#### UNIVERSITY of WISCONSIN-MADISON Computer Sciences Department

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## CONCURRENCY: LOCKS

#### Questions answered in this lecture:

Review threads and mutual exclusion for critical sections

How can locks be used to protect shared data structures such as linked lists?

Can locks be implemented by disabling interrupts?

Can locks be implemented with loads and stores?

Can locks be implemented with atomic hardware instructions?

Are spinlocks a good idea?

## **ANNOUNCEMENTS**

P2: Due this Friday  $\rightarrow$  Extension to Sunday evening...

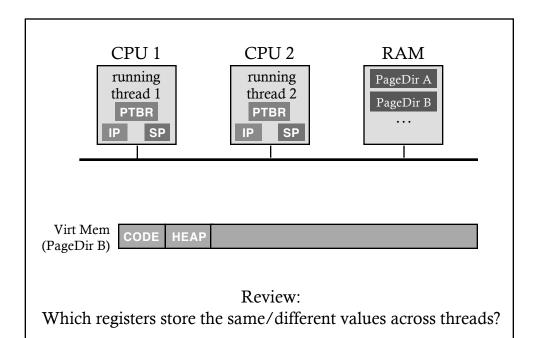
- Test scripts and handin directories available
- Purpose of graph is to demonstrate scheduler is working correctly

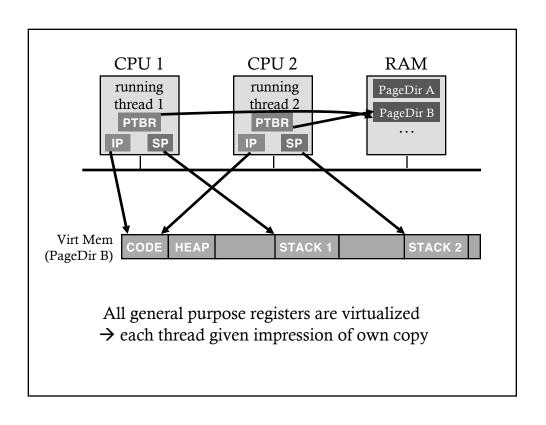
1st Exam: Congratulations for completing!

- Grades posted to Learn@UW: Average around 80%
  - 90% and up: A
  - 85 90: AB
  - 80 85: B
  - 70 80: BC
  - 60 70: C
  - Below 60: D
- · Return individual sheets in discussion section
- Exam with answers will be posted to course web page soon...

Read as we go along!

• Chapter 28





## REVIEW: WHAT IS NEEDED FOR CORRECTNESS?

Balance = balance + 1;

Instructions accessing shared memory must execute as uninterruptable group

• Need group of assembly instructions to be atomic

mov 0x123, %eax add %0x1, %eax mov %eax, 0x123

- critical section

More general: Need **mutual exclusion** for critical sections

if process A is in critical section C, process B can't (okay if other processes do unrelated work)

## OTHER EXAMPLES

Consider multi-threaded applications that do more than increment shared balance

Multi-threaded application with shared linked-list

- All concurrent:
  - Thread A inserting element a
  - Thread B inserting element b
  - Thread C looking up element c

## SHARED LINKED LIST

```
Void List_Insert(list_t *L,
                                    typedef struct __node_t {
                int key) {
                                       int key;
   node t *new =
                                       struct __node_t *next;
      malloc(sizeof(node_t));
                                    } node t;
   assert(new);
   new->key = key;
                                    Typedef struct __list_t {
   new->next = L->head;
   L->head = new;
                                       node_t *head;
                                    } list_t;
int List_Lookup(list_t *L,
                                    Void List_Init(list_t *L)
              int key) {
                                       L->head = NULL;
   node t *tmp = L->head;
   while (tmp) {
      if (tmp->key == key)
         return 1;
                                 What can go wrong?
      tmp = tmp->next;
                        Find schedule that leads to problem?
return 0;
```

## LINKED-LIST RACE

new->key = key

new->next = L->head

new->key = key

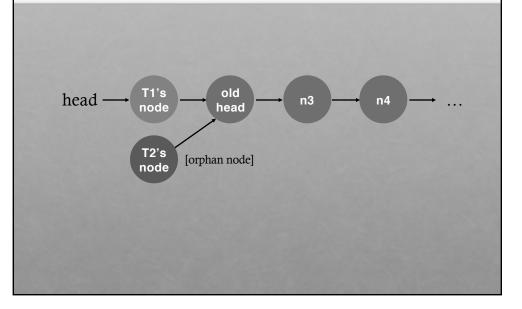
new->next = L->head

L->head = new

Both entries point to old head

Only one entry (which one?) can be the new head.

## RESULTING LINKED LIST



## LOCKING LINKED LISTS

```
Void List_Insert(list_t *L,
                                    typedef struct __node_t {
                int key) {
                                       int key;
   node t *new =
                                       struct __node_t *next;
      malloc(sizeof(node t));
  assert(new);
                                    } node_t;
  new->key = key;
  new->next = L->head;
                                    Typedef struct __list_t {
  L->head = new;
                                       node_t *head;
                                    } list t;
int List_Lookup(list_t *L,
                  int key) {
                                   Void List Init(list t *L) {
   node_t *tmp = L->head;
                                      L->head = NULL;
   while (tmp) {
      if (tmp->key == key)
      return 1;
                                       How to add locks?
      tmp = tmp->next;
return 0;
```

## LOCKING LINKED LISTS

```
typedef struct __node_t {
                           typedef struct node t {
   int key;
                               int key;
   struct __node_t *next;
                               struct __node_t *next;
} node_t;
                             } node t;
Typedef struct __list_t {
                            Typedef struct __list_t {
   node_t *head;
                               node t *head;
} list t;
                               pthread mutex t lock;
                             } list t;
Void List_Init(list_t *L) {
   L->head = NULL;
                            Void List Init(list t *L) {
                               L->head = NULL;
                               pthread mutex init(&L->lock,
How to add locks?
                                  NULL);
pthread mutex t lock; }
One lock per list – Fine if add to OTHER lists concurrently
```

# LOCKING LINKED LISTS : APPROACH #1

```
Void List_Insert(list_t *L,
                                                  int key) {
  Pthread_mutex_lock(&L->lock); node_t *new =
                                     malloc(sizeof(node_t));
Consider everything critical section assert(new);
  Can critical section be smaller?
                                   new->key = key;
                                   new->next = L->head;
Pthread_mutex_unlock(&L->lock); ->head = new;
                                int List_Lookup(list_t *L,
                                                 int key) {
 Pthread_mutex_lock(&L->lock)<del>,</del>
                                  node_t *tmp = L->head;
                                   while (tmp) {
                                     if (tmp->key == key)
                                         return 1;
                                     tmp = tmp->next;
Pthread_mutex_unlock(&L->lock), return 0;
```

## LOCKING LINKED LISTS : APPROACH #2

```
Void List_Insert(list_t *L,
                                                  int key) {
                                   node_t *new =
                                      malloc(sizeof(node_t));
 Critical section small as possible
                                   assert(new);
                                   new->key = key;
  Pthread_mutex_lock(&L->lock); new ->next = L->head;
 Pthread_mutex_unlock(&L->lock), ->head = new;
                                int List_Lookup(list_t *L,
                                                  int key) {
 Pthread_mutex_lock(&L->lock)<del>,</del>
                                  node t *tmp = L->head;
                                   while (tmp) {
                                      if (tmp->key == key)
                                         return 1;
                                      tmp = tmp->next;
Pthread_mutex_unlock(&L->lock), return 0;
```

# LOCKING LINKED LISTS : APPROACH #3

```
Void List_Insert(list_t *L,
                                                 int key) {
                                  node_t *new =
                                     malloc(sizeof(node_t));
     What about Lookup()?
                                  assert(new);
                                  new_{\sim}>key = key;
  Pthread_mutex_lock(&L->lock); new->next = L->head;
Pthread_mutex_unlock(&L->lock), ->head = new;
                               int List_Lookup(list_t *L,
                                                int key) {
 Pthread_mutex_lock(&L->lock);
                                  node t *tmp = L->head;
                                  while (tmp) {
                                    if (tmp->key == key)
If no List_Delete(), locks not needed
                                        return 1;
                                     tmp = tmp->next;
Pthread_mutex_unlock(&L->lock), return 0;
```

Build higher-level synchronization primitives in OS

• Operations that ensure correct ordering of instructions across threads

Motivation: Build them once and get them right

Monitors Locks Semaphores Condition Variables

Loads Stores Test&Set
Disable Interrupts

# LOCK IMPLEMENTATION GOALS

#### Correctness

- · Mutual exclusion
  - Only one thread in critical section at a time
- Progress (deadlock-free)
  - · If several simultaneous requests, must allow one to proceed
- Bounded waiting (starvation-free)
  - Must eventually allow each waiting thread to eventually enter

#### Fairness

Each thread waits in some defined order

#### Performance

CPU is not used unnecessarily (e.g., spinning)

Fast to acquire lock if no contention with other threads

To implement, need atomic operations

Atomic operation: No other instructions can be interleaved

### Examples of atomic operations

- Code between interrupts on uniprocessors
  - Disable timer interrupts, don't do any I/O
- Loads and stores of words
  - · Load r1, B
  - Store r1, A
- · Special hw instructions
  - · Test&Set
  - · Compare&Swap

# IMPLEMENTING LOCKS: W/ INTERRUPTS

### Turn off interrupts for critical sections

Prevent dispatcher from running another thread Code between interrupts executes atomically

```
Void acquire(lockT *1) {
          disableInterrupts();
}

Void release(lockT *1) {
          enableInterrupts();
}
```

#### Disadvantages??

Only works on uniprocessors

Process can keep control of CPU for arbitrary length

Cannot perform other necessary work

To implement, need atomic operations

Atomic operation: No other instructions can be interleaved

### Examples of atomic operations

- Code between interrupts on uniprocessors
  - Disable timer interrupts, don't do any I/O
- Loads and stores of words
  - · Load r1, B
  - Store r1, A
- · Special hw instructions
  - · Test&Set
  - · Compare&Swap

# IMPLEMENTING LOCKS: W/ LOAD+STORE

```
Code uses a single shared lock variable
Boolean lock = false; // shared variable
void acquire(Boolean *lock) {
    while (*lock) /* wait */;
    *lock = true;
}
void release(Boolean *lock) {
    *lock = false;
}
```

Why doesn't this work? Example schedule that fails with 2 threads?

# RACE CONDITION WITH LOAD AND STORE

## **DEMO**

Main-thread-3.c

Critical section not protected with faulty lock implementation

## PETERSON'S ALGORITHM

```
Assume only two threads (tid = 0, 1) and use just loads and stores

int turn = 0; // shared across threads - PER LOCK

Boolean lock[2] = {false, false}; // shared - PER LOCK

Void acquire() {

lock[tid] = true;

turn = 1-tid;

While (lock[1-tid] && turn == 1-tid) /* wait */;

}

Void release() {

lock[tid] = false;
}
```

# DIFFERENT CASES: ALL WORK

### Only thread 0 wants lock initially

# DIFFERENT CASES: ALL WORK

Thread 0 and thread 1 both try to acquire lock at same time

## DIFFERENT CASES: ALL WORK

```
Thread 0 and thread 1 both want lock
```

```
Lock[0] = true;

Lock[1] = true;

turn = 0;

turn = 1;

while (lock[1] && turn ==1)

while (lock[0] && turn == 0);
;
```

## DIFFERENT CASES: All Work

Thread 0 and thread 1 both want lock;

# PETERSON'S ALGORITHM: INTUITION

Mutual exclusion: Enter critical section if and only if Other thread does not want to enter OR Other thread wants to enter, but your turn (only 1 turn)

Progress: Both threads cannot wait forever at while() loop Completes if other process does not want to enter

Other process (matching turn) will eventually finish

Bounded waiting (not shown in examples)

Each process waits at most one critical section (because turn given to other)

Problem: doesn't work on modern hardware (doesn't provide sequential consistency due to caching)

To implement, need atomic operations

Atomic operation: No other instructions can be interleaved

### Examples of atomic operations

- Code between interrupts on uniprocessors
  - Disable timer interrupts, don't do any I/O
- · Loads and stores of words
  - · Load r1, B
  - Store r1, A
- · Special hw instructions
  - · Test&Set
  - · Compare&Swap

### XCHG: ATOMIC EXCHANGE, OR TEST-AND-SET

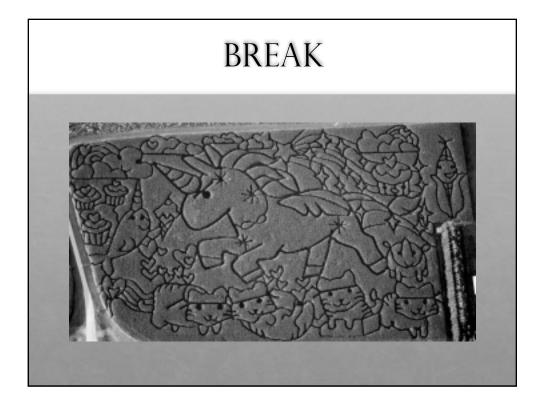
# LOCK IMPLEMENTATION WITH XCHG

## XCHG IMPLEMENTATION

## **DEMO: XCHG**

Critical section protected with our lock implementation!!

Main-thread-5.c



# OTHER ATOMIC HW INSTRUCTIONS

# OTHER ATOMIC HW INSTRUCTIONS

# LOCK IMPLEMENTATION GOALS

#### Correctness

- · Mutual exclusion
  - Only one thread in critical section at a time
- Progress (deadlock-free)
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- Bounded (starvation-free)
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#### **Fairness**

Each thread waits in some determined ordered

#### Performance

CPU is not used unnecessarily

### BASIC SPINLOCKS ARE **UNFAIR** unlock lock unlock unlock unlock lock lock lock spin → < spin → В В В В 20 40 60 80 100 120 140 160 Scheduler is independent of locks/unlocks

## FAIRNESS: TICKET LOCKS

```
Idea: reserve each thread's turn to use a lock.
Each thread spins until their turn.
Use new atomic primitive, fetch-and-add:
int FetchAndAdd(int *ptr) {
   int old = *ptr;
   *ptr = old + 1;
   return old;
}
Acquire: Grab ticket;
Wait while not thread's ticket != turn
Release: Advance to next turn
```

### TICKET LOCK EXAMPLE A lock(): Turn Ticket\_ B lock(): 0 C lock(): 1 A unlock(): 2 B runs A lock(): 3 B unlock(): 4 C runs 5 C unlock(): 6 A runs 7 A unlock(): C lock():

## TICKET LOCK EXAMPLE

```
A lock(): gets ticket 0, spins until turn = 0 \rightarrow runs
B lock(): gets ticket 1, spins until turn=1
                                                       0
C lock(): gets ticket 2, spins until turn=2
                                                       1
A unlock(): turn++(turn = 1)
                                                       2
B runs
A lock(): gets ticket 3, spins until turn=3
                                                       3
B unlock(): turn++(turn = 2)
                                                       4
C runs
                                                       5
C \text{ unlock(): } turn++ (turn = 3)
                                                       6
A runs
A unlock(): turn++(turn = 4)
C lock(): gets ticket 4, runs
```

# TICKET LOCK IMPLEMENTATION

```
typedef struct __lock_t {
    int ticket;
    int turn;
    while (lock->turn != myturn); // spin
}

void lock_init(lock_t *lock) {
    lock->ticket = 0;
    lock->turn = 0;
}
```

## TICKET LOCK

```
typedef struct __lock_t {

int ticket;

int turn;

void acquire(lock_t *lock) {

int myturn = FAA(&lock->ticket);

while(lock->turn!= myturn)

yield(); // spin

}

void lock_init(lock_t *lock) {

lock->ticket = 0;

lock->turn = 0;

}

FAA() used in textbook → conservative

Try this modification in Homework simulations
```

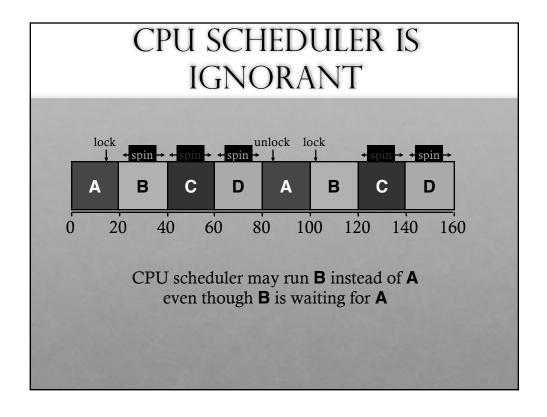
## SPINLOCK PERFORMANCE

#### Fast when...

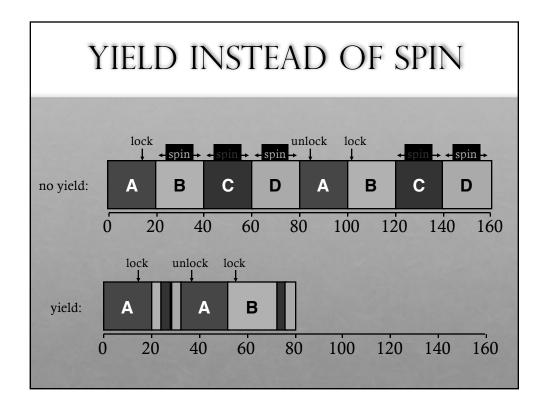
- many CPUs
- locks held a short time
- advantage: avoid context switch

#### Slow when...

- one CPU
- locks held a long time
- disadvantage: spinning is wasteful



### TICKET LOCK WITH YIELD() void acquire(lock\_t \*lock) { typedef struct \_\_lock\_t { int myturn = FAA(&lock->ticket); int ticket; while(lock->turn != myturn) int turn; yield(); void lock\_init(lock\_t \*lock) { void release (lock\_t \*lock) { lock->ticket = 0;FAA(&lock->turn); lock->turn = 0;Remember: yield() voluntarily relinquishes CPU for remainder of timeslice, but process remains READY



## SPINLOCK PERFORMANCE

Waste...

Without yield: O(threads \* time\_slice)

With yield: O(threads \* context\_switch)

So even with yield, spinning is slow with high thread contention

Next improvement: Block and put thread on waiting queue instead of spinning