

Humans Perform Semi-Supervised Classification Too

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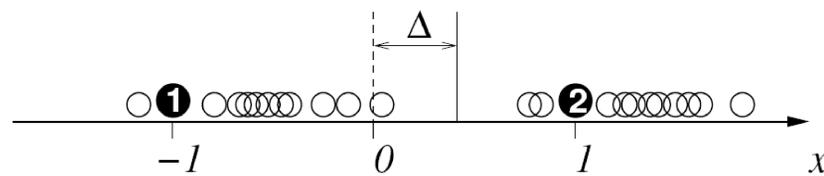
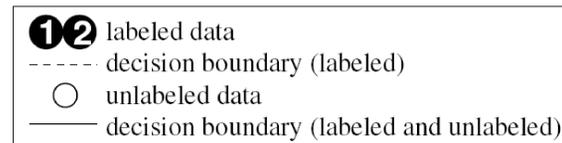
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Abstract

This work explores the connections between machine learning and human learning. Under a specific setting, human behavior conforms well to a generative model (Gaussian Mixture Models) for semi-supervised learning. We seem to learn semi-supervisedly.

The semi-supervised learning task

Two-class classification. Two labeled examples. Decision boundary in the middle.

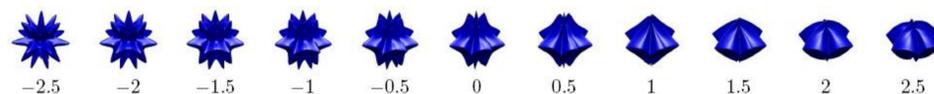


With labeled and unlabeled examples, and under the assumption that each class form a coherent group (e.g., follow a Gaussian distribution), **decision boundary shifts**.

Well-known in machine learning. We want to show such decision boundary shift exists in humans.

Participants and Materials

22 University of Wisconsin students. Novel visual stimuli, parameterized by a single parameter x , shown on screen one at a time. Classification by pressing B or N key. Audio feedback (affirmative sound if correct, warning sound if wrong) serves as label. No audio feedback for unlabeled examples.

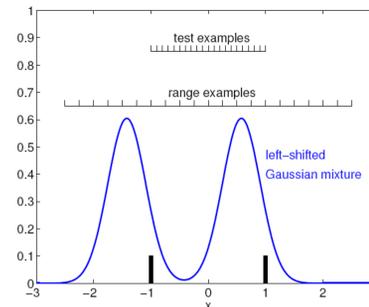


a few examples of our stimuli, with the parameters x

Procedure

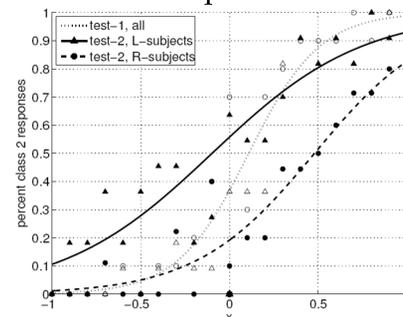
Two groups: L-subjects and R-subjects. Each subject sees 6 blocks of stimuli. Order within each block is randomized. Only block 1 is labeled.

- [labeled] 10 ($x=1, y=1$), 10 ($x=-1, y=-1$)
- [test-1] $x=-1, -0.9, \dots, 0.9, 1$
- [unlabeled-1] 230 sampled from two Gaussian (left or right shifted). 21 "range stimuli" evenly in $[-2.5, 2.5]$.
- [unlabeled-2] same as block 3
- [unlabeled-3] same as block 3
- [test-2] $x=-1, -0.9, \dots, 0.9, 1$



Behavioral experiment results

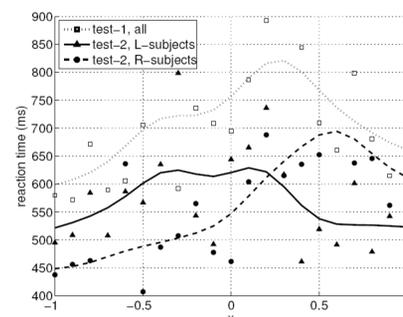
Observation 1: Unlabeled data changes the decision boundary. [test-1] (0.11); L-subjects [test-2] (-0.1); R-subjects [test-2] (0.48) The shift represents the effect of unlabeled data on subjects, and fits the expectation of semi-supervised classification.



(a) classification

Observation 2: Reaction time reflects decision boundary shift.

- The harder the stimuli, the longer the reaction time
- Peaks shift to follow new decision boundary



(b) reaction time

The machine learning model

We can explain the human experiment using a Gaussian Mixture Model (GMM) with 2 components:

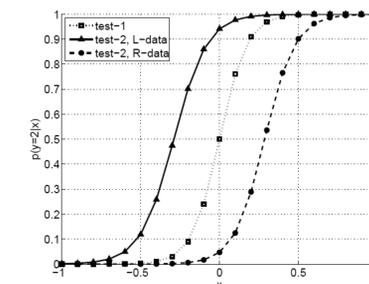
$$w_1 N(\mu_1, \sigma_1^2) + w_2 N(\mu_2, \sigma_2^2), w_1 + w_2 = 1, w_i \geq 0$$

$$\text{Prior } w_k \sim \text{Uniform}[0, 1], \mu_k \sim N(0, \infty), \sigma_k^2 \sim \text{Inv-}\chi^2(\nu, s^2), k = 1, 2$$

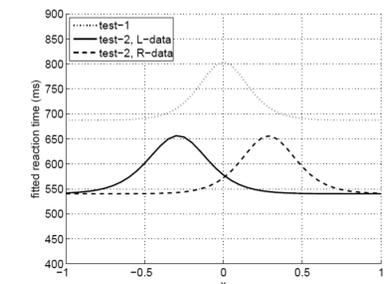
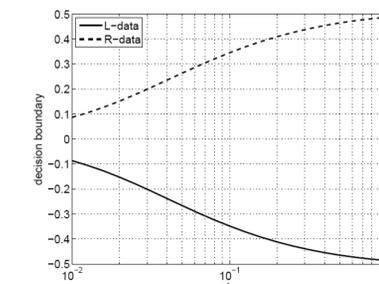
We fit the GMM with EM on blocks 1,2 vs. blocks 1–6. The EM algorithm maximizes the following objective, where $\lambda \leq 1$ is a weight on unlabeled examples:

$$\log p(\theta) + \sum_{i=1}^l \log p(x_i, y_i | \theta) + \lambda \sum_{i=l+1}^n \log p(x_i | \theta)$$

Observation 3: GMMs predict the decision boundary shift.



Observation 4: Unlabeled example weight λ controls the amount of decision boundary shift. Unlabeled data seems to worth less than labeled data. Best fit: $\lambda=0.06$.



Observation 5: GMMs also explain reaction time $t=aH(x)+b$, where $H(x)$ is the entropy of class prediction for x .

Conclusions

- Humans and machines both perform semi-supervised learning.
- Flatness of classification curves on [test-2] not well explained.
- Other forms of semi-supervised machine learning (e.g., manifold regularization, S3VMs, co-training) in humans should be explored.
- Further study may lead to new learning algorithms.