

# Stochastic Multiple Optimization Problems with Equilibrium Constraints

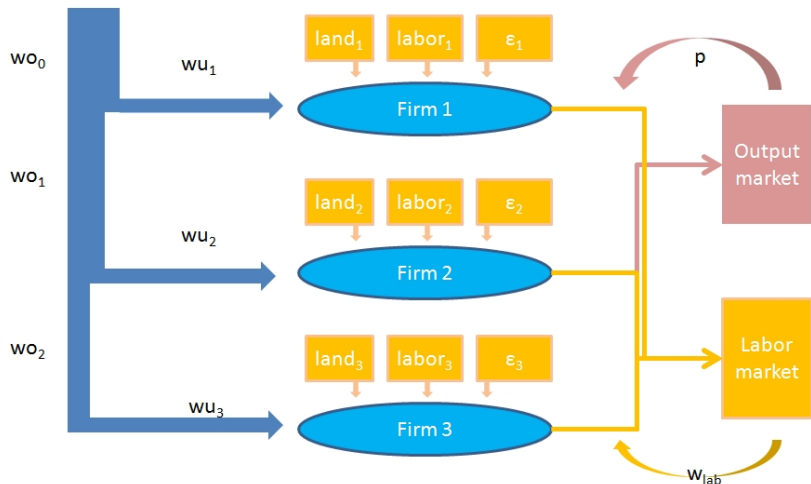
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# Water rights pricing (Britz/F./Kuhn)



# The model AO

$$\max_{q_i, x_i, w_{O_i} \geq 0} \sum_i \left( q_i \cdot p - \sum_{f \in \{int, lab\}} x_{i,f} \cdot w_f \right)$$

$$\text{s.t.} \quad q_i \leq \prod_f (x_{i,f} + e_{i,f})^{\epsilon_{i,f}}$$

$$x_{i,land} \leq e_{i,land}$$

$$w_{O_{i-1}} = x_{i,wat} + w_{O_i}$$

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$$x_{i,land} \leq e_{i,land}$$

$$w_{o_{i-1}} = x_{i,wat} + w_{o_i}$$

$$0 \leq \sum_i q_i - d(p) \perp p \geq 0$$

$$0 \leq \sum_i e_{i,lab} - \sum_i x_{i,lab} \perp w_{lab} \geq 0$$

# (M)OPEC

$$\max_x \theta(x, p) \text{ s.t. } g(x, p) \leq 0,$$

and

$$0 \leq h(x, p) \perp p \geq 0$$

equilibrium

max theta x g

vi h p

is solved concurrently (in a Nash manner)

# (M)OPEC

$$\max_x \theta(x, p) \text{ s.t. } g(x, p) \leq 0,$$

and

$$h(x, p) = 0$$

equilibrium

$\max_x \theta(x, p)$

$\forall h, p$

is solved concurrently (in a Nash manner)

# MOPEC

$$\min_{x_i} \theta_i(x_i, x_{-i}, p) \text{ s.t. } g_i(x_i, x_{-i}, p) \leq 0, \forall i$$

and

$$p \text{ solves VI}(h(x, \cdot), C)$$

equilibrium

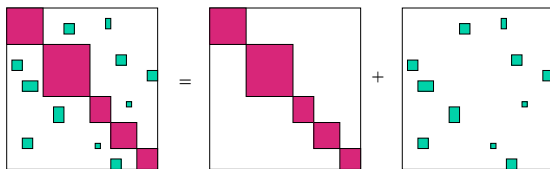
$$\min \theta(1) \quad x(1) \quad g(1)$$

...

$$\min \theta(m) \quad x(m) \quad g(m)$$

vi h p cons

- Reformulate optimization problem as first order conditions (complementarity)
- Use nonsmooth Newton methods to solve complementarity problem
- Precondition using “individual optimization” with fixed externalities



# The model IO

$$\begin{aligned} \max_{q_i, x_i, w_i \geq 0} & \left( q_i \cdot p - \sum_f x_{i,f} \cdot w_f \right) \\ \text{s.t.} & q_i \leq \prod_f (x_{i,f} + e_{i,f})^{\epsilon_{i,f}} \\ & x_{i,land} \leq e_{i,land} \\ & w_{i-1} = x_{i,wat} + w_i \end{aligned}$$

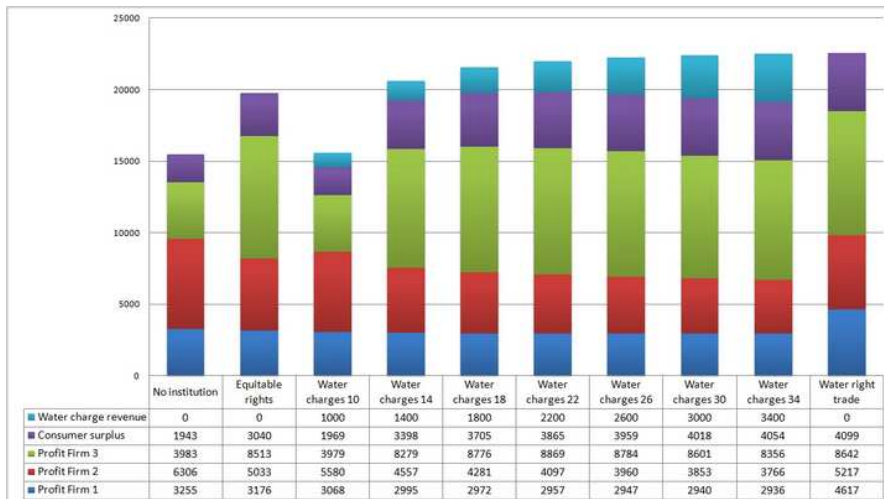
$$\begin{aligned} 0 \leq \sum_i q_i - d(p) & \perp p \geq 0 \\ 0 \leq \sum_i e_{i,lab} - \sum_i x_{i,lab} & \perp w_{lab} \geq 0 \end{aligned}$$



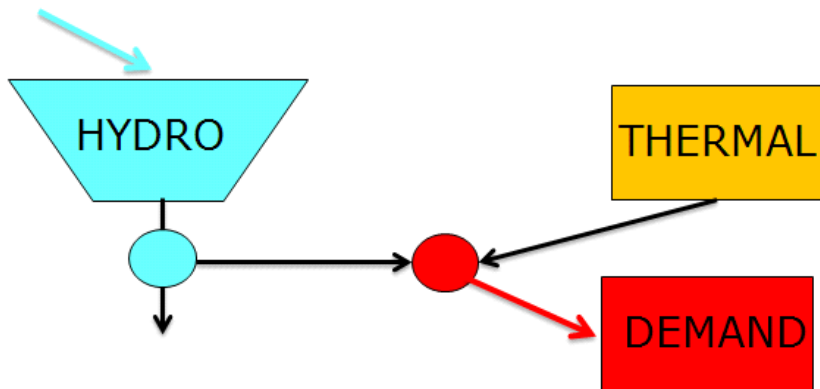
# The model IO

$$\begin{aligned}
 & \max_{q_i, x_i, w_{o_i}, w_{r_i}^b, w_{r_i}^s \geq 0} \left( q_i \cdot p - \sum_f x_{i,f} \cdot w_f - w_{r_i}^b \cdot (w_{wr} + \tau) + w_{r_i}^s \cdot w_{wr} \right) \\
 \text{s.t.} \quad & q_i \leq \prod_f (x_{i,f} + e_{i,f})^{\epsilon_{i,f}} \\
 & x_{i,land} \leq e_{i,land} \\
 & w_{o_{i-1}} = x_{i,wat} + w_{o_i} \\
 & w_{r_i} + w_{r_i}^b \geq x_{i,wat} + w_{r_i}^s \\
 \\ 
 & 0 \leq \sum_i q_i - d(p) \perp p \geq 0 \\
 & 0 \leq \sum_i e_{i,lab} - \sum_i x_{i,lab} \perp w_{lab} \geq 0 \\
 & 0 \leq \sum_i w_{r_i}^s - \sum_i w_{r_i}^b \perp w_{wr} \geq 0
 \end{aligned}$$

# Different Management Strategies



# Hydro-Thermal System (Philpott/F./Wets)



## Simple electricity system optimization problem

$$\text{SSP: } \min \sum_{j \in \mathcal{T}} C_j(v(j)) - \sum_{i \in \mathcal{H}} V_i(x(i))$$

$$\begin{aligned} \text{s.t. } & \sum_{i \in \mathcal{H}} U_i(u(i)) + \sum_{j \in \mathcal{T}} v(j) \geq d, \\ & x(i) = x_0(i) - u(i), \quad i \in \mathcal{H} \\ & u(i), v(j), x(i) \geq 0. \end{aligned}$$

- $u(i)$  water release of hydro reservoir  $i \in \mathcal{H}$
- $v(j)$  thermal generation of plant  $j \in \mathcal{T}$
- production function  $U_i$  (strictly concave) converts water release to energy
- water level reservoir  $i \in \mathcal{H}$  is denoted  $x(i)$
- $C_j(v(j))$  denote the cost of generation by thermal plant
- $V_i(x(i))$  to be the future value of terminating the period with storage  $x$  (assumed separable)

# SSP equivalent to CE

Thermal plants solve

$$\text{TP}(j): \quad \max \quad p^T v(j) - C_j(v(j))$$

$$\text{s.t.} \quad v(j) \geq 0.$$

The hydro plants  $i \in \mathcal{H}$  solve

$$\text{HP}(i): \quad \max \quad p^T U_i(u(i)) + V_i(x(i))$$

$$\text{s.t.} \quad x(i) = x_0(i) - u(i) \\ u(i), x(i) \geq 0.$$

Perfectly competitive (Walrasian) equilibrium is a MOPEC

$$\begin{aligned} \text{CE:} \quad & u(i), x(i) \in \arg \max \text{HP}(i), & i \in \mathcal{H}, \\ & v(j) \in \arg \max \text{TP}(j), & j \in \mathcal{T}, \\ & 0 \leq (\sum_{i \in \mathcal{H}} U_i(u(i)) + \sum_{j \in \mathcal{T}} v(j)) - d \perp p \geq 0. \end{aligned}$$

## Agents have stochastic recourse?

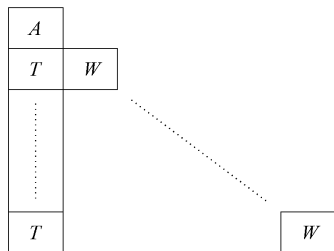
- Two stage stochastic programming,  $x$  is here-and-now decision, recourse decisions  $y$  depend on realization of a random variable
- $\mathbb{R}$  is a risk measure (e.g. expectation, CVaR)

$$\text{SP: } \min \quad c^T x + \mathbb{R}[q^T y]$$

$$\text{s.t. } Ax = b, \quad x \geq 0,$$

$$\forall \omega \in \Omega : \quad T(\omega)x + W(\omega)y(\omega) \leq d(\omega),$$

$$y(\omega) \geq 0.$$



EMP/SP extensions to facilitate these models

## Two stage problems

$$\text{TP}(j): \quad \max \quad p_1 v_1(j) - C_j(v_1(j)) + \\ R_\omega [p_2(\omega) v_2(j, \omega) - C_j(v_2(j, \omega))]$$

$$\text{s.t.} \quad v_1(j) \geq 0, \quad v_2(j, \omega) \geq 0, \quad \text{for all } \omega \in \Omega.$$

$$\text{HP}(i): \quad \max \quad p_1 U_i(u_1(i)) + \\ R_\omega [p_2(\omega) U_i(u_2(i, \omega)) + V_i(x_2(i, \omega))]$$

$$\text{s.t.} \quad x_1(i) = x_0(i) - u_1(i) + h_1(i), \\ x_2(i, \omega) = x_1(i) - u_2(i, \omega) + h_2(i, \omega), \quad \text{for all } \omega \in \Omega, \\ u_1(i), x_1(i) \geq 0, \quad u_2(i, \omega), x_2(i, \omega) \geq 0, \quad \text{for all } \omega \in \Omega.$$

# Results

- Suppose every agent is risk neutral and has knowledge of all deterministic data, as well as sharing the same probability distribution for inflows. **SP solution is same as CE solution**
- Using coherent risk measure (weighted sum of expected value and conditional variance at risk), 10 scenarios for rain
  - 1 High initial storage: risk-averse central plan (**RSP**) and the risk-averse competitive equilibrium (**RCE**) **have same solution** (but different to risk neutral case)
  - 2 Low initial storage: **RSP and RCE are very different**. Since the hydro generator and the system do not agree on a worst-case outcome, the probability distributions that correspond to an equivalent risk neutral decision will not be common.
  - 3 **Extension: Construct MOPEC models for trading risk**



# Stochastic competing agent models (F./Wets)

- Competing agents (consumers, or generators in energy market)
- Each agent minimizes objective independently (cost)
- Market prices are function of all agents activities
- Additional twist: model must “hedge” against uncertainty
- Facilitated by allowing contracts bought now, for goods delivered later
- Conceptually allows to transfer goods from one period to another (provides wealth retention or pricing of ancillary services in energy market)
- Can investigate new instruments to mitigate risk, or move to system optimal solutions from equilibrium (or market) solutions

# Example as MOPEC: agents solve a Stochastic Program

Each agent minimizes:

$$u_a = (\kappa - f(q_{a,0}))^2 + \sum_s \pi_s (\kappa - f(q_{a,s}))^2$$

$$\text{Budget time 0: } p_0^T q_{a,0} + v^T y_a \leq p_0^T e_{a,0}$$

$$\text{Budget time 1: } p_s^T q_{a,s} \leq p_s^T (D_s y_a + e_{a,s})$$

Additional constraints (complementarity) outside of control of agents:

$$\text{(contract) } 0 \leq - \sum_a y_a \perp v \geq 0$$

$$\text{(walras) } 0 \leq \sum_a (D_s y_a + e_{a,s} - q_{a,s}) \perp p_s \geq 0$$

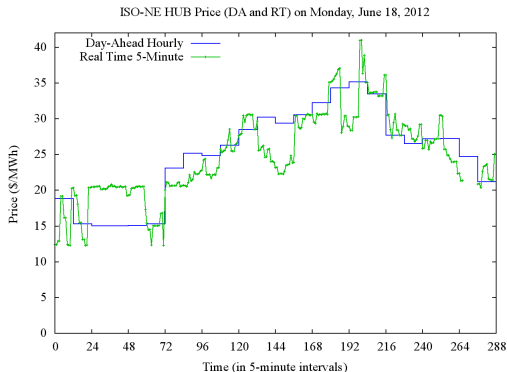
# Observations

- Examples from literature solved using homotopy continuation seem incorrect - need transaction costs to guarantee solution
- Solution possible via disaggregation only seems possible in special cases
  - ▶ When problem is block diagonally dominant
  - ▶ When overall (complementarity) problem is monotone
  - ▶ (Pang): when problem is a potential game
- Progressive hedging possible to decompose in these settings by agent and scenario

# PJM buy/sell model (2009)

- Storage transfers energy over time (horizon =  $T$ ).
- PJM: given price path  $p_t$ , determine charge  $q_t^+$  and discharge  $q_t^-$ :

$$\begin{aligned} \max_{h_t, q_t^+, q_t^-} \quad & \sum_{t=0}^T p_t (q_t^- - q_t^+) \\ \text{s.t.} \quad & \partial h_t = e q_t^+ - q_t^- \\ & 0 \leq h_t \leq S \\ & 0 \leq q_t^+ \leq Q \\ & 0 \leq q_t^- \leq Q \\ & h_0, h_T \text{ fixed} \end{aligned}$$



- Uses: price shaving, load shifting, transmission line deferral
- what about different storage technologies?

# Stochastic price paths (day ahead market)

$$\begin{aligned} \min_{x, s, q^+, q^-} \quad & c^0(x) + \mathbb{E}_\omega \left[ \sum_{t=0}^T p_{\omega t} (q_{\omega t}^+ - q_{\omega t}^-) + c^1(q_{\omega t}^+ + q_{\omega t}^-) \right] \\ \text{s.t.} \quad & \partial h_{\omega t} = e q_{\omega t}^+ - q_{\omega t}^- \\ & 0 \leq h_{\omega t} \leq \mathcal{S}x \\ & 0 \leq q_{\omega t}^+, q_{\omega t}^- \leq \mathcal{Q}x \\ & h_{\omega 0}, h_{\omega T} \text{ fixed} \end{aligned}$$

- First stage decision  $x$ : amount of storage to deploy.
- Second stage decision: charging strategy in face of uncertainty

## Distribution of (multiple) storage types

Determine storage facilities  $x_k$  to build, given distribution of price paths: no entry barriers into market, etc. MOPEC: for all  $k$  solve a two stage stochastic program

$$\begin{aligned} \forall k : \quad & \min_{x_k, h_k, q_k^+, q_k^-} c_k^0(x_k) + \mathbb{E}_\omega \left[ \sum_{t=0}^T p_{\omega t} (q_{\omega kt}^+ - q_{\omega kt}^-) + c_k^1(q_{\omega kt}^+ + q_{\omega kt}^-) \right] \\ & \text{s.t. } \partial h_{\omega kt} = e q_{\omega kt}^+ - q_{\omega kt}^- \\ & \quad 0 \leq h_{\omega kt} \leq S x_k \\ & \quad 0 \leq q_{\omega kt}^+, q_{\omega kt}^- \leq Q x_k \\ & \quad h_{\omega k0}, h_{\omega kT} \text{ fixed} \end{aligned}$$

and

$$p_{\omega t} = f \left( \theta, D_{\omega t} + \sum_k (q_{\omega kt}^+ - q_{\omega kt}^-) \right)$$

Parametric function  $(\theta)$  determined by regression. Storage operators react to shift in demand.

# What is EMP?

Annotates existing equations/variables/models for modeler to provide/define additional structure

- equilibrium
- vi (agents can solve min/max/vi)
- bilevel (reformulate as MPEC, or as SOCP)
- disjunction (or other constraint logic primitives)
- randvar
- dualvar (use multipliers from one agent as variables for another)
- extended nonlinear programs (library of plq functions)

Currently available within GAMS

# Conclusions

- Modern optimization within applications requires multiple model formats, computational tools and sophisticated solvers
- EMP model type is clear and extensible, additional structure available to solver
- Stochastic MOPEC models capture behavioral effects (as an EMP)
- Policy implications addressable using Stochastic MOPEC
- Extended Mathematical Programming available within the GAMS modeling system