### CS731 Spring 2011 Advanced Artificial Intelligence

# Background

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# 1 Probability Measure

A sample space  $\Omega$  is the set of all possible outcomes. Elements  $\omega \in \Omega$  are called sample outcomes, while subsets  $A \subseteq \Omega$  are called events. For example, for a die roll,  $\Omega = \{1, 2, 3, 4, 5, 6\}$ ,  $\omega = 5$  is an outcome,  $A_1 = \{5\}$  is the event that the outcome is 5, and  $A_2 = \{1, 3, 5\}$  is the event that the outcome is odd. Ideally, one would like to be able to assign probabilities to all As. This is trivial for finite  $\Omega$ . However, when  $\Omega = \mathbb{R}$  strange things happen: it is no longer possible to consistently assign probabilities to all subsets of  $\mathbb{R}$ .

Instead, we will restrict ourselves to only some of the events. A  $\sigma$ -algebra  $\mathcal{B}$  is a set of  $\Omega$  subsets satisfying:

- 1.  $\emptyset \in \mathcal{B}$
- 2. if  $A \in \mathcal{B}$  then  $A^c \in \mathcal{B}$  (complementarity)
- 3. if  $A_1, A_2, \ldots \in \mathcal{B}$  then  $\bigcup_{i=1}^{\infty} A_i \in \mathcal{B}$  (countable unions)

The sets in  $\mathcal{B}$  are called *measurable*. The pair  $(\Omega, \mathcal{B})$  is called a *measurable space*. For  $\Omega = \mathbb{R}$ , we take the smallest  $\sigma$ -algebra that contains all the open subsets and call it the *Borel*  $\sigma$ -algebra.

A measure is a function  $P: \mathcal{B} \mapsto \mathbb{R}$  satisfying:

- 1. P(A) > 0 for all  $A \in \mathcal{B}$
- 2. If  $A_1, A_2, \ldots$  are disjoint then  $P(\bigcup_{i=1}^{\infty} A_i) = \sum_{i=1}^{\infty} P(A_i)$

Note these imply  $P(\emptyset) = 0$ . The triple  $(\Omega, \mathcal{B}, P)$  is called a measure space. The Lebesgue measure is a uniform measure over the Borel  $\sigma$ -algebra with the usual meaning of length, area or volume, depending on dimensionality. For example, for  $\mathbb{R}$  the Lebesgue measure of the interval (a, b) is b - a.

A probability measure is a measure satisfying additionally the normalization constraint:

$$3 P(\Omega) = 1.$$

Such a triple  $(\Omega, \mathcal{B}, P)$  is called a *probability space*.

## 2 Random Variables

Let  $(\Omega, \mathcal{B}, P)$  be a probability space. Let  $(\mathbb{R}, \mathcal{R})$  be the usual measurable space of reals and its Borel  $\sigma$ -algebra. A random variable is a function  $X : \Omega \to \mathbb{R}$  such that the preimage of any set  $A \in \mathcal{R}$  is measurable in  $\mathcal{B}: X^{-1}(A) = \{\omega : X(\omega) \in A\} \in \mathcal{B}$ . This allows us to define the following (the first P is the new definition, while the 2nd and 3rd Ps are the already-defined probability measure on  $\mathcal{B}$ ):

$$P(X \in A) = P(X^{-1}(A)) = P(\{\omega : X(\omega) \in A\})$$
(1)

$$P(X = x) = P(X^{-1}(x)) = P(\{\omega : X(\omega) = x\})$$
(2)

**Example 1** Let  $\Omega = \{(x,y) : x^2 + y^2 \le 1\}$  be the unit disk. Consider drawing a point at random from  $\Omega$ . The outcome is of the form  $\omega = (x,y)$ . Some example random variables are  $X(\omega) = x, Y(\omega) = y, Z(\omega) = xy$ , and  $W(\omega) = \sqrt{x^2 + y^2}$ .

**Example 2** Let  $X = \omega$  be a uniform random variable (to be defined later) with the sample space  $\Omega = [0, 1]$ . A sequence of different random variables  $\{X_n\}_{n=1}^{\infty}$  can be defined as follows, where  $1\{z\}=1$  if z is true, and 0 otherwise:

$$X_1(\omega) = \omega + 1\{\omega \in [0,1]\} \tag{3}$$

$$X_2(\omega) = \omega + 1\{\omega \in [0, \frac{1}{2}]\}$$
 (4)

$$X_3(\omega) = \omega + 1\{\omega \in [\frac{1}{2}, 1]\}$$
 (5)

$$X_4(\omega) = \omega + 1\{\omega \in [0, \frac{1}{3}]\}$$
 (6)

$$X_5(\omega) = \omega + 1\{\omega \in [\frac{1}{3}, \frac{2}{3}]\}$$
 (7)

$$X_6(\omega) = \omega + 1\{\omega \in \left[\frac{2}{3}, 1\right]\}\tag{8}$$

Given a random variable X, the cumulative distribution function (CDF) is the function  $F_X: \mathbb{R} \mapsto [0,1]$ 

$$F_X(x) = P(X \le x) = P(X \in (-\infty, x]) = P(\{\omega : X(\omega) \in (-\infty, x]\}).$$
 (9)

A random variable X is discrete if it takes countably many values. We define the probability mass function  $f_X(x) = P(X = x)$ .

A random variable X is continuous if there exists a function  $f_X$  such that

- 1.  $f_X(x) \geq 0$  for all  $x \in \mathbb{R}$
- $2. \int_{-\infty}^{\infty} f_X(x) dx = 1$
- 3. for every  $a \leq b$ ,  $P(X \in [a,b]) = \int_a^b f_X(x) dx$ .

The function  $f_X$  is called the probability density function (PDF) of X. CDF and PDF are related by

$$F_X(x) = \int_{-\infty}^x f_X(t)dt \tag{10}$$

$$f_X(x) = F'_X(x)$$
 at all points  $x$  at which  $F_X$  is differentiable. (11)

#### Some Random Variables 3

### Discrete

**Dirac** or point mass distribution  $X \sim \delta_a$  if P(X = a) = 1 with CDF F(x) = 0 if x < a and 1 if  $x \ge a$ .

**Binomial.** A random variable X has a binomial distribution with parameters n (number of trials) and p (head probability)  $X \sim \text{Binomial}(n, p)$  with probability mass function

$$f(x) = \begin{cases} \binom{n}{x} p^x (1-p)^{n-x} & \text{for } x = 0, 1, \dots, n \\ 0 & \text{otherwise} \end{cases}$$
 (12)

If  $X_1 \sim \text{Binomial}(n_1, p)$  and  $X_2 \sim \text{Binomial}(n_2, p)$  then  $X_1 + X_2 \sim \text{Binomial}(n_1 + n_2, p)$ . Think this as merging two coin flip experiments on the same coin.

**Bernoulli**. Binomial with n = 1.

**Multinomial.** The d-dimensional version of binomial. The parameter  $p = (p_1, \ldots, p_d)^{\top}$  is now the probabilities of a d-sided die, and  $x = (x_1, \ldots, x_d)^{\top}$  is the counts of each face.

$$f(x) = \begin{cases} \binom{n}{x_1, \dots, x_d} \prod_{k=1}^d p_k^{x_k} & \text{if } \sum_{k=1}^d x_k = n \\ 0 & \text{otherwise} \end{cases}$$
 (13)

**Poisson**.  $X \sim \text{Poisson}(\lambda)$  if  $f(x) = e^{-\lambda} \frac{\lambda^x}{x!}$  for  $x = 0, 1, 2, \dots$  If  $X_1 \sim \text{Poisson}(\lambda_1)$  and  $X_2 \sim \text{Poisson}(\lambda_2)$  then  $X_1 + X_2 \sim \text{Poisson}(\lambda_1 + \lambda_2)$ .

**Geometric.**  $X \sim \widetilde{\text{Geom}}(p)$  if  $f(x) = p(1-p)^{x-1}$  for x = 1, 2, ...

### 3.2 Continuous

Gaussian (also called Normal distribution).  $X \sim N(\mu, \sigma^2)$  with parameters  $\mu \in \mathbb{R}$  (the mean) and  $\sigma^2$  (the variance) if

$$f(x) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left(-\frac{(x-\mu)^2}{2\sigma^2}\right). \tag{14}$$

The square root of variance  $\sigma > 0$  is called the standard deviation. If  $\mu = 0, \sigma = 1, X$  has a standard normal distribution. In this case, X is usually written as Z. Some useful properties:

- (Scaling) If  $X \sim N(\mu, \sigma^2)$ , then  $Z = (X \mu)/\sigma \sim N(0, 1)$
- (Independent sum) If  $X_i \sim N(\mu_i, \sigma_i^2)$  are independent, then  $\sum_i X_i \sim N\left(\sum_i \mu_i, \sum_i \sigma_i^2\right)$

 $\chi^2$  distribution. If  $Z_1, \ldots, Z_k$  are independent standard normal random variables, then  $Y = \sum_i^k Z_i^2$  has a  $\chi^2$  distribution with k degrees of freedom. If  $X_i \sim N(\mu_i, \sigma_i^2)$  are independent, then  $\sum_i \left(\frac{X_i - \mu_i}{\sigma_i}\right)^2$  has a  $\chi^2$  distribution with k degrees of freedom. The PDF for the  $\chi^2$  distribution with k degrees of freedom is

$$f(x) = \frac{1}{2^{k/2}\Gamma(k/2)} x^{k/2-1} e^{-x/2}, \ x > 0.$$
 (15)

**Multivariate Gaussian.** Let  $x, \mu \in \mathbb{R}^d$ ,  $\Sigma \in S^d_+$  a symmetric, positive definite matrix of size  $d \times d$ . Then  $X \sim N(\mu, \Sigma)$  with PDF

$$f(x) = \frac{1}{|\Sigma|^{1/2} (2\pi)^{d/2}} \exp\left(-\frac{1}{2} (x - \mu)^{\top} \Sigma^{-1} (x - \mu)\right).$$
 (16)

Here,  $\mu$  is the mean vector,  $\Sigma$  is the covariance matrix,  $|\Sigma|$  its determinant, and  $\Sigma^{-1}$  its inverse (exists because  $\Sigma$  is positive definite).

If we have two (groups of) variables that are jointly Gaussian:

then we have:

- (Marginal)  $x \sim N(\mu_x, A)$
- (Conditional)  $y|x \sim N(\mu_y + C^{\top}A^{-1}(x \mu_x), B C^{\top}A^{-1}C)$

**Exponential.**  $X \sim \text{Exp}(\beta)$  with parameter  $\beta > 0$ , if  $f(x) = \frac{1}{\beta}e^{-x/\beta}$ .

**Gamma**. The Gamma function (not distribution) is defined as  $\Gamma(\alpha) = \int_0^\infty y^{\alpha-1} e^{-y} dy$  with  $\alpha > 0$ . The Gamma function is an extension to the factorial function:  $\Gamma(n) = (n-1)!$  when n is a positive integer. It

also satisfies  $\Gamma(\alpha+1) = \alpha\Gamma(\alpha)$  for  $\alpha > 0$ . X has a Gamma distribution with shape parameter  $\alpha > 0$  and scale parameter  $\beta > 0$ , denoted by  $X \sim \text{Gamma}(\alpha, \beta)$ , if

$$f(x) = \frac{1}{\beta^{\alpha} \Gamma(\alpha)} x^{\alpha - 1} e^{-x/\beta}, \ x > 0.$$
(18)

 $Gamma(1, \beta)$  is the same as  $Exp(\beta)$ .

**Beta**.  $X \sim \text{Beta}(\alpha, \beta)$  with parameters  $\alpha, \beta > 0$ , if

$$f(x) = \frac{\Gamma(\alpha + \beta)}{\Gamma(\alpha)\Gamma(\beta)} x^{\alpha - 1} (1 - x)^{\beta - 1}, \ x \in (0, 1).$$

$$\tag{19}$$

Beta(1,1) is uniform in [0,1]. Beta( $\alpha < 1, \beta < 1$ ) has a U-shape. Beta( $\alpha > 1, \beta > 1$ ) is unimodal with mean  $\alpha/(\alpha+\beta)$  and mode  $(\alpha-1)/(\alpha+\beta-2)$ .

**Dirichlet.** The Dirichlet distribution is the multivariate version of the beta distribution.  $X \sim \text{Dir}(\alpha_1, \dots, \alpha_d)$  with parameters  $\alpha_i > 0$ , if

$$f(x) = \frac{\Gamma(\sum_{i}^{d} \alpha_{i})}{\prod_{i}^{d} \Gamma(\alpha_{i})} \prod_{i}^{d} x_{i}^{\alpha_{i}-1}, \tag{20}$$

where  $x = (x_1, \dots, x_d)$  with  $x_i > 0, \sum_i^d x_i = 1$ . This support is called the open (d-1) dimensional simplex. t (or Student's t) Distribution  $X \sim t_{\nu}$  has a t distribution with  $\nu$  degrees of freedom, if

$$f(x) = \frac{\Gamma\left(\frac{\nu+1}{2}\right)}{\sqrt{\nu\pi}\Gamma\left(\frac{\nu}{2}\right)} \left(1 + \frac{x^2}{\nu}\right)^{-(\nu+1)/2} \tag{21}$$

It is similar to a Gaussian distribution, but with heavier tails (more likely to produce extreme values). When  $\nu = \infty$ , it becomes a standard Gaussian distribution.

Cauchy. The Cauchy distribution is a special case of t-distribution with  $\nu=1$ . The PDF is

$$f(x) = \frac{1}{\pi \gamma \left(1 + \left(\frac{x - x_0}{\gamma}\right)^2\right)} \tag{22}$$

where  $x_0$  is the location parameter for the mode, and  $\gamma$  is the scale parameter. It is notable for the lack of mean:  $\mathbb{E}(X)$  does not exist because  $\int_x |x| dF_X(x) = \infty$ . Similarly, it has no variance or higher moments. However, the mode and median are both  $x_0$ .

# 4 Convergence of Random Variables

Let  $X_1, X_2, ..., X_n, ...$  be a sequence of random variables, and X be another random variable.  $X_n$  converges to X in distribution, written  $X_n \rightsquigarrow X$ , if

$$\lim_{n \to \infty} F_{X_n}(t) = F(t) \tag{23}$$

at all t where F is continuous. Here,  $F_{X_n}$  is the CDF of  $X_n$ , and F is the CDF of X. We expect to see the next outcome in a sequence of random experiments becoming better and better modeled by the probability distribution of X. In other words, the probability for  $X_n$  to be in a given interval is approximately equal to the probability for X to be in the same interval, as n grows.

**Example 3** Let  $X_1, ..., X_n$  be iid continuous random variables. Then trivially  $X_n \rightsquigarrow X_1$ . But note  $P(X_1 = X_n) = 0$ .

**Example 4** Let  $X_2, ..., X_n$  be identical (but not independent) copies of  $X_1 \sim N(0,1)$ . Then  $X_n \rightsquigarrow Y = -X_1$ .

**Example 5** Let  $X_n \sim \text{uniform}[0, 1/n]$ . Then  $X_n \leadsto \delta_0$ . This is often written as  $X_n \leadsto 0$ .

**Example 6** Let  $X_n$  has the PDF  $f_n(x) = (1 - \cos(2\pi nx)), x \in (0,1)$ . Then  $X_n \leadsto \text{uniform}(0,1)$ .

**Theorem 1** (The Central Limit Theorem). Let  $X_1, \ldots, X_n$  be iid with finite mean  $\mu$  and finite variance  $\sigma^2 > 0$ . Let  $\bar{X}_n = \frac{1}{n} \sum_{i=1}^n X_i$ . Then

$$Z_n = \frac{\bar{X}_n - \mu}{\sigma/\sqrt{n}} \rightsquigarrow N(0, 1). \tag{24}$$

Example 7 Let  $X_i \sim \text{uniform}(-1,1)$  for  $i=1,\ldots$  Note  $\mu=0,\sigma^2=1/3$ . Then  $Z_n=\sqrt{\frac{3}{n}}\sum_i X_i \rightsquigarrow N(0,1)$ .

**Example 8** Let  $X_i \sim \text{beta}(\frac{1}{2}, \frac{1}{2})$ . Note  $\mu = \frac{1}{2}, \sigma^2 = \frac{1}{8}$ . Then  $Z_n = \sqrt{8n} \left( \frac{1}{n} \sum_i X_i - 1/2 \right) \rightsquigarrow N(0, 1)$ .

 $X_n$  converges to X in probability, written  $X_n \stackrel{P}{\rightarrow} X$ , if for any  $\epsilon > 0$ 

$$\lim_{n \to \infty} P(|X_n - X| > \epsilon) = 0. \tag{25}$$

Convergence in probability implies convergence in distribution. The reverse is not true in general. However, convergence in distribution to a point mass distribution implies convergence in probability.

Example 9 Example 2 converges in probability to X there.

 $X_n$  converges almost surely to X, written  $X_n \stackrel{as}{\to} X$ , if

$$P\left(\left\{\omega: \lim_{n \to \infty} X_n(\omega) = X(\omega)\right\}\right) = 1 \tag{26}$$

**Example 10** Example 2 does not converge almost surely to X there. This is because  $\lim_{n\to\infty} X_n(\omega)$  does not exist for any  $\omega$ . Pointwise convergence is central to  $\stackrel{as}{\to}$ .

 $\stackrel{as}{\rightarrow}$  implies  $\stackrel{P}{\rightarrow}$ , which in turn implies  $\leadsto$ .

**Example 11**  $X_n \stackrel{as}{\to} 0$  (and hence  $X_n \stackrel{P}{\to} 0$  and  $X_n \leadsto 0$ ) does not imply convergence in expectation  $\mathbb{E}(X_n) \to 0$ . To see this, let

$$P(X_n) = \begin{cases} 1/n, & \text{if } X_n = n^2 \\ 1 - 1/n, & \text{if } X_n = 0 \end{cases}$$
 (27)

Then  $X_n \stackrel{as}{\to} 0$ . However,  $\mathbb{E}(X_n) = \frac{1}{n}n^2 = n$  does not converge.

 $X_n$  converges in rth mean where  $r \ge 1$ , written as  $X_n \xrightarrow{L'} X$ , if

$$\lim_{n \to \infty} \mathbb{E}(|X_n - X|^r) = 0. \tag{28}$$

 $\stackrel{L^r}{\rightarrow}$  implies  $\stackrel{P}{\rightarrow}$ .

**Theorem 2** (The Weak Law of Large Numbers). If  $X_1, \ldots, X_n$  are iid, then  $\bar{X}_n = \frac{1}{n} \sum_{i=1}^n X_i \xrightarrow{P} \mu(X_1)$ .

**Theorem 3** (The Strong Law of Large Numbers). If  $X_1, \ldots, X_n$  are iid, and  $E(|X_1|) < \infty$ , then  $\bar{X}_n = \frac{1}{n} \sum_{i=1}^n X_i \stackrel{as}{\to} \mu(X_1)$ .