

Nonparametric Density Estimation and Regression

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The methods in this lecture are nonparametric.

1 Kernel Density Estimation

Let f be a probability density function. Given $x_1 \dots x_n \sim f$, the goal is to estimate f .

Let us introduce the concept of *smoothing kernel*, not to be confused with the Mercer kernels used in the Reproducing Kernel Hilbert Space sense. A smoothing kernel K is any smooth function satisfying

$$K(x) \geq 0 \tag{1}$$

$$\int K(x)dx = 1 \tag{2}$$

$$\int xK(x)dx = 0. \tag{3}$$

Some common smoothing kernels are

- The Gaussian kernel $K(x) = \frac{1}{\sqrt{2\pi}} \exp(-x^2/2)$
- The Epanechnikov kernel $K(x) = \frac{3}{4}(1 - x^2)$, $x \in [-1, 1]$, 0 otherwise

Given a kernel K and a positive *bandwidth* h , the *kernel density estimator* is defined to be

$$\hat{f}_n(x) = \frac{1}{n} \sum_{i=1}^n \frac{1}{h} K\left(\frac{x - x_i}{h}\right) \tag{4}$$

where the subscript n in $\hat{f}_n(x)$ denotes the training sample size. The intuition is to put a little bump on each training point and sum them up. It turns out that the choice of K is not crucial, but the choice of h is important. In general, we let the bandwidth depend on sample size with the notation h_n .

Theorem 1 Assume that f is continuous at x , $h_n \rightarrow 0$, and $nh_n \rightarrow \infty$ as $n \rightarrow \infty$. Then $\hat{f}_n(x) \xrightarrow{P} f(x)$.

Notice that $\hat{f}_n(x)$ is a random variable. Let $R_x = \mathbb{E}(\hat{f}_n(x) - f(x))^2$ be the risk at point x (with squared loss), and $R = \int R_x dx$ be the integrated risk. Then the asymptotically optimal bandwidth is

$$h_n^* = cn^{-1/(4+d)}, \tag{5}$$

and the risk decreases as

$$R = O(n^{-4/(4+d)}), \tag{6}$$

where d is the dimensionality of x . However, the constant c in the optimal bandwidth depends on the unknown density f , rendering this theoretical result useless in practice. One typically find the optimal bandwidth by cross validation, as follows.

We will work with the loss function called the *integrated squared error*

$$L(h) = \int (\hat{f}_n(x) - f(x))^2 dx \quad (7)$$

$$= \int \hat{f}_n^2(x) dx - 2 \int \hat{f}_n(x)f(x) dx + \text{const}(h). \quad (8)$$

Let

$$J(h) = \int \hat{f}_n^2(x) dx - 2 \int \hat{f}_n(x)f(x) dx \quad (9)$$

be the part of the loss that depends on h . The *cross-validation estimator of risk* is

$$\hat{J}(h) = \int \hat{f}_n^2(x) dx - \frac{2}{n} \sum_{i=1}^n \hat{f}_{-i}(x_i) \quad (10)$$

where $\hat{f}_{-i}(x_i)$ is the kernel density estimator obtained on the training data excluding x_i . This is leave-one-out cross validation. It turns out that there is a short cut to computing $\hat{J}(h)$ without the need to do leave-one-out:

Theorem 2 For any $h > 0$,

$$\mathbb{E}[\hat{J}(h)] = \mathbb{E}[J(h)]. \quad (11)$$

Furthermore,

$$\hat{J}(h) = \frac{1}{n^2 h} \sum_{i,j=1}^n \left(G\left(\frac{x_i - x_j}{h}\right) - 2K\left(\frac{x_i - x_j}{h}\right) \right) + \frac{2}{nh} K(0) + O\left(\frac{1}{n^2}\right), \quad (12)$$

where $G(z) = \int K(z - y)K(y)dy$.

For example, when $K = N(0, 1)$, $G = N(0, 2)$.

2 Nonparametric Regression

Let

$$y_i = r(x_i) + \epsilon_i \quad (13)$$

for $i = 1 \dots n$, $\mathbb{E}[\epsilon_i] = 0$, $\mathbb{V}[\epsilon_i] = \sigma^2$. The goal is to estimate $r(x)$ from $(x_1, y_1) \dots (x_n, y_n)$.

An estimator \hat{r} of r is a *linear smoother* if, for each x , there exists a vector $\gamma(x) = (\gamma_1(x), \dots, \gamma_n(x))^\top$ such that

$$\hat{r}(x) = \sum_{i=1}^n \gamma_i(x) y_i. \quad (14)$$

That is, $\gamma(x)$ is the weight given to y_i in forming the estimate $\hat{r}(x)$.

★ This does not mean $\hat{r}(x)$ is necessarily linear in x !

Example 1 Linear regression is a special case of linear smoother:

$$\hat{r}(x) = \sum_{d=1}^D \beta_d x_d = \sum_{i=1}^n \gamma_i(x) y_i, \quad (15)$$

where

$$\gamma(x)^\top = x^\top (X^\top X)^{-1} X^\top. \quad (16)$$

2.1 The Nadaraya-Watson Kernel Estimator

Let $h > 0$ be the bandwidth, and K a smoothing kernel. The *Nadaraya-Watson kernel estimator* is a linear smoother

$$\hat{r}(x) = \sum_{i=1}^n \gamma_i(x) y_i \quad (17)$$

where

$$\gamma_i(x) = \frac{K\left(\frac{x-x_i}{h}\right)}{\sum_{j=1}^n K\left(\frac{x-x_j}{h}\right)}. \quad (18)$$

To select the bandwidth in practice, we use cross-validation. The risk under squared loss is

$$\mathbb{E} \left(\frac{1}{n} \sum_{i=1}^n (\hat{r}(x_i) - r(x_i))^2 \right). \quad (19)$$

The corresponding leave-one-out score is

$$\frac{1}{n} \sum_{i=1}^n (\hat{r}(x_i) - \hat{r}_{-i}(x_i))^2. \quad (20)$$

For each point x_i , the leave-one-out estimator is

$$\hat{r}_{-i}(x) = \sum_{j=1}^n \gamma_{-i,j}(x) y_j \quad (21)$$

where

$$\gamma_{-i,j}(x) = \begin{cases} \frac{\gamma_j(x)}{\sum_{k \neq i} \gamma_k(x)} & j \neq i \\ 0 & j = i. \end{cases} \quad (22)$$

That is, $\gamma_{-i,j}(x)$ is a renormalized version of $\gamma_j(x)$ after removing the i -th weight. Again, there is no need to actually compute n different estimates \hat{r}_{-i} , because the leave-one-out score can be computed in closed-form.

Theorem 3 *The leave-one-out score can be written as*

$$\frac{1}{n} \sum_{i=1}^n \left(\frac{y_i - \hat{r}(x_i)}{1 - \gamma_i(x_i)} \right)^2. \quad (23)$$

One then selects the optimal bandwidth by minimizing the score above (could have multiple local minima).

2.2 Local Linear Regression

First, consider the best constant function fit $hat{r}(x) = a$ to training data:

$$\min_a \frac{1}{n} \sum_i (a - y_i)^2. \quad (24)$$

The solution is simply $a = \frac{1}{n} \sum_i y_i$. Now, consider the weighted version “centered” at x where the i -th training point is associated with a weight $\gamma_i(x) = K((x - x_i)/h)$. The constant fit to this weighted training data is

$$\min_a \frac{1}{n} \sum_i \gamma_i(x) (a - y_i)^2. \quad (25)$$

The solution turns out to be

$$a = \frac{\sum_{i=1}^n \gamma_i(x) y_i}{\sum_{i=1}^n \gamma_i(x)}. \quad (26)$$

Because it is a constant function, in particular at x we have $\hat{r}(x) = a$. This recovers the Nadaraya-Watson kernel estimator.

More importantly, this suggests a way to improve upon the Nadaraya-Watson kernel estimator: instead of assuming a constant function $\hat{r}(u) = a$ in (25), we may assume a family of linear functions, one of each x 's neighborhood:

$$\hat{r}_x(u) = a_0(x) + a_1(x)(u - x). \quad (27)$$

We now minimize the following objective:

$$\min_{a_0(x), a_1(x)} \frac{1}{n} \sum_i \gamma_i(x) (a_0(x) + a_1(x)(u - x_i) - y_i)^2. \quad (28)$$

Once the solution $\hat{a}_0(x)$ and $\hat{a}_1(x)$ are found, we have

$$\hat{r}_x(u = x) = \hat{a}_0(x). \quad (29)$$

This is called *local linear regression*. Even though this is the constant term, it is different from a local constant fit (which would be Nadaraya-Watson). See AoS Theorem 5.57 for the closed-form solution.