

#### Counting in Prolog

Rules that involve counting often use the **is** predicate to evaluate a numeric value.

Consider the relation len(L,N) that is true if the length of list L is N.

```
len([],0).
len([_|T],N) :-
    len(T,M), N is M+1.
| ?- len([1,2,3],X).
X = 3
| ?- len(Y,2).
Y = [_10903,_10905]
The symbols 10903 and 1
```

The symbols \_10903 and \_10905 are "internal variables" created as needed when a particular value is not forced in a solution.

# DEBUGGING PROLOG

Care is required in developing and testing Prolog programs because the language is untyped; undeclared predicates or relations are simply treated as false.

Thus in a definition like

adj([A,B|\_]) :- A=B. adj([\_,B|T]) :- adk([B|T]). | ?- adj([1,2,2]).

no

(Some Prolog systems warn when an undefined relation is referenced, but many others don't).

```
Similarly, given
 member(A, [A | ]).
 member(A,[_|T]) :-
  member(A,[T]).
| ?- member(2, [1, 2]).
Infinite recursion! (Why?)
If you're not sure what is going
on, Prolog's trace feature is very
handy.
The command
trace.
turns on tracing. (notrace turns
tracing off).
Hence
?- trace.
yes
[trace]
?- member(2,[1,2]).
```

```
(1) 0 Call: member(2,[1,2]) ?
   (1) 1 Head [1->2]:
member(2,[1,2]) ?
   (1) 1 Head [2]:
member(2,[1,2]) ?
   (2) 1 Call: member(2,[[2]]) ?
   (2) 2 Head [1->2]:
member(2,[[2]]) ?
   (2) 2 Head [2]:
member(2,[[2]]) ?
   (3) 2 Call: member(2,[[]]) ?
   (3) 3 Head [1->2]:
member(2,[[]]) ?
   (3) 3 Head [2]: member(2,[[]])
?
   (4) 3 Call: member(2,[[]]) ?
   (4) 4 Head [1->2]:
member(2,[[]]) ?
   (4) 4 Head [2]: member(2,[[]])
?
   (5) 4 Call: member(2,[[]]) ?
```

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## TERMINATION ISSUES IN PROLOG

Searching infinite domains (like integers) can lead to nontermination, with Prolog trying every value. Consider odd(1). odd(N) :- odd(M), N is M+2. | ?- odd(X). X = 1 ; X = 3 ;

```
x = 5 ;
```

```
x = 7
```

#### A query

| ?- odd(X), X=2.

going into an *infinite* search, generating each and every odd integer and finding none is equal to 2!

The obvious alternative,

odd(2) (which is equivalent to

**x=2, odd(x)**) also does an infinite, but fruitless search. We'll soon learn that Prolog does have a mechanism to "cut off" fruitless searches.

```
Definition Order can Matter
Ideally, the order of definition of
facts and rules should not matter.
But,
in practice definition order can
matter. A good general guideline
is to define facts before rules. To
see why, consider a very complete
database of motherOf relations
that goes back as far as
motherOf(cain, eve).
Now we define
isMortal(X) :=
isMortal(Y), motherOf(X,Y).
isMortal(eve).
```

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These definitions state that the first woman was mortal, and all individuals descended from her are also mortal. But when we try as trivial a quer

But when we try as trivial a query as

?- isMortal(eve).

we go into an infinite search! Why?

Let's trace what Prolog does when it sees

?- isMortal(eve).

It matches with the first definition involving **isMortal**, which is **isMortal**(**x**) :-

isMortal(Y), motherOf(X,Y).

It sets X=eve and tries to solve isMortal(Y), motherOf(eve,Y). It will then expand isMortal(Y) into

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isMortal(Z), motherOf(Y,Z). An infinite expansion ensues. The solution is simple—place the "base case" fact that terminates recursion first. If we use isMortal(eve). isMortal(X) :isMortal(Y), motherOf(X,Y). yes | ?isMortal(eve). yes But now another problem appears! If we ask ?- isMortal(clarkKent). we go into another infinite search! Why? The problem is that Clark Kent is from the planet Krypton, and

hence won't appear in our **motherOf** database.

Let's trace the query.

It doesn't match

isMortal(eve).

We next try

isMortal(clarkKent) : isMortal(Y),
 motherOf(clarkKent,Y).

We try **y=eve**, but **eve** isn't Clark's mother. So we recurse, getting:

isMortal(Z), motherOf(Y,Z),
motherOf(clarkKent,Y).

But **eve** isn't Clark's grandmother either! So we keep going further back, trying to find a chain of descendents that leads from **eve** to **clarkKent**. No such chain exists, and there is no limit to how long a chain Prolog will try.

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There is a solution though! We simply rewrite our recursive definition to be

# isMortal(X) : motherOf(X,Y),isMortal(Y).

This is logically the same, but now we work from the individual **x** back toward **eve**, rather than from **eve** toward **x**. Since we have no **motherOf** relation involving **clarkKent**, we immediately stop our search and answer **no**!

#### Extra-logical Aspects of Prolog

To make a Prolog program more efficient, or to represent negative information, Prolog needs features that have a procedural flavor. These constructs are called "extra-logical" because they go beyond Prolog's core of logicbased inference.

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## Тне Сит

The most commonly used extralogical feature of Prolog is the "cut symbol," "!"

A ! in a goal, fact or rule "cuts off" backtracking.

In particular, once a **!** is reached (and automatically matched), we may *not backtrack* across it. The rule we've selected and the bindings we've already selected are "locked in" or "frozen."

For example, given

x(A) := y(A,B), z(B), !, v(B,C).once the ! is hit we can't backtrack to resatisfy y(A,B) or z(B) in some other way. We are locked into this rule, with the bindings of A and B already in place. We *can* backtrack to try various solutions to **v(B,C)**.

It is sometimes useful to have several 1's in a rule. This allows us to find a partial solution, lock it in, find a further solution, then lock it in, etc.

For example, in a rule

**a**(**x**) - **b**(**x**), !, **c**(**x**,**y**), !, **d**(**y**). we first try to satisfy **b**(**x**), perhaps trying several facts or rules that define the **b** relation. Once we have a solution to **b**(**x**), we lock it in, along with the binding for **x**.

Then we try to satisfy  $c(\mathbf{X}, \mathbf{Y})$ , using the fixed binding for  $\mathbf{X}$ , but perhaps trying several bindings for  $\mathbf{Y}$  until  $c(\mathbf{X}, \mathbf{Y})$  is satisfied. We then lock in this match using another  $\mathbf{I}$ .

Finally we check if  $\mathbf{d}(\mathbf{y})$  can be satisfied with the binding of  $\mathbf{y}$  already selected and locked in.

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## WHEN ARE CUTS NEEDED?

A cut can be useful in improving efficiency, by forcing Prolog to avoid useless or redundant searches.

Consider a query like

member(X,list1),
 member(X,list2), isPrime(X).

This asks Prolog to find an **x** that is in **list1** and also in **list2** and also is prime.

**x** will be bound, in sequence, to each value in **list1**. We then check if **x** is also in **list2**, and then check if **x** is prime.

Assume we find **x=8** is in **list1** and **list2**. **isPrime(8)** fails (of course). We backtrack to **member(X,list2)** and resatisfy it with the same value of **x**.

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But clearly there is *never* any point in trying to resatisfy **member(X,list2)**. Once we know a value of **x** is in **list2**, we test it using **isPrime(X)**. If it fails, we want to go right back to **member(X,list1)** and get a different **x**.

To create a version of member that never backtracks once it has been satisfied we can use !.

```
We define
```

```
member1(X,[X|_]) :- !.
member1(X,[_|Y]) :-
member1(X,Y).
Our query is now
member(X,list1),
member1(X,list2), isPrime(X).
(Why isn't member1 used in both
terms?)
```

#### Expressing Negative Information

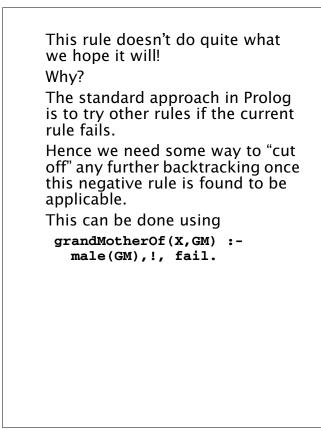
Sometimes it is useful to state rules about what *can't* be true. This allows us to avoid long and fruitless searches.

**fail** is a goal that always fails. It can be used to represent goals or results that can never be true.

Assume we want to optimize our **grandMotherOf** rules by stating that a male can never be anyone's grandmother (and hence a complete search of all **motherOf** and **fatherOf** relations is useless).

A rule to do this is

grandMotherOf(X,GM) : male(GM), fail.



#### Other Extra-Logical Operators

assert and retract

These operators allow a Prolog program to add new rules during execution and (perhaps) later remove them. This allows programs to learn as they execute.

#### •findall

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Called as findall(x,goal,List) where x is a variable in goal. All possible solutions for x that satisfy goal are found and placed in List.

For example, findall(x, (append(\_,[X|\_],[-1,2,-3,4]),(X<0)), L). L = [-1,-3]

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• **var** and **nonvar** 

var(X) tests whether X is
unbound (free).

**nonvar(Y)** tests whether **Y** is *bound* (no longer free).

These two operators are useful in tailoring rules to particular combinations of bound and unbound variables. For example,

grandMotherOf(X,GM) : male(GM),!, fail.

might backfire if **GM** is not yet bound. We could set **GM** to a person for whom **male(GM)** is true, then fail because we don't want grandmothers who are male!

To remedy this problem. we use the rule only when **GM** is bound. Our rule becomes

grandMotherOf(X,GM) : nonvar(GM), male(GM),!, fail.

#### An Example of Extra-Logical Programming

Factorial is a very common example program. It's well known, and easy to code in most languages.

In Prolog the "obvious" solution is:

fact(N,1) := N = < 1.

fact(N,F) :- N > 1, M is N-1,
 fact(M,G), F is N\*G.

This definition is certainly correct. It mimics the usual recursive solution.

But,

in Prolog "inputs" and "outputs" are less distinct than in most languages.

In fact, we can envision 4 different combinations of inputs

and outputs, based on what is Our solution works for fixed (and thus an input) and what is free (and hence is to be computed): 1. **N** and **F** are both ground (fixed). We simply must decide if F=N! 2. **N** is ground and **F** is free. This is how **fact** is usually used. We must compute an  $\mathbf{F}$  such that F=N!3. **F** is fixed and **N** is free. This is is around: an uncommon usage. We must fact(1,1). find an **\mathbf{N}** such that F=N!, or determine that no such **n** is possible. 4. Both **n** and **F** are free. We generate, in sequence, pairs of  $\mathbf{N}$ case of **N=1**. and  $\mathbf{r}$  values such that F=N! of **N<1**. CS 538 Spring 2008 CS 538 Spring 2008 472

The third rule handles the case of **N** >1. The value of **F** is computed recursively. The first ! in each of these rules forces that rule to be the *only one* used for the values of **n** that match. Moreover, the second ! in the third rule states that after  $\mathbf{F}$  is computed, further backtracking is useless; there is only one  $\mathbf{F}$  value for any given  $\mathbf{N}$ value.

To handle the case where  $\mathbf{F}$  is bound and  $\mathbf{N}$  is free, we use

fact(N,F) :- nonvar(F), !, fact(M,G), N is M+1, F2 is N\*G,  $F = \langle F2, !, F = F2.$ 

In this rule we generate **N**, **F**2 pairs until  $F2 \rightarrow = F$ . Then we check if **F=F2**. If this is so, we have the  $\mathbf{N}$  we want. Otherwise. no such **n** can exist and we fail (and answer no).

combinations 1 and 2 (where  $\mathbf{N}$  is fixed), but not combinations 3 and 4. (The problem is that  $\mathbf{N} = <$ 1 and N > 1 can't be satisfied when **n** is free). We'll need to use **nonvar** and **!** to form a solution that works for all 4 combinations of inputs. We first handle the case where **n** 

fact(N,1) := nonvar(N), N = < 1, !.fact(N,F) :- nonvar(N), N > 1, !, M is N-1, fact(M,G), F is N\*G, !. The first rule handles the base

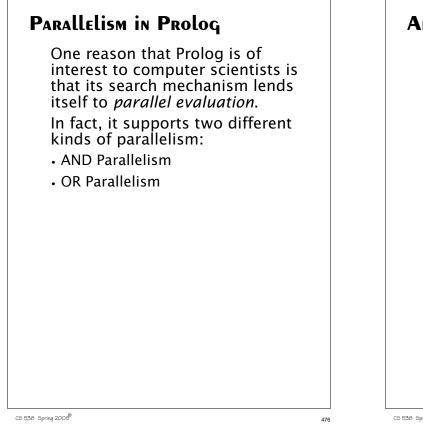
The second rule handles the case

For the case where both  $\mathbf{N}$  and  $\mathbf{F}$ are free we use:

fact(N,F) :- fact(M,G), N is M+1, F is N\*G.

This systematically generates **N**, **F** pairs, starting with N=2, F=2 and then recursively building successor values (**N=3**, **F=6**, then **N=4**, **F=24**, etc.)

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## And PARAllelism

When we have a goal that contains subgoals connected by the "," (And) operator, we may be able to utilize "and parallelism." Rather than solve subgoals in sequence, we may be able to solve them in parallel *if* bindings can be properly propagated. Thus in

a(X), b(X,Y), c(X,Z), d(Y,Z).

we may be able to first solve **a**(**x**), binding **x**, then solve  $\mathbf{b}(\mathbf{x}, \mathbf{y})$  and  $\mathbf{c}(\mathbf{x}, \mathbf{z})$  in parallel, binding  $\mathbf{y}$  and  $\mathbf{z}$ , then finally solve d(Y,Z).

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An example of this sort of and parallelism is member(X,list1), member1(X,list2), isPrime(X). Here we can let member(X, list1) select an **x** value, then test member1(X,list2) and **isPrime**(**x**) in parallel. If one or the other fails, we just select another **x** from **list1** and retest member1(X,list2) and **isPrime(X)** in parallel.

#### **OR PARALLELISM**

When we match a goal we almost always have a choice of several rules or facts that may be applicable. Rather than try them in sequence, we can try several matches of different facts or rules in parallel. This is "or parallelism." Thus given

a(X) := b(X).

a(Y) := c(Y).

when we try to solve

a(10).

we can simultaneously check both **b(10)** and **c(10)**.

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```
Recall our definition of
member(X,L) :-
 append(P,[X|S],L).
where append is defined as
append([],L,L).
append([X|L1],L2,[X|L3]) :-
 append(L1,L2,L3).
Assume we have the query
? member(2,[1,2,3]).
This immediately simplifies to
append(P,[2|S],[1,2,3]).
Now there are two append
definitions we can try in parallel:
(1) match append (P, [2|S], [1,2,3])
with append([],L,L). This
requires that [2|s] = [1, 2, 3],
which must fail.
(2) match
append(P,[2|S],[1,2,3]) With
append([X|L1],L2,[X,L3]).
```

This requires that P=[x|L1], [2|S]=L2, [1,2,3]=[X,L3].Simplifying, we require that **x=1**, P = [1|L1], L3 = [2,3].Moreover we must solve append(L1,L2,L3) which simplifies to append(L1, [2|S], [2,3]).We can match this call to **append** in two different ways, so or parallelism can be used again. When we try matching append(L1, [2|S], [2,3]) against append([],L,L) We get [2|s] = [2,3], which is satisfiable if **s** is bound to **131**. We therefore signal back that the guery is true.

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#### **Speculative Parallelism**

Prolog also lends itself nicely to *speculative* parallelism. In this form of parallelism, we "guess" or speculate that some computation *may* be needed in the future and start it early. This speculative computation can often be done in parallel with the main (non-speculative) computation.

Recall our example of

```
member(X,list1),
member1(X,list2), isPrime(X).
```

After member(X, list1) has generated a preliminary solution for x, it is tested (perhaps in parallel) by member1(X, list2) and isPrime(X).

But this value of  $\mathbf{x}$  may be rejected by one or both of these

tests. If it is, we'll ask member (X, list1) to find a new binding for x. If we wish, this next binding can be generated *speculatively*, while the current value of x is being tested. In this way if the current value of x is rejected, we'll have a new value ready to try (or know that no other binding of x is possible).

If the current value of **x** is accepted, the extra speculative work we did is ignored. It wasn't needed, but was useful insurance in case further **x** bindings were needed.

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