Manifold-valued Dirichlet Processes

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http://pages.cs.wisc.edu/~hwkim/projects/dp-mglm/



Regression

 $f: \mathbf{R}^d \to \mathcal{M}$

 $\mathcal{M} = \mathrm{SPD}(n)$



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 $\mathcal{M} = \mathrm{SPD}(n)$

- Covariance matrix
- Diffusion tensor imaging



Regression

 $f: \mathbf{R}^d \to \mathcal{M}$

 $\mathcal{M} = \mathrm{SPD}(n)$

- Covariance matrix
- Diffusion tensor imaging
- Region covariance



M.Cimpoi et al., CVPR 2014

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Linear regression on manifolds

$$f: R \to \mathcal{M} \quad y_i = \operatorname{EXP}(\operatorname{EXP}(B, vx_i), \epsilon)$$

$$\mathsf{GR} \quad \mathsf{Fletcher, IJCV 2013.}$$

$$f: R^n \to \mathcal{M} \quad y_i = \operatorname{EXP}(\operatorname{EXP}(B, \sum_{j=1}^d V^j x_i^j), \epsilon)$$

$$\mathsf{MGLM} \quad \mathsf{Kim \ et \ al., CVPR \ 2014.}$$

$$\mathsf{IR} \quad \mathsf{Thu \ et \ al., JASA, 2009.}$$

Build models on manifolds

Locally defined parametric models PGA (Fletcher et al., 2004), GR (Fletcher, IJCV 2013), MGLM (Kim et al., CVPR 2014), RCCA (Kim et al., ECCV 2014)



General Linear Model

$$\boldsymbol{y}_i = \boldsymbol{\beta}^0 + \boldsymbol{\beta}^1 x_i^1 + \ldots + \boldsymbol{\beta}^d x_i^d + \boldsymbol{\epsilon}$$

What if data have nonlinear correlation?

General Linear Model

$$\boldsymbol{y}_i = \boldsymbol{\beta}^0 + \boldsymbol{\beta}^1 x_i^1 + \ldots + \boldsymbol{\beta}^d x_i^d + \boldsymbol{\epsilon}$$

- Generalized Linear Model (fixed link function) $y_i = g^{-1}(\beta^0 + \beta^1 x_i^1 + \ldots + \beta^d x_i^d) + \epsilon$
- Single Index Model (searching link function) $\boldsymbol{y}_i = g^{-1}(\beta^0 + \beta^1 x_i^1 + \ldots + \beta^d x_i^d) + \epsilon$

General Linear Model

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- Single Index Model (searching link function) $\boldsymbol{y}_i = g^{-1}(\beta^0 + \beta^1 x_i^1 + \ldots + \beta^d x_i^d) + \epsilon$

Link functions for manifold-valued response?

• GLM

$$\boldsymbol{y}_i = \boldsymbol{\beta}^0 + \boldsymbol{\beta}^1 x_i^1 + \ldots + \boldsymbol{\beta}^d x_i^d + \boldsymbol{\epsilon}$$

• ?-GLM

 $\boldsymbol{y}_{i} = \boldsymbol{\beta}_{i}^{0} + \boldsymbol{\beta}_{i}^{1} \boldsymbol{x}_{i}^{1} + \ldots + \boldsymbol{\beta}_{i}^{d} \boldsymbol{x}_{i}^{d} + \boldsymbol{\epsilon}$

• GLM

$$\boldsymbol{y}_i = \boldsymbol{\beta}^0 + \boldsymbol{\beta}^1 x_i^1 + \ldots + \boldsymbol{\beta}^d x_i^d + \boldsymbol{\epsilon}$$

• DP-GLM

$$\boldsymbol{y}_{i} = \boldsymbol{\beta}_{i}^{0} + \boldsymbol{\beta}_{i}^{1} \boldsymbol{x}_{i}^{1} + \ldots + \boldsymbol{\beta}_{i}^{d} \boldsymbol{x}_{i}^{d} + \boldsymbol{\epsilon}$$

 $(x_i, y_i)|\theta_i \sim F(\theta_i), \theta_i|G \sim G, G \sim DP(G_0, \nu)$

Hannah et al., JMLR 2011

 $y_i = \text{EXP}(\text{EXP}(B, \sum^d V^j x_i^j), \epsilon)$ j=1



 $y_i = \text{EXP}(\text{EXP}(\underline{B}, \sum_{j=1}^d V^j x_i^j), \epsilon)$



$$y_i = \text{EXP}(\text{EXP}(\underline{B}, \sum_{j=1}^d \underline{V^j} x_i^j), \epsilon)$$



























DP-GLM

$$G \sim DP(G_0, \nu)$$

$$\theta_i = (\theta_{x_i}, \theta_{y_i}) | G \sim G,$$

$$x_i | \theta_{x_i} \sim f_x(\theta_{x_i}),$$

$$y_i | x_i, \theta_{y_i} \sim GLM(x_i, \theta_{y_i}),$$

Hannah et al. JMLR 2011

$$\begin{aligned} & \mathsf{DP}\text{-}\mathsf{GLM} \\ & \mathsf{Manifold-valued?} \\ & y_i \in \mathcal{M} \\ & G \sim DP(G_0, \nu) \\ & \theta_i = (\theta_{x_i}, \theta_{y_i}) | G \sim G, \\ & x_i | \theta_{x_i} \sim f_x(\theta_{x_i}), \\ & y_i | x_i, \theta_{y_i} \sim GLM(x_i, \theta_{y_i}), \end{aligned}$$

Hannah et al. JMLR 2011

$$\begin{split} & \text{DP-MGLM} \\ & G \sim DP(G_0,\nu) \\ & \theta_i = (\theta_{x_i},\theta_{y_i}) | G \sim G, \\ & \text{MGLM on} \\ & x_i | \theta_{x_i} \sim f_x(\theta_{x_i}), \\ & y_i | x_i, \theta_{y_i} \sim MGLM(x_i,\theta_{y_i}) \end{split}$$

DP-MGLM $G \sim DP(G_0, \nu)$ $\theta_i = (\theta_{x_i}, \theta_{y_i}) | G \sim G,$ $x_i|\theta_{x_i} \sim f_x(\theta_{x_i}),$ $\frac{y_i | x_i}{\text{manifold-valued}} \theta_{y_i} \sim MGLM(x_i, \theta_{y_i}),$ parameters? $\theta_{y_i} \in \mathrm{SPD}(n) \times \mathrm{Sym}(n)^d$

DP-MGLM
• Distribution on
manifolds
• Intrinsic metric

$$G \sim DP(G_0, \nu)$$

$$\theta_i = (\theta_{x_i}, \theta_{y_i}) | G \sim G,$$

$$x_i | \theta_{x_i} \sim f_x(\theta_{x_i}),$$

$$y_i | x_i, \theta_{y_i} \sim MGLM(x_i, \theta_{y_i}),$$

$$\theta_{y_i} \in \text{SPD}(n) \times \text{Sym}(n)^d$$

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DP-MGLM

Hamiltonian Monte Carlo (HMC) sampling

$$G \sim DP(G_0, \nu)$$

$$\theta_i = (\theta_{x_i}, \theta_{y_i}) | G \sim G,$$

$$x_i | \theta_{x_i} \sim f_x(\theta_{x_i}),$$

$$y_i | x_i, \theta_{y_i} \sim MGLM(x_i, \theta_{y_i}),$$

$$\theta_{y_i} \in \text{SPD}(n) \times \text{Sym}(n)^d$$

H(q,p) = U(q) + K(p)

Duane, S., et al, "Hybrid Monte Carlo", 1987.

Neal, R. "MCMC using Hamiltonian dynamics", 2011

H(q, p) = U(q) + K(p) $q = \theta \in \mathbf{R}^d$ $p = \dot{\theta} \in \mathbf{R}^d$

Duane, S., et al, "Hybrid Monte Carlo", 1987.

Neal, R. "MCMC using Hamiltonian dynamics", 2011

$$H(q, p) = U(q) + K(p)$$
$$U(q) := -\log f(q)$$
$$K(p) := \frac{1}{2}p^T M^{-1}p$$

Duane, S., et al, "Hybrid Monte Carlo", 1987.

Neal, R. "MCMC using Hamiltonian dynamics", 2011































Experiments



















Clustering result of patch 1







Clustering result of patch 1





3D ellipsoid patch of ICML



3D ellipsoid patch of ICML



Clustering results

Experiment 3 Age versus landmark appearance



Experiment 3 Age versus landmark appearance



Landmarks

Experiment 3 Age versus landmark appearance



Correlation Magnitude

Conclusion

- DP-MGLM (Dirichlet process multivariate general linear model) for Riemannian manifolds (SPD(n)) learns more complicated models than MGLM
- Clustering based on nonlinear correlation between Euclidian covariates and manifold-valued response
- New distribution (over base point and tangent vectors) and HMC algorithm for DP-MGLM on SPD(n).



Thank you!

