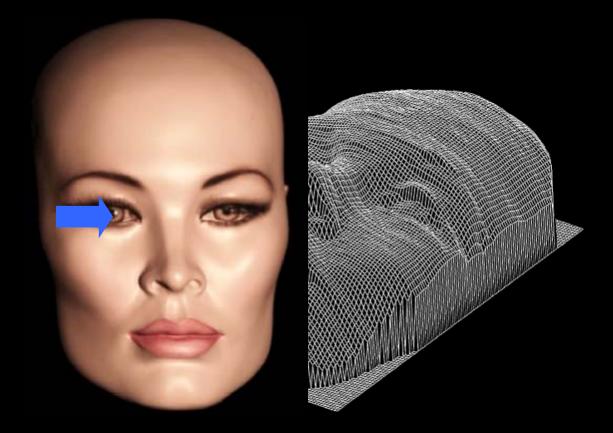
## **CS559: Computer Graphics**

Lecture 42: 3D Photography Li Zhang Spring 2008

# Today

- 3D Photography
- Reading
  - -NO

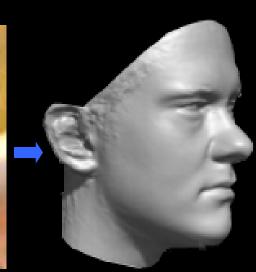
#### What is 3D Photography?



#### Computing the 3rd Dimension (depth) from 2D Photographs

# Why 3D Photography?





#### Google Earth



#### **Face Modeling**

#### Virtual World

## How to get a 3D model?

- Buy it (or find a free one)
  - Free meshes typically are not very good quality
- User defined: A user builds the mesh
  - Tools help with specifying many vertices and faces quickly
- More Automated techniques
  - Scan a real object
    - 3D probe-based systems
    - Range finders
  - Image based reconstruction



 Take a bunch of pictures, and infer the object's shape (CS766)

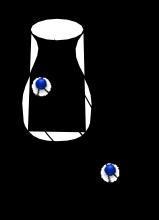
# Today

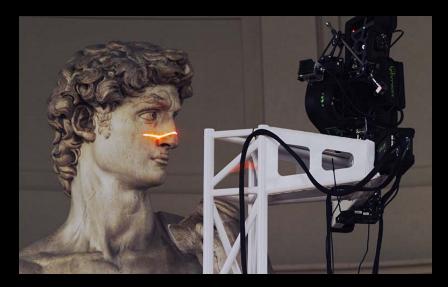
• Laser Scanner - Static Shapes

Stereo - for Dynamic Surfaces

 Photometric Stereo - for Complex Reflectance

#### Laser Scanning



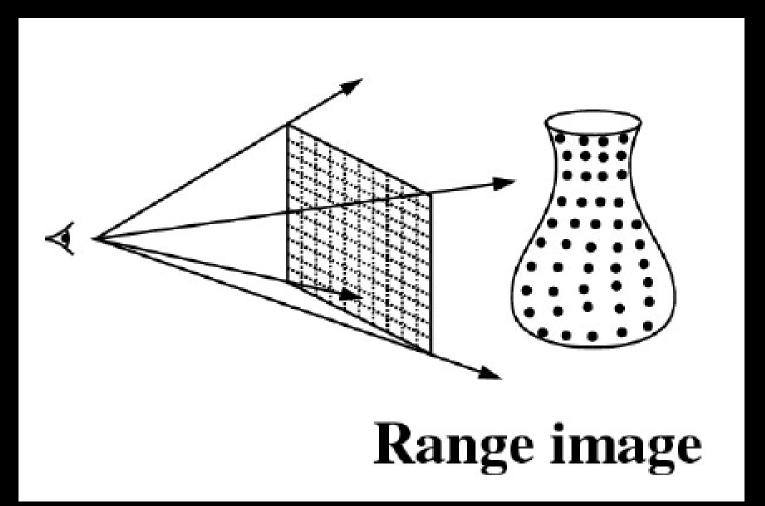


Digital Michelangelo Project http://graphics.stanford.edu/projects/mich/

#### **Optical triangulation**

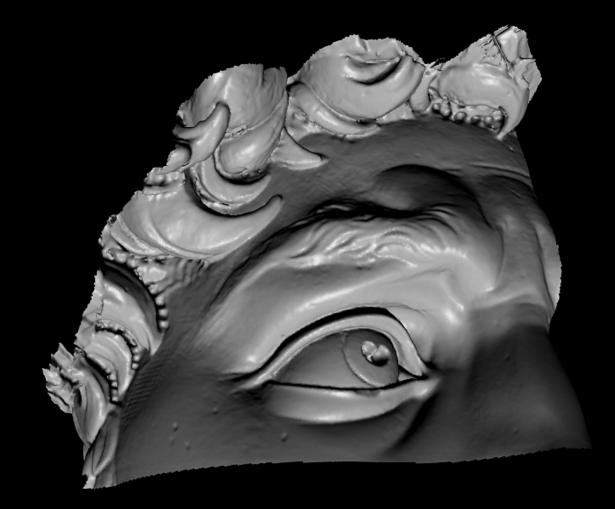
- Project a single stripe of laser light
- Scan it across the surface of the object

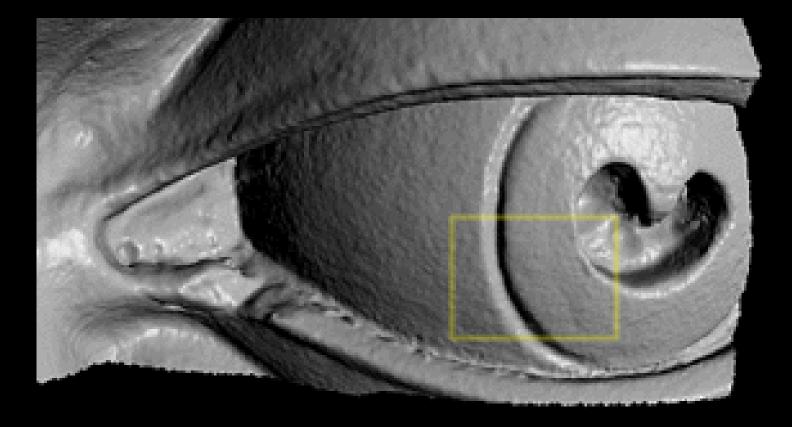
# Laser Scanning

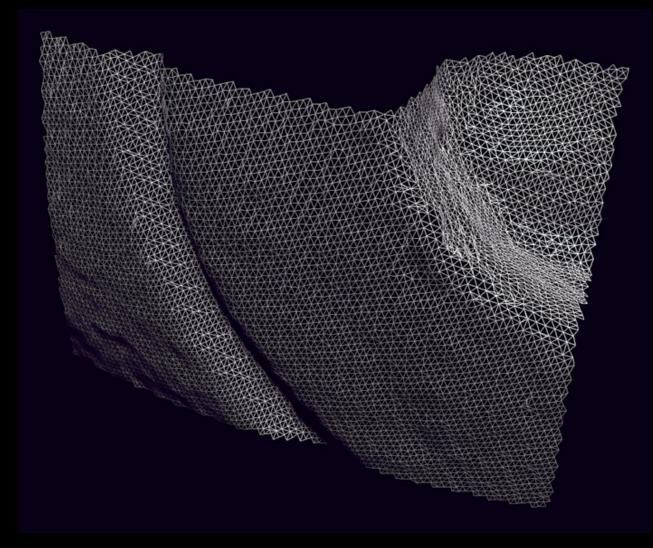














# St Matthew



#### 372 million triangles

## Forma Urbis Romae

- A giant marble map of ancient Rome.
  - 60 feet X 45 feet
  - in fragments:1,186 of them



#### 3 feet long, 150 pounds

# Forma Urbis Romae

- A giant marble map of ancient Rome.
  - 60 feet X 45 feet
  - in fragments:1,186 of them



#### 8 billion polygons

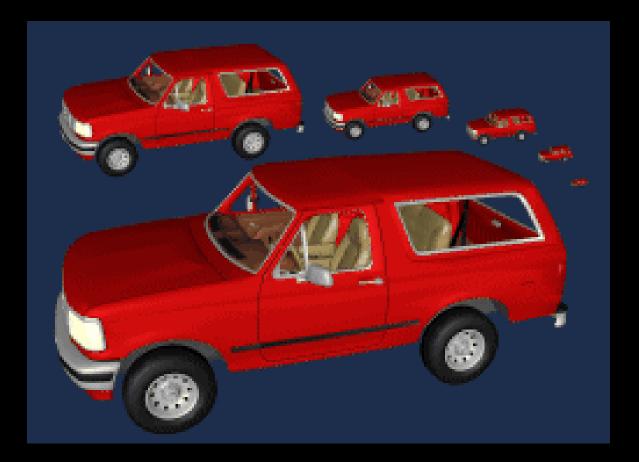
#### We have a problem here

Too many triangles

# Level Of Detail

- There is no point in having more than 1 polygon per pixel
- Level of detail strategies
  - balance the resolution of the mesh against the viewing conditions
    - Must have a way to reduce the complexity of meshes
    - Must have a way to switch from one mesh to another
    - An ongoing research topic, made even more important as laser scanning becomes popular
    - Also called mesh decimation, multi-resolution modeling and other things

#### Level of Detail



#### http://www.cs.unc.edu/~geom/SUCC\_MAP/

## Level of Detail

- Basic Idea: reducing # vertices
  - Vertex decimation
  - Edge collapsing

# Scanning a Face

R



500,000 POLYS [CPV]

# Scanning a Face

#### Create a Plaster Mold



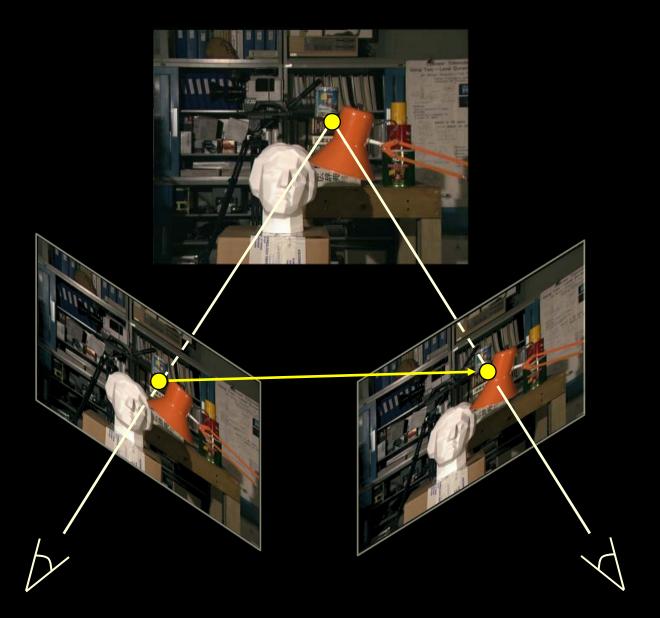
- Scan the mold
- Why?
  - Keep the Subject Static
  - Skin Reflectance

## Meshes from Scanning

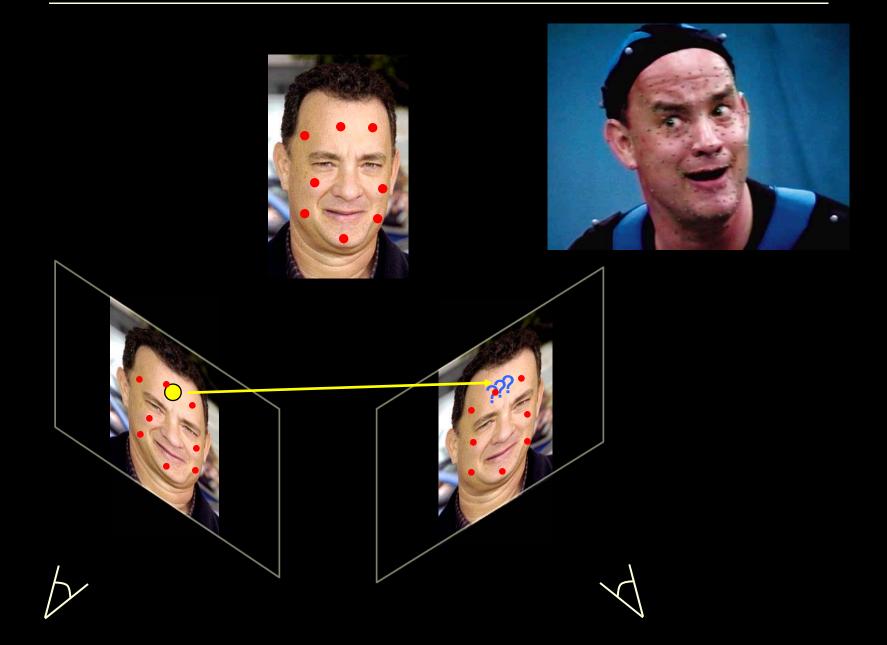
- Laser scanners sample 3D positions
  - One method uses triangulation
  - Another method uses time of flight
  - Some take images also for use as textures

#### http://www.mandli.com/systems/srh.php

# Stereo



# Stereo



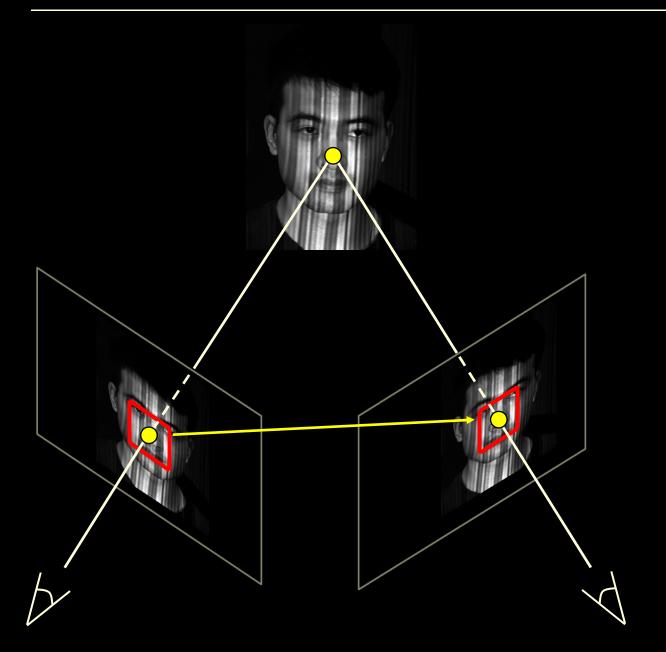
#### **Marker-based Face Capture**



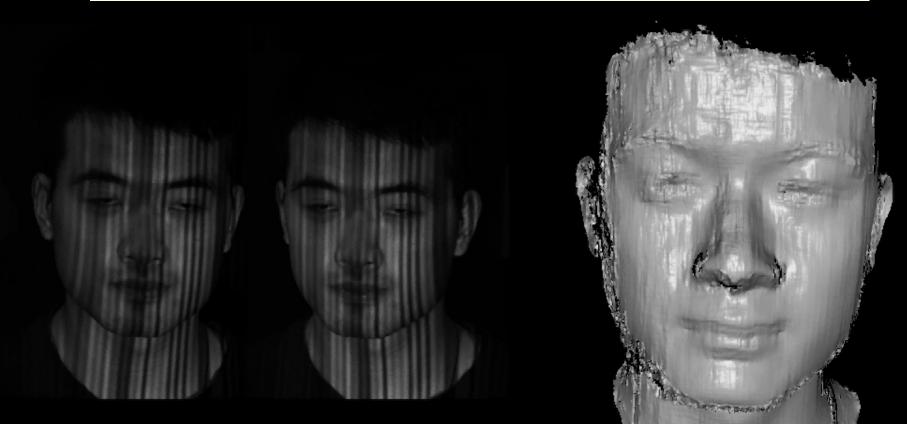
#### The Polar Express, 2004

"The largest intractable problem with 'The Polar Express' is that the motion-capture technology used to create the human figures has resulted in a film filled with creepily unlifelike beings." *New York Times Review,* Nov 2004

# Stereo



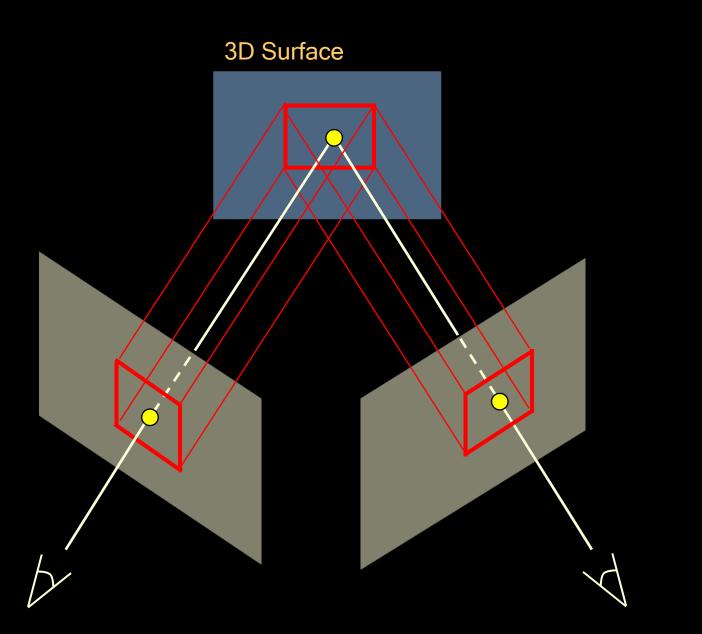
#### Stereo

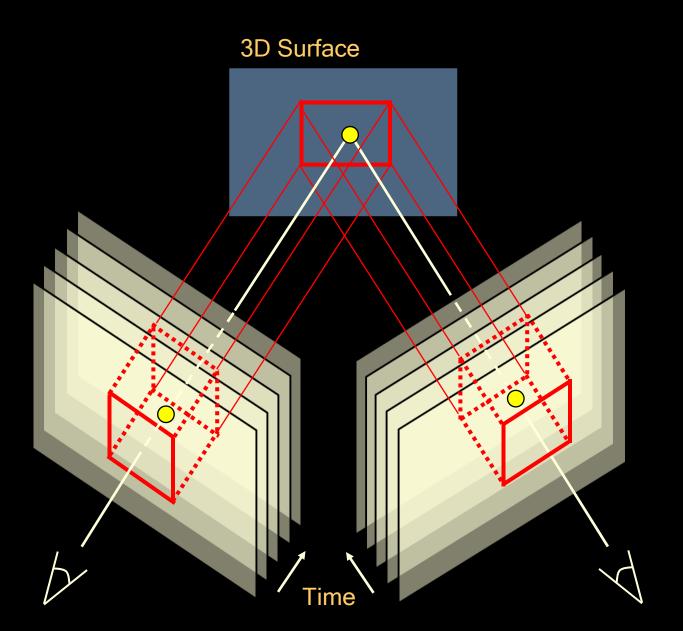


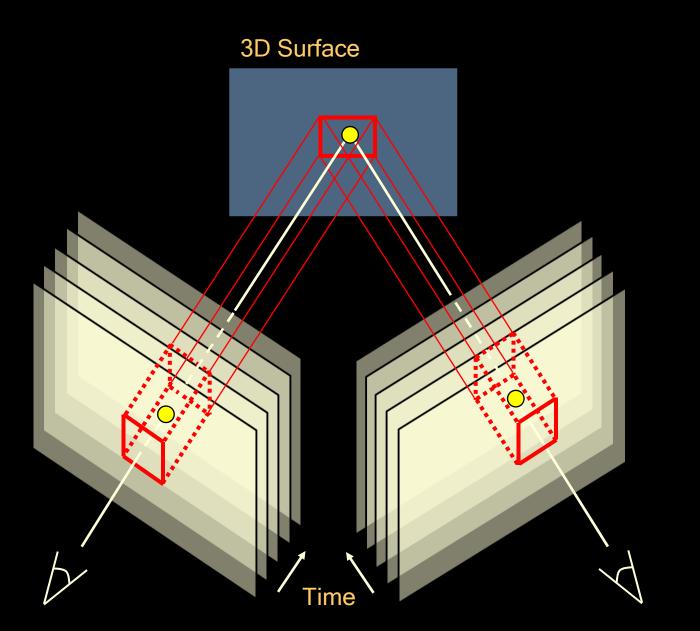
A Pair of Videos 640×480@60fps Each A STATE OF THE DESIGN OF THE PARTY OF THE PA

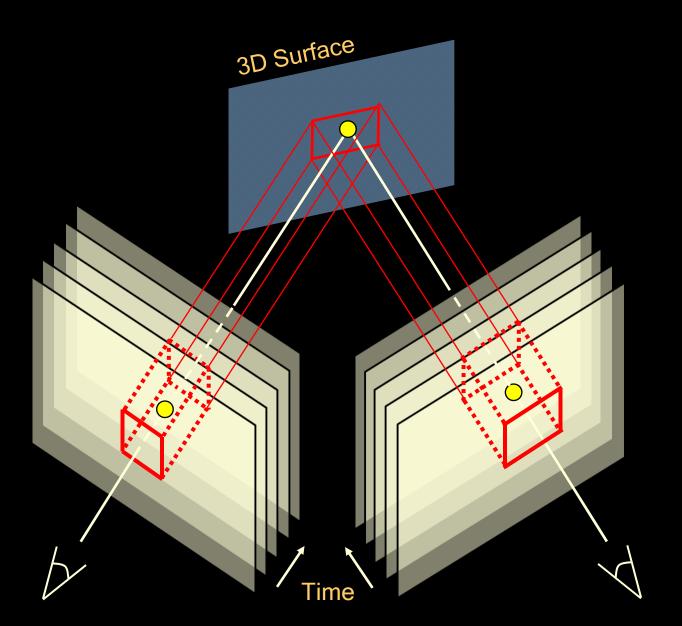
Frame-by-Frame Stereo W×H = 15×15 Window

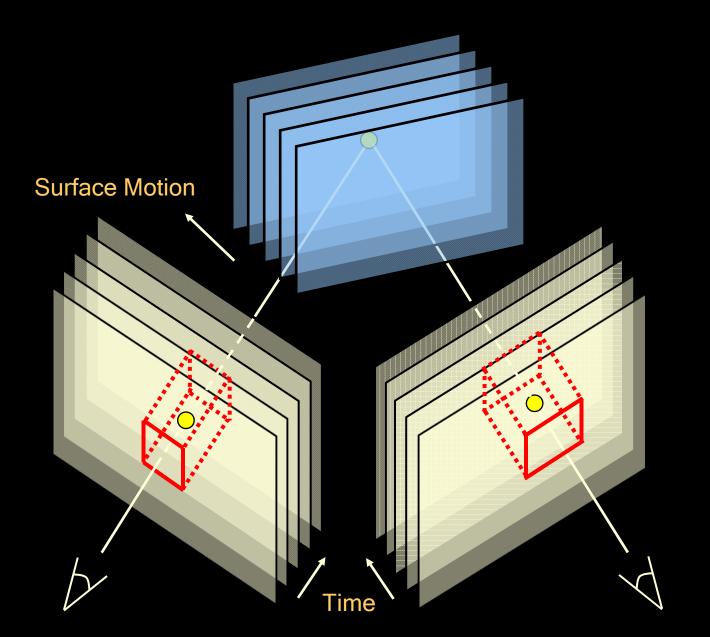
Inaccurate & Jittering

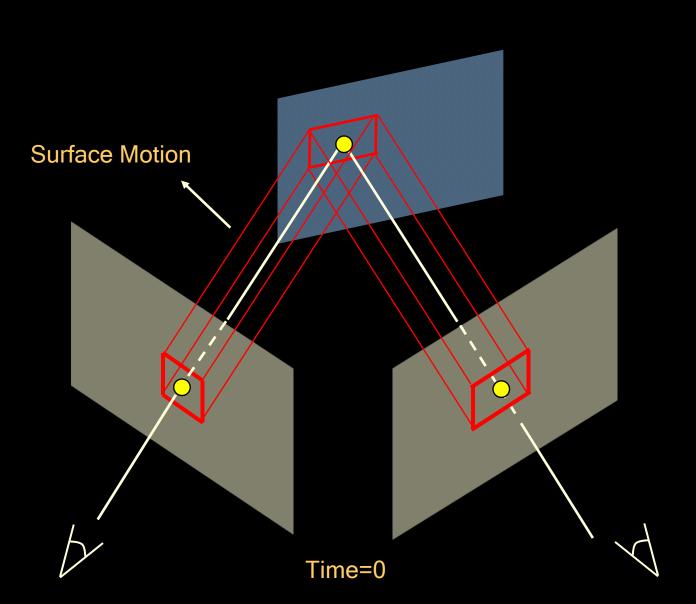


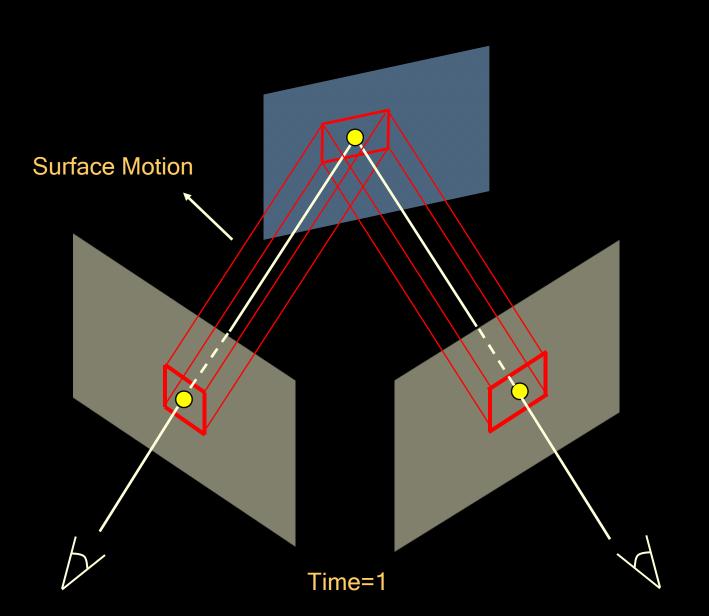


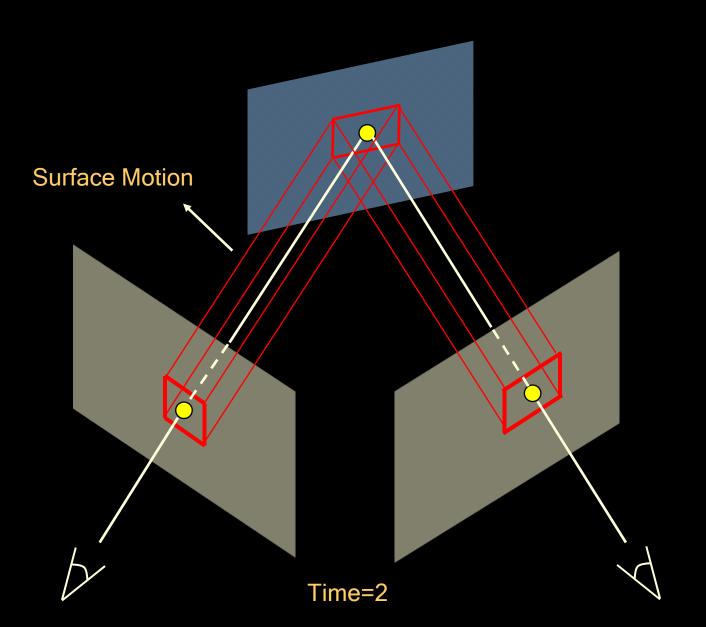


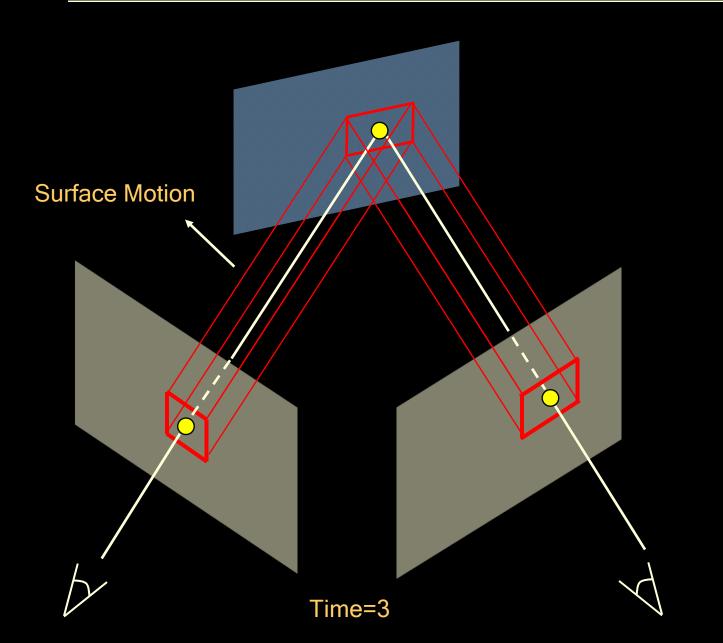


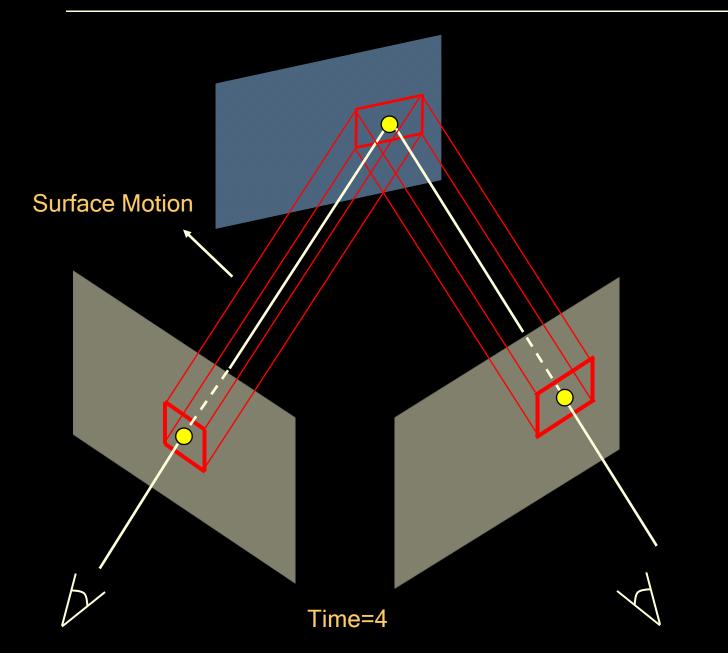


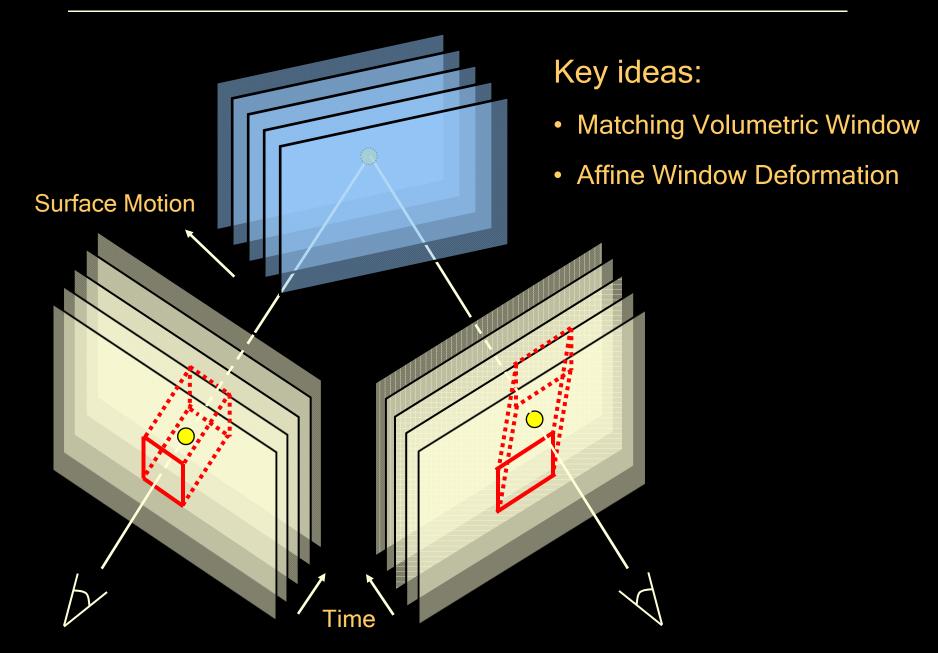


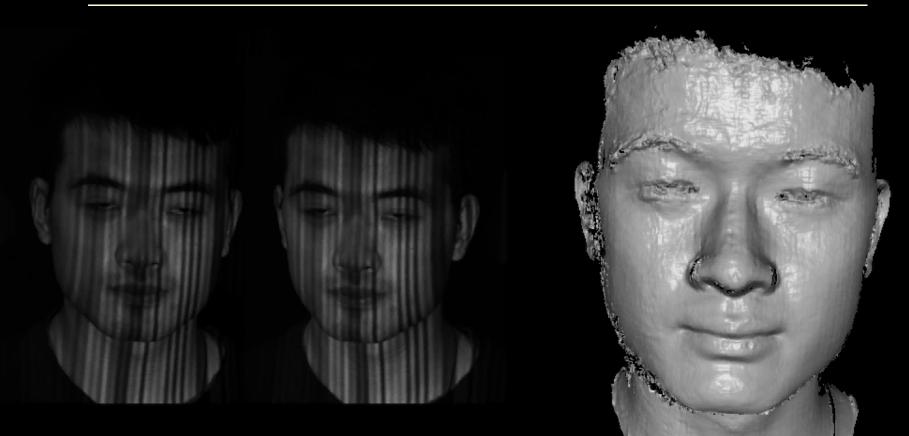






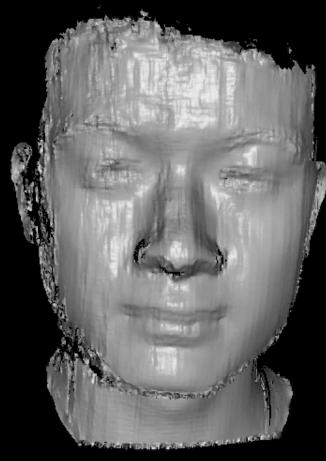




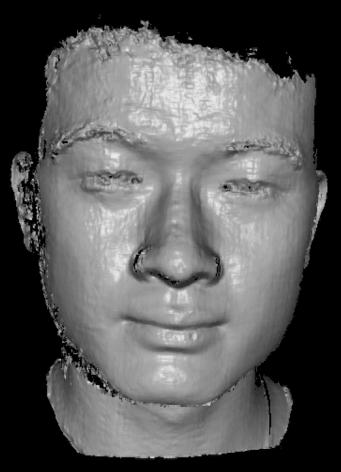


A Pair of Videos 640×480@60fps Each Spacetime Stereo W×H×T =  $9\times5\times5$  Window

### Frame-by-Frame vs. Spacetime Stereo

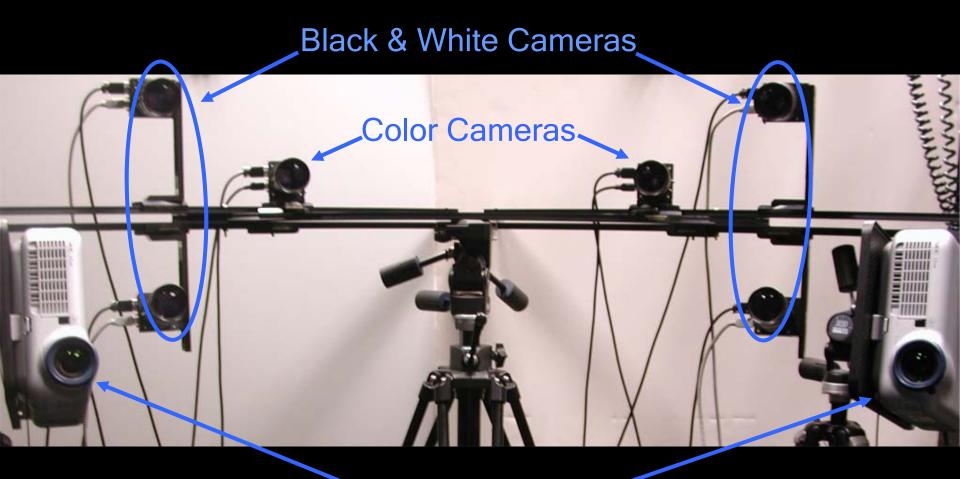


Frame-by-Frame  $W \times H = 15 \times 15$  Window



Spacetime Stereo W×H×T = 9×5×5 Window Spatially More Accurate Temporally More Stable

### **Spacetime Face Capture System**



Video Projectors

# System in Action



# Input Videos (640×480, 60fps)



Black & White Top Left



Black & White Bottom Left



Color Left



Color Right

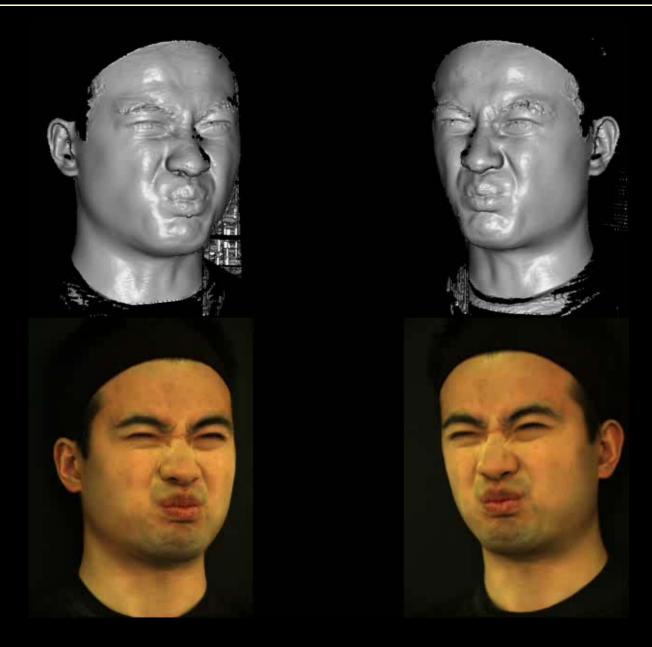


Black & White Top Right

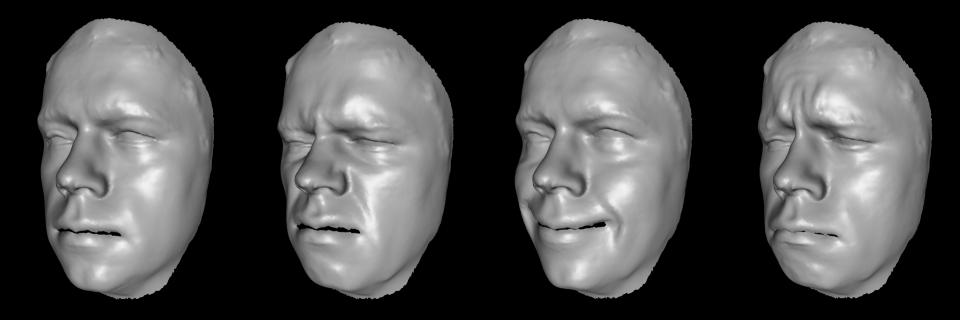


Black & White Bottom Right

# **Spacetime Stereo Reconstruction**



#### **Spacetime Stereo Reconstruction**



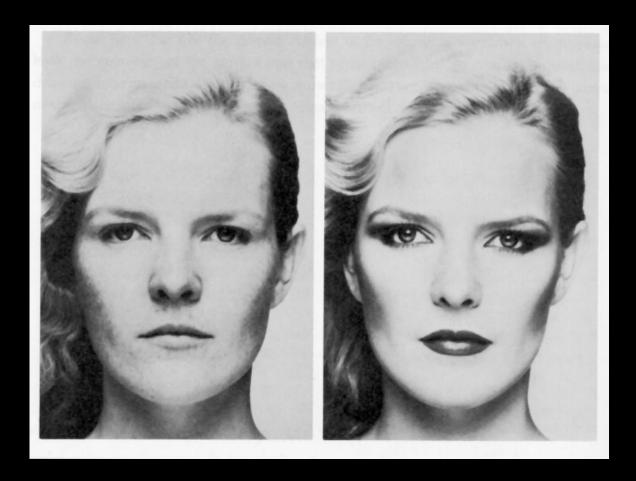
#### **Brett Allen**

#### **Spacetime Stereo Reconstruction**

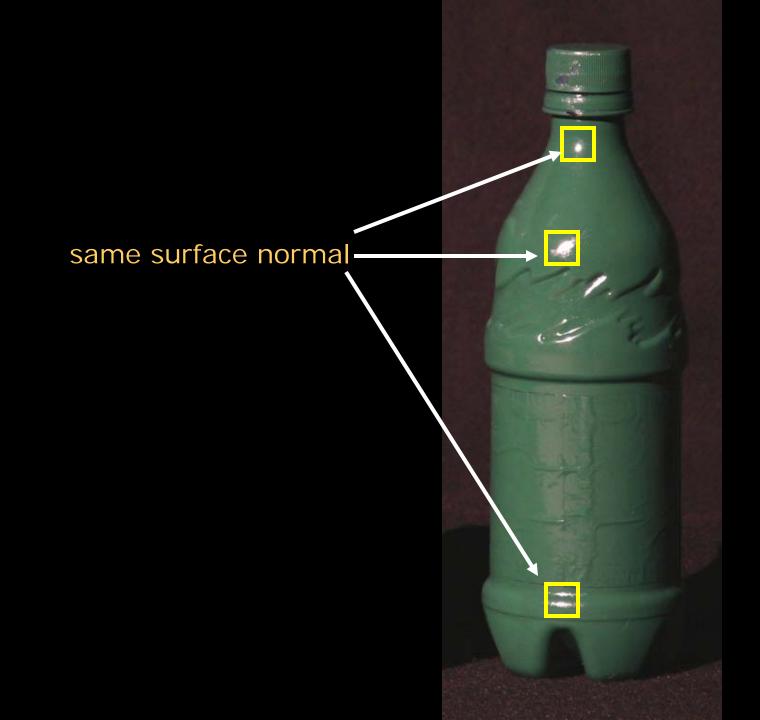


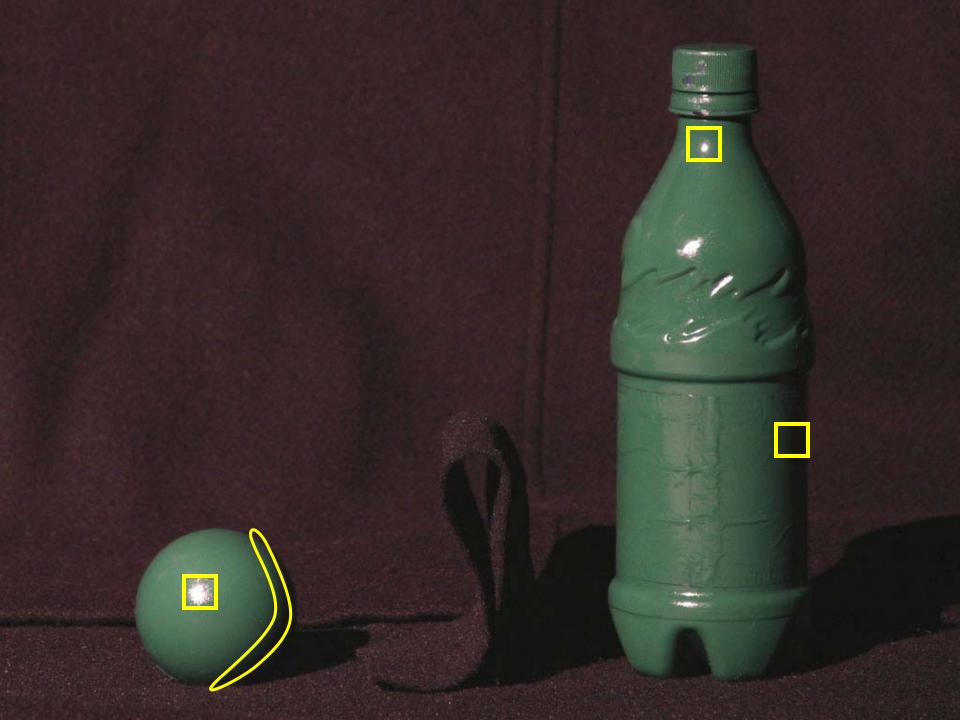
#### Daichi Sasaki

# Shading Cue



Merle Norman Cosmetics, Los Angeles

























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# Virtual views





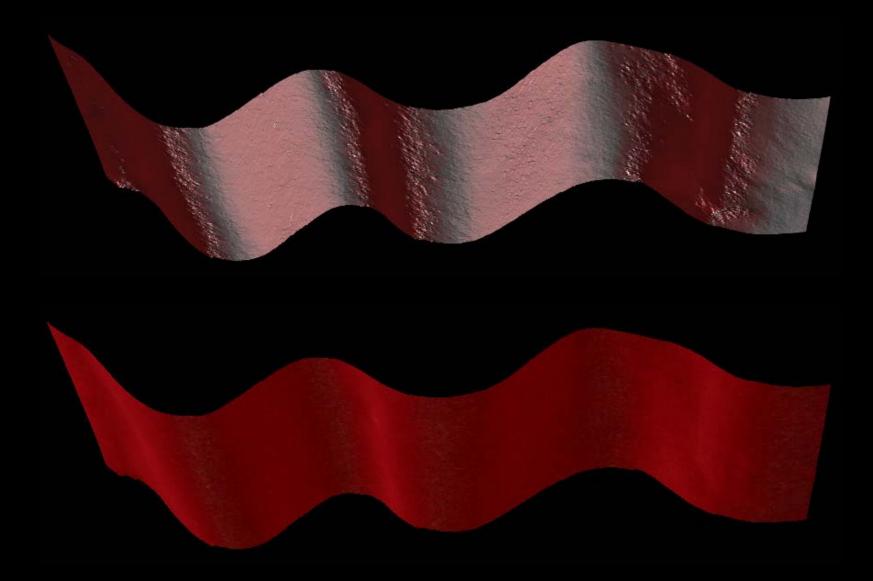




# Velvet



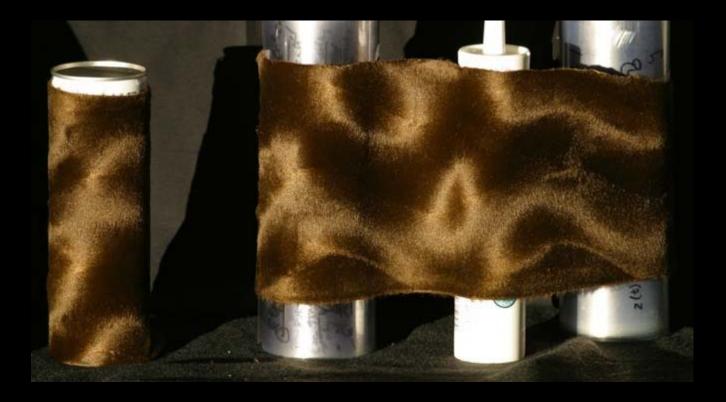
# **Virtual Views**



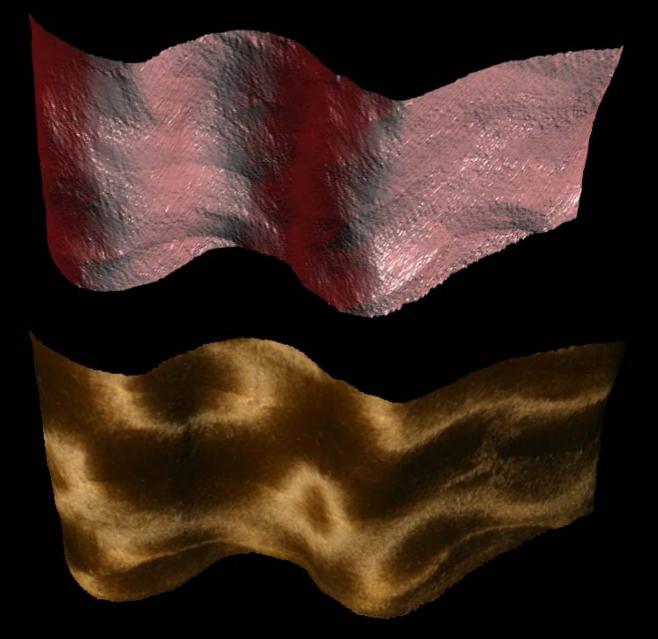
# **Brushed Fur**



# **Brushed Fur**



# **Virtual Views**





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#### Photo

#### laser scan

#### photometric stereo

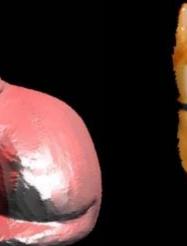
# Virtual views







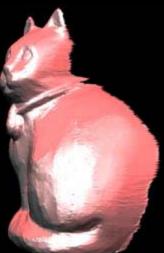


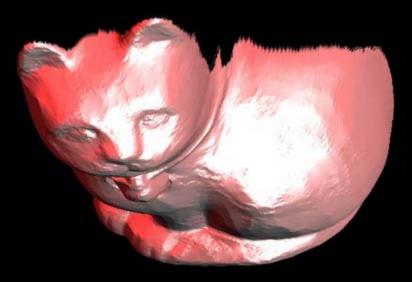












### Summary

• Laser Scanner - Static Shapes

Stereo - for Dynamic Surfaces

 Photometric Stereo - for Complex Reflectance