

Extended Mathematical Programming: Competition and Stochasticity

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The PIES Model (Hogan)

$$\begin{aligned} \min_x \quad & c^T x && \text{cost} \\ \text{s.t.} \quad & Ax = d(p) && \text{balance} \\ & Bx = b && \text{technical constr} \\ & x \geq 0 && \end{aligned}$$

- Issue is that p is the multiplier on the “balance” constraint of LP
- Extended Mathematical Programming (EMP) facilitates annotations of models to describe additional structure
- Can solve the problem by writing down the KKT conditions of this LP, forming an LCP and exposing p to the model
- EMP does this automatically from the annotations

Reformulation details

$$\begin{array}{ll} 0 = Ax - d(p) & \perp \mu \\ 0 = Bx - b & \perp \lambda \\ 0 \leq -A^T \mu - B^T \lambda + c & \perp x \geq 0 \end{array}$$

- empinfo: dualvar p balance
- replaces $\mu \equiv p$
- LCP/MCP is then solvable using PATH

$$z = \begin{bmatrix} p \\ \lambda \\ x \end{bmatrix}, \quad F(z) = \begin{bmatrix} A \\ B \\ -A^T & -B^T \end{bmatrix} z + \begin{bmatrix} -d(p) \\ -b \\ c \end{bmatrix}$$

Understand: demand response and FERC Order No. 745

$$\begin{aligned} \min_{q,z,\theta,R,p} \quad & \sum_k p_k R_k \\ \text{s.t.} \quad & C_1 \geq \sum_k p_k d_k / \sum_k d_k \\ & C_2 \geq \sum_k p_k (q_k + R_k) / \sum_k (d_k - R_k) \\ & 0 \leq R_k \leq u_k, \end{aligned}$$

and (q, z, θ) solves

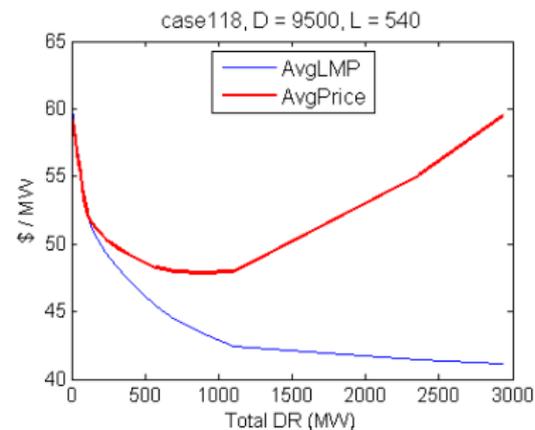
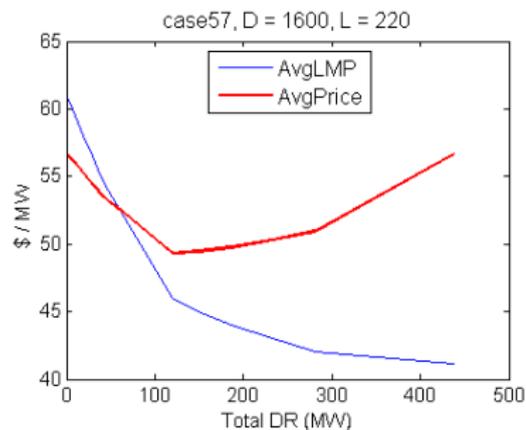
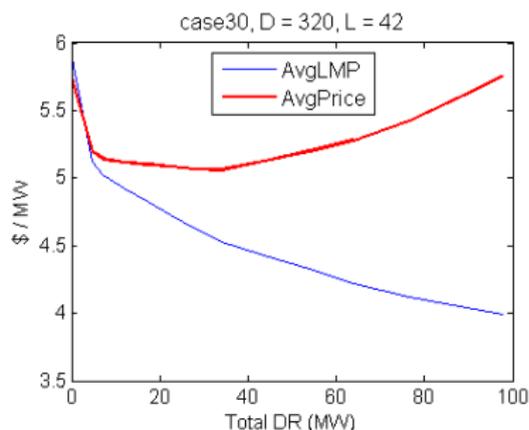
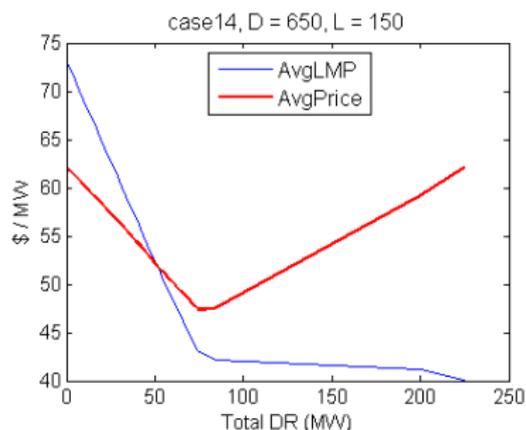
$$\begin{aligned} \min_{(q,z,\theta) \in \mathcal{F}} \quad & \sum_k C(q_k) \\ \text{s.t.} \quad & q_k - \sum_{(l,c)} z_{(k,l,c)} = d_k - R_k \end{aligned} \tag{1}$$

where p_k is the multiplier on constraint (1)

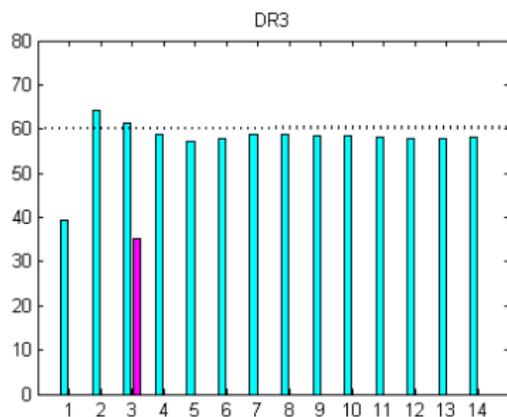
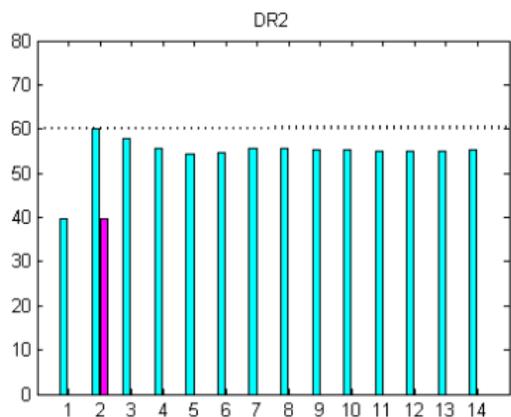
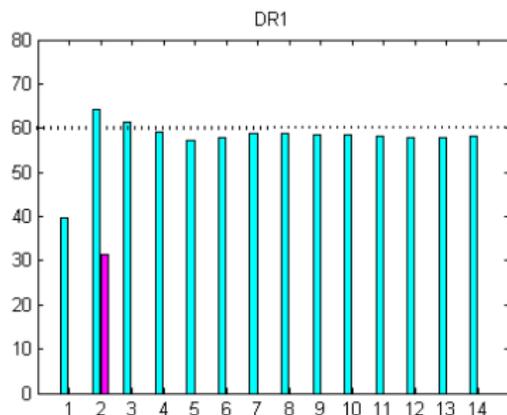
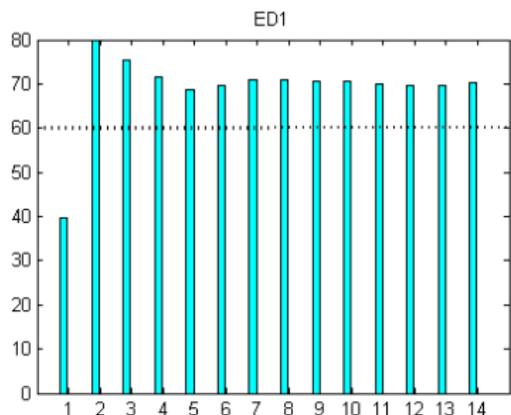
Solution Process (F./Liu)

- Bilevel program (hierarchical model)
- Upper level objective involves multipliers on lower level constraints
- Extended Mathematical Programming (EMP) annotates model to facilitate communicating structure to solver
 - ▶ dualvar p balance
 - ▶ bilevel R min cost q z θ balance . . .
- Automatic reformulation as an MPEC (single optimization problem with equilibrium constraints)
- Model solved using NLPEC and Conopt
- bilevel \implies MPEC \implies NLP
- Potential for solution of “consumer level” demand response
- Challenge: devise robust algorithms to exploit this structure for fast solution

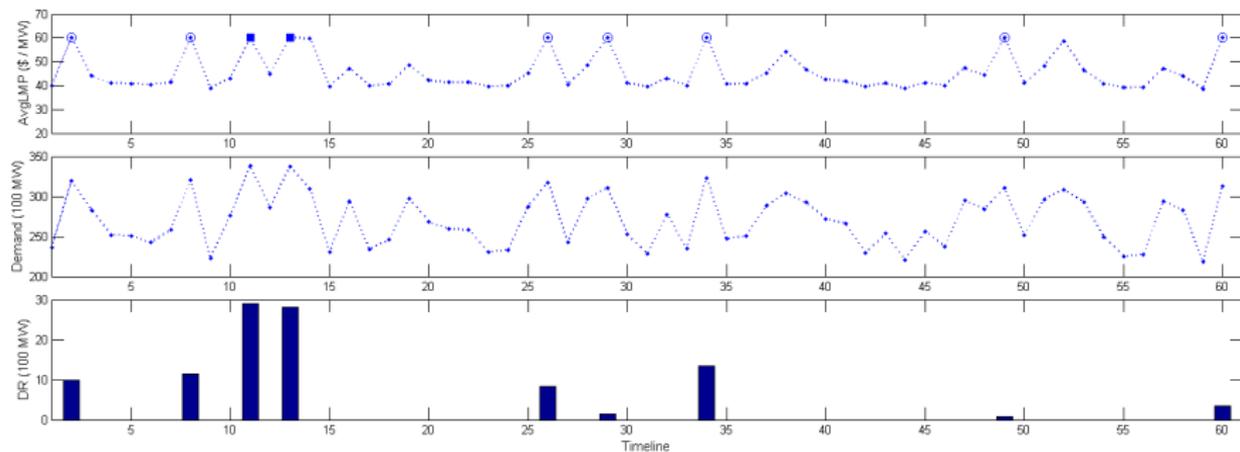
Stability and feasibility (vary C_1)



Alternative models: ED, avg, max, weighted avg



Operational view: LMP, Demand, Response



MOPEC

$$\min_{x_i} \theta_i(x_i, x_{-i}, y) \text{ s.t. } g_i(x_i, x_{-i}, y) \leq 0, \forall i$$

and

$$y \text{ solves } VI(h(x, \cdot), C)$$

equilibrium

```
min theta(1) x(1) g(1)
```

```
...
```

```
min theta(m) x(m) g(m)
```

```
vi h y cons
```

is solved in a Nash manner

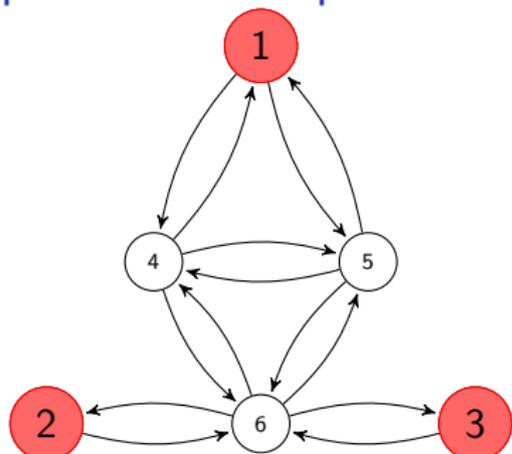
Spatial Price Equilibrium

$$n \in \{1, 2, 3, 4, 5, 6\}$$

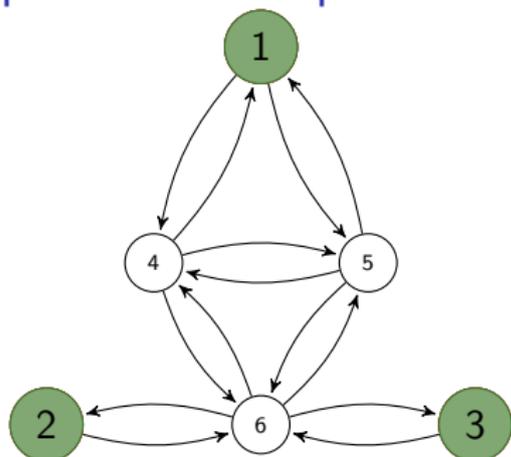
$$L \in \{1, 2, 3\}$$

Supply quantity: S_L

Production cost: $\Psi(S_L) = ..$



Spatial Price Equilibrium



$$n \in \{1, 2, 3, 4, 5, 6\}$$

$$L \in \{1, 2, 3\}$$

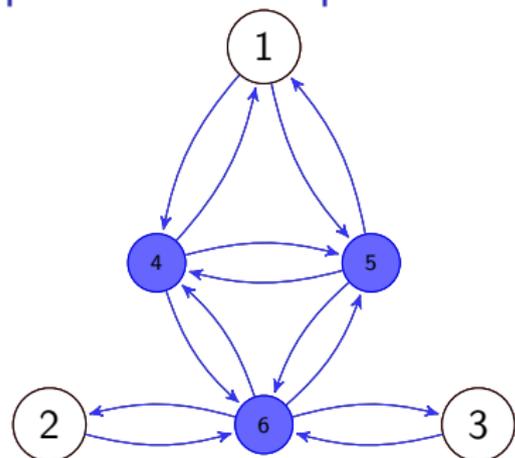
Supply quantity: S_L

Production cost: $\Psi(S_L) = ..$

Demand: D_L

Unit demand price: $\theta(D_L) = ..$

Spatial Price Equilibrium



$$n \in \{1, 2, 3, 4, 5, 6\}$$

$$L \in \{1, 2, 3\}$$

Supply quantity: S_L

Production cost: $\Psi(S_L) = ..$

Demand: D_L

Unit demand price: $\theta(D_L) = ..$

Transport: T_{ij}

Unit transport cost: $c_{ij}(T_{ij}) = ..$

One large system of equations and inequalities to describe this (GAMS).

$$\max_{(D,S,T) \in \mathcal{F}} \sum_{l \in L} \pi_l D_l - \sum_{l \in L} \Psi_l(S_l) - \sum_{i,j} p_{ij} T_{ij}$$

$$\text{s.t. } S_l + \sum_{i,l} T_{il} = D_l + \sum_{l,j} T_{lj}, \quad \forall l \in L$$

$$p_{ij} = c_{ij}(T_{ij}), \pi_l = \theta_l(D_l)$$

Cournot-Nash equilibrium (multiple agents)

Assumes that each agent (producer):

- Treats other agent decisions as fixed
- Is a price-taker in transport and demand

EMP info file

equilibrium

```
max obj('one') vars('one') eqns('one')
max obj('two') vars('two') eqns('two')
max obj('three') vars('three') eqns('three')
vi tcDef tc
vi pricedef price
```

EMP = MOPEC \implies MCP

Bilevel Program (Stackelberg)

- Assumes one leader firm, the rest follow
- Leader firm optimizes subject to expected follower behavior
- Follower firms act in a Nash manner
- All firms are price-takers in transport and demand

EMP info file

```
bilevel obj('one') vars('one') eqns('one')
max obj('two') vars('two') eqns('two')
max obj('three') vars('three') eqns('three')
vi tcDef tc
vi pricedef price
```

EMP = bilevel \implies MPEC \implies (via NLPEC) NLP(μ)

What is EMP?

Annotates existing equations/variables/models for modeler to provide/define additional structure

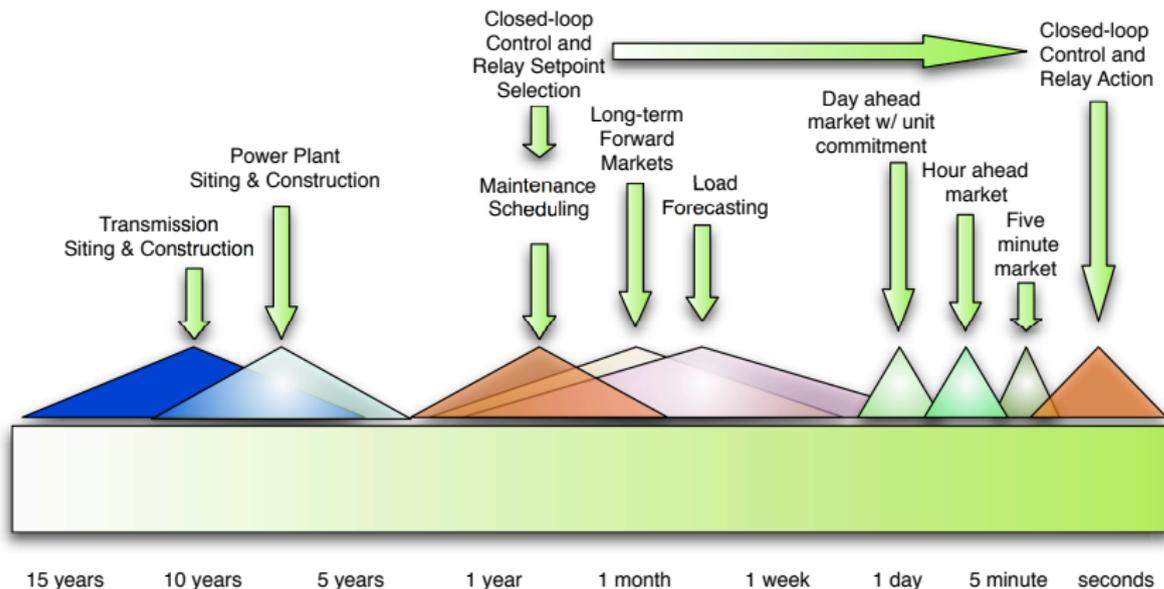
- equilibrium
- vi (agents can solve min/max/vi)
- bilevel (reformulate as MPEC, or as SOCP)
- disjunction (or other constraint logic primitives)
- randvar
- dualvar (use multipliers from one agent as variables for another)
- extended nonlinear programs (library of plq functions)

Currently available within GAMS

Extension: The smart grid

- The next generation electric grid will be more dynamic, flexible, constrained, and more complicated.
- Decision processes (in this environment) are predominantly hierarchical.
- Models to support such decision processes must also be layered or hierarchical.
- Optimization and computation facilitate adaptivity, control, treatment of uncertainties and understanding of interaction effects.
- Developing interfaces and exploiting hierarchical structure using computationally tractable algorithms will provide FLEXIBILITY, overall solution speed, understanding of localized effects, and value for the coupling of the system.

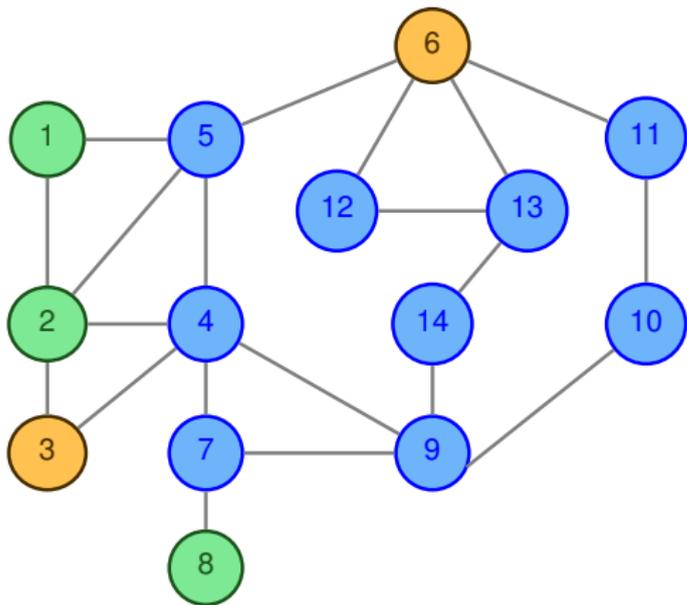
Representative decision-making timescales in electric power systems



A monster model is difficult to validate, inflexible, prone to errors.

Combine: Transmission Line Expansion Model (F./Tang)

$$\min_{x \in X} \sum_{\omega} \pi_{\omega} \sum_{i \in N} d_i^{\omega} p_i^{\omega}(x)$$



- Nonlinear system to describe power flows over (large) network
- Multiple time scales
- Dynamics (bidding, failures, ramping, etc)
- Uncertainty (demand, weather, expansion, etc)
- $p_i^{\omega}(x)$: Price (LMP) at i in scenario ω as a function of x
- Use other models to construct approximation of $p_i^{\omega}(x)$

Generator Expansion (2): $\forall f \in F$:

$$\min_{y_f} \sum_{\omega} \pi_{\omega} \sum_{j \in G_f} C_j(y_j, q_j^{\omega}) - r(h_f - \sum_{j \in G_f} y_j)$$

s.t. $\sum_{j \in G_f} y_j \leq h_f, y_f \geq 0$

G_f : Generators of firm $f \in F$
 y_j : Investment in generator j
 q_j^{ω} : Power generated at bus j in scenario ω
 C_j : Cost function for generator j
 r : Interest rate

Market Clearing Model (3): $\forall \omega$:

$$\min_{z, \theta, q^{\omega}} \sum_f \sum_{j \in G_f} C_j(y_j, q_j^{\omega}) \quad \text{s.t.}$$

$$q_j^{\omega} - \sum_{i \in I(j)} z_{ij} = d_j^{\omega} \quad \forall j \in N(\perp p_j^{\omega})$$

$$z_{ij} = \Omega_{ij}(\theta_i - \theta_j) \quad \forall (i, j) \in A$$

$$-b_{ij}(x) \leq z_{ij} \leq b_{ij}(x) \quad \forall (i, j) \in A$$

$$\underline{u}_j(y_j) \leq q_j^{\omega} \leq \bar{u}_j(y_j)$$

z_{ij} : Real power flowing along line ij
 q_j^{ω} : Real power generated at bus j in scenario ω
 θ_i : Voltage phase angle at bus i
 Ω_{ij} : Susceptance of line ij
 $b_{ij}(x)$: Line capacity as a function of x
 $\underline{u}_j(y)$, $\bar{u}_j(y)$: Generator j limits as a function of y

Solution approach

- Use derivative free method for the upper level problem (1)
- Requires $p_i^\omega(x)$
- Construct these as multipliers on demand equation (per scenario) in an Economic Dispatch (market clearing) model
- But transmission line capacity expansion typically leads to generator expansion, which interacts directly with market clearing
- Interface blue and black models using Nash Equilibria (as EMP):

empinfo: equilibrium

forall f: min expcost(f) y(f) budget(f)

forall ω : min scencost(ω) q(ω) ...

Feasibility

$$\text{KKT of } \min_{y_f \in Y} \sum_{\omega} \pi_{\omega} \sum_{j \in G_f} C_j(y_j, q_j^{\omega}) - r(h_f - \sum_{j \in G_f} y_j) \quad \forall f \in F \quad (2)$$

$$\text{KKT of } \min_{(z, \theta, q^{\omega}) \in Z(x, y)} \sum_f \sum_{j \in G_f} C_j(y_j, q_j^{\omega}) \quad \forall \omega \quad (3)$$

- Models (2) and (3) form a complementarity problem (CP via EMP)
- Solve (3) as NLP using global solver (actual $C_j(y_j, q_j^{\omega})$ are not convex), per scenario (SNLP) this provides starting point for CP
- Solve (KKT(2) + KKT(3)) using EMP and PATH, then repeat
- Identifies CP solution whose components solve the scenario NLP's (3) to global optimality

Scenario	ω_1	ω_2
Probability	0.5	0.5
Demand Multiplier	8	5.5

SNLP (1):

Scenario	q_1	q_2	q_3	q_6	q_8
ω_1	3.05	4.25	3.93	4.34	3.39
ω_2		4.41	4.07	4.55	

Scenario	ω_1	ω_2
Probability	0.5	0.5
Demand Multiplier	8	5.5

SNLP (1):

Scenario	q_1	q_2	q_3	q_6	q_8
ω_1	3.05	4.25	3.93	4.34	3.39
ω_2		4.41	4.07	4.55	

EMP (1):

Scenario	q_1	q_2	q_3	q_6	q_8
ω_1	2.86	4.60	4.00	4.12	3.38
ω_2		4.70	4.09	4.24	

Firm	y_1	y_2	y_3	y_6	y_8
f_1	167.83	565.31			266.86
f_2			292.11	207.89	

Scenario	ω_1	ω_2
Probability	0.5	0.5
Demand Multiplier	8	5.5

SNLP (2):

Scenario	q_1	q_2	q_3	q_6	q_8
ω_1	0.00	5.35	4.66	5.04	3.91
ω_2		4.70	4.09	4.24	

Scenario	ω_1	ω_2
Probability	0.5	0.5
Demand Multiplier	8	5.5

SNLP (2):

Scenario	q_1	q_2	q_3	q_6	q_8
ω_1	0.00	5.35	4.66	5.04	3.91
ω_2		4.70	4.09	4.24	

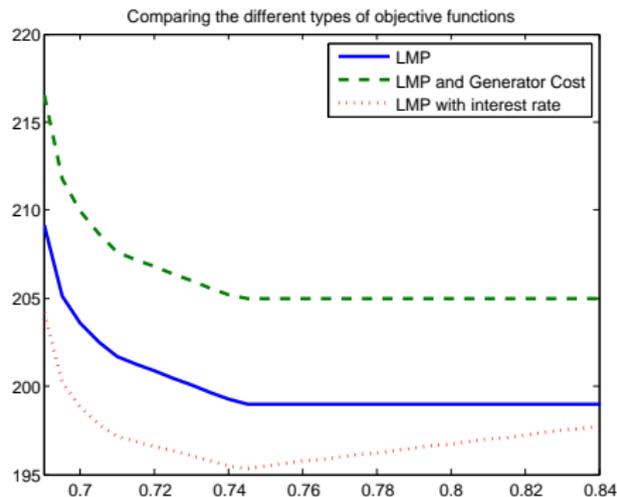
EMP (2):

Scenario	q_1	q_2	q_3	q_6	q_8
ω_1	0.00	5.34	4.62	5.01	3.99
ω_2		4.71	4.07	4.25	

Firm	y_1	y_2	y_3	y_6	y_8
f_1	0.00	622.02			377.98
f_2			283.22	216.79	

Observations

- But this is simply one function evaluation for the outer “transmission capacity expansion” problem
- Number of critical arcs typically very small
- But in this case, p_j^ω are very volatile
- Outer problem is small scale, objectives are open to debate, possibly ill conditioned
- Economic dispatch should use AC power flow model
- Structure of market open to debate
- Types of “generator expansion” also subject to debate
- Suite of tools is very effective in such situations



Agents have stochastic recourse?

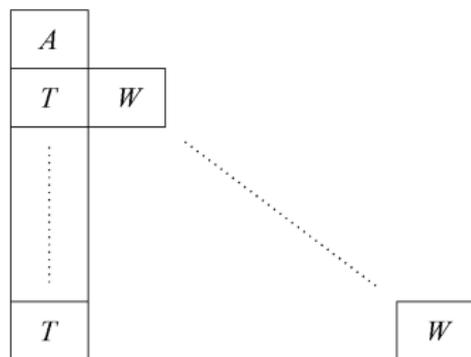
- Two stage stochastic programming, x is here-and-now decision, recourse decisions y depend on realization of a random variable
- \mathbb{R} is a risk measure (e.g. expectation, CVaR)

$$\text{SP: } \min \quad c^T x + \mathbb{R}[q^T y]$$

$$\text{s.t. } Ax = b, \quad x \geq 0,$$

$$\forall \omega \in \Omega : \quad T(\omega)x + W(\omega)y(\omega) \leq d(\omega),$$

$$y(\omega) \geq 0.$$

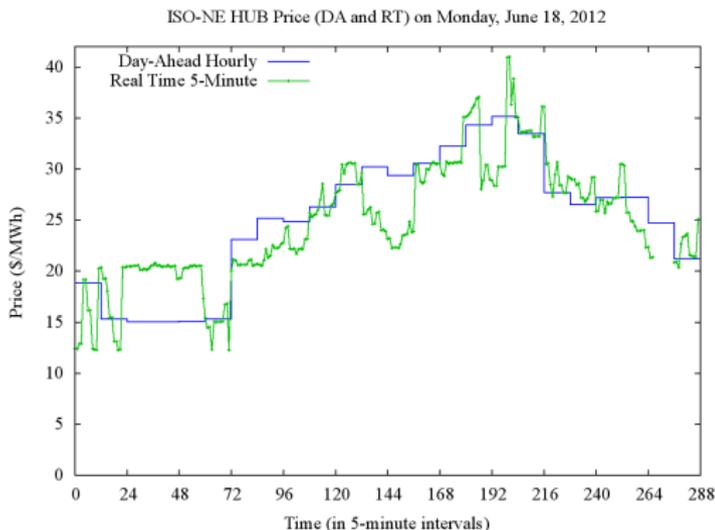


EMP/SP extensions to facilitate these models

PJM buy/sell model (2009)

- Storage transfers energy over time (horizon = T).
- PJM: given price path p_t , determine charge q_t^+ and discharge q_t^- :

$$\begin{aligned} \max_{h_t, q_t^+, q_t^-} & \sum_{t=0}^T p_t (q_t^- - q_t^+) \\ \text{s.t.} & \partial h_t = e q_t^+ - q_t^- \\ & 0 \leq h_t \leq S \\ & 0 \leq q_t^+ \leq Q \\ & 0 \leq q_t^- \leq Q \\ & h_0, h_T \text{ fixed} \end{aligned}$$



- Uses: price shaving, load shifting, transmission line deferral
- what about different storage technologies?

Stochastic price paths (day ahead market)

$$\begin{aligned} \min_{x, s, q^+, q^-} \quad & c^0(x) + \mathbb{E}_\omega \left[\sum_{t=0}^T p_{\omega t} (q_{\omega t}^+ - q_{\omega t}^-) + c^1(q_{\omega t}^+ + q_{\omega t}^-) \right] \\ \text{s.t.} \quad & \partial h_{\omega t} = e q_{\omega t}^+ - q_{\omega t}^- \\ & 0 \leq h_{\omega t} \leq \mathcal{S}x \\ & 0 \leq q_{\omega t}^+, q_{\omega t}^- \leq \mathcal{Q}x \\ & h_{\omega 0}, h_{\omega T} \text{ fixed} \end{aligned}$$

- First stage decision x : amount of storage to deploy.
- Second stage decision: charging strategy in face of uncertainty

Distribution of (multiple) storage types

Determine storage facilities x_k to build, given distribution of price paths: no entry barriers into market, etc. MOPEC: for all k solve a two stage stochastic program

$$\begin{aligned} \forall k : \quad & \min_{x_k, h_k, q_k^+, q_k^-} c_k^0(x_k) + \mathbb{E}_\omega \left[\sum_{t=0}^T p_{\omega t} (q_{\omega kt}^+ - q_{\omega kt}^-) + c_k^1(q_{\omega kt}^+ + q_{\omega kt}^-) \right] \\ & \text{s.t. } \partial h_{\omega kt} = e q_{\omega kt}^+ - q_{\omega kt}^- \\ & \quad 0 \leq h_{\omega kt} \leq S x_k \\ & \quad 0 \leq q_{\omega kt}^+, q_{\omega kt}^- \leq Q x_k \\ & \quad h_{\omega k0}, h_{\omega kT} \text{ fixed} \end{aligned}$$

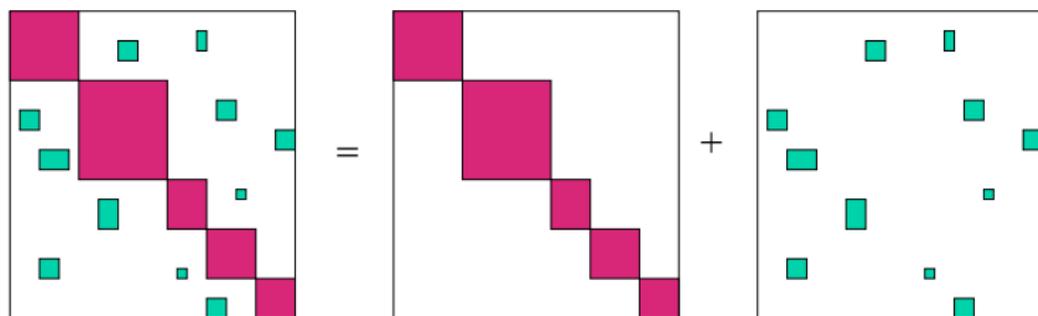
and

$$p_{\omega t} = f \left(\theta, D_{\omega t} + \sum_k (q_{\omega kt}^+ - q_{\omega kt}^-) \right)$$

Parametric function (θ) determined by regression. Storage operators react to shift in demand.

Model and solve

- Can model financial instruments such as “financial transmission rights”, “spot markets”, “reactive power markets”
- Reduce effects of uncertainty, not simply quantify
- Use structure in preconditioners
 - ▶ Use nonsmooth Newton methods to formulate complementarity problem
 - ▶ Solve each “Newton” system using GMRES
 - ▶ Precondition using “individual optimization” with fixed externalities



Additional techniques requiring extensive computation

- Continuous distributions, sampling functions, density estimation
- Chance constraints: $Prob(T_i x + W_i y_i \geq h_i) \geq 1 - \alpha$ - can reformulate as MIP and adapt cuts (Luedtke) **empinfo: chance E1 E2 0.95**
- Use of discrete variables (in submodels) to capture logical or discrete choices (logmip - Grossmann et al)
- Robust or stochastic programming
- Decomposition approaches to exploit underlying structure identified by EMP
- Nonsmooth penalties and reformulation approaches to recast problems for existing or new solution methods (ENLP)
- Conic or semidefinite programs - alternative reformulations that capture features in a manner amenable to global computation

Conclusions

- Optimization helps understand what drives a system
- Modern optimization within applications requires multiple model formats, computational tools and sophisticated solvers
- EMP model type is clear and extensible, additional structure available to solver
- Extended Mathematical Programming available within the GAMS modeling system
- Uncertainty is present everywhere (the world is not “normal”)
- We need not only to quantify it, but we need to hedge/control/ameliorate it
- Modeling, optimization, and computation embedded within the application domain is critical

Stochastic competing agent models (F./Wets)

- Competing agents (consumers, or generators in energy market)
- Each agent minimizes objective independently (cost)
- Market prices are function of all agents activities
- Additional twist: model must “hedge” against uncertainty
- Facilitated by allowing contracts bought now, for goods delivered later
- Conceptually allows to transfer goods from one period to another (provides wealth retention or pricing of ancillary services in energy market)
- Can investigate new instruments to mitigate risk, or move to system optimal solutions from equilibrium (or market) solutions

Example as MOPEC: agents solve a Stochastic Program

Each agent minimizes:

$$u_a = (\kappa - f(q_{a,0,*}))^2 + \sum_s \pi_s (\kappa - f(q_{a,s,*}))^2$$

Budget time 0: $\sum_i p_{0,i} q_{a,0,i} + \sum_j v_j y_{a,j} \leq \sum_i p_{0,i} e_{a,0,i}$

Budget time 1: $\sum_i p_{s,i} q_{a,s,i} \leq \sum_i p_{s,i} \sum_j D_{s,i,j} y_{a,j} + \sum_i p_{s,i} e_{a,s,i}$

Additional constraints (complementarity) outside of control of agents:

$$\text{(contract)} \quad 0 \leq - \sum_a y_{a,j} \perp v_j \geq 0$$

$$\text{(walras)} \quad 0 \leq - \sum_a d_{a,s,i} \perp p_{s,i} \geq 0$$