### Optimization and Equilibrium in Energy Economics

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Equilibrium and Energy Economics

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### Power generation, transmission and distribution



• Determine generators' output to reliably meet the load

- $\sum$  Gen MW  $\geq \sum$  Load MW, at all times.
- Power flows cannot exceed lines' transfer capacity.

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# Single market, single good: equilibrium



Walras: 
$$0 \leq s(\pi) - d(\pi) \perp \pi \geq 0$$

Market design and rules to foster competitive behavior/efficiency

 Spatial extension: Locational Marginal Prices (LMP) at nodes (buses) in the network



- Supply arises often from a generator offer curve (lumpy)
- Technologies and physics affect production and distribution

# A Simple Network Model

Load segments *s* represent electrical load at various instances

- $d_n^s$  Demand at node *n* in load segment *s* (MWe)
- X<sup>s</sup><sub>i</sub> Generation by unit *i* (MWe)
- F<sup>s</sup><sub>L</sub> Net electricity transmission on link L (MWe)
- Y<sup>s</sup><sub>n</sub> Net supply at node n
   (MWe)
- $\pi_n^s$  Wholesale price (\$ per MWhe)



Nodes *n*, load segments *s*, generators *i*,  $\Psi$  is node-generator map

$$\max_{X,F,d,Y} \sum_{s} \left( W(d^{s}(\lambda^{s})) - \sum_{i} c_{i}(X_{i}^{s}) \right)$$
  
s.t. 
$$\Psi(X^{s}) - d^{s}(\lambda^{s}) = Y^{s}$$
$$0 \le X_{i}^{s} \le \overline{X}_{i}, \quad \overline{G}_{i} \ge \sum_{s} X_{i}^{s}$$
$$Y \in \mathcal{X}$$

where the network is described using:

$$\mathcal{X} = \left\{ Y : \exists F, F^{s} = \mathcal{H}Y^{s}, -\overline{F}^{s} \leq F^{s} \leq \overline{F}^{s}, \sum_{n} Y_{n}^{s} \geq 0, \forall s \right\}$$

- Key issue: decompose. Introduce multiplier π<sup>s</sup> on supply demand constraint (and use λ<sup>s</sup> := π<sup>s</sup>)
- $\bullet$  How different approximations of  ${\mathcal X}$  affect the overall solution

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### Decomposition by prices $\pi$

$$\max_{X,d,Y} \sum_{s} \left( W(d^{s}(\pi^{s})) - \sum_{i} c_{i}(X_{i}^{s}) + \pi^{s}(\Psi(X^{s}) - d^{s}(\pi^{s}) - Y^{s}) \right)$$
  
s.t.  $0 \leq X_{i}^{s} \leq \overline{X}_{i}, \quad \overline{G}_{i} \geq \sum_{s} X_{i}^{s}$   
 $\sum_{i} Y_{i}^{s} \geq 0, -\overline{F}^{s} \leq \mathcal{H}Y^{s} \leq \overline{F}^{s}$ 

Problem then decouples into multiple optimizations

$$\max_{d} \sum_{s} \left( W(d^{s}(\pi^{s})) - \pi^{s} d^{s}(\pi^{s}) \right) + \max_{X} \sum_{s} \left( \pi^{s} \Psi(X^{s}) - \sum_{i} c_{i}(X_{i}^{s}) \right) \\ + \max_{Y} \sum_{s} -\pi^{s} Y^{s}$$
  
s.t.  $0 \leq X_{i}^{s} \leq \overline{X}_{i}, \quad \overline{G}_{i} \geq \sum_{s} X_{i}^{s}, \sum_{i} Y_{i}^{s} \geq 0, -\overline{F}^{s} \leq \mathcal{H}Y^{s} \leq \overline{F}^{s}$ 

#### Case $\mathcal{H}$ : Loop flow model

$$\max_{d} \sum_{s} (W(d^{s}(\pi^{s})) - \pi^{s}d^{s}(\pi^{s})) + \max_{X} \sum_{s} \left( \pi^{s}\Psi(X^{s}) - \sum_{i}c_{i}(X_{i}^{s}) \right)$$
  
s.t.  $0 \le X_{i}^{s} \le \overline{X}_{i}, \quad \overline{G}_{i} \ge \sum_{s} X_{i}^{s} + \max_{Y} \sum_{s} -\pi^{s}Y^{s}$   
s.t.  $\sum_{i} Y_{i}^{s} \ge 0, -\overline{F}^{s} \le \mathcal{H}Y^{s} \le \overline{F}^{s}$ 

$$\pi^{s} \perp \Psi(X^{s}) - d^{s}(\pi^{s}) - Y^{s} = 0$$

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# Example of a MOPEC

$$\min_{\mathsf{x}_i} \theta_i(\mathsf{x}_i, \mathsf{x}_{-i}, \pi) \text{ s.t. } g_i(\mathsf{x}_i, \mathsf{x}_{-i}, \pi) \leq 0, \forall i$$

 $\pi$  solves  $h(x,\pi) = 0$ 

```
equilibrium
min theta(1) x(1) g(1)
...
```

```
min theta(m) x(m) g(m)
vi h pi
```

- (Generalized) Nash
- Reformulate optimization problem as first order conditions (complementarity)
- Use nonsmooth Newton methods to solve
- Solve overall problem using "individual optimizations"?



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### Approximating details of transmission

Let  $\mathcal{A}$  be the node-arc incidence matrix,  $\mathcal{H}$  be the shift matrix,  $\mathcal{L}$  be the loop constraint matrix. Standard results show:

$$\mathcal{X} = \{Y : \exists F, F = \mathcal{H}Y, F \in \mathcal{F}\}$$
$$\mathcal{X} = \left\{Y : \exists (F, \theta), Y = \mathcal{A}F, \mathcal{B}\mathcal{A}^{\mathsf{T}}\theta = F, \theta \in \Theta, F \in \mathcal{F}\right\}$$
$$\mathcal{X} = \{Y : \exists F, Y = \mathcal{A}F, \mathcal{L}F = 0, F \in \mathcal{F}\}$$

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Loopflow model (using  $\mathcal{A}, \mathcal{L}$ )

$$\begin{split} \max_{d} & \sum_{s} \left( W(d^{s}(\pi^{s})) - \pi^{s} d^{s}(\pi^{s}) \right) \\ &+ \max_{X} & \sum_{s} \left( \pi^{s} \Psi(X^{s}) - \sum_{i} c_{i}(X_{i}^{s}) \right) \\ &\text{s.t.} & 0 \leq X_{i}^{s} \leq \overline{X}_{i}, \quad \overline{G}_{i} \geq \sum_{s} X_{i}^{s} \end{split}$$

$$\begin{split} &+ \max_{F,Y} \quad \sum_{s} -\pi^{s} Y^{s} \\ &\text{s.t.} \quad Y^{s} = \mathcal{A} F^{s}, \mathcal{L} F^{s} = 0, -\overline{F}^{s} \leq F^{s} \leq \overline{F}^{s} \end{split}$$

$$\pi^s \perp \Psi(X^s) - d^s(\pi^s) - Y^s = 0$$

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### Network model

Drop loop constraints:

$$\begin{split} \max_{d} & \sum_{s} \left( W(d^{s}(\pi^{s})) - \pi^{s} d^{s}(\pi^{s}) \right) \\ + \max_{X} & \sum_{s} \left( \pi^{s} \Psi(X^{s}) - \sum_{i} c_{i}(X_{i}^{s}) \right) \\ \text{s.t.} & 0 \leq X_{i}^{s} \leq \overline{X}_{i}, \quad \overline{G}_{i} \geq \sum_{s} X_{i}^{s} \end{split}$$

$$\begin{array}{ll} +\max\limits_{F,Y} & \sum\limits_{s} -\pi^{s}Y^{s} \\ \text{s.t.} & Y^{s} = \mathcal{A}F^{s}, -\overline{F}^{s} \leq F^{s} \leq \overline{F} \end{array}$$

$$\pi^s \perp \Psi(X^s) - d^s(\pi^s) - Y^s = 0$$

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### Comparing Network and Loopflow: Demand

Here we look at simulations which impose a proportional reduction in transmission across the network. The *network* and *loopflow* models demonstrate similar responses:



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#### Comparing Network and Loopflow: Generation

Likewise, generation is similar in the two models:



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#### Comparing Network and Loopflow: Transmission

Network transmission levels reveal that the two models are quite different:



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#### The Game: update red, blue and purple components

$$\begin{split} \max_{d} & \sum_{s} \left( W(d^{s}(\pi^{s})) - \pi^{s} d^{s}(\pi^{s}) \right) \\ + \max_{X} & \sum_{s} \left( \pi^{s} \Psi(X^{s}) - \sum_{i} c_{i}(X_{i}^{s}) \right) \\ \text{s.t.} & 0 \leq X_{i}^{s} \leq \overline{X}_{i}, \quad \overline{G}_{i} \geq \sum_{s} X_{i}^{s} \\ + \max_{Y} & \sum_{s} -\pi^{s} Y^{s} \\ \text{s.t.} & \sum_{i} Y_{i}^{s} \geq 0, -\overline{F}^{s} \leq \mathcal{H}Y^{s} \leq \overline{F}^{s} \end{split}$$

$$\pi^s \perp \Psi(X^s) - d^s(\pi^s) - Y^s = 0$$

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# Top down/bottom up

- $\lambda^s = \pi^s$  so use complementarity to expose multipliers
- Change interaction via new price mechanisms
- All network constraints encapsulated in (bottom up) NLP (or its approximation by dropping *LF<sup>s</sup>* = 0):

$$\begin{array}{ll} \max_{F,Y} & \sum_{s} -\pi^{s} Y^{s} \\ \text{s.t.} & Y^{s} = \mathcal{A}F^{s}, \mathcal{L}F^{s} = 0, -\overline{F}^{s} \leq F^{s} \leq \overline{F}^{s} \end{array}$$

- Could instead use the NLP over Y with  $\mathcal H$
- Clear how to instrument different behavior or different policies in interactions (e.g. Cournot, etc) within EMP
- Can add additional detail into top level economic model describing consumers and producers
- Can solve iteratively using SELKIE

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### Pricing

Our implementation of the heterogeneous demand model incorporates three alternative pricing rules. The first is *average cost pricing*, defined by

$$P_{ ext{ACP}} = rac{\sum_{jn \in \mathcal{R}_{ ext{ACP}}} \sum_{s} p_{jns} q_{jns}}{\sum_{jn \in \mathcal{R}_{ ext{ACP}}} \sum_{s} q_{jns}}$$

The second is *time of use pricing*, defined by:

$$P_{s}^{\text{TOU}} = \frac{\sum_{jn \in \mathcal{R}_{\text{TOU}}} p_{jns} q_{jns}}{\sum_{jn \in \mathcal{R}_{\text{TOU}}} q_{jns}}$$

The third is *location marginal pricing* corresponding to the wholesale prices denoted  $P_{ns}$  above. Prices for individual demand segments are then assigned:

$$p_{jns} = \begin{cases} P_{ACP} & (jn) \in \mathcal{R}_{ACP} \\ P_{s}^{TOU} & (jn) \in \mathcal{R}_{TOU} \\ P_{ns} & (jn) \in \mathcal{R}_{LMP} \end{cases}$$

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#### Smart Metering Lowers the Cost of Congestion



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### Other specializations and extensions

 $\min_{\mathbf{x}_i} \theta_i(\mathbf{x}_i, \mathbf{x}_{-i}, \mathbf{z}(\mathbf{x}_i, \mathbf{x}_{-i}), \pi) \text{ s.t. } g_i(\mathbf{x}_i, \mathbf{x}_{-i}, \mathbf{z}, \pi) \leq 0, \forall i, f(\mathbf{x}, \mathbf{z}, \pi) = 0$ 

 $\pi$  solves VI( $h(x, \cdot), C$ )

- NE: Nash equilibrium (no VI coupling constraints,  $g_i(x_i)$  only)
- GNE: Generalized Nash Equilibrium (feasible sets of each players problem depends on other players variables)
- Implicit variables:  $z(x_i, x_{-i})$  shared
- Shared constraints: f is known to all (many) players
- Force all shared constraints to have same dual variable (VI solution)
- Can use EMP to write all these problems, and convert to MCP form
- Use models to evaluate effects of regulations and their implementation in a competitive environment

### **Economic Application**

- Model is a partial equilibrium, geographic exchange model.
- Goods are distinguished by region of origin.
- There is one unit of region *r* goods.
- These goods may be consumed in region r or they may be exported.
- Each region solves:

 $\min_{X,T_r} f_r(X,T) \text{ s.t. } H(X,T) = 0, \ T_j = \overline{T}_j, j \neq r$ 

where  $f_r(X, T)$  is a quadratic form and H(X, T) defines X uniquely as a function of T, the taxes and tariffs.

- *H*(*X*, *T*) defines an equilibrium; here it is simply a set of equations, not a complementarity problem
- Applications: Brexit, modified GATT, Russian Sanctions

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### Model statistics and performance comparison of the EPEC

MCP statistics according to the shared variable formulation			
Replication	Switching	Substitution	
12,144 rows/cols	6,578 rows/cols	129,030 rows/cols	
544,019 non-zeros	444,243 non-zeros	3,561,521 non-zeros	
0.37% dense	1.03% dense	0.02% dense	

PATH		Shared variable formulation (major, time)			
crash	spacer	prox	Replication	Switching	Substitution
$\checkmark$		$\checkmark$	7 iters	20 iters	20 iters
			8 secs	22 secs	406 secs
		$\checkmark$	24 iters	22 iters	21 iters
			376 secs	19 secs	395 secs
	$\checkmark$		8 iters	8 iters	8 iters
			28 secs	18 secs	219 secs

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# Results

Gauss-Seidel residuals					
Iteration	deviation				
1	3.14930	Tariff revenue			
2	0.90970		region	SysOpt	MOPEC
3	0.14224		1	0.117	0.012
4	0.02285		2	0.517	0.407
5	0.00373		3	0.496	0.214
6	0.00061		4	0.517	0.407
7	0.00010		5	0.117	0.012
8	0.00002				
9	0.00000				

- Note that competitive solution produces much less revenue than system optimal solution
- Model has non-convex objective, but each subproblem is solved globally (lindoglobal)

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# What is EMP?

Annotates existing equations/variables/models for modeler to provide/define additional structure

- equilibrium
- vi (agents can solve min/max/vi)
- bilevel (reformulate as MPEC, or as SOCP)
- dualvar (use multipliers from one agent as variables for another)
- QS functions (both in objectives and constraints)
- implicit functions and shared constraints
- Currently available within GAMS
- Some solution algorithms implemented in modeling system limitations on size, decomposition and advanced algorithms
- Can evaluate effects of regulations and their implementation in a competitive environment

# Conclusions

- Showed equilibrium problems built from interacting optimization problems
- Equilibrium problems can be formulated naturally and modeler can specify who controls what
- It's available (in GAMS)
- Allows use and control of dual variables / prices
- MOPEC facilitates easy "behavior" description at model level
- Enables modelers to convey simple structures to algorithms and allows algorithms to exploit this
- New decomposition algorithms available to modeler (Gauss Seidel, Randomized Sweeps, Gauss Southwell, Grouping of subproblems)
- Can evaluate effects of regulations and their implementation in a competitive environment
- Stochastic equilibria clearing the market in each scenario
- Ability to trade risk using contracts

### Stochastic: Agents have recourse?

- Agents face uncertainties in reservoir inflows
- Two stage stochastic programming,  $x^1$  is here-and-now decision, recourse decisions  $x^2$  depend on realization of a random variable
- $\rho$  is a risk measure (e.g. expectation, CVaR)

SP: min 
$$c(x^1) + \rho[q^T x^2]$$
  
s.t.  $Ax^1 = b$ ,  $x^1 \ge 0$ ,  
 $T(\omega)x^1 + W(\omega)x^2(\omega) \ge d(\omega)$ ,  
 $x^2(\omega) \ge 0, \forall \omega \in \Omega$ .



### **Risk Measures**

- Modern approach to modeling risk aversion uses concept of risk measures
- $\overline{CVaR}_{\alpha}$ : mean of upper tail beyond  $\alpha$ -quantile (e.g.  $\alpha = 0.95$ )





- mean-risk, mean deviations from quantiles, VaR, CVaR
- Much more in mathematical economics and finance literature
- Optimization approaches still valid, different objectives, varying convex/non-convex difficulty

# Contracts in MOPEC (Philpott/F./Wets)

- Can we modify (complete) system to have a social optimum by trading risk?
- How do we design these instruments? How many are needed? What is cost of deficiency?
- Facilitated by allowing contracts bought now, for goods delivered later (e.g. Arrow-Debreu Securities)
- Conceptually allows to transfer goods from one period to another (provides wealth retention or pricing of ancilliary services in energy market)
- Can investigate new instruments to mitigate risk, or move to system optimal solutions from equilibrium (or market) solutions

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$$\begin{array}{ll} \text{CP:} & \min_{d^{1}, d_{\omega}^{2} \ge 0} & p^{1}d^{1} - W(d^{1}) + \rho_{C} \left[ p_{\omega}^{2}d_{\omega}^{2} - W(d_{\omega}^{2}) & \right] \\ \text{TP:} & \min_{v^{1}, v_{\omega}^{2} \ge 0} & C(v^{1}) - p^{1}v^{1} + \rho_{T} \left[ C(v_{\omega}^{2}) - p_{\omega}^{2}v^{2}(\omega) & \right] \\ \text{HP:} & \min_{u^{1}, x^{1} \ge 0} & -p^{1}U(u^{1}) + \rho_{H} \left[ -p^{2}(\omega)U(u_{\omega}^{2}) - V(x_{\omega}^{2}) & \right] \\ & \text{s.t.} & x^{1} = x^{0} - u^{1} + h^{1}, \\ & x_{\omega}^{2} = x^{1} - u_{\omega}^{2} + h_{\omega}^{2} \end{array}$$

$$0 \le p^{1} \perp U(u^{1}) + v^{1} \ge d^{1}$$
$$0 \le p_{\omega}^{2} \perp U(u_{\omega}^{2}) + v_{\omega}^{2} \ge d_{\omega}^{2}, \forall \omega$$

Trading risk: pay  $\sigma_{\omega}$  now, deliver 1 later in  $\omega$ 

$$\begin{aligned} \text{CP:} & \min_{\substack{d^1, d_{\omega}^2 \ge 0, t^C}} & \sigma t^C + p^1 d^1 - W(d^1) + \rho_C \left[ p_{\omega}^2 d_{\omega}^2 - W(d_{\omega}^2) - t_{\omega}^C \right] \\ \text{TP:} & \min_{\substack{v^1, v_{\omega}^2 \ge 0, t^T}} & \sigma t^T + C(v^1) - p^1 v^1 + \rho_T \left[ C(v_{\omega}^2) - p_{\omega}^2 v^2(\omega) - t_{\omega}^T \right] \\ \text{HP:} & \min_{\substack{u^1, x^1 \ge 0 \\ u_{\omega}^2, x_{\omega}^2 \ge 0, t^H}} & \sigma t^H - p^1 U(u^1) + \rho_H \left[ -p^2(\omega) U(u_{\omega}^2) - V(x_{\omega}^2) - t_{\omega}^H \right] \\ & \text{s.t.} & x^1 = x^0 - u^1 + h^1, \\ & x_{\omega}^2 = x^1 - u_{\omega}^2 + h_{\omega}^2 \end{aligned}$$

$$\begin{split} 0 &\leq p^{1} \perp U(u^{1}) + v^{1} \geq d^{1} \\ 0 &\leq p_{\omega}^{2} \perp U(u_{\omega}^{2}) + v_{\omega}^{2} \geq d_{\omega}^{2}, \forall \omega \\ 0 &\leq \sigma_{\omega} \perp t_{\omega}^{C} + t_{\omega}^{T} + t_{\omega}^{H} \geq 0, \forall \omega \ \sigma = (\sigma_{\omega}) \end{split}$$

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### Reserves, interruptible load, demand response

- Generators set aside capacity for "contingencies" (reserves)
- Separate energy  $\pi_d$  and reserve  $\pi_r$  prices
- Consumers may also be able to reduce consumption for short periods
- Alternative to sharp price increases during peak periods
- Constraints linking energy "bids" and reserve "bids"

$$\mathbf{v}_j + \mathbf{u}_j \leq \mathcal{U}_j, \mathbf{u}_j \leq \mathcal{B}_j \mathbf{v}_j$$

 Multiple scenarios - linking constraints on bids require "bid curve to be monotone"

# Price taking: model is MOPEC

Consumption  $d_k$ , demand response  $r_k$ , energy  $v_i$ , reserves  $u_i$ , prices  $\pi$ 

Consumer 
$$\max_{\substack{(d_k, r_k) \in \mathcal{C} \\ (d_k, r_k) \in \mathcal{C}}} \text{utility}(d_k) - \pi_d^T d_k + \text{profit}(r_k, \pi_r)$$
  
Generator 
$$\max_{\substack{(v_j, u_j) \in \mathcal{G} \\ \text{s.t. } v_j + u_j \leq \mathcal{U}_j, u_j \leq \mathcal{B}_j v_j}$$
  
s.t.  $v_j + u_j \leq \mathcal{U}_j, u_j \leq \mathcal{B}_j v_j$   
Transmission 
$$\max_{\substack{f \in \mathcal{F}}} \text{congestion rates}(f, \pi_d)$$

Market clearing

$$0 \le \pi_d \perp \sum_j \mathbf{v}_j - \sum_k \mathbf{d}_k - \mathcal{A}\mathbf{f} \ge 0$$
$$0 \le \pi_r \perp \sum_j \mathbf{u}_j + \sum_k \mathbf{r}_k - \mathcal{R} \ge 0$$

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#### Large consumer is price making: MPEC

Leader/follower

Consumer max utility
$$(d_k) - \pi_d^T d_k + \text{profit}(r_k, \pi_r)$$

with the constraints:

 $\begin{aligned} & (d_k, r_k) \in \mathcal{C} \\ & \text{Generator} \quad \max_{\substack{(v_j, u_j) \in \mathcal{G}'}} \operatorname{profit}(v_j, \pi_d) + \operatorname{profit}(u_j, \pi_r) \\ & \text{Transmission} \quad \max_{f \in \mathcal{F}} \text{ congestion rates}(f, \pi_d) \\ & 0 \leq \pi_d \perp \sum_j v_j - \sum_k d_k - \mathcal{A}f \geq 0 \\ & 0 \leq \pi_r \perp \sum_j u_j + \sum_k r_k - \mathcal{R} \geq 0 \end{aligned}$ 

#### Solution and observations

- Formulate as MIP, add mononticity constraints and scenarios
- New Zealand (NZEM) data, large consumer at bottom of South Island
- Expected difference percentage between "wait and see" solutions versus model solution (evaluated post optimality with simulation)

Sample Size	1	2	4	6	8
Expected diff	31.34	17.83	9.22	7.35	9.26
Standard dev	22.86	9.62	4.86	7.69	6.59
Bound gap (%)	0	0	0	12.7	24.8

- More samples better(!)
- More research to model/solve more detailed problems

# Satellite data, FERC and Reserves

Solar transmittance and power



- Generators set aside capacity for "contingencies" (reserves)
- Separate energy π<sub>d</sub> and reserve π<sub>r</sub> prices
- Use 12 hour cloud cover forecasts to reduce reserves

- Federal Energy Regulatory Commission (FERC) contract to build models and data
- Provided on NEOS (Network enabled optimization system)



• Integrate satellite forecast data with power system data and smoke models to provide reliability and savings outcomes