

Why use a modeling language: a view from optimization

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Mathematical tools for evolutionary systems biology
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Why use optimization

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Tradeoff accuracy and simple structure

Many models from statistics: e.g. regression:

$$\min_x \|Ax - y\|^2$$

Additional structure: Compressed sensing: sparse signal to account for y

$$\min_x \|Ax - y\|_2^2 \text{ s.t. } \|x\|_0 \leq c$$

Regularized regression:

$$\min_x \|Ax - y\|_2^2 + \alpha \|x\|_1$$

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Machine learning: SVM for classification

$$\min_{w, \xi, \gamma} \sum_i \xi_i + \frac{\alpha}{2} \|w\|^2 \text{ s.t. } D(Aw - \gamma \mathbf{1}) \geq 1 - \xi$$

General model:

$$\min_{x \in X} E(x) + \alpha S(x)$$

X are constraints, E measures "error" and S penalizes bad structure

Image denoising (Wright)

Rudin-Osher-Fatemi (ROF) model (ℓ_2 -TV). Given a domain $\Omega \subset \mathbb{R}^2$ and an observed image $f : \Omega \rightarrow \mathbb{R}$, seek a restored image $u : \Omega \rightarrow \mathbb{R}$ that preserves edges while removing noise. The regularized image u can typically be stored more economically. Seek to “minimize” both

- $\|u - f\|_2$ and
- the total-variation (TV) norm $\int_{\Omega} |\nabla u| dx$

Use constrained formulations, or a weighting of the two objectives:

$$\min_u P(u) := \|u - f\|_2^2 + \alpha \int_{\Omega} |\nabla u| dx$$

The minimizing u tends to have regions in which u is constant ($\nabla u = 0$). More “cartoon-like” when α is large.

Original, noisy, denoised (tol = 10^{-2} , 10^{-4})



Parameter estimation

Example (Crombach):

$$\min_p J(x(p) - \bar{x}) \text{ s.t. } \frac{\partial x}{\partial t} = D\Delta x + f(x, p), p \in P$$

Key points:

- Constraints on parameter choice $p \in P$
- Can solve using PDE constrained optimization. Huge literature in applied mathematics. Key computational idea for optimization is that of the adjoint operator

Parameter estimation

Example (Crombach):

$$\min_p J(x(p) - \bar{x}) + \alpha \|p\|_1 \text{ s.t. } \frac{\partial x}{\partial t} = D\Delta x + f(x, p), p \in P$$

Key points:

- Constraints on parameter choice $p \in P$
- Can solve using PDE constrained optimization. Huge literature in applied mathematics. Key computational idea for optimization is that of the adjoint operator
- Can discretize/optimize, and then add L_1 penalization to get “sparse” (parameter) solution via nonlinear optimization
- Extension to nonsmooth f - DVI, and MPEC, allows for switching

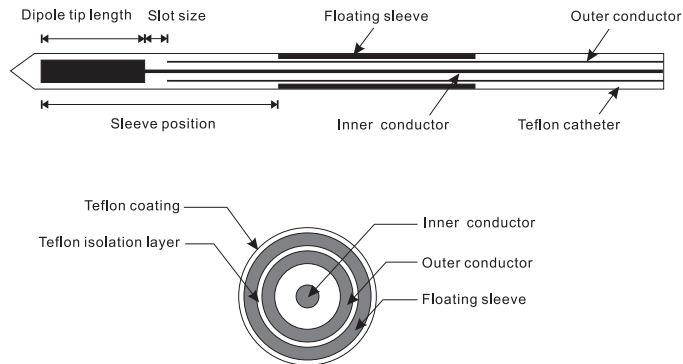
Simulation Optimization

- Computer simulations are used as substitutes to understand or predict the behavior of a complex system when exposed to a variety of realistic, stochastic input scenarios
- Widely used in epidemiology, engineering design, manufacturing, supply chain management, medical treatment and many other fields (calibration, parameter tuning, inverse optimization)

$$\min_{p \in P} f(p) = \mathbb{E}[F(p, \xi)],$$

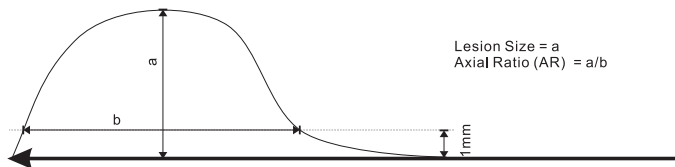
- The sample response function $F(p, \xi)$
 - ▶ typically does not have a closed form, thus cannot provide gradient or Hessian information
 - ▶ is normally computationally expensive
 - ▶ is affected by uncertain factors in simulation

Design a coaxial antenna for hepatic tumor ablation



Simulation of the electromagnetic radiation profile

Finite element models (COMSOL MultiPhysics) are used to generate the electromagnetic (EM) radiation fields in liver given a particular design

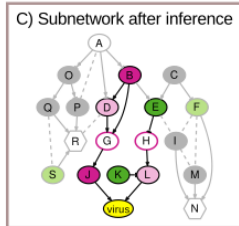
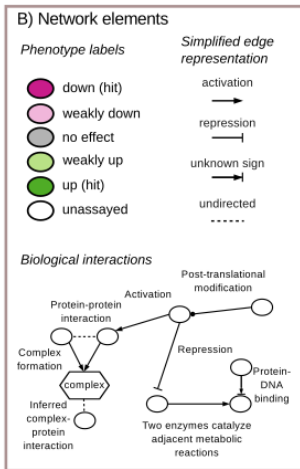
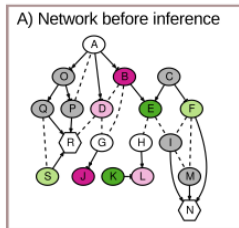


Metric	Measure of	Goal
Lesion radius	Size of lesion in radial direction	Maximize
Axial ratio	Proximity of lesion shape to a sphere	Fit to 0.5
S_{11}	Tail reflection of antenna	Minimize

Computational results

- Use of derivative free (surrogate) methods
- Our approach only valid for small scale (≤ 30) design variables (but the simulation may be very complex - black box)
- Evaluations may be noisy:
 - ▶ Application: Dielectric tissue properties varied within $\pm 10\%$ of average properties to simulate the individual variation.
 - ▶ Bayesian VNSP (variable number sample path) algorithm yields an optimal design that is a 27.3% improvement over the original design and is more robust in terms of lesion shape and efficiency.

Network inference



- Given prior knowledge, select paths, color nodes and sign arcs to explain as many hits as possible
- e.g. sign of a relevant edge is consistent with the phenotypes of nodes it connects

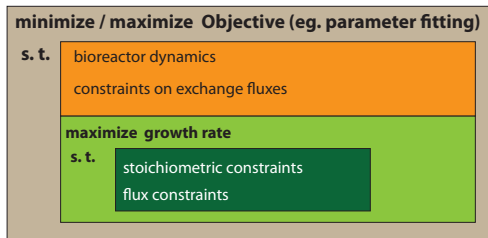
- Can model (propositional) logic constraints in a mixed integer program
- Key issue is to determine objective

Biological Hierarchical Models

I: Opt knock (a bilevel program)

- max bioengineering objective (through gene knockouts)
- s.t. max cellular objective (over fluxes)
- s.t. fixed substrate uptake
- network stoichiometry
- blocked reactions (from outer problem)
- number of knockouts \leq limit

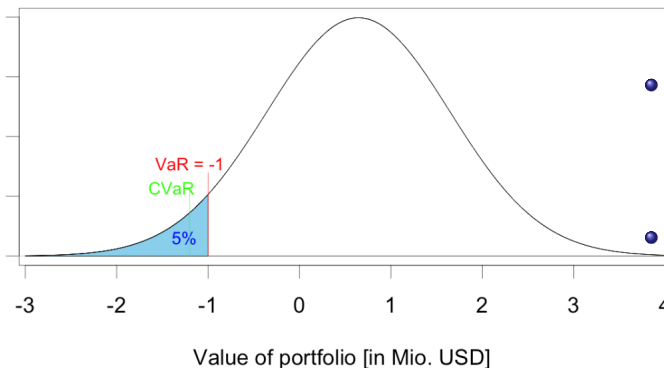
II: Bio-reactor dynamics:



Different mathematical programming techniques are used to transform the problem to a nonlinear program. The differential equations are transformed into nonlinear constraints using collocation methods.

Optimization of risk measures

- Determine portfolio weights w_j for each of a collection of assets
- Asset returns v are random, but jointly distributed
- Portfolio return $r(w, v)$



- Value at Risk (VaR) can be viewed as a chance constraint (hard):
- CVaR gives rise to a convex optimization problem (easy)

- Chance constraints (implemented using mixed integer programming):

$$\min_x c^T x \text{ s.t. } Pr(Ax \leq b) \geq \pi$$

Example: Portfolio Model

- Maximize the mean of the lower tail (mean tail loss):

$$\begin{aligned} \max \quad & \underline{CVaR}_\alpha(r) \\ \text{s.t.} \quad & r = \sum_j v_j * w_j \\ & \sum_j w_j = 1, w \geq 0 \end{aligned}$$

- Jointly distributed random variables v , realized at stage 2
- Variables: portfolio weights w in stage 1, returns r in stage 2
- Coherent risk measures \mathbb{E} and \underline{CVaR} (or convex combination)

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- Variables: portfolio weights w in stage 1, returns r in stage 2
- Coherent risk measures \mathbb{E} and \underline{CVaR} (or convex combination)
- Optimization modeling systems have new tools for sampling, risk measures and solution of stochastic programs (ref: M. Loewe)
- Classical: mean-variance model (Markowitz)

$$\begin{aligned} \min \quad & w^T \Sigma w - q \sum_j v_j * w_j \\ & \sum_j w_j = 1, w \geq 0 \end{aligned}$$

Conclusions

- Optimization helps understand what drives a system
- Constraints are a crucial design/modeling tool
- **Uncertainty is present everywhere**: we need to **hedge/control/ameliorate** it
- Collections of, and interactions between, models are critical
- Modern computational optimization tools can be very fast, deal with large amounts of data and variables, address non-convex and discrete issues, interact with dynamics