Spring 2017

QUERY PROCESSING [BASED ON CH 12.1-12.3 AND 14 IN THE COW BOOK]

Life Cycle of a Query



Problem Statement

	uid	INTEGER,		unique id or the user
	login	VARCHAR(20)		unique login name
	lname	VARCHAR(80),		lastname
	fname	VARCHAR(80),		firstname
	dob	DATE,		date of birth
	PRIMARY KEY	(uid),		primary key for the table
	UNIQUE (log-	in)		twid is also unique
);				
CRI	EATE TABLE Me uniqueMsgID tstamp uid msg zip reposted PRIMARY KEY FOREIGN KEY);	essages (INTEGER, TIMESTAMP, INTEGER, VARCHAR (140), INTEGER, BOOLEAN (uniqueMsgID), (uid) REFERENCE	 ES (unique message id when was the message posted unique id of the user the actual message zipcode when the message was posted is this a reposted message? primary key JSER - Foreign key to the User table

Problem Statement

• Run the following query:

SELECT	U.login AS login, COUNT(*) AS I	NumMsgsToday
FROM	User U, Messages M	
WHERE	U.uid = M.uid	
AND	M.Date(tstamp) = CURRENT_DATE	select msgs posted today
GROUP	BY U.login	group by login
ORDER	BY NumMsgsToday DESC	order by descending msg count

Sample output table

login	NumMsgsToday	
angelak	211	
jackdr	101	
petescafe	10	



Logical Query Plan

Here the ovals are logical operators. There are many different algorithms for each of these operators.

We study these algorithms next.

You already know the sort algorithm. So we can skip that one!



Select Operation

- Algorithms: File Scan or Index Scan
- File Scan: Disk I/O cost:
- Index Scan: (on some predicate). Disk I/O cost:
 - Hash: O() can only use with equality predicates
 - B+-tree: O() + X
 - X = number of selected tuples/number of tuples per page
 - X = 1 per selected tuple with an unclustered index. To reduce the value of X, we could sort the rids and then fetch the tuples.
 - Bitmap Index:

When to use a B+tree index

- Consider
 - A relation with 1M tuples
 - 100 tuples on a page
 - 500 (key, rid) pairs on a page

data pages = 1M/100 = 10K pages # leaf idx pgs = 1M / (500 * 0.67)

~ 3K pages 1% Selection 10% Selection Clustered 300 + 100030 + 100Non-Clustered 30 + 10,000300 + 100,000NC + Sort Rids $30 + (\sim 10,000)$ $300 + (\sim 10,000)$

> Choice of Index access plan, consider:

> > **1. Index Selectivity** 2. Clustering

Similar consideration for hash based indices

When can we use an index

- Notion of "index matches a predicate"
- Basically mean when can an index be used to evaluate predicates in the query

General Selection Conditions

- Index on (R.a, R.b)
 - Hash or tree-based
- Predicate:
 - R.a > 10
 - R.b < 30
 - R.a = 10 and R.b = 30
 - R.a = 10 or R.b = 30
- Predicate: (p1 and p2) or p3
- Convert to Conjunctive Normal Form(CNF) (p1 or p3) and (p2 or p3)
- An index *matches* a predicate
 - Index can be used to evaluate the predicate

Index Matching



- Index matches (part of) a predicate
 - 1. Conjunction of terms involving only attributes (no disjuctions)
 - 2. Hash: only equality operation, predicate has all index attributes.
 - 3. Tree: Attributes are a prefix of the search key, any ops.

Index Matching

- A predicate could match more than 1 index
- Hash index on <a, b> and B+tree index on <a, c>
 - a=7 and b=5 and c=4 Which index?

- Option1: Use either (or a file scan!)
 - Check selectivity of the primary conjuct
- Option2: Use both! Algorithm: Intersect rid sets.
 - Sort rids, retrieve rids in both sets.
 - Side-effect: tuples retrieved in the order on disk!

Selection

- Hash index on <a> and Hash index on
 - a=7 or b>5
 Which index?
 - Neither! File scan required for b>5
- Hash index on <a> and B+-tree on
 - a=7 or b>5
 Which index?
 - Option 1: Neither
 - Option 2: Use both! Fetch rids and union
 - Look at selectivities closely. Optimizer!
- Hash index on <a> and B+-tree on
 - (a=7 or c>5) and b > 5 Which index?
 - Could use B+-tree (check selectivity)

Projection Algorithm

- Used to project the selected attributes.
- Simple case: Example SELECT R.a, R.d.
 - Algorithm: for each tuple, only output R.a, R.d

Harder case: DISTINCT clause

- Example: SELECT DISTINCT R.a, R.d
 - Remove attributes <u>and</u> eliminate duplicates
- Algorithms
 - Sorting: Sort on <u>all</u> the projection attributes
 - Pass 0: eliminate unwanted fields. Tuples in the sorted-runs may be smaller
 - Eliminate duplicates in the merge pass & in-memory sort
 - Hashing: Two phases
 - Partitioning
 - Duplicate elimination



Projection ...

- Sort-based approach
 - better handling of skew
 - result is sorted
 - I/O costs are comparable if $B^2 > |R'|$
- Index-only scan
 - Projection attributes subset of index attributes
 - Apply projection techniques to data entries (much smaller!)
- If an ordered (i.e., tree) index contains all projection attributes as *prefix* of search key:
 - 1. Retrieve index data entries in order
 - 2. Discard unwanted fields
 - 3. Compare adjacent entries to eliminate duplicates (if required)