

## Lecture 14:

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A matrix  $A \in \{0, 1\}^{m \times n}$  is said to be decomposable if there exists  $I$  and  $J$ ,  $I, J \neq \emptyset$ ,  $I \subseteq [m], J \subseteq [n]$  such that  $A[I, \bar{J}] = 0$  and  $A[\bar{I}, J] = 0$  as shown in Fig. 1. Furthermore, at least one of them needs to be non-empty, i.e., either  $I \neq [m]$  or  $J \neq [n]$ .

We can think of this as a bipartite graph on  $[m] \times [n]$ . Then the decomposability is equivalent to saying the underlying bipartite graph is disconnected. The connected components constitute blocks, which are made up of pairs  $(I_1, J_1), (I_2, J_2), \dots, (I_k, J_k)$  with no edges between  $I_i$  and  $J_j$  for all  $i \neq j$ . Note that some  $I_s$  might be empty, in which case the corresponding  $J_s$  must be singleton isolated points.

We can generalize this to matrices in  $\mathbb{C}$ . Replace the non-zero elements by 1. For symmetric  $m \times m$  matrix, it is equivalent to the graph  $G$  on  $[m]$  as adjacency matrix in the following ways. If  $I_1 \cap J_1$  is non-empty, then  $I_1 = J_1$ . and the  $|I_1|$  points of  $G$  correspond to a single connected component (of  $2|I_1|$  points) of the graph  $H$  on  $[m]$ . If  $I_1 \cap J_1$  is empty, then there is a bipartite component of size  $|I_1| + |J_1|$ , of the graph  $G$  on  $[m]$ , which corresponds to two connected components, one of size  $|I_1|$  on the left and  $|J_1|$  on the right, and another one of size  $|J_1|$  on the left and  $|I_1|$  on the right.

Given an  $m \times m$  symmetric matrix  $A$ , recall that the graph homomorphism function is defined as:

$$Z_A(G) = \sum_{\sigma: V \rightarrow [m]} \prod_{(u,v) \in E} A_{\sigma(u), \sigma(v)}. \quad (1)$$

In the following subsequence lectures we will prove that for every  $A$ ,  $Z_A$  is either in P or #P-hard. The #P hardness is proved by showing there exists a reduction. In the case it is tractable, we give an algorithm. We further prove that the tractability criterion on  $A$  is polynomial-time decidable.

We build our work on the ones by Dyer and Greenhill as well as Bulatov and Grohe. Recall the theorem by Dyer and Greenhill, which states as follows:

|           |     |           |
|-----------|-----|-----------|
|           | $J$ | $\bar{J}$ |
| $I$       | *   | 0         |
| $\bar{I}$ | 0   | *         |

Figure 1:

**Theorem 1** (Dyer and Greenhill). *A symmetric  $\{0, 1\}$  matrix  $A$  defines a tractable graph homomorphism  $Z_A(\cdot)$  if and only if  $A$  is rectangular or if and only if the connected components of  $G(A)$  consists of complete bipartite graphs or cliques with loops or isolated points.*

Bulatov and Grohe then extends this result to all non-negative symmetric matrix  $A$  (every block of all 1's becomes rank 1 blocks). From their results,  $Z_A(\cdot)$  is computable in P if each block of  $A$  has rank at most one, and #P-hard otherwise.

To be more precise, if  $G$  has connected component  $G_1, G_2, \dots, G_k$ , then computing  $Z_A(G)$  is the same as computing  $\prod_i^k Z_A(G_i)$ . If the problem on any  $G$  is tractable, then it is in particular tractable on connected subgraphs. We can decompose the underlying graph  $A$  as a direct sum of  $A_i$ , each being a connected component. Then for a connected graph  $G$ , we must have

$$Z_A(G) = \sum_{j=1}^l Z_{A_j}(G). \quad (2)$$

This implies if  $Z_{A_j}(\cdot)$  is tractable for all  $j$ , then  $Z_A(\cdot)$  is tractable. However we would like to have the converse as well, i.e., if one of  $Z_{A_j}(\cdot)$  is hard, so is  $Z_A(\cdot)$ . That is the reduction from  $Z_{A_j}(\cdot)$  to  $Z_A(\cdot)$  for all  $j$ .

Let  $wt_A(\sigma) = \prod_{\sigma \in \{u,v\}} A_{\sigma(u),\sigma(v)}$ . Given a symmetric matrix  $C \in \mathbb{C}^{m \times m}$  and let  $\mathfrak{D} = [D^{[0]}, D^{[1]}, \dots, D^{[N-1]}]$  be a sequence of diagonal matrices in  $\mathbb{C}^{m \times m}$  for some  $N \geq 1$  (we use  $D_i^{[r]}$  to denote the  $(i, i)^{th}$  entry of  $D^{[r]}$ ). We define the following EVAL( $C, \mathfrak{D}$ ) problem

$$Z_{C,\mathfrak{D}}(G) = \sum_{\sigma: V \rightarrow [m]} wt_{C,\mathfrak{D}}(\sigma), \quad (3)$$

where  $wt_{C,\mathfrak{D}}(\sigma)$  is defined as:

$$wt_{C,\mathfrak{D}}(\sigma) = \left( \prod_{(u,v) \in E(G)} C_{\sigma(u),\sigma(v)} \right) \left( \prod_{v \in V} D_{\sigma(v)}^{[\deg(v) \bmod N]} \right). \quad (4)$$

Suppose  $C$  is the bipartisation of an  $m \times n$  matrix  $F$ , i.e.,

$$C = \begin{pmatrix} 0 & F \\ F^T & 0 \end{pmatrix}. \quad (5)$$

For any graph  $G$  and vertex  $u$  in  $G$ , we define  $Z_{C,\mathfrak{D}}^{\rightarrow}(G, u)$  and  $Z_{C,\mathfrak{D}}^{\leftarrow}(G, u)$  as follows. Let  $\mathcal{X}_1$  denote the set of  $\sigma : V \rightarrow [m+n]$  with  $\sigma(u) \in [m]$  and  $\mathcal{X}_2$  denote the set of  $\sigma$  with  $\sigma(u) \in [m+1 : m+n]$ , then we have

$$Z_{C,\mathfrak{D}}^{\rightarrow}(G, u) = \sum_{\sigma \in \mathcal{X}_1} wt_{C,\mathfrak{D}}(\sigma) \quad (6)$$

$$Z_{C,\mathfrak{D}}^{\leftarrow}(G, u) = \sum_{\sigma \in \mathcal{X}_2} wt_{C,\mathfrak{D}}(\sigma) \quad (7)$$

Then it follows that  $Z_{C, \mathfrak{D}}(G) = Z_{C, \mathfrak{D}}^{\rightarrow}(G, u) + Z_{C, \mathfrak{D}}^{\leftarrow}(G, u)$ .

Let  $A$  be an  $m \times m$  symmetric matrix, we consider a EVALP( $A$ ) problem as follows. The input is a triple  $(G, w, i)$  where  $G = (V, E)$  is an undirected graph,  $w \in V$  is a vertex and  $i \in [m]$ . The output is:

$$Z_A(G, w, i) = \sum_{\substack{\sigma: V \rightarrow [m] \\ \sigma(w)=i}} wt_A(\sigma). \quad (8)$$

Then we have the First Pinning Lemma, stated as follows:

**Lemma 1** (First Pinning Lemma). *We have  $EVALP(A) \equiv EVAL(A)$ .*

It is easy to see that  $EVALP(A) \geq EVAL(A)$ . We need to prove the other direction also holds. We define the following equivalence relation ( $i \sim j$ ) over  $[m]$ :

$$i \sim j \quad \text{if } Z_A(G, w, i) = Z_A(G, w, j) \quad \forall G, w \in V(G). \quad (9)$$

This equivalence relation divides the set  $[m]$  into  $s$  equivalent classes  $\mathcal{A}_1, \mathcal{A}_2, \dots, \mathcal{A}_s$  for some positive integer  $s$ . For any  $t \neq t' \in [s]$ , there exists a pair  $P_{t, t'} = (G, w)$  that distinguish them, i.e.,

$$Z_A(G, w, i) \neq Z_A(G, w, i') \quad \forall i \in \mathcal{A}_t \quad \forall i' \in \mathcal{A}_{t'}. \quad (10)$$

Now for any subset  $S \subseteq [s]$ , we define

$$Z_A(G, w, S) = \sum_{\substack{\sigma: V \rightarrow [m] \\ \sigma(w) \in \bigcup_{t \in S} \mathcal{A}_t}} wt_A(\sigma). \quad (11)$$

To prove Lemma 1, we first present the following shrinking lemma:

**Lemma 2** (Shrinking Lemma). *If  $S \subseteq [s]$  and  $|S| \geq 2$ , then there exists a partition  $\{S_1, \dots, S_k\}$  of  $S$  for some  $k > 1$  and  $EVAL(A, S_l) \leq EVAL(A, S)$  for all  $l$ .*

*Proof.* Let  $t \neq t'$  be two integers in  $S$ . We let  $P_{t, t'} = (G^*, w^*)$ . For all  $a, b \in S$  we define a equivalence relation  $\sim^*$  over  $S$ :

$$a \sim^* b \quad \text{if } Z_A(G^*, w^*, i) = Z_A(G^*, w^*, j) \quad i \in \mathcal{A}_a, j \in \mathcal{A}_b. \quad (12)$$

The foregoing relation is independent of the choice of  $i$  and  $j$  and it gives us equivalence partition  $\{S_1, S_2, \dots, S_k\}$  of  $S$ . We let  $X_a$  denote  $Z_A(G^*, w^*, i)$  where  $i \in \mathcal{A}_a$  and  $X_a$  is independent of the choice of  $i$ . We define  $X_b$  similarly. Then  $X_b \neq X_a$  if  $a \not\sim^* b$ . Let  $G$  be an undirected graph and  $w$  be a vertex. For each  $p : 0 \leq p \leq k - 1$ , we construct a sequence of graphs  $G^{[p]}$  where  $G^{[p]}$  is the disjoint union of  $G$  and  $p$  independent copies of  $P_{t, t'}$ , except

the  $w$  in the input  $G$  and all  $w^*$  in the copies of  $P_{t,t'}$  as one single vertex  $w' \in V^{[p]}$ . We then have the following collection of equations:

$$Z_A(G^{[p]}, w', S) = \sum_{l=1}^k Z_A(G, w, S_l) X_l^p, \quad (13)$$

where  $S_l$ 's are equivalence classes. Since  $X_b \neq X_a$  for all  $a \approx^* b$ , this is a Vandermonde system and we can solve it to get  $Z_A(G, w, S_l)$  for all  $l \in [k]$ . This gives us a polynomial time reduction from  $\text{EVAL}(A, S_l)$  to  $\text{EVAL}(A, S)$  for every  $l \in [k]$ .  $\square$

We now prove Lemma 1.

*Proof.* We apply Lemma 2 to  $S = [s]$ . By Lemma 2, there exists a partition  $\{S_1, \dots, S_k\}$  of  $S$ , for some  $k > 1$ , such that  $\text{EVAL}(A, S_d) \leq \text{EVAL}(A, S)$  for all  $d \in [k]$ . Consider some  $t \in [s]$ , without loss of generality, assume  $t \in S_1$  (or we can always shrink  $S_1$  using Lemma 2 until  $t$  is the only element in  $S_1$ ). When this is true, we simply have

$$Z_A(G, w, i) = \frac{1}{|\mathcal{A}_t|} \cdot Z_A(G, w, \{t\}). \quad (14)$$

This completes the proof of Lemma 1.  $\square$