Lecture Outline: Phylogeny Reconstruction using Distance Methods

1. Summary of Models of Molecular Evolution

(a) The standard form for the rate matrix of a time-reversible continuous-time Markov model of DNA substitution is the following, where the base order is A, C, G, T and the dots on the main diagonal represent the negative row-sum of the off-diagonal elements. The most general model is the general time-reversible model (GTR).

\[
Q_{\text{GTR}} = \begin{pmatrix}
\cdot & s_{AC}\pi_C & s_{AG}\pi_G & s_{AT}\pi_T \\
\cdot & s_{AC}\pi_A & \cdot & s_{CT}\pi_T \\
\cdot & s_{AG}\pi_A & s_{CG}\pi_G & \cdot \\
s_{AT}\pi_A & s_{CT}\pi_C & \cdot & s_{GT}\pi_T \\
\end{pmatrix}
\]

(b) The six parameters \( s_{ij} = s_{ji} \) for each pair of bases appear symmetrically in the matrix across the main diagonal.

(c) The four parameters \( \pi = (\pi_A, \pi_C, \pi_G, \pi_T) \) are the stationary distribution and represent both the long-run relative frequency of the bases but also the probabilities of the bases at any given time.

(d) There are only nine free parameters as the stationary distribution satisfies the constraint \( \sum_i \pi_i = 1 \).

(e) Some models also define \( \pi_R = \pi_A + \pi_G \) for the sum of purine probabilities and \( \pi_Y = \pi_C + \pi_T \) for the sum of pyrimidine probabilities.

(f) The expected number of substitutions per unit time is the weighted average of the negative main diagonal elements.

\[
\mu = \pi_A(s_{AC}\pi_c + s_{AG}\pi_G + s_{AT}\pi_T) + \pi_C(s_{AC}\pi_A + s_{CG}\pi_G + s_{CT}\pi_T) \\
+ \pi_G(s_{AG}\pi_A + s_{CG}\pi_C + s_{GT}\pi_T) + \pi_T(s_{AT}\pi_A + s_{CT}\pi_C + s_{GT}\pi_G) \\
= 2(\pi_A\pi_Cs_{AC} + \pi_A\pi_Gs_{AG} + \pi_A\pi Ts_{AT} + \pi_C\pi_Gs_{CG} + \pi_C\pi Ts_{CT} + \pi_G\pi Ts_{GT})
\]

(g) Often the matrix \( Q \) is rescaled so that one unit of time represents one expected substitution (per site) by dividing each element by \( \mu \) which reduces the number of free parameters by one.

(h) There are many standard models that are special cases of the GTR model. These are:

<table>
<thead>
<tr>
<th>Jukes-Cantor (JC69)</th>
<th>Kimura 2-parameter (K80)</th>
<th>Felsenstein (F81)</th>
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</table>
| \( Q_{\text{JC69}} = \begin{pmatrix}
\cdot & 1 & 1 & 1 \\
1 & \cdot & 1 & 1 \\
1 & 1 & \cdot & 1 \\
1 & 1 & 1 & \cdot \\
\end{pmatrix} \) | \( Q_{\text{K80}} = \begin{pmatrix}
\cdot & 1 & \kappa & 1 \\
1 & \cdot & 1 & \kappa \\
\kappa & 1 & \cdot & 1 \\
1 & \kappa & 1 & \cdot \\
\end{pmatrix} \) | \( Q_{\text{F81}} = \begin{pmatrix}
\cdot & \pi_C & \pi_G & \pi_T \\
\pi_A & \cdot & \pi_G & \pi_T \\
\pi_A & \pi_C & \cdot & \pi_T \\
\pi_A & \pi_C & \pi_G & \cdot \\
\end{pmatrix} \) |

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<tr>
<th>Felsenstein (F84)</th>
<th>HKY85</th>
<th>Tamura-Nei (TN93)</th>
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</thead>
</table>
| \( Q_{\text{F84}} = \begin{pmatrix}
\cdot & \pi_C & (1 + \kappa/\pi_R)\pi_G & \pi_T \\
\pi_A & \cdot & \pi_G & (1 + \kappa/\pi_Y)\pi_T \\
(1 + \kappa/\pi_R)\pi_A & \pi_C & \cdot & \pi_T \\
\pi_A & (1 + \kappa/\pi_Y)\pi_C & \pi_G & \cdot \\
\end{pmatrix} \) | \( Q_{\text{HKY85}} = \begin{pmatrix}
\cdot & \pi_C & \kappa\pi_G & \pi_T \\
\pi_A & \cdot & \pi_G & \kappa\pi_T \\
\kappa\pi_A & \pi_C & \cdot & \pi_T \\
\pi_A & \kappa\pi_C & \pi_G & \cdot \\
\end{pmatrix} \) | \( Q_{\text{TN93}} = \begin{pmatrix}
\cdot & \pi_C & \kappa R\pi_G & \pi_T \\
\pi_A & \cdot & \pi_G & \kappa Y\pi_T \\
\kappa R\pi_A & \pi_C & \cdot & \pi_T \\
\pi_A & \kappa Y\pi_C & \pi_G & \cdot \\
\end{pmatrix} \) |
(i) The probability transition matrix has the form \( P(t) = \{p_{ij}(t)\} = e^{Qt} \) where \( p_{ij}(t) \) equals the probability of being in state \( j \) after \( t \) time units given that the process begins in state \( i \).

(j) The spectral decomposition of \( Q \) is \( Q = V \Lambda V^{-1} \) where

i. \( V \) is a \( 4 \times 4 \) matrix whose columns are eigenvectors of \( Q \);

ii. \( \Lambda \) is a \( 4 \times 4 \) diagonal matrix whose diagonal elements are eigenvalues of \( Q \);

iii. \( V^{-1} \) is the \( 4 \times 4 \) matrix such that \( V V^{-1} = V^{-1} V = I \).

(k) The probability transition matrix has the form \( P(t) = V e^{\Lambda t} V^{-1} \).

(l) If the eigenvalues of \( Q \) are \( \lambda_1 = 0, \lambda_2, \lambda_3, \lambda_4 < 0 \), then

\[
p_{ij}(t) = \pi_j + e_2^{(ij)} e^{\lambda_2 t} + e_3^{(ij)} e^{\lambda_3 t} + e_4^{(ij)} e^{\lambda_4 t}
\]

where

\[
e_2^{(ij)} + e_3^{(ij)} + e_4^{(ij)} = \begin{cases} 1 - \pi_j & \text{when } i = j \\ -\pi_j & \text{when } i \neq j \end{cases}
\]

so that

\[
p_{ij}(0) = \begin{cases} 1 & \text{when } i = j \\ 0 & \text{when } i \neq j \end{cases}
\]

(m) The probability transition matrix of the GTR model does not have an algebraic form and must be computed numerically.
(n) The TN93 model has the following spectral decomposition, $Q = V \Lambda V^{-1}$, with

$$Q_{\text{TN93}} = \begin{pmatrix}
\pi_C & \pi_R \pi_G & \pi_T \\
\pi_A & \pi_G & \pi_Y \pi_T \\
\kappa_R \pi_A & \pi_C & \pi_T \\
\pi_A & \kappa_Y \pi_C & \pi_G
\end{pmatrix}$$

$$V = \begin{pmatrix}
1 & -1 & 0 & 0 \\
1 & 1 & 0 & 1 \\
1 & 1 & 0 & 0 \\
1 & 1 & 0 & 0
\end{pmatrix}$$

$$\Lambda = \begin{pmatrix}
0 & 0 & 0 & 0 \\
0 & 0 & (\kappa_R \pi_R + \pi_Y) & 0 \\
0 & 0 & 0 & -(\kappa_Y \pi_Y + \pi_R) \\
0 & 0 & 0 & 0
\end{pmatrix}$$

$$V^{-1} = \begin{pmatrix}
\pi_A & \pi_C & \pi_G & \pi_T \\
-\pi_A \pi_Y & \pi_C \pi_R & -\pi_G \pi_Y & \pi_T \pi_R \\
1 & 0 & -1 & 0 \\
0 & -1 & 0 & 1
\end{pmatrix}$$

(o) The probability transition matrix is $P_{\text{TN93}} = V e^{\Lambda t} V^{-1}$ which equals

$$P_{\text{TN93}} = \begin{pmatrix}
\pi_A + \frac{\pi_A \pi_Y}{\pi_R} e_2 + \frac{\pi_G}{\pi_R} e_3 & \pi_C - \pi_C e_2 & \pi_G + \frac{\pi_G \pi_Y}{\pi_R} e_2 - \frac{\pi_G}{\pi_R} e_3 & \pi_T - \pi_T e_2 \\
\pi_A - \pi_A e_2 & \pi_C + \frac{\pi_G \pi_R}{\pi_Y} e_2 + \frac{\pi_T}{\pi_Y} e_4 & \pi_G - \pi_G e_2 & \pi_T + \frac{\pi_G \pi_R}{\pi_Y} e_2 - \frac{\pi_T}{\pi_Y} e_4 \\
\pi_A + \frac{\pi_A \pi_Y}{\pi_R} e_2 - \frac{\pi_A}{\pi_R} e_3 & \pi_C - \pi_C e_2 & \pi_G + \frac{\pi_G \pi_R}{\pi_Y} e_2 - \frac{\pi_G}{\pi_R} e_3 & \pi_T - \pi_T e_2 \\
\pi_A - \pi_A e_2 & \pi_C + \frac{\pi_G \pi_R}{\pi_Y} e_2 - \frac{\pi_C}{\pi_Y} e_4 & \pi_G - \pi_G e_2 & \pi_T + \frac{\pi_G \pi_R}{\pi_Y} e_2 + \frac{\pi_C}{\pi_Y} e_4
\end{pmatrix}$$

where $e_2 = e^{-t}$, $e_3 = e^{-(\kappa_R \pi_R + \pi_Y)t}$, and $e_4 = e^{-(\kappa_Y \pi_Y + \pi_R)t}$.

2. Distance Estimation

(a) Consider estimating pairwise distances under the TN93 model.

Assume that we have estimates of all parameters, $\pi$, $\kappa_R$, and $\kappa_Y$.

Then we would want to find the time $t$ that would maximize the probability of the observed data.

If we observed a site AC, the probability of this would be

$$\pi_A P_{AC}(t)$$

as a function of $t$.

(b) The likelihood of the data would be

$$L(t) = \prod_i \prod_j (\pi_i P_{ij}(t))^{n_{ij}}$$

where $n_{ij}$ is the number of times that pattern $ij$ is observed.

(c) In practice, it is easier to work with the natural logarithm of this expression.

$$\ell(t) = \sum_i \sum_j n_{ij} (\log \pi_i + \log P_{ij}(t))$$

(d) For a pair of sequences, you can summarize the number of observed site patterns in a $4 \times 4$ matrix.
Above are the first 50 bases of the *cytochrome oxidase I* mitochondrial gene from swan and osprey.

Here is a summary of the count data.

<table>
<thead>
<tr>
<th></th>
<th>A</th>
<th>C</th>
<th>G</th>
<th>T</th>
<th>Total</th>
</tr>
</thead>
<tbody>
<tr>
<td>Swan</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>A</td>
<td>16</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>16</td>
</tr>
<tr>
<td>C</td>
<td>3</td>
<td>9</td>
<td>0</td>
<td>1</td>
<td>13</td>
</tr>
<tr>
<td>G</td>
<td>1</td>
<td>0</td>
<td>6</td>
<td>0</td>
<td>7</td>
</tr>
<tr>
<td>T</td>
<td>0</td>
<td>4</td>
<td>0</td>
<td>10</td>
<td>14</td>
</tr>
<tr>
<td>Total</td>
<td>20</td>
<td>13</td>
<td>6</td>
<td>11</td>
<td>50</td>
</tr>
</tbody>
</table>

(e) If we assume the TN93 model, how can we estimate all of the parameters?

Here is one approach: Estimate the stationary distribution by the observed frequencies. With 50 bases per species, there are 100 observed bases. The estimate is $\pi = (0.36, 0.26, 0.13, 0.25)$.

The two parameters $\kappa_R$ and $\kappa_Y$ can be estimated by considering the expected proportions of transitions in purines and pyrimidines and the expected proportion of transversions.

The probability of a transition in a purine after $t$ time units is

$$\pi_A P_{AG}(t) + \pi_G P_{GA}(t) = 2\pi_A \pi_G \left(1 + \frac{\pi_Y}{\pi_R} e_2 - \frac{1}{\pi_R} e_3\right)$$

The probability of a transition in a pyrimidine after $t$ time units is

$$\pi_C P_{CT}(t) + \pi_T P_{TC}(t) = 2\pi_C \pi_T \left(1 + \frac{\pi_R}{\pi_Y} e_2 - \frac{1}{\pi_Y} e_4\right)$$

The probability of a transversion after $t$ time units is

$$\pi_A P_{AC}(t) + \pi_A P_{AT}(t) + \pi_C P_{CA}(t) + \pi_C P_{CG}(t) + \pi_G P_{GC}(t) + \pi_G P_{GT}(t) + \pi_T P_{TA}(t) + \pi_T P_{TG}(t)$$

which simplifies to

$$2(1 - e_2)(\pi_A \pi_C + \pi_A \pi_T + \pi_C \pi_G + \pi_G \pi_T)$$

The observed proportions of these three types of site patterns are $S_R = 1/50 = 0.02$, $S_Y = 5/50 = 0.10$, and $V = 3/50 = 0.06$.

Equating these observed frequencies with the expected proportions gives three linear equations in three unknowns, which can be solved for $e_2$, $e_3$, and $e_4$.

When these expressions are plugged in, we can solve for $\kappa_R$, $\kappa_Y$, and $t$.

Finally, the distance is found by multiplying this time $t$ by the expected number of substitutions per unit time, $\mu$.

The equations are:

$$\kappa_R = \frac{a_R - \pi_Y b}{\pi_R b}$$

$$\kappa_Y = \frac{a_Y - \pi_R b}{\pi_Y b}$$
where

\[ a_R = - \log \left( 1 - \frac{\pi_R S_R}{2\pi A \pi_G} - \frac{V}{2\pi R} \right) \]
\[ a_Y = - \log \left( 1 - \frac{\pi_Y S_Y}{2\pi C \pi_T} - \frac{V}{2\pi Y} \right) \]
\[ b = - \log \left( 1 - \frac{V}{2\pi R \pi Y} \right) \]

3. **UPGMA**

(a) UPGMA is an algorithm that will produce a rooted ultrametric tree from pairwise distance data.

(b) If the data matches such a tree exactly, the algorithm will recover the tree.

(c) Here is the algorithm:

i. Find the \( i \) and \( j \) with the smallest distance \( D_{ij} \).

ii. Create a new group \( (ij) \) which has \( n_{(ij)} = n_i + n_j \) members.

iii. Connect \( i \) and \( j \) on the tree to a new node \( (ij) \). Give the edges connecting \( i \) to \( (ij) \) and \( j \) to \( (ij) \) each length so that the depth of group \( (ij) \) is \( D_{ij}/2 \).

iv. Compute the distance between the new group and all other groups except \( i \) and \( j \) by using

\[ D_{(ij),k} = \left( \frac{n_i}{n_i + n_j} \right) D_{ik} + \left( \frac{n_j}{n_i + n_j} \right) D_{jk} \]

v. Delete columns and rows corresponding to \( i \) and \( j \) and add one for \( (ij) \). If there are two or more groups left, go back to the first step.

4. **Neighbor-Joining**

(a) Neighbor-joining produces an unrooted tree from pairwise distance data.

(b) If the data matches such a tree exactly, the algorithm will recover the tree.

(c) Here is the algorithm:

i. For each leaf, compute \( u_i = \sum_{j \neq i} D_{ij} / (n - 2) \).

ii. Choose the \( i \) and \( j \) for which \( D_{ij} - u_i - u_j \) is smallest.

iii. Join \( i \) and \( j \) to a new node with lengths \( (D_{ij} + u_i - u_j)/2 \) to node \( i \) and \( (D_{ij} + u_j - u_i)/2 \) to node \( j \).

iv. Compute the distance to the new node \( (ij) \) and the other groups as

\[ D_{(ij),k} = \frac{D_{ik} + D_{jk} - D_{ij}}{2} \]

v. Delete columns and rows corresponding to \( i \) and \( j \) and add one for \( (ij) \). If there are three or more groups left, go back to the first step. Otherwise, connect the two remaining nodes with their distance.