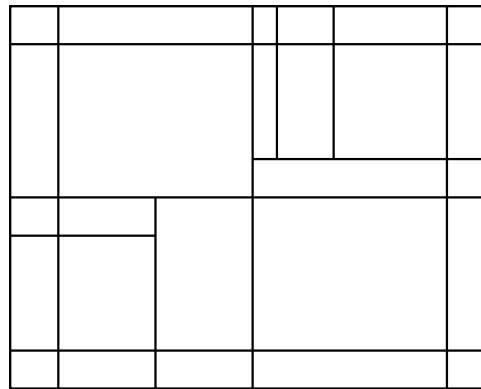


Generalized Splines over T-meshes

- **T-mesh: \mathcal{T}**

partition of a (rectangular) domain by rectangles

so that **T-junctions** (hanging vertices) are allowed



$$\widehat{\mathbb{S}}_{\mathbf{d}}^{\mathbf{r}}(\mathcal{T}) := \{s(x, y) \in C^{\mathbf{r}}, \ s(x, y)|_{\tau_i} \in \mathbb{P}_{d_1}^{u_1, v_1} \otimes \mathbb{P}_{d_2}^{u_2, v_2}, \ \tau_i \in \mathcal{T}\},$$

$$\mathbb{P}_p^{u, v} := \langle 1, t, \dots, t^{p-2}, u(t), v(t) \rangle$$

Generalized Splines over T-meshes

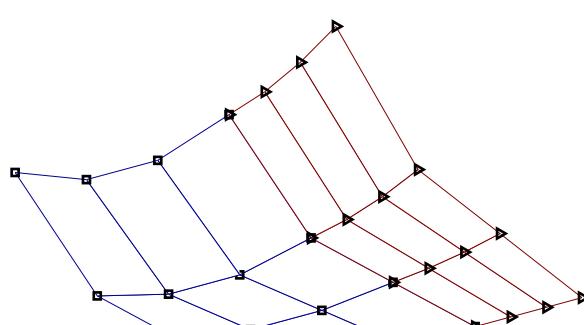
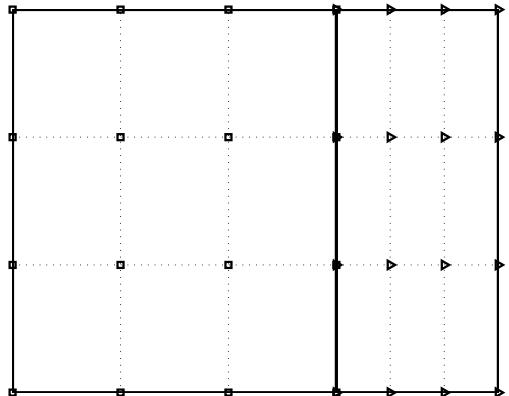
- suitable spaces : exponential, trigonometric

Generalized Splines over T-meshes

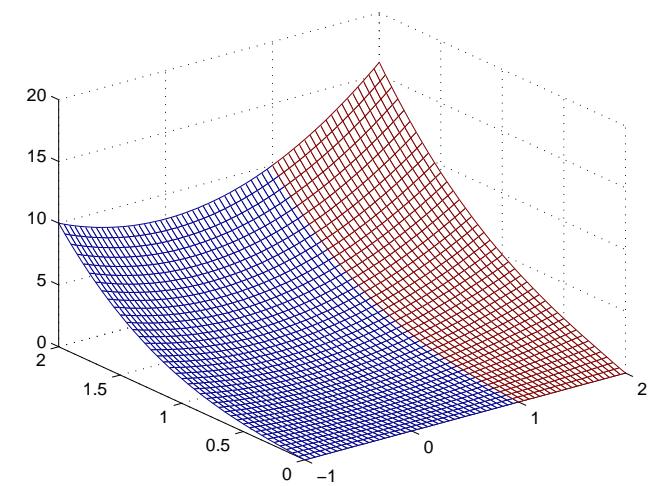
- suitable spaces : exponential, trigonometric
- smoothness cond.: Bernstein like representation

Generalized Splines over T-meshes

- suitable spaces : exponential, trigonometric
- smoothness cond.: Bernstein like representation

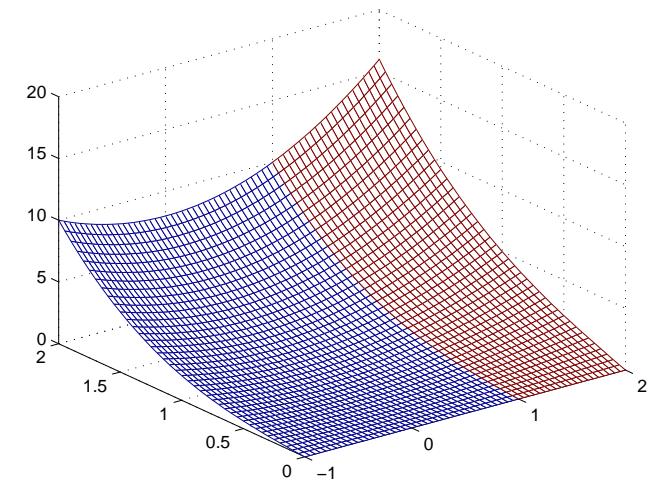
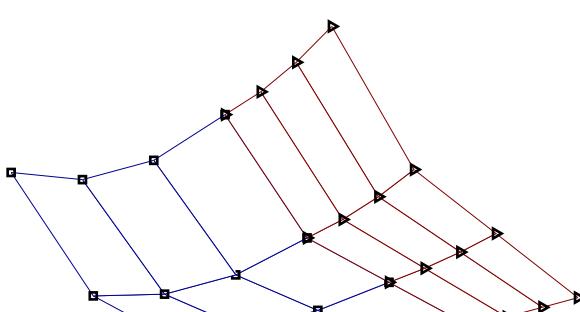
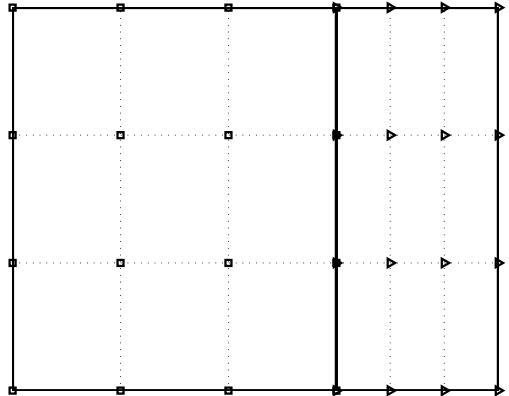


C^1 cubics

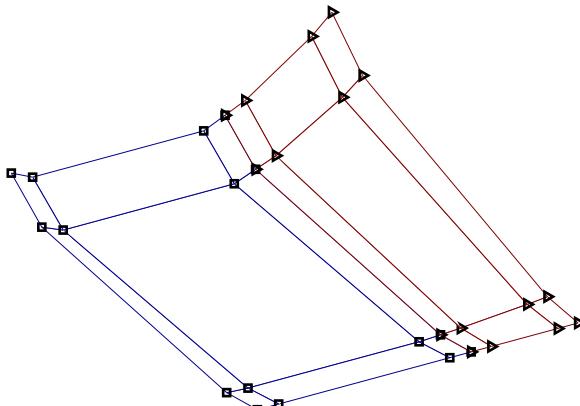
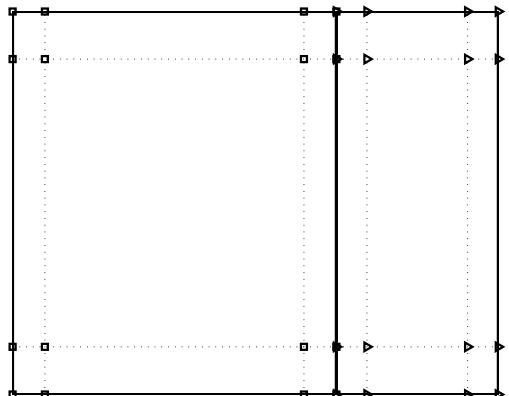


Generalized Splines over T-meshes

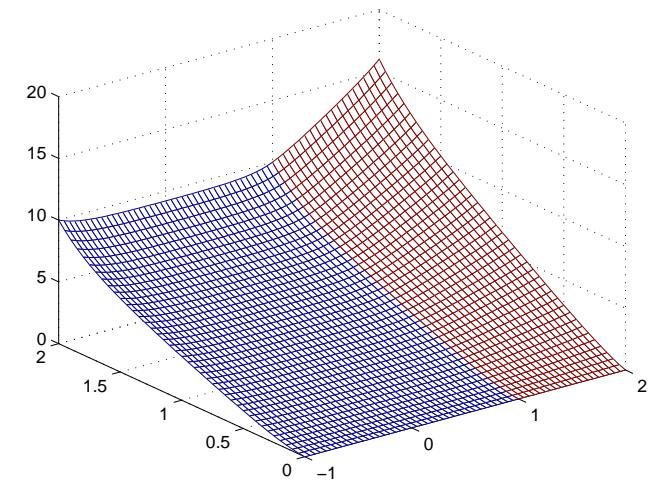
- suitable spaces : exponential, trigonometric
- smoothness cond.: Bernstein like representation



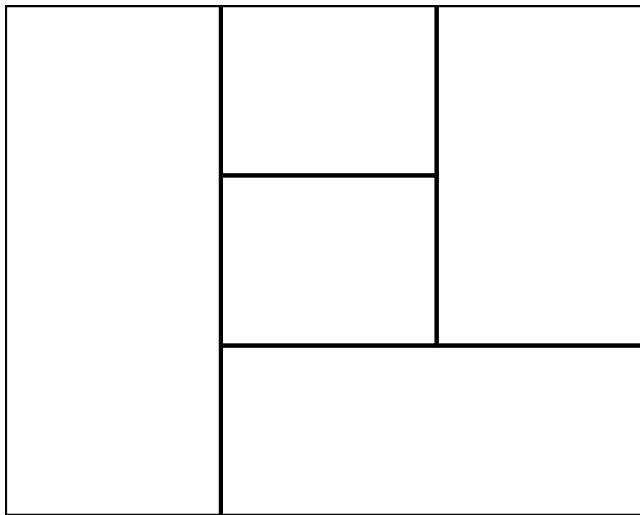
C^1 cubics



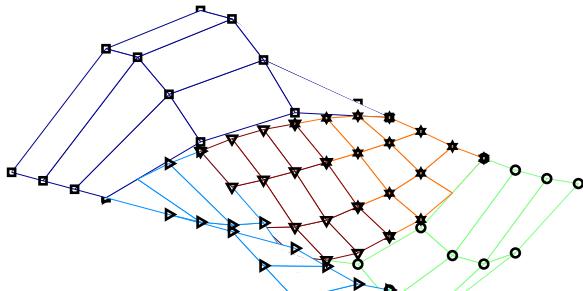
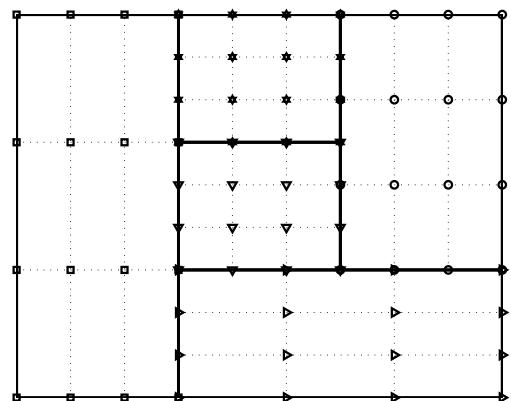
C^1 exponential (cubics)



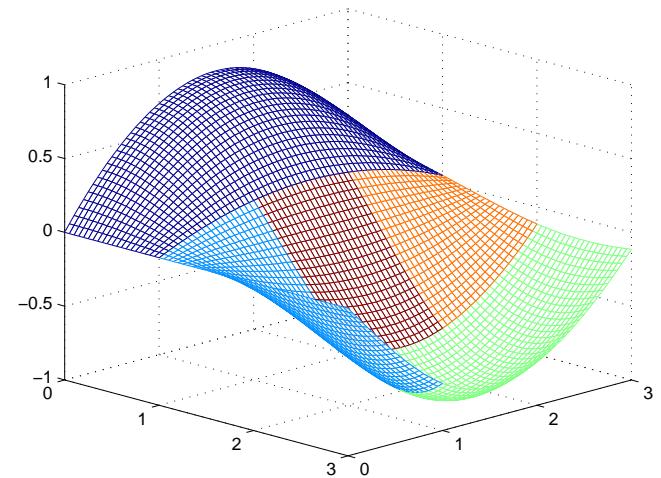
Generalized Splines over T-meshes



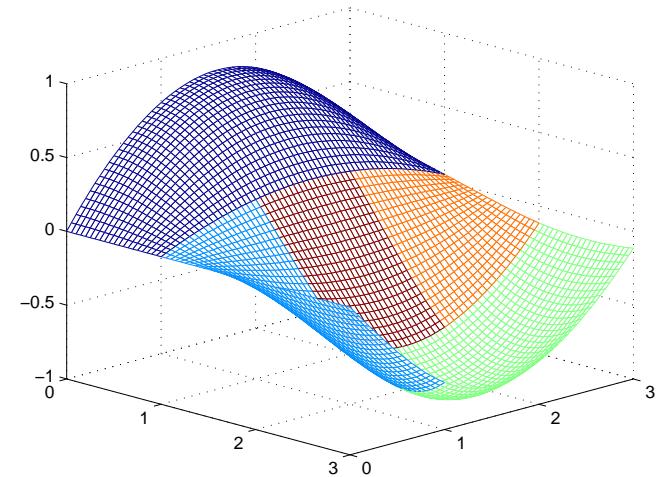
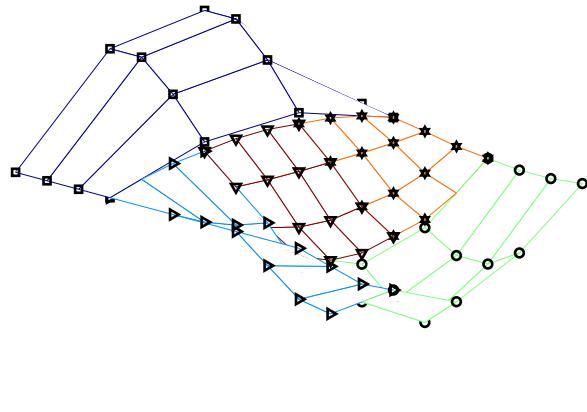
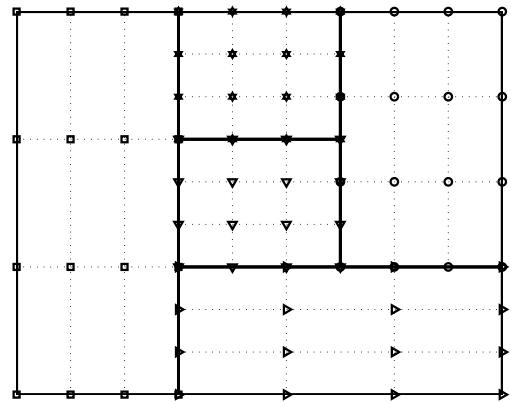
Generalized Splines over T-meshes



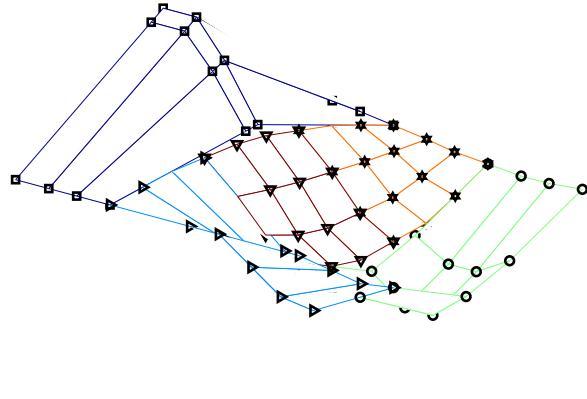
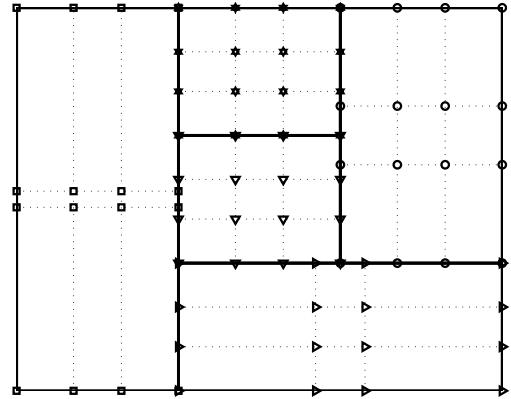
C^1 cubics



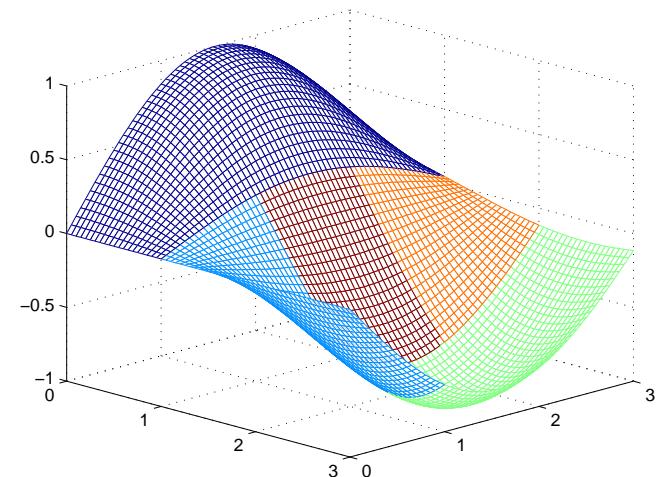
Generalized Splines over T-meshes



C^1 cubics



C^1 trigonometric (cubics), $\omega = \frac{2}{5}\pi$

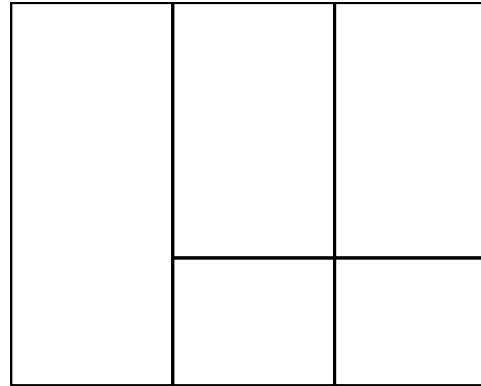


Generalized Splines over T-meshes: dimension

- trigonometric/exponential C^1 cubics:

$$\dim(\widehat{\mathbb{S}}_3^1(\mathcal{T})) = 4(V_b + V_+)$$

V_b : #b. vertices, V_+ : #cross. vertices



$$\dim(\mathbb{S}_3^1(\mathcal{T})) = 4(9 + 1)$$

So far so good...

- Hierarchical bases, T-meshes: similar behavior of B-splines/GB-splines

-
- Hierarchical bases, T-meshes: similar behavior of B-splines/GB-splines
 - Triangulations?

Quadratic Generalized Splines over Triangles

Quadratic Generalized Splines over Triangles

- $\mathbb{P}_2^{u,v} := \langle 1, u(t), v(t) \rangle$

Quadratic Generalized Splines over Triangles

- $\mathbb{P}_2^{u,v} := \langle 1, u(t), v(t) \rangle$
- ONTP basis $\{B_0, B_1, B_2\}$ $B_0(0) = 1, B_0(1) = B'_0(1) = 0, \dots$

Quadratic Generalized Splines over Triangles

- $\mathbb{P}_2^{u,v} := \langle 1, u(t), v(t) \rangle$
- ONTP basis $\{B_0, B_1, B_2\}$ $B_0(0) = 1, B_0(1) = B'_0(1) = 0, \dots$
- Bernstein like representation
control polygon for functions?

$$t \notin \langle 1, u(t), v(t) \rangle$$

No Greville abscissae

Quadratic Generalized Splines over Triangles

- $\mathbb{P}_2^{u,v} := \langle 1, u(t), v(t) \rangle$
- ONTP basis $\{B_0, B_1, B_2\}$ $B_0(0) = 1, B_0(1) = B'_0(1) = 0, \dots$
- control points $f = b_0 B_0 + b_1 B_1 + b_2 B_2 \in \mathbb{P}_2^{u,v}$

\Downarrow

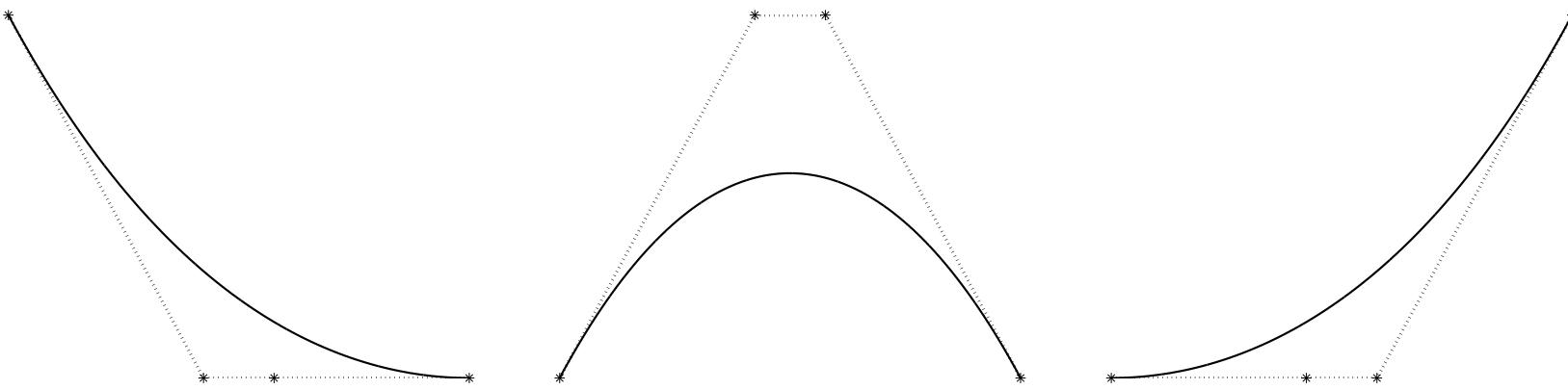
$$(0, b_0), (\xi, b_1), (1 - \xi, b_1), (1, b_2) \quad B_0(t) = B_2(1 - t) \quad \xi = -1/B'_0(0) = 1/B'_2(1)$$

Quadratic Generalized Splines over Triangles

- $\mathbb{P}_2^{u,v} := \langle 1, u(t), v(t) \rangle$
- ONTP basis $\{B_0, B_1, B_2\}$ $B_0(0) = 1, B_0(1) = B'_0(1) = 0, \dots$
- control points $f = b_0 B_0 + b_1 B_1 + b_2 B_2 \in \mathbb{P}_2^{u,v}$

\Downarrow

$$(0, b_0), (\xi, b_1), (1 - \xi, b_1), (1, b_2) \quad B_0(t) = B_2(1 - t) \quad \xi = -1/B'_0(0) = 1/B'_2(1)$$

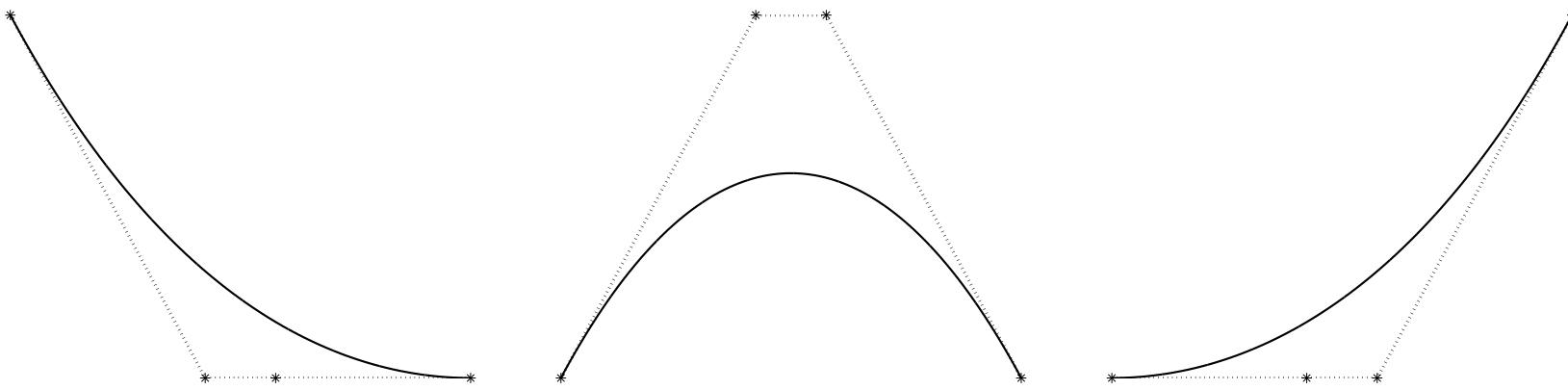


Quadratic Generalized Splines over Triangles

- $\mathbb{P}_2^{u,v} := \langle 1, u(t), v(t) \rangle$
- ONTP basis $\{B_0, B_1, B_2\}$ $B_0(0) = 1, B_0(1) = B'_0(1) = 0, \dots$
- control points $f = b_0 B_0 + b_1 B_1 + b_2 B_2 \in \mathbb{P}_2^{u,v}$

\Downarrow

$$(0, b_0), (\xi, b_1), (1 - \xi, b_1), (1, b_2) \quad B_0(t) = B_2(1 - t) \quad \xi = -1/B'_0(0) = 1/B'_2(1)$$



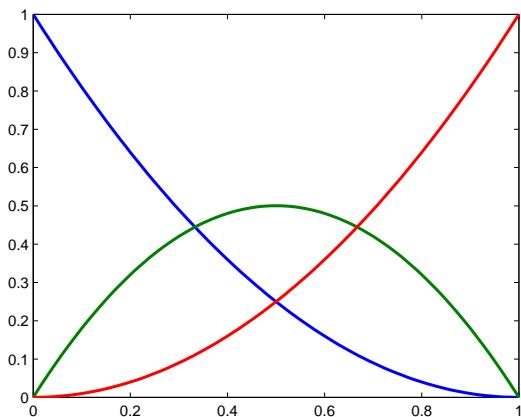
- geometric properties of the usual control polygon

Quadratic Generalized Splines over Triangles

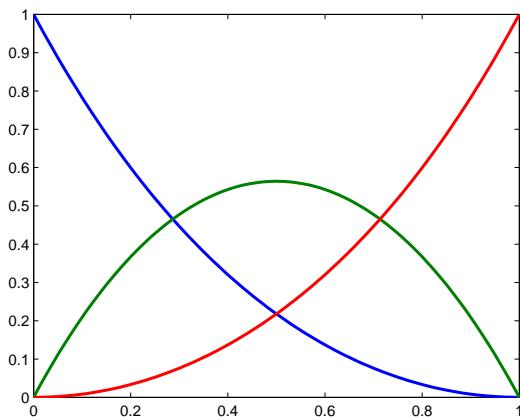
$$\mathbb{H}_\omega := \langle 1, \cosh \omega t, \sinh \omega t \rangle, \quad t \in [0, 1]$$

Quadratic Generalized Splines over Triangles

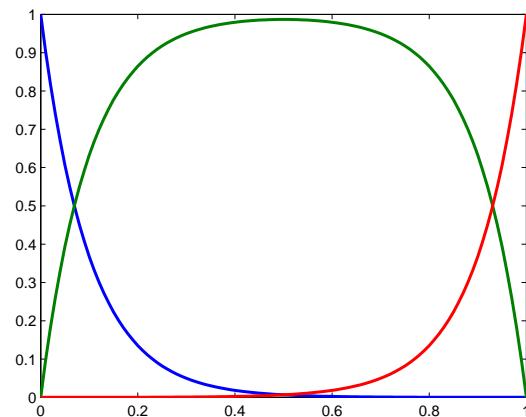
$$\mathbb{H}_\omega := \langle 1, \cosh \omega t, \sinh \omega t \rangle, \quad t \in [0, 1]$$



$$\omega = 0.1$$



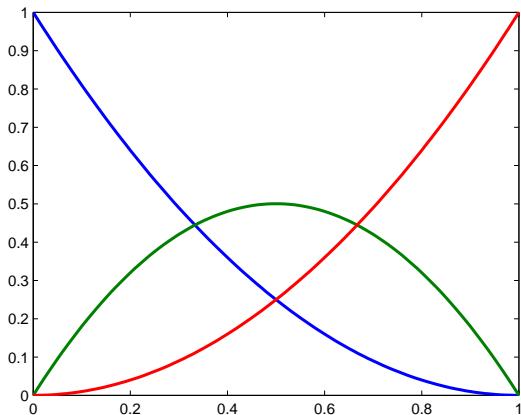
$$\omega = 1.5$$



$$\omega = 10$$

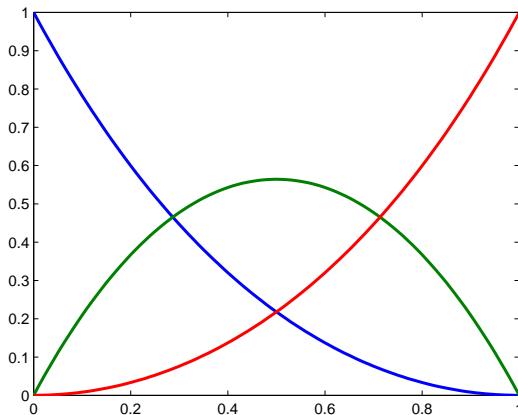
Quadratic Generalized Splines over Triangles

$$\mathbb{H}_\omega := \langle 1, \cosh \omega t, \sinh \omega t \rangle, \quad t \in [0, 1]$$



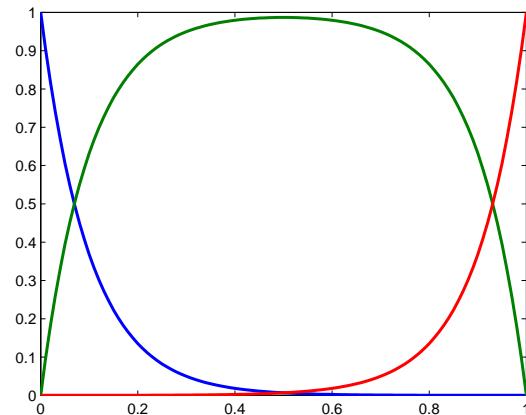
$$\omega = 0.1$$

ONTP basis $B_{0,\omega}, B_{1,\omega}, B_{2,\omega}$, $\omega \rightarrow 0$ quadratic Bernstein pol.



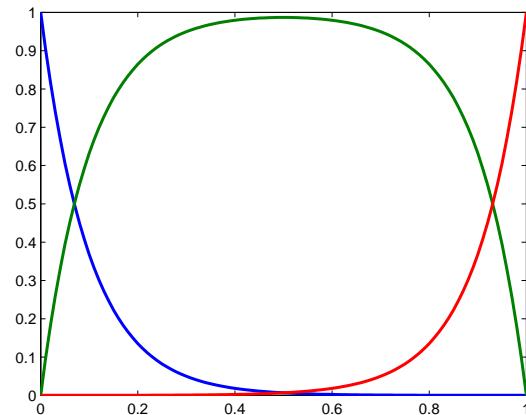
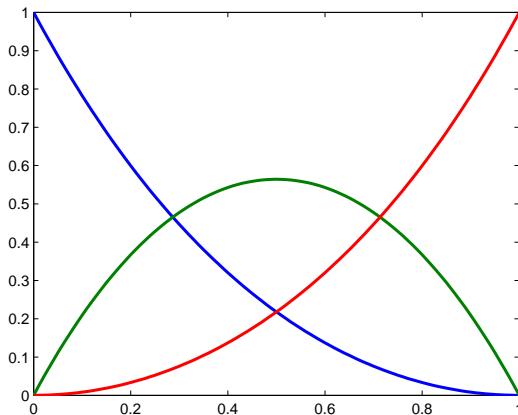
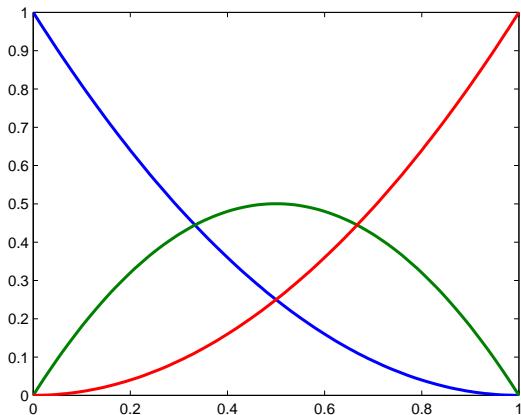
$$\omega = 1.5$$

$$\omega = 10$$

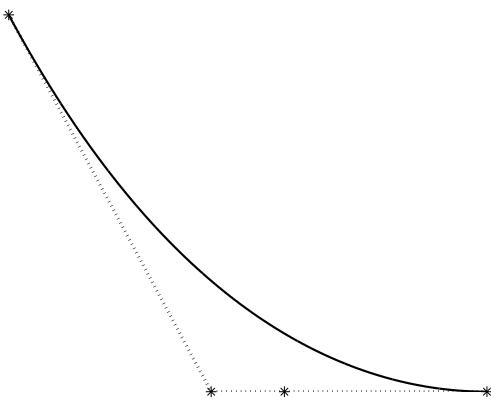


Quadratic Generalized Splines over Triangles

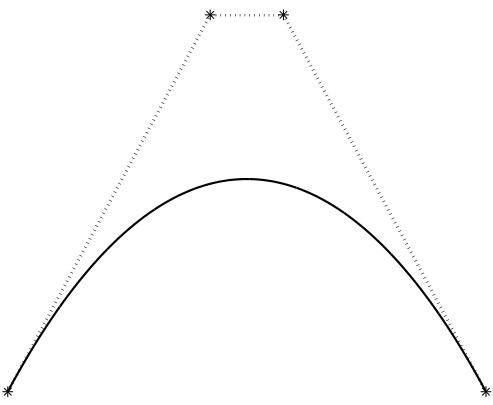
$$\mathbb{H}_\omega := \langle 1, \cosh \omega t, \sinh \omega t \rangle, \quad t \in [0, 1]$$



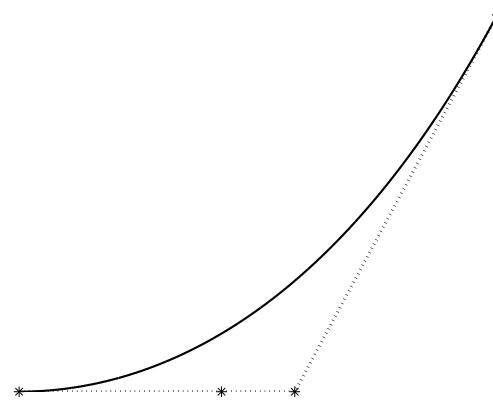
$\omega = 0.1$



$\omega = 1.5$



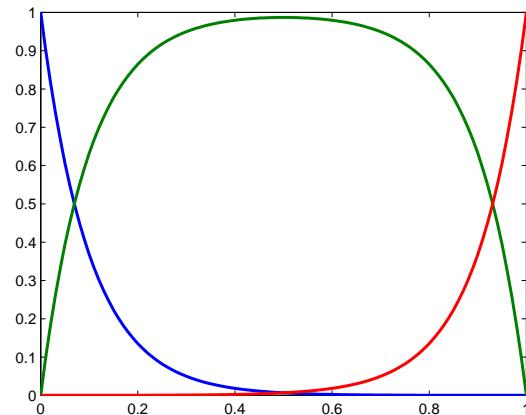
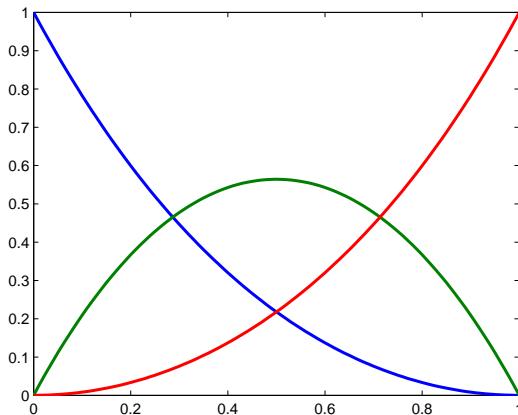
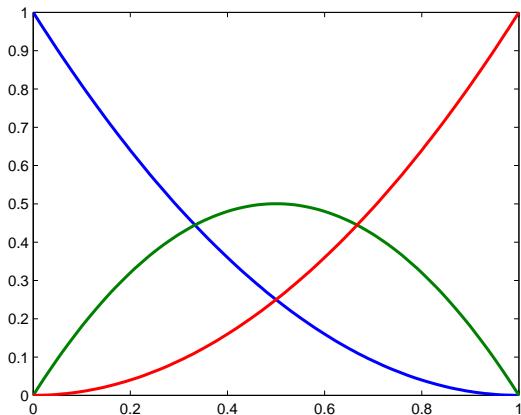
$\omega = 10$



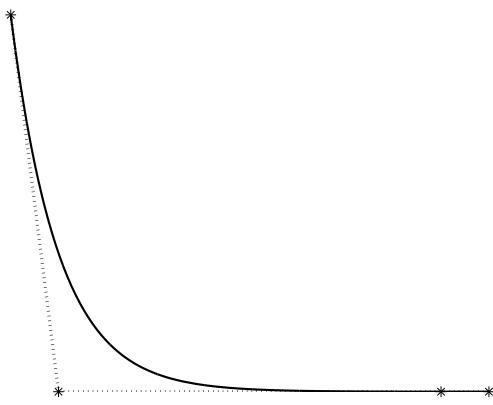
$\omega = 1.5$

Quadratic Generalized Splines over Triangles

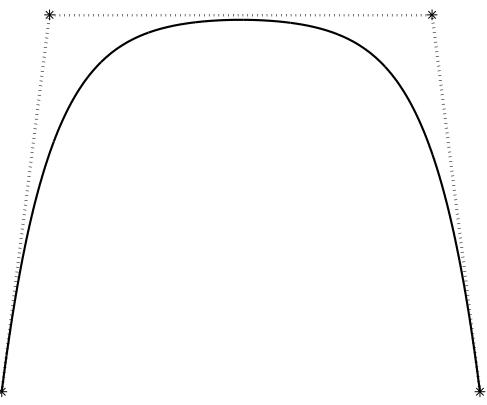
$$\mathbb{H}_\omega := \langle 1, \cosh \omega t, \sinh \omega t \rangle, \quad t \in [0, 1]$$



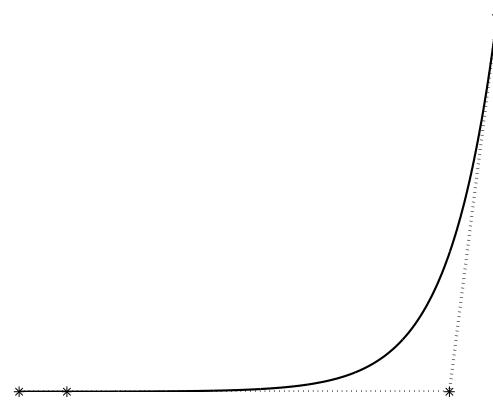
$\omega = 0.1$



$\omega = 1.5$



$\omega = 10$



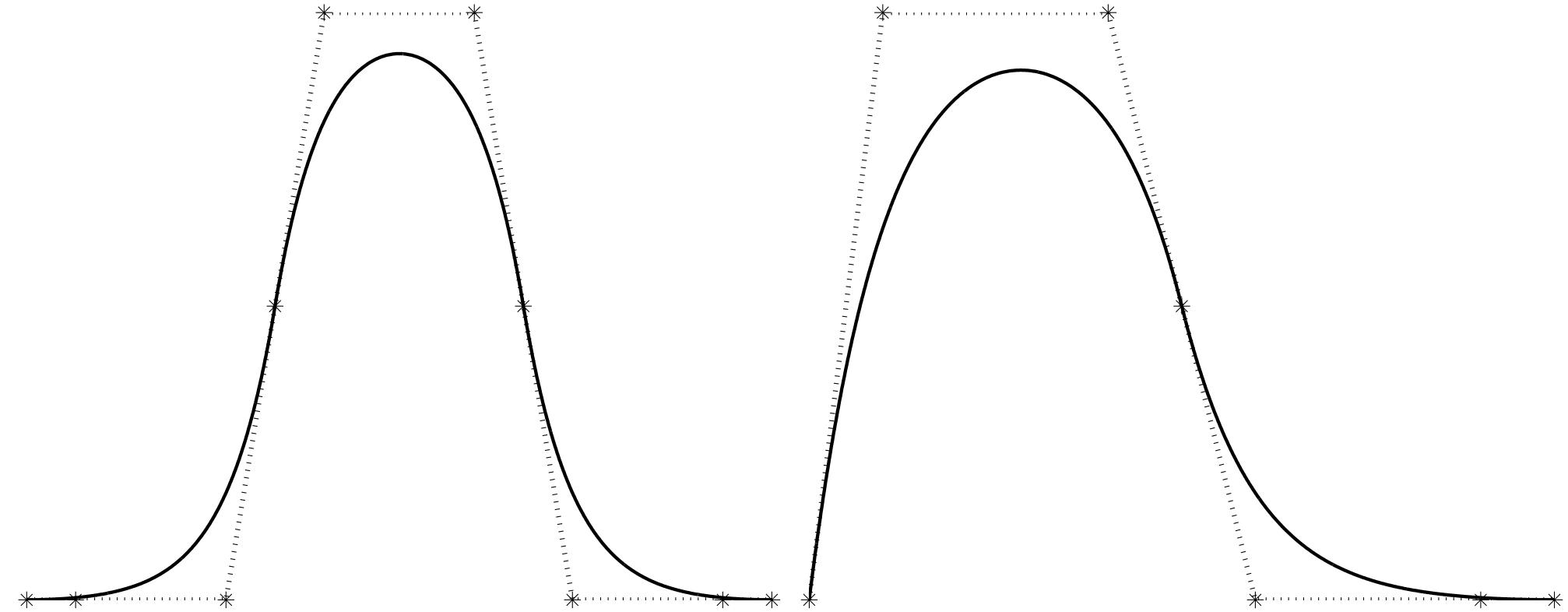
$\omega = 10$

Quadratic Generalized Splines over Triangles

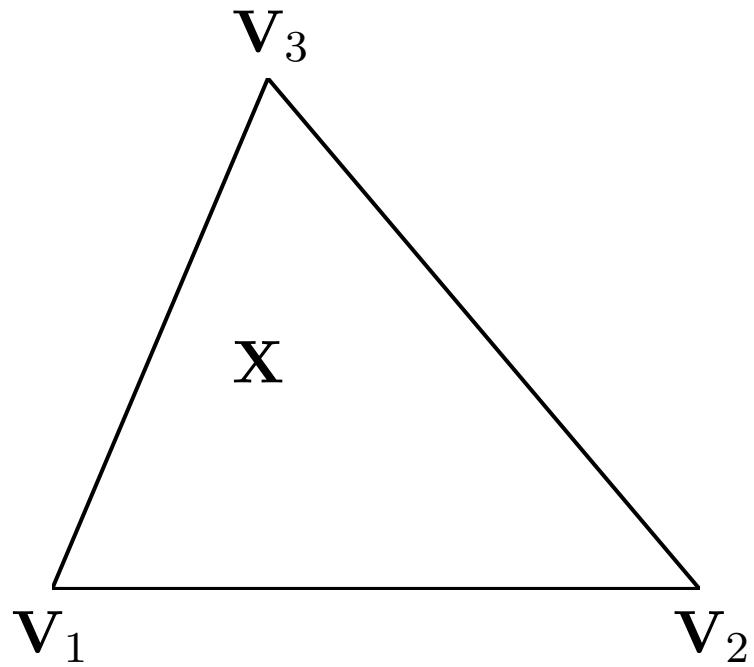
$$\mathbb{H}_\omega := \langle 1, \cosh \omega t, \sinh \omega t \rangle, \quad t \in [0, 1]$$

Quadratic Generalized Splines over Triangles

$$\mathbb{H}_\omega := \langle 1, \cosh \omega t, \sinh \omega t \rangle, \quad t \in [0, 1]$$

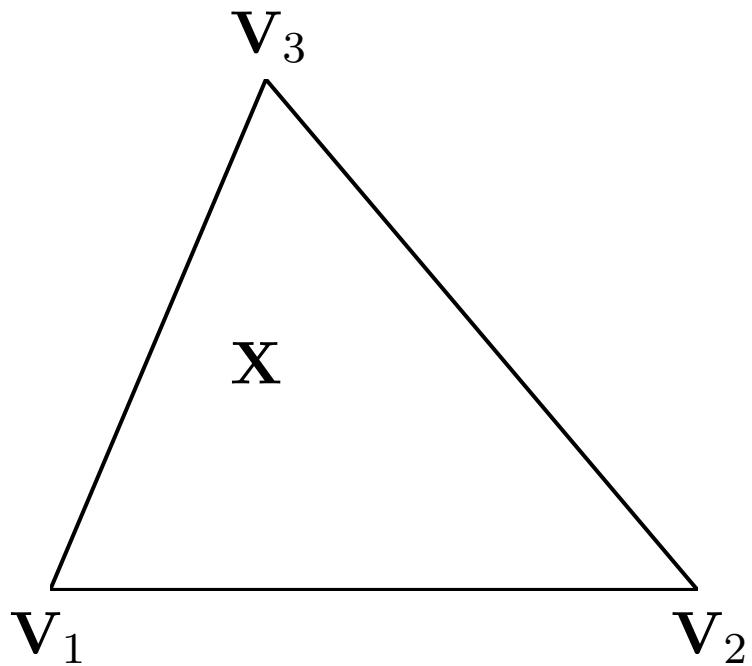


Quadratic Generalized Splines over Triangles



$$\mathbf{X} = \tau_1 \mathbf{V}_1 + \tau_2 \mathbf{V}_2 + \tau_3 \mathbf{V}_3$$

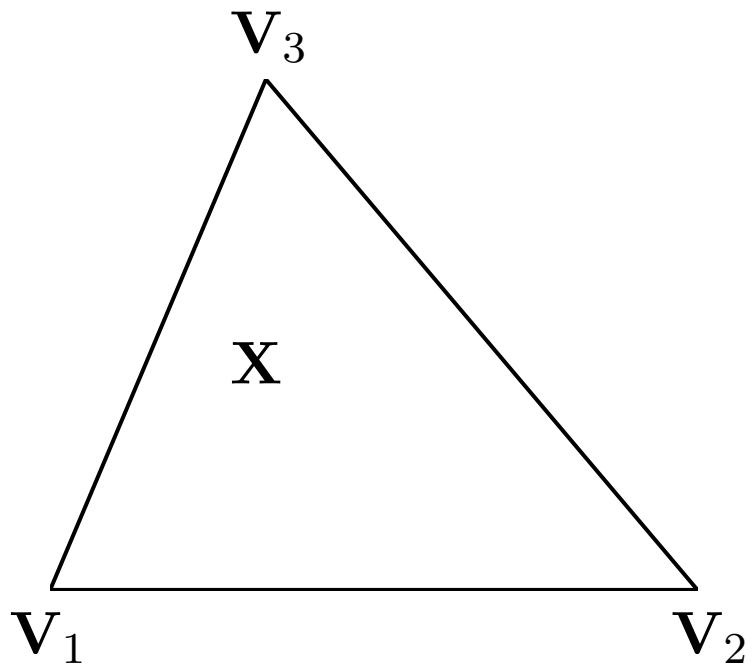
Quadratic Generalized Splines over Triangles



$$\mathbf{X} = \tau_1 \mathbf{V}_1 + \tau_2 \mathbf{V}_2 + \tau_3 \mathbf{V}_3$$

$$<1, \tau_1, \tau_2, \tau_3 = 1 - \tau_1 - \tau_2, \tau_1^2, \tau_2^2, \tau_3^2>,$$

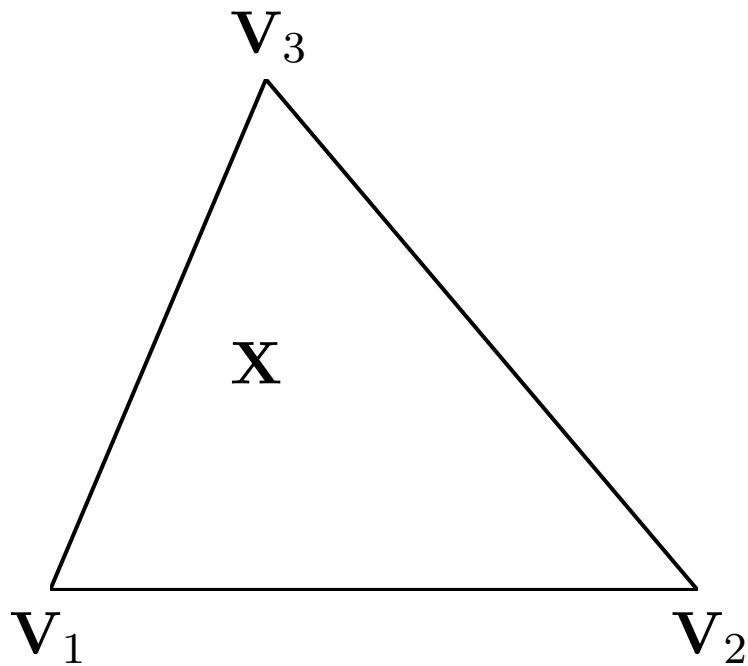
Quadratic Generalized Splines over Triangles



$$\mathbf{X} = \tau_1 \mathbf{V}_1 + \tau_2 \mathbf{V}_2 + \tau_3 \mathbf{V}_3$$

$$\mathbb{H}_\omega := < 1, \cosh \omega \tau_1, \sinh \omega \tau_1, \cosh \omega \tau_2, \sinh \omega \tau_2, \cosh \omega \tau_3, \sinh \omega \tau_3 >,$$

Quadratic Generalized Splines over Triangles

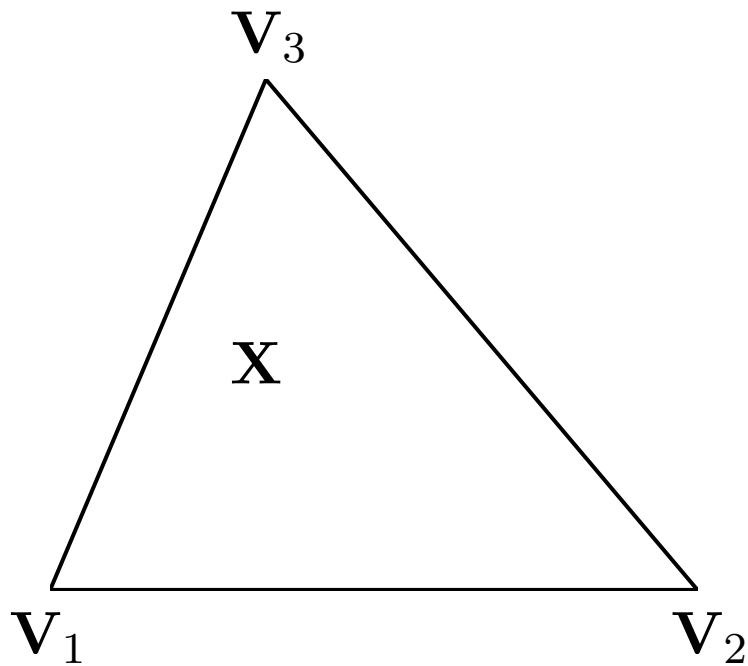


$$\mathbf{X} = \tau_1 \mathbf{V}_1 + \tau_2 \mathbf{V}_2 + \tau_3 \mathbf{V}_3$$

$$\mathbb{H}_\omega := < 1, \cosh \omega \tau_1, \sinh \omega \tau_1, \cosh \omega \tau_2, \sinh \omega \tau_2, \cosh \omega \tau_3, \sinh \omega \tau_3 >,$$

$$\dim(\mathbb{H}_\omega) = 7$$

Quadratic Generalized Splines over Triangles

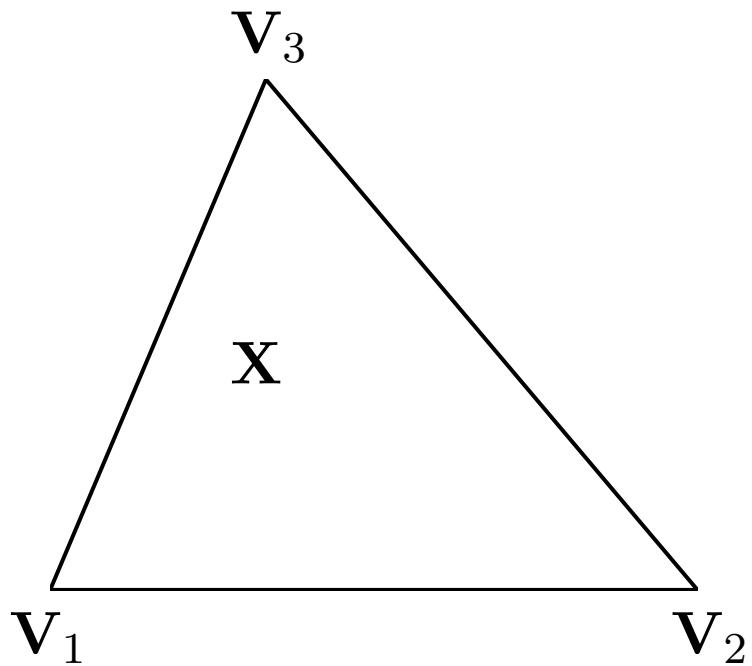


$$\mathbf{X} = \tau_1 \mathbf{V}_1 + \tau_2 \mathbf{V}_2 + \tau_3 \mathbf{V}_3$$

$$\mathbb{H}_\omega := < 1, \cosh \omega \tau_1, \sinh \omega \tau_1, \cosh \omega \tau_2, \sinh \omega \tau_2, \cosh \omega \tau_3, \sinh \omega \tau_3 >,$$

$$\mathbb{H}_{\omega|_{\tau_3=0}} := < 1, \cosh \omega \tau_1, \sinh \omega \tau_1 >,$$

Quadratic Generalized Splines over Triangles



$$\mathbf{X} = \tau_1 \mathbf{V}_1 + \tau_2 \mathbf{V}_2 + \tau_3 \mathbf{V}_3$$

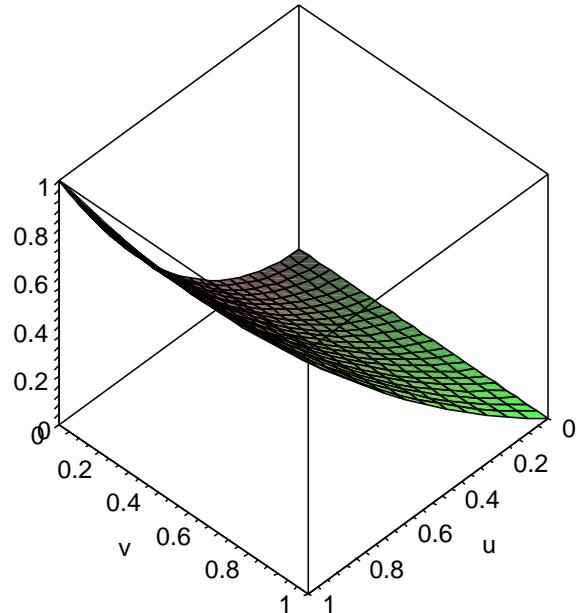
$$B_{200,\omega}(\mathbf{X}) = B_{2,\omega}(\tau_1),$$

$$B_{020,\omega}(\mathbf{X}) = B_{2,\omega}(\tau_2),$$

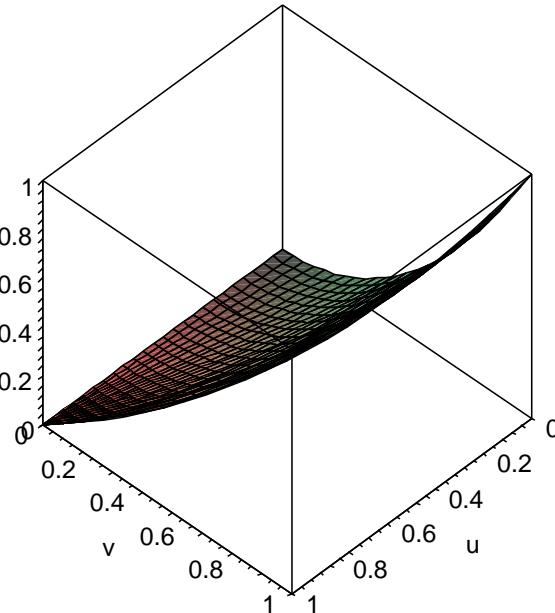
$$B_{002,\omega}(\mathbf{X}) = B_{2,\omega}(\tau_3)$$

Quadratic Generalized Splines over Triangles

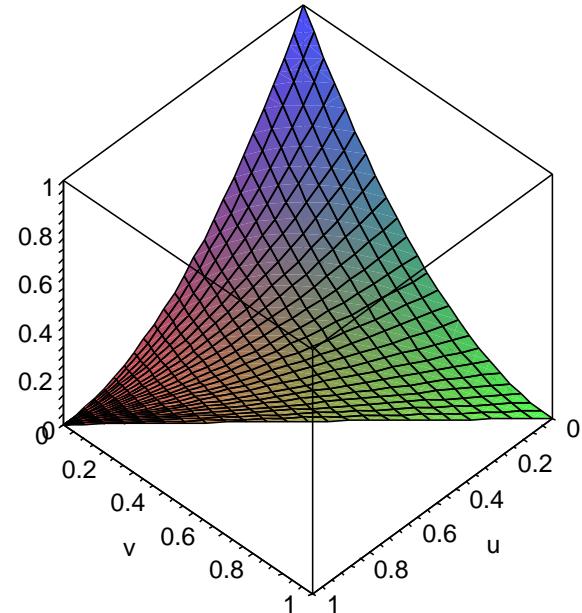
$B_{200,\omega}$



$B_{020,\omega}$



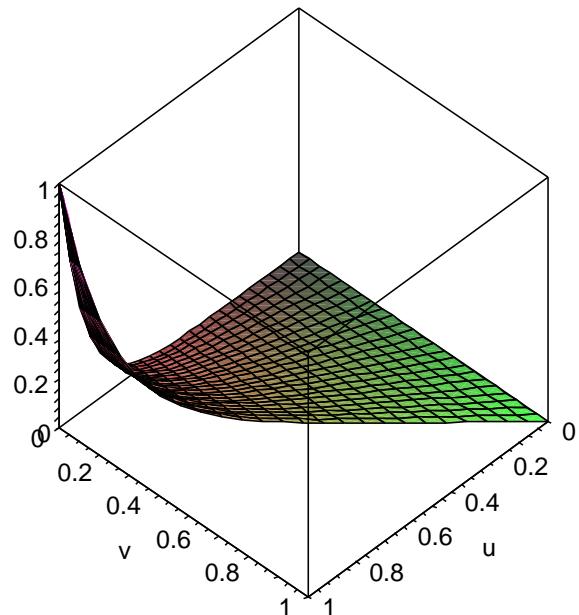
$B_{002,\omega}$



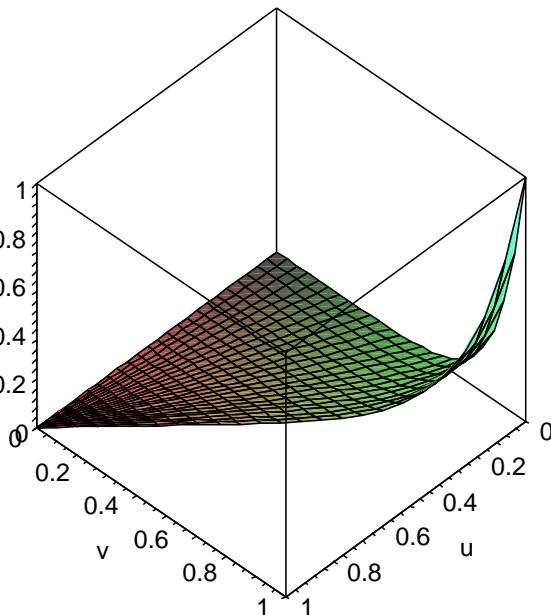
$$\omega = 0.1$$

Quadratic Generalized Splines over Triangles

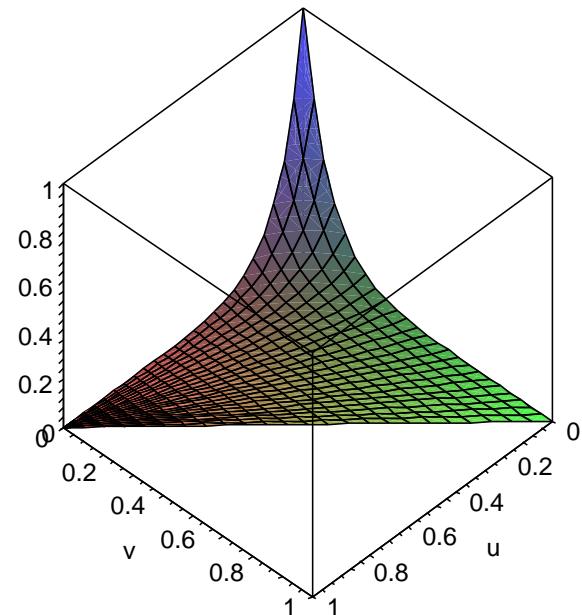
$B_{200,\omega}$



$B_{020,\omega}$

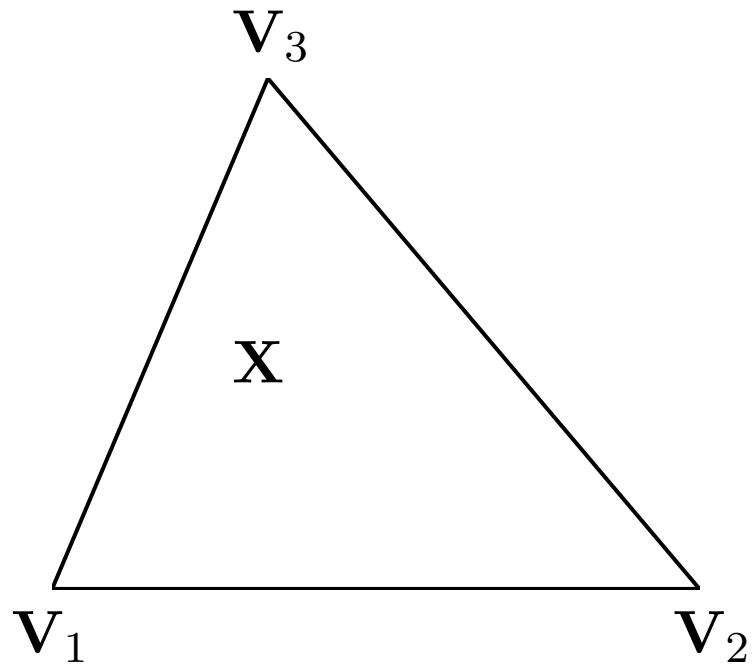


$B_{002,\omega}$



$\omega = 10$

Quadratic Generalized Splines over Triangles



$$B_{110,\omega} \text{ ???}$$

Quadratic Generalized Splines over Triangles

$$B_{110,\omega} \quad ???$$

Quadratic Generalized Splines over Triangles

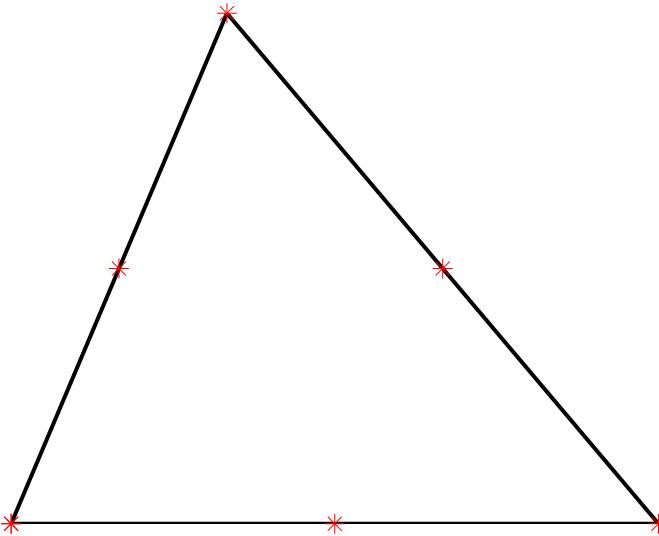
$$B_{110,\omega} \quad ???$$

7 **suitable** interp. conditions to recover edge behavior

Quadratic Generalized Splines over Triangles

$$B_{110,\omega} \quad ???$$

7 **suitable** interp. conditions to recover edge behavior

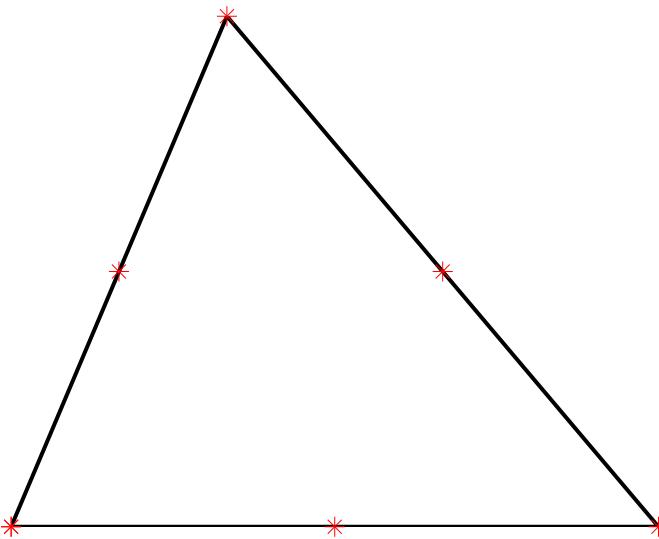


- easy: 6 function values at *

Quadratic Generalized Splines over Triangles

$$B_{110,\omega} \quad ???$$

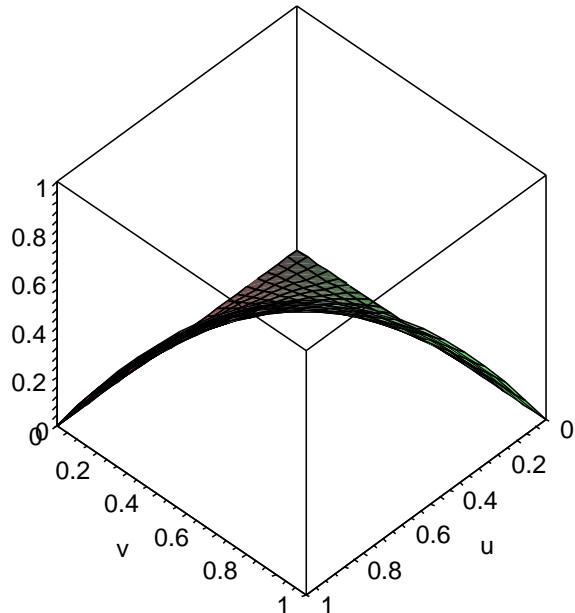
7 **suitable** interp. conditions to recover edge behavior



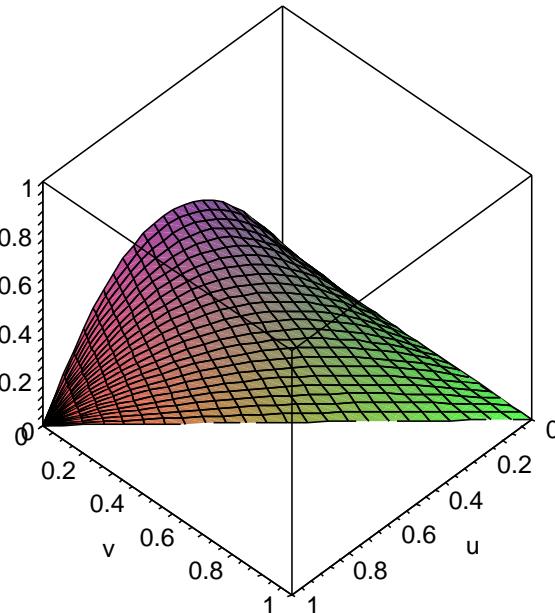
- easy: 6 function values at *
- exotic: second derivative at one vertex to mimic the polynomial case

Quadratic Generalized Splines over Triangles

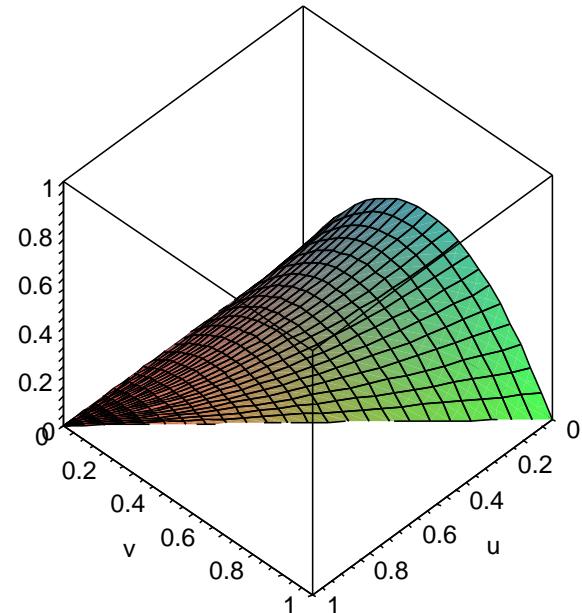
$B_{110,\omega}$



$B_{101,\omega}$



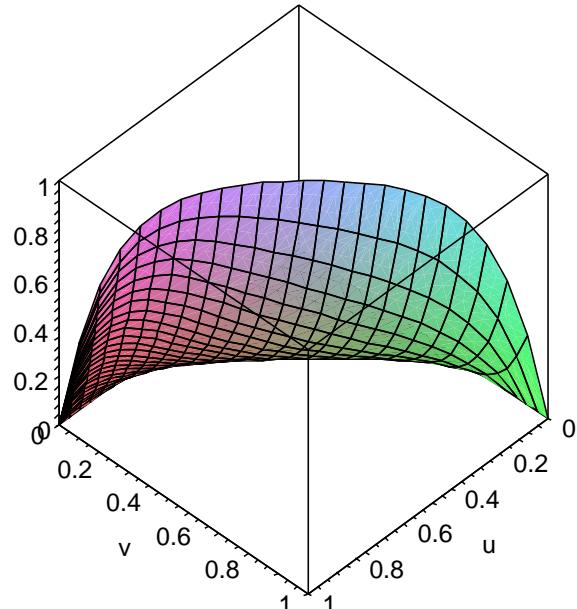
$B_{011,\omega}$



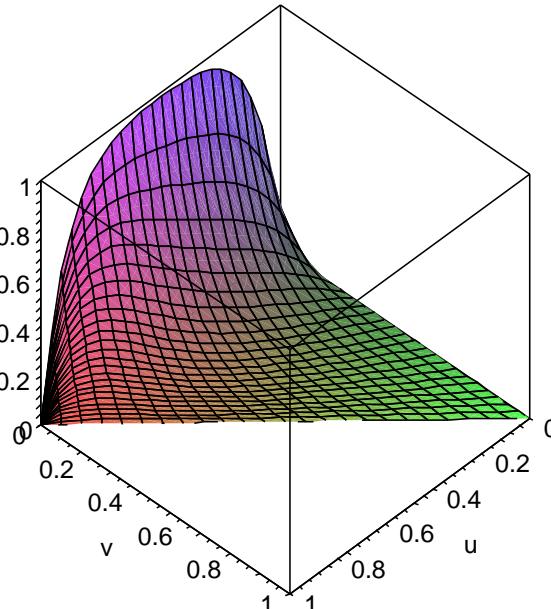
$$\omega = 0.1$$

Quadratic Generalized Splines over Triangles

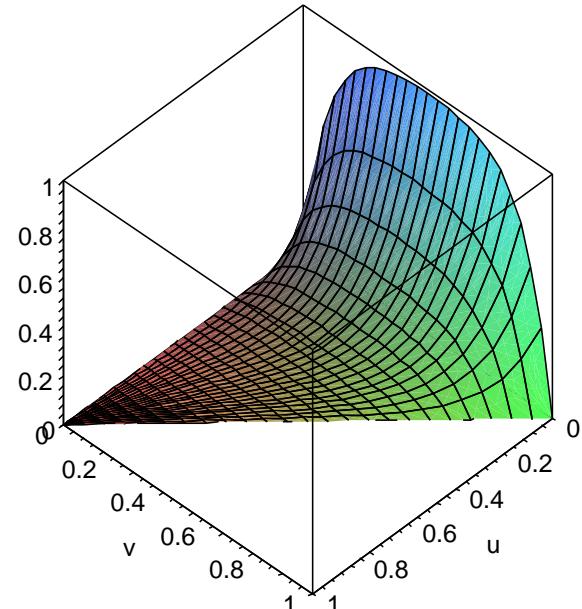
$B_{110,\omega}$



$B_{101,\omega}$



$B_{011,\omega}$



$$\omega = 10$$

Quadratic Generalized Splines over Triangles

one function still **missed**

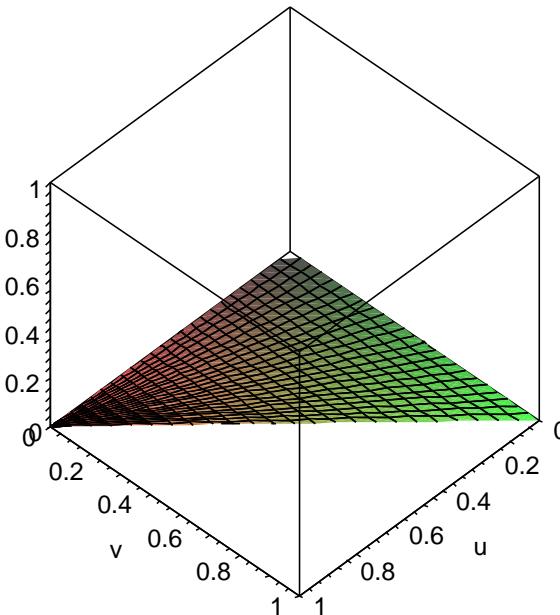
$$B_{111,\omega} \quad ???$$

Quadratic Generalized Splines over Triangles

$$B_{111,\omega} = 1 - \sum_{i+j+k=2} B_{ijk,\omega}$$

Quadratic Generalized Splines over Triangles

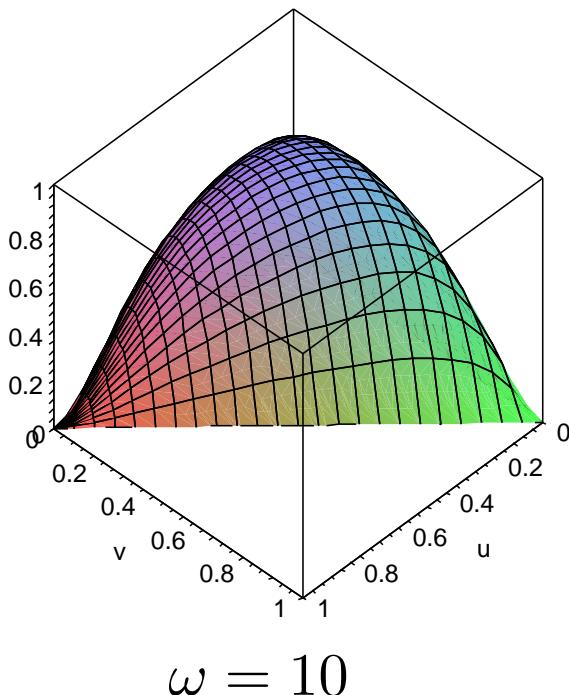
$$B_{111,\omega} = 1 - \sum_{i+j+k=2} B_{ijk,\omega}$$



$$\omega = .1$$

Quadratic Generalized Splines over Triangles

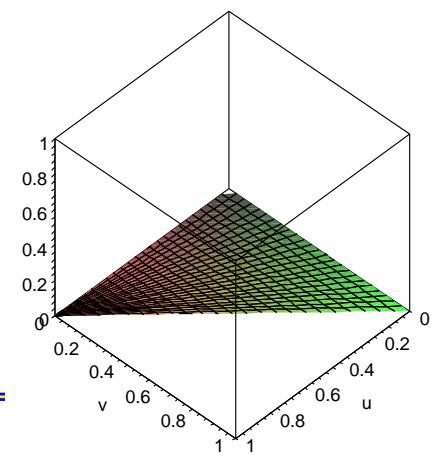
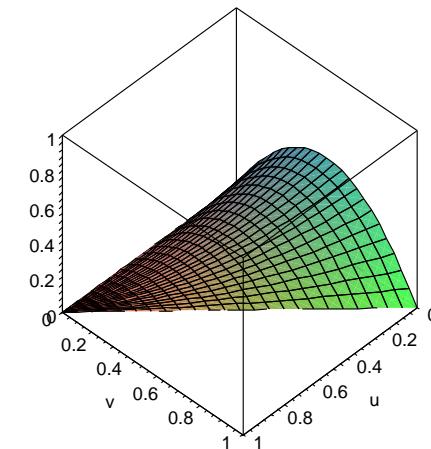
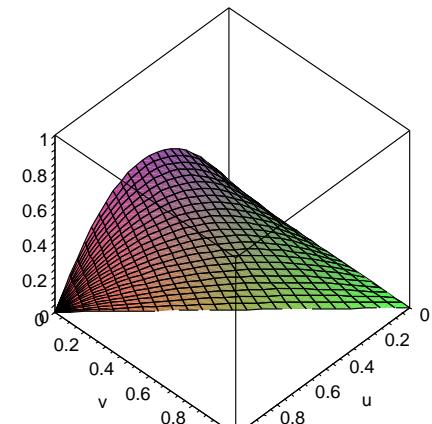
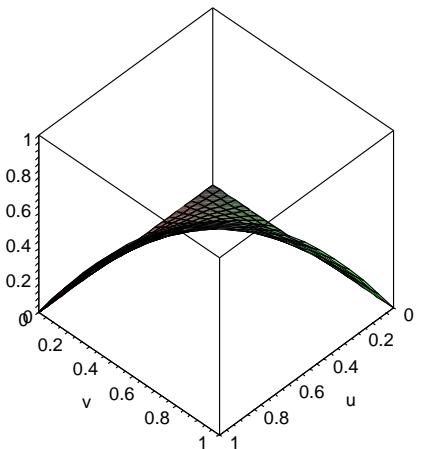
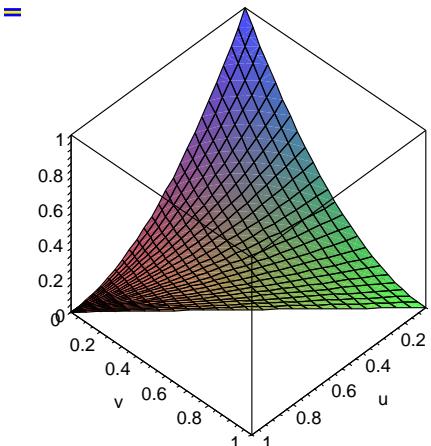
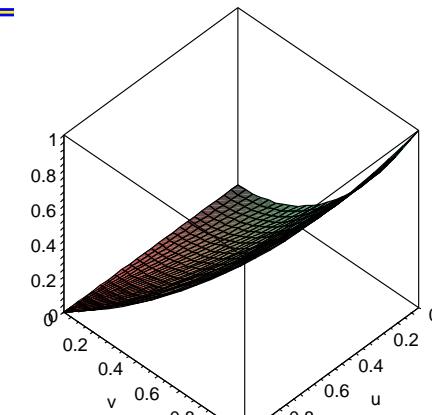
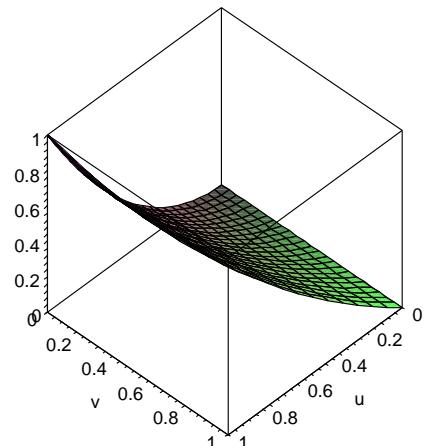
$$B_{111,\omega} = 1 - \sum_{i+j+k=2} B_{ijk,\omega}$$



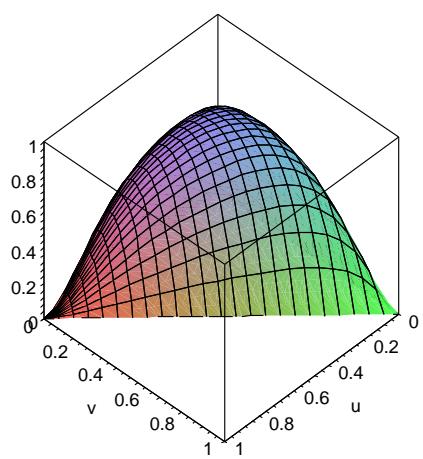
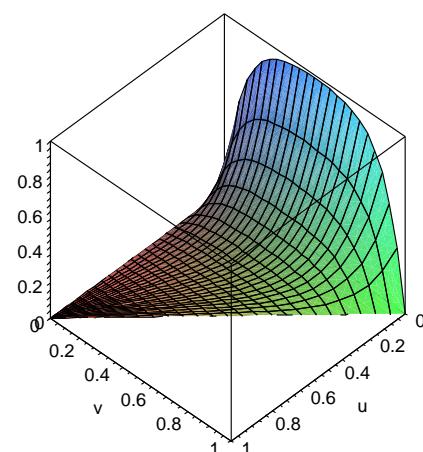
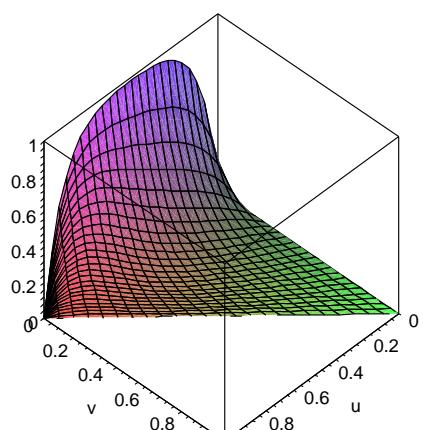
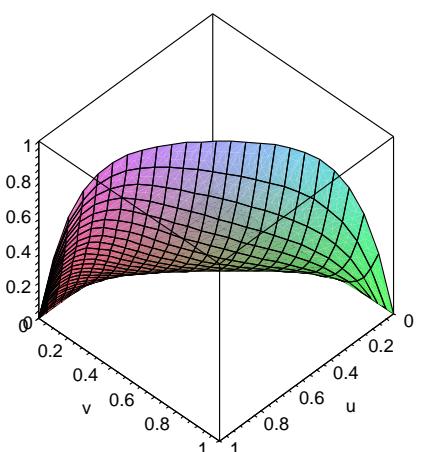
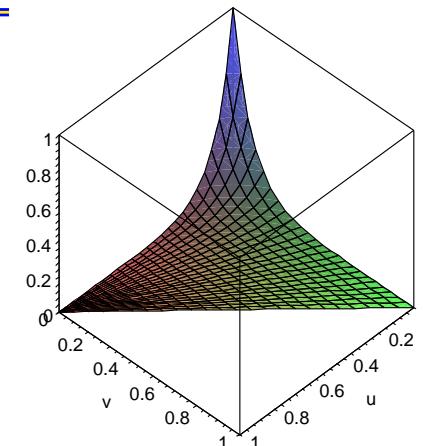
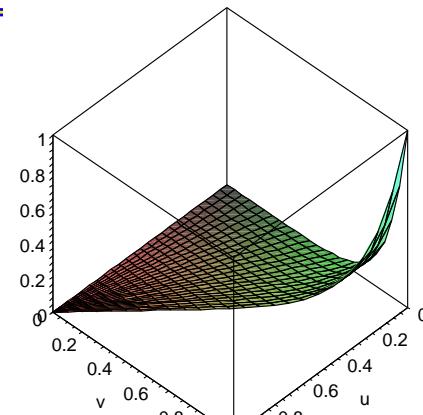
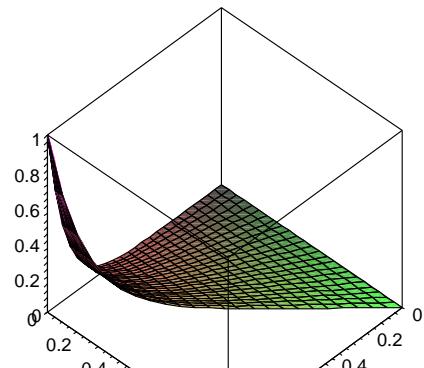
Quadratic Generalized Splines over Triangles

- $B_{ijk,\omega} \geq 0$
- partition of unity

Quadratic Generalized Splines over Triangles



Quadratic Generalized Splines over Triangles

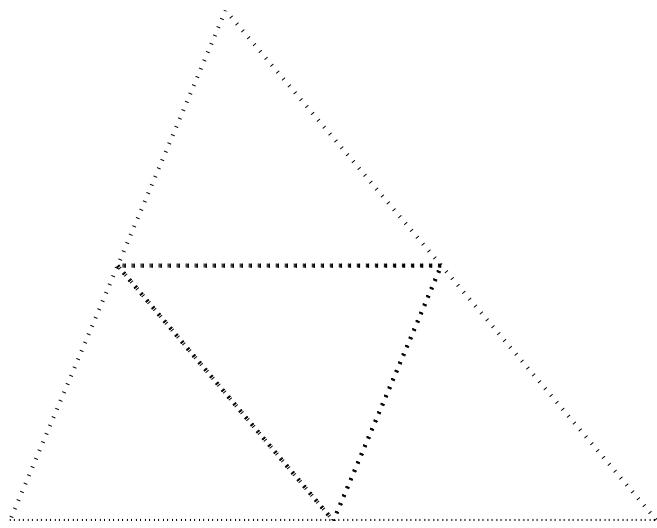


Quadratic G. Splines over Triangles: control net.

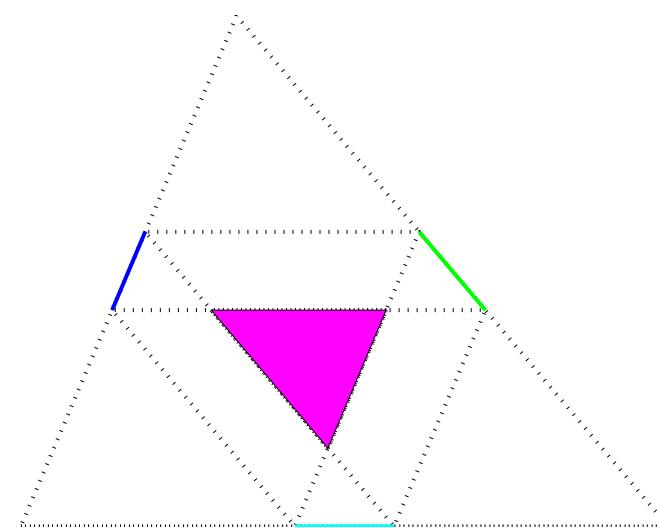
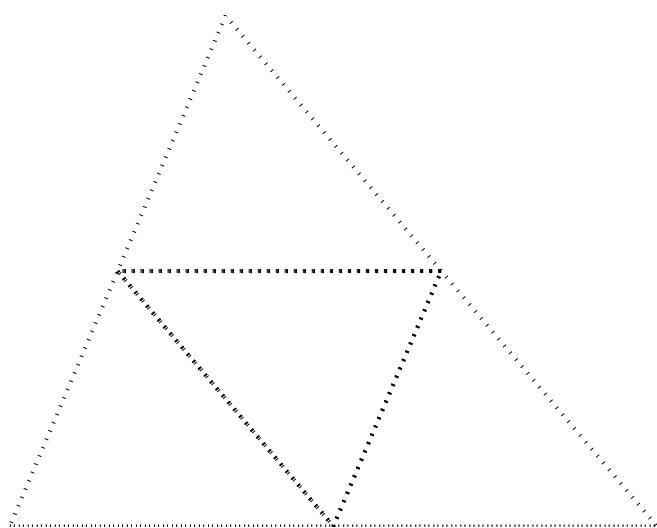
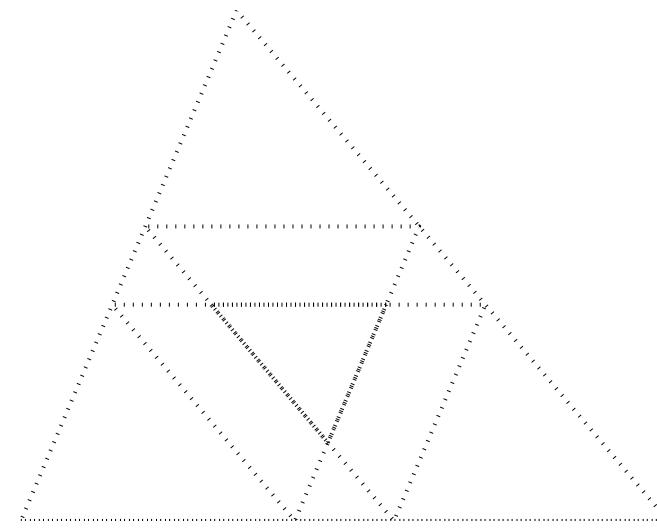
NO Greville abscissae

Quadratic G. Splines over Triangles: control net.

$$\omega = 0.01$$

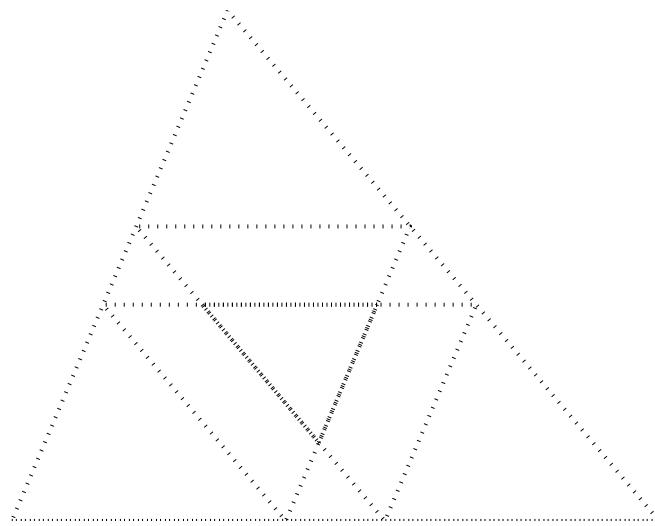


$$\omega = 1.5$$

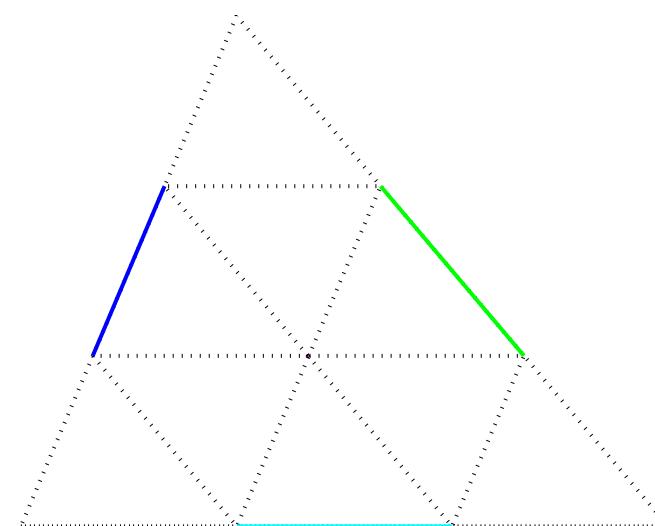
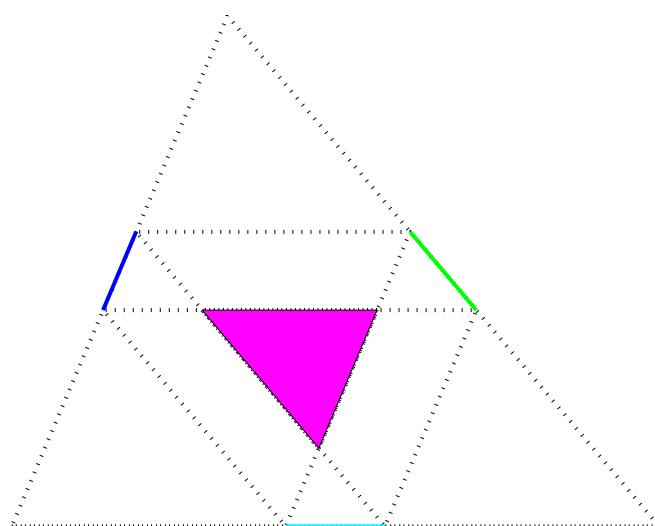
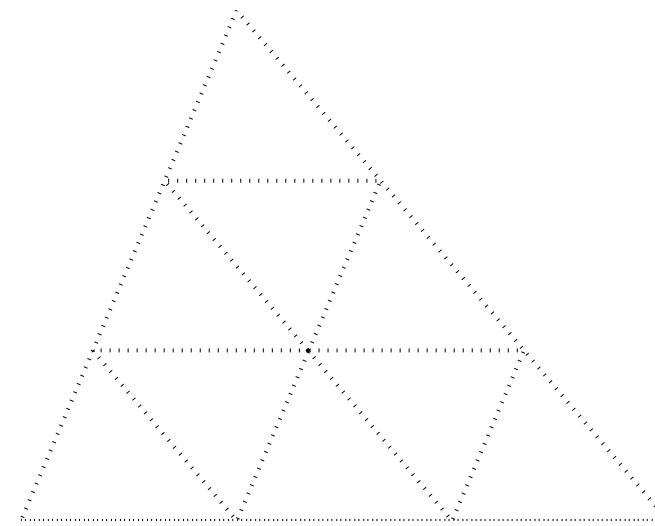


Quadratic G. Splines over Triangles: control net.

$$\omega = 1.5$$

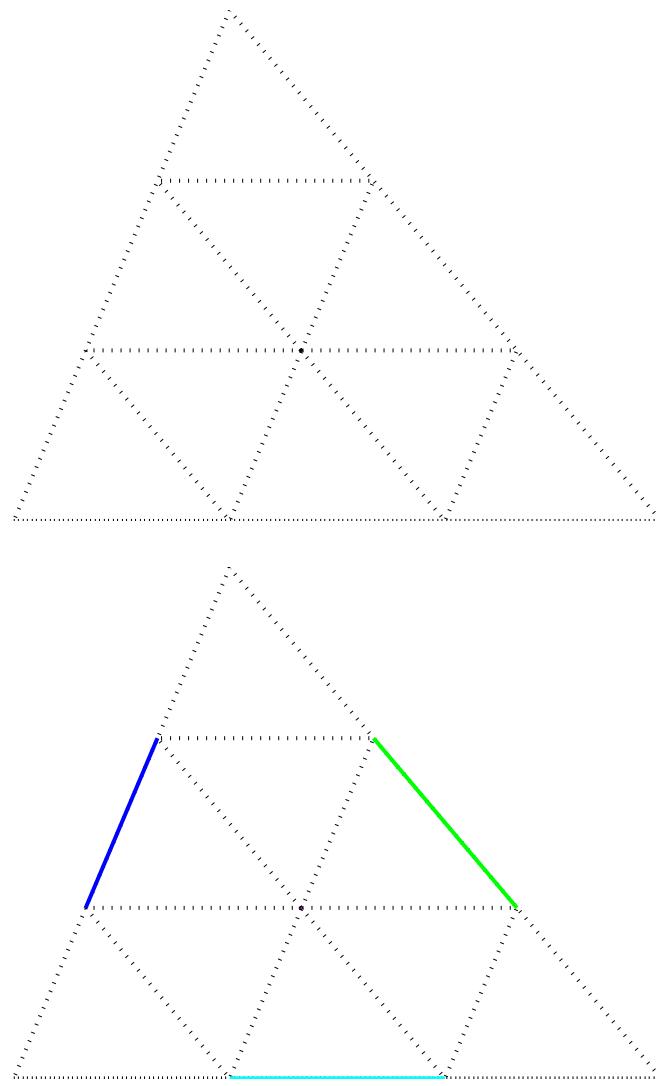


$$\omega = 2.57$$

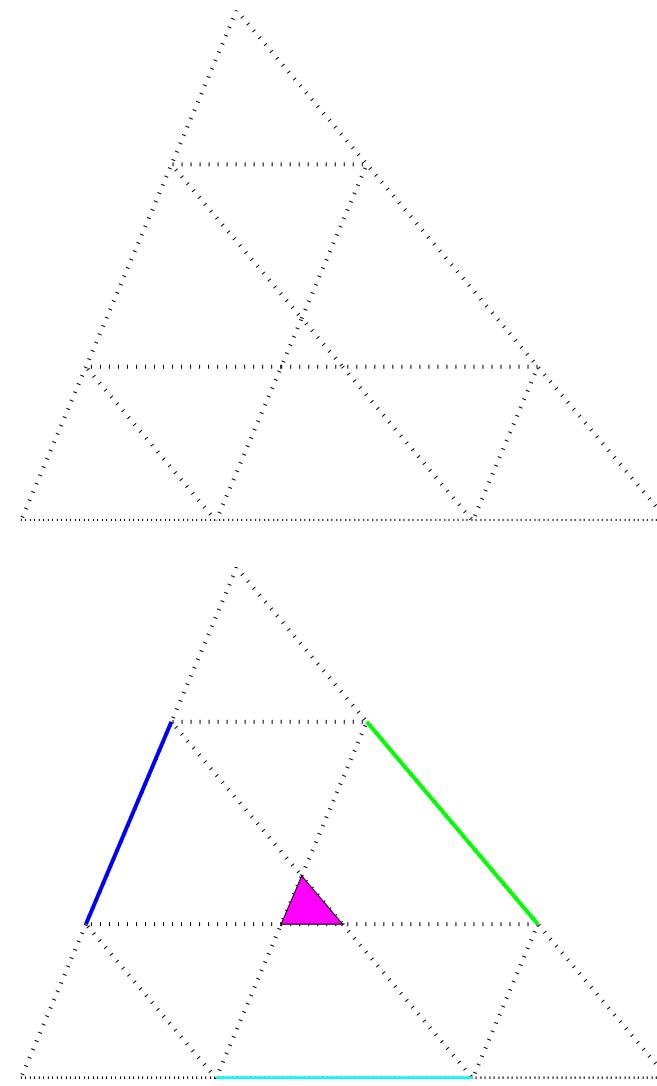


Quadratic G. Splines over Triangles: control net.

$$\omega = 2.57$$

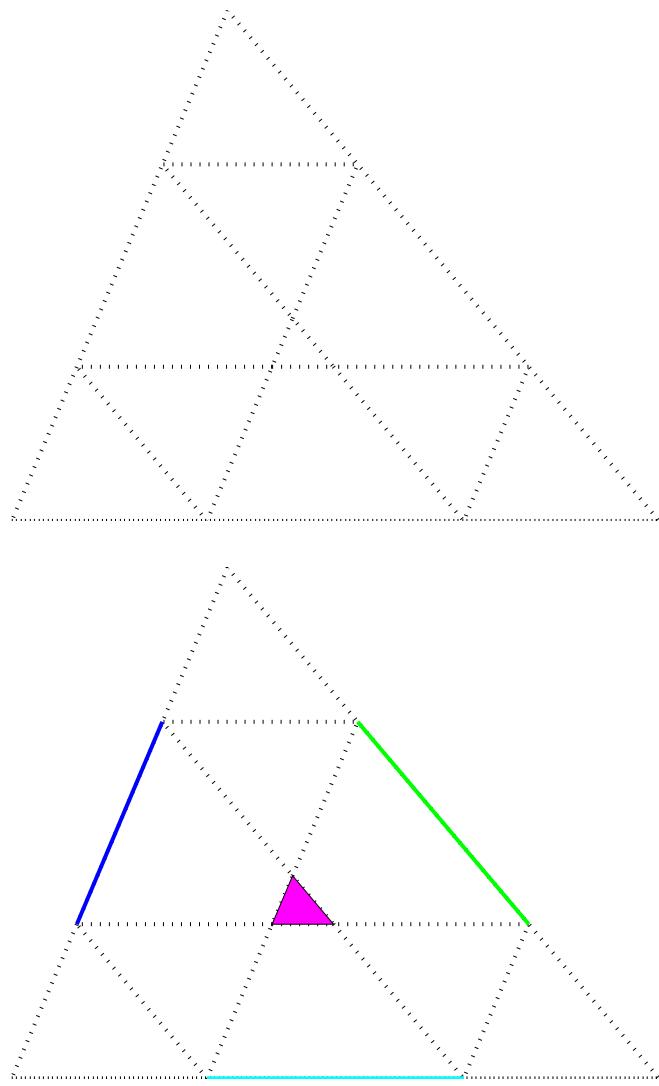


$$\omega = 3$$

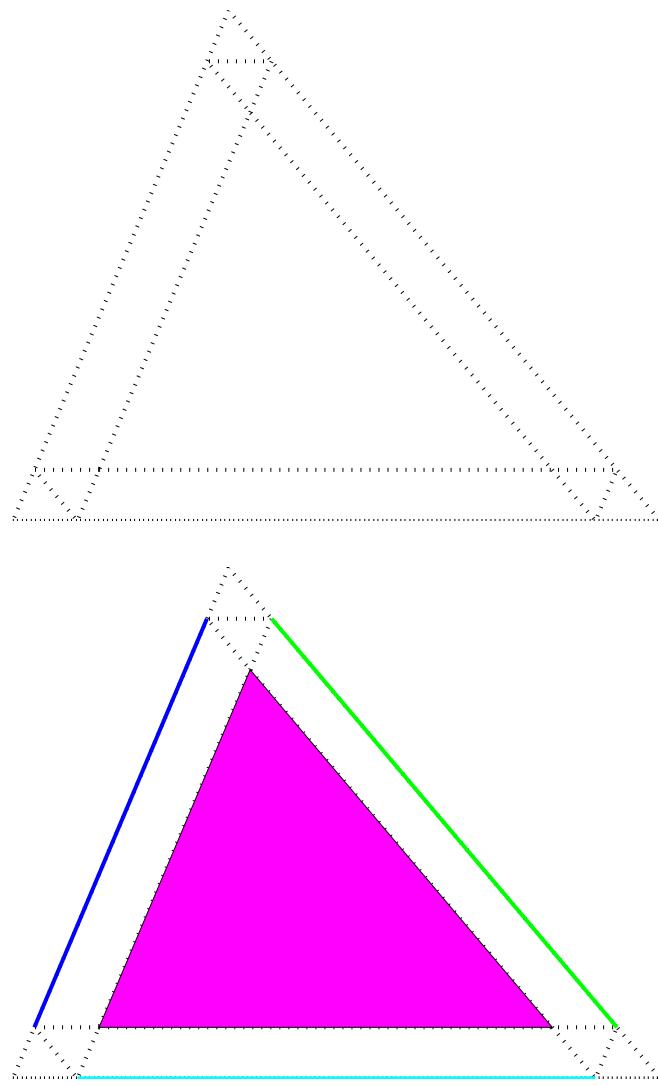


Quadratic G. Splines over Triangles: control net.

$\omega = 3$



$\omega = 10$



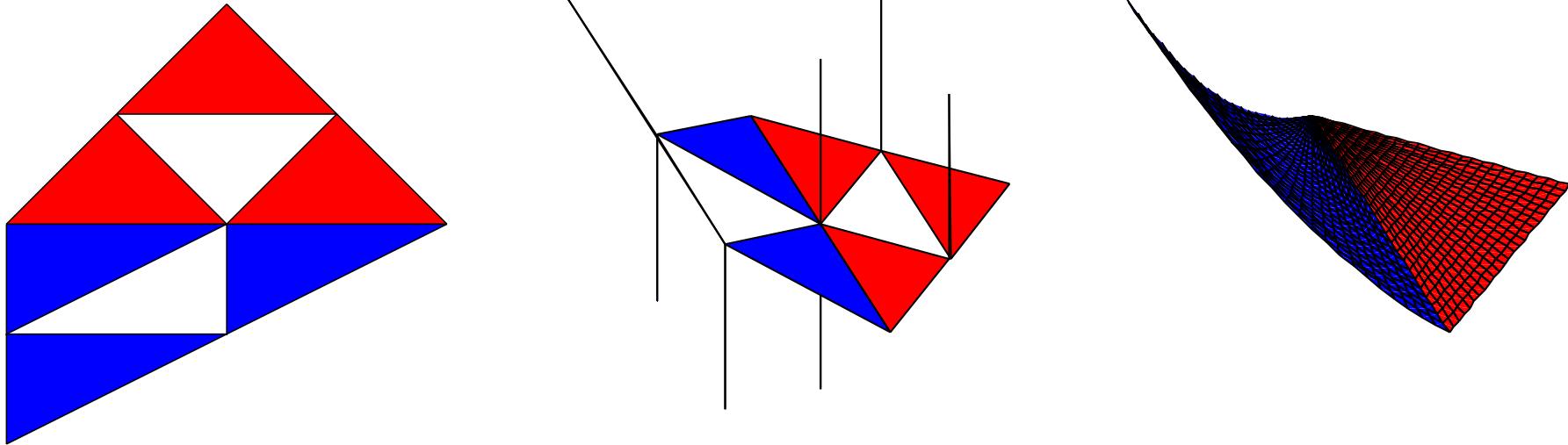
Quadratic G. Splines over Triangles: Smoothness

USUAL geometric interpretation

Quadratic G. Splines over Triangles: Smoothness

USUAL geometric interpretation

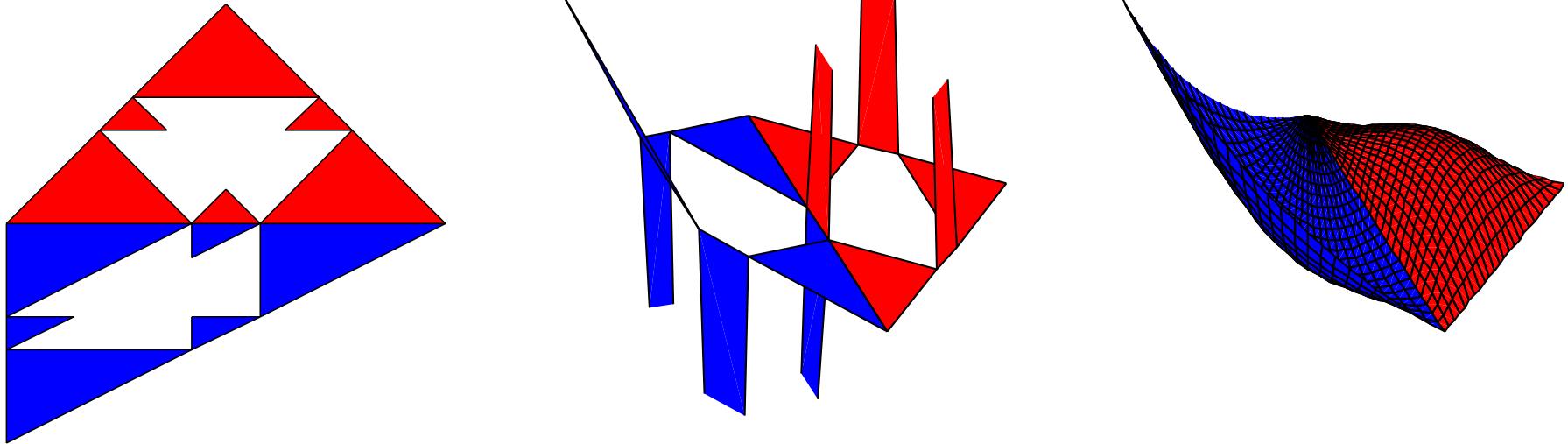
$$\omega = 0.1$$



Quadratic G. Splines over Triangles: Smoothness

USUAL geometric interpretation

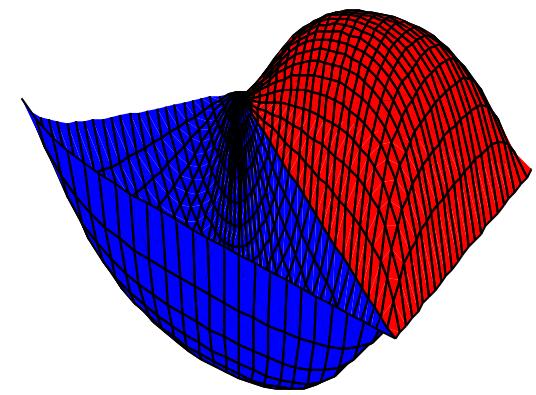
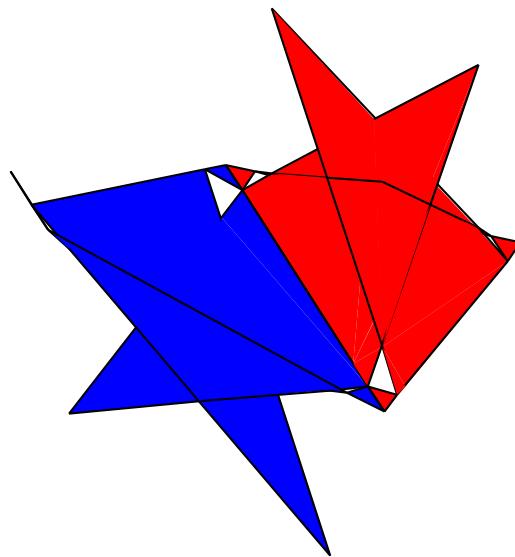
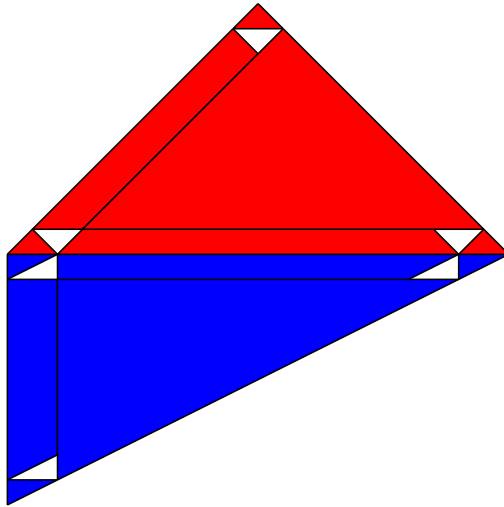
$$\omega = 1.5$$



Quadratic G. Splines over Triangles: Smoothness

USUAL geometric interpretation

$$\omega = 10$$



Conclusions

- Bernstein-like representations
 - optimal from geometrical and computational point of view
 - not confined to (piecewise) polynomial spaces

Conclusions

- Bernstein-like representations
 - optimal from geometrical and computational point of view
 - not confined to (piecewise) polynomial spaces
- Generalized (trigonometric/exponential/...) B-splines possible alternative to the rational model
 - Bernstein-like representations
 - CAGD applications
 - IgA applications

Conclusions

- Bernstein-like representations
 - optimal from geometrical and computational point of view
 - not confined to (piecewise) polynomial spaces
- Generalized (trigonometric/exponential/...) B-splines possible alternative to the rational model
 - Bernstein-like representations
 - CAGD applications
 - IgA applications
- Local refinements B-splines/Generalized B-splines
 - Hierarchical bases
 - T-meshes

Conclusions

- Bernstein-like representations
 - optimal from geometrical and computational point of view
 - not confined to (piecewise) polynomial spaces
 - Generalized (trigonometric/exponential/...) B-splines possible alternative to the rational model
 - Bernstein-like representations
 - CAGD applications
 - IgA applications
 - Local refinements B-splines/Generalized B-splines
 - Hierarchical bases
 - T-meshes
 - B-splines and GB-splines **similar** structure/properties thanks to 1D Bernstein-like representation.
-

Conclusions

- Bernstein-like representations
 - optimal from geometrical and computational point of view
 - not confined to (piecewise) polynomial spaces
 - Generalized (trigonometric/exponential/...) B-splines possible alternative to the rational model
 - Bernstein-like representations
 - CAGD applications
 - IgA applications
 - Local refinements B-splines/Generalized B-splines
 - Hierarchical bases
 - T-meshes
 - B-splines and GB-splines **similar** structure/properties thanks to 1D Bernstein-like representation.
 - Extending Bernstein representations/Generalized B-splines to triangles is **not trivial**
-

Many Thanks!
