

CS559: Computer Graphics

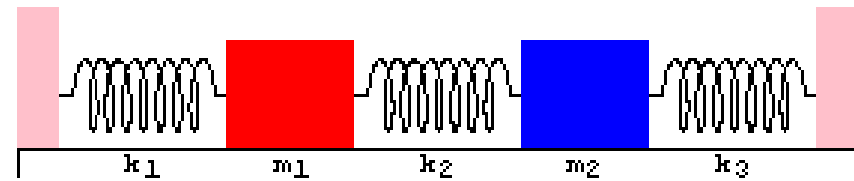
Lecture 27: Animation, Depth & Motion Blur, Ray Tracing

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Spring 2010

Particle system diff. eq. solver

We can solve the evolution of a particle system again using the Euler method:

$$\begin{bmatrix} \mathbf{x}_1^{i+1} \\ \mathbf{v}_1^{i+1} \\ \vdots \\ \mathbf{x}_n^{i+1} \\ \mathbf{v}_n^{i+1} \end{bmatrix} = \begin{bmatrix} \mathbf{x}_1^i \\ \mathbf{v}_1^i \\ \vdots \\ \mathbf{x}_n^i \\ \mathbf{v}_n^i \end{bmatrix} + \Delta t \begin{bmatrix} \mathbf{v}_1^i \\ \mathbf{f}_1^i / m_1 \\ \vdots \\ \mathbf{v}_n^i \\ \mathbf{f}_n^i / m_n \end{bmatrix}$$

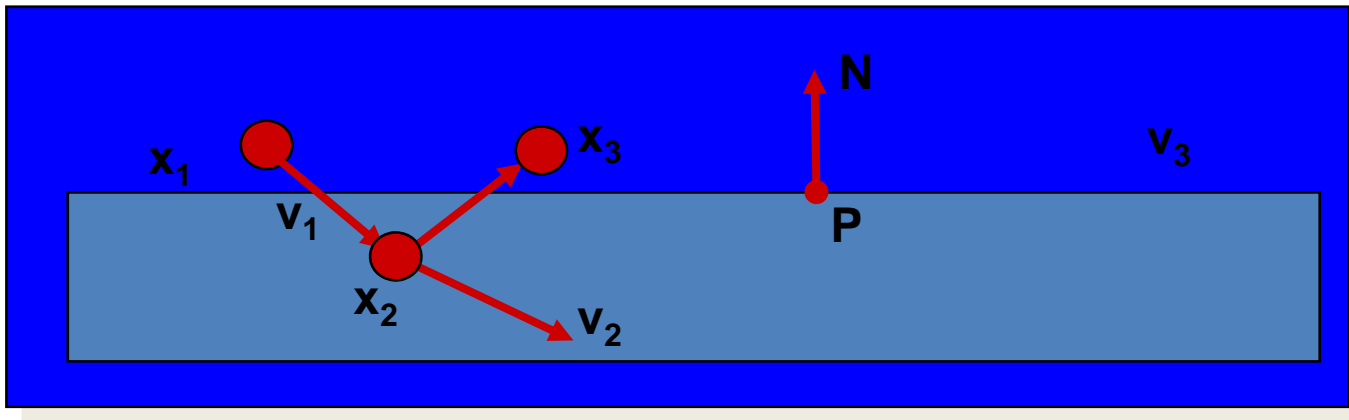


```
void EulerStep(ParticleSystem p, float DeltaT){
    ParticleDeriv(p,temp1); /* get deriv */
    ScaleVector(temp1,DeltaT) /* scale it */
    ParticleGetState(p,temp2); /* get state */
    AddVectors(temp1,temp2,temp2); /* add -> temp2 */
    ParticleSetState(p,temp2); /* update state */
    p->t += DeltaT; /* update time */
}
```



Very simple collision response

- How do you decide when you've had a collision?

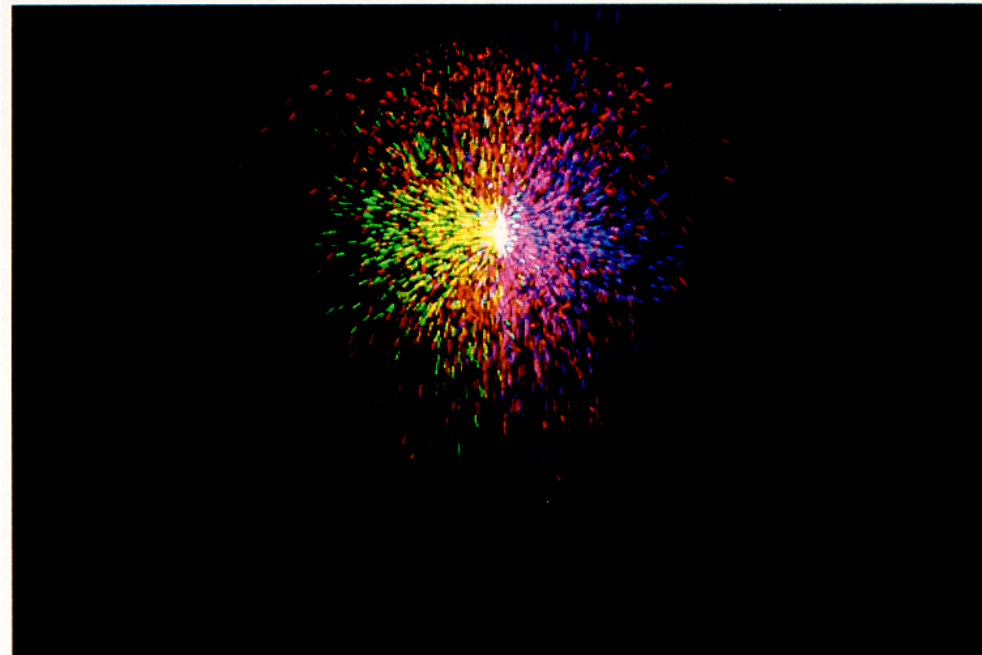


A problem with this approach is that particles will disappear under the surface.

Also, the response may not be enough to bring a particle to the other side of a wall.

Generate Particles

- Particle Attributes
 - initial position,
 - initial velocity (both speed and direction),
 - initial size,
 - initial color,
 - initial transparency,
 - shape,
 - lifetime.



WILLIAM T. REEVES, ACM Transactions
on Graphics, Vol. 2, No. 2, April 1983

Generate Particles

- Initial Particle Distribution

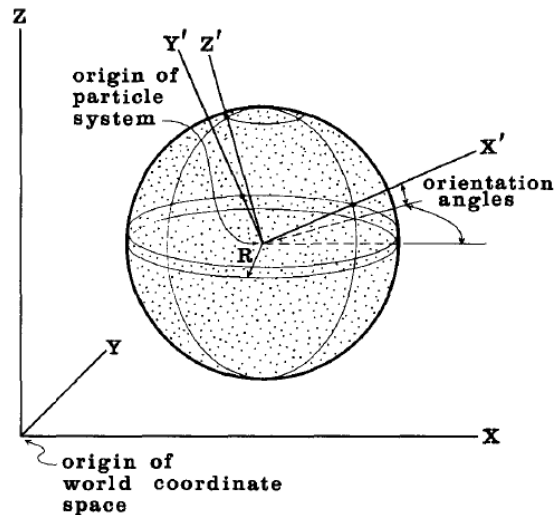
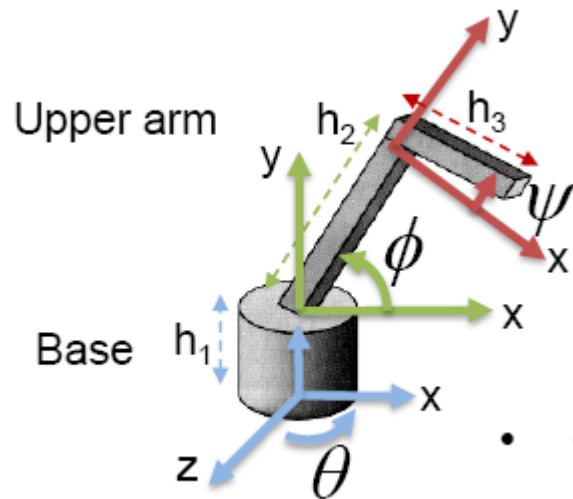
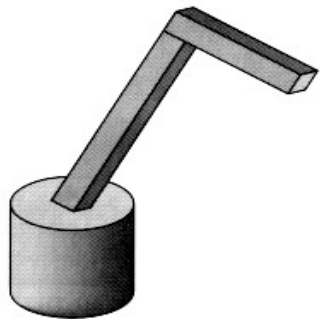


Fig. 1. Typical particle system with spherical generation shape.

- Particle hierarchy, for example
 - Skyrocket : firework
 - Clouds : water drops

Throwing a ball from a robot arm

- Let's say we had our robot arm example and we wanted to launch particles from its tip.



- How would we calculate initial speed?
 $Q = R(\theta) * T1 * R(\phi) * T2 * R(\psi) * P$
We want dQ/dt

Principles of Animation

- The following are a set of principles to keep in mind:
 1. Squash and stretch
 2. Staging
 3. Timing
 4. Anticipation
 5. Follow through
 6. Secondary action
 7. Straight-ahead vs. pose-to-pose vs. blocking
 8. Arcs
 9. Slow in, slow out
 10. Exaggeration
 11. Appeal

Squash and stretch (cont'd)

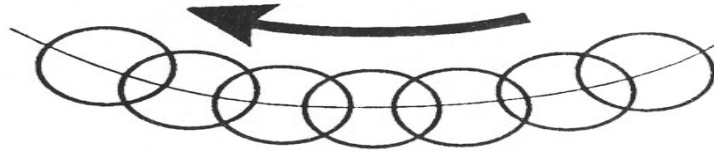


FIGURE 4a. In slow action, an object's position overlaps from frame to frame which gives the action a smooth appearance to the eye.

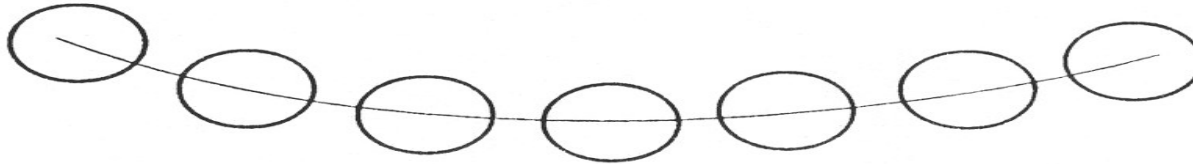


FIGURE 4b. Strobing occurs in a faster action when the object's positions do not overlap and the eye perceives separate images.

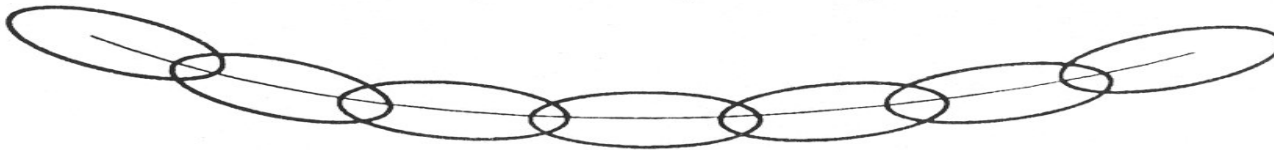
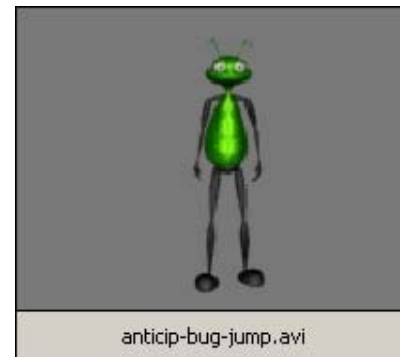


FIGURE 4c. Stretching the object so that its positions overlap again will relieve the strobing effect.

Anticipation

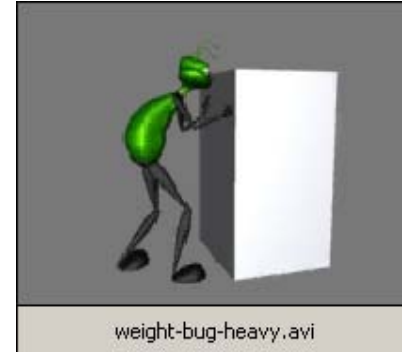
- An action has three parts: anticipation, action, reaction.
- Anatomical motivation: a muscle must extend before it can contract.



- Watch: [bugs-bunny.virtualdub.new.mpg](#)
- Prepares audience for action so they know what to expect.
- Directs audience's attention.

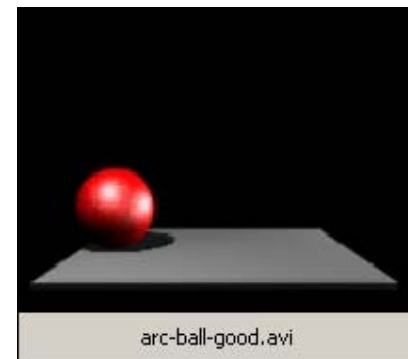
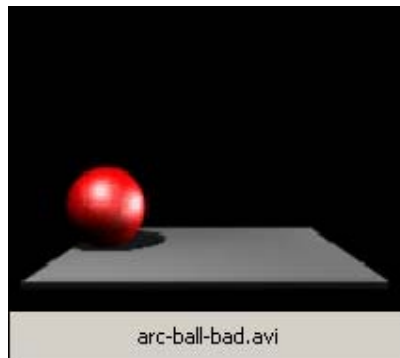
Anticipation (cont'd)

- Amount of anticipation (combined with timing) can affect perception of speed or weight.



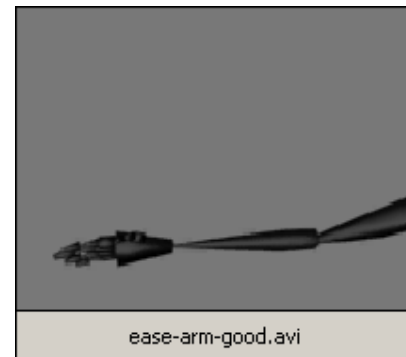
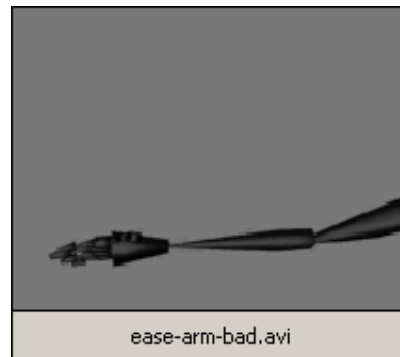
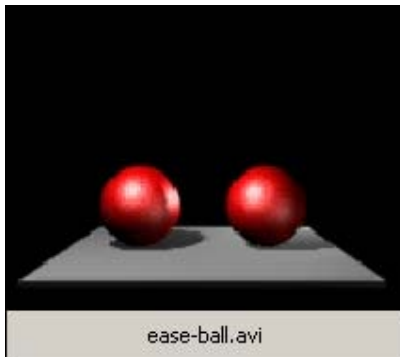
Arcs

- Avoid straight lines since most things in nature move in arcs.



Slow in and slow out

- An extreme pose can be emphasized by slowing down as you get to it (and as you leave it).
- In practice, many things do not move abruptly but start and stop gradually.



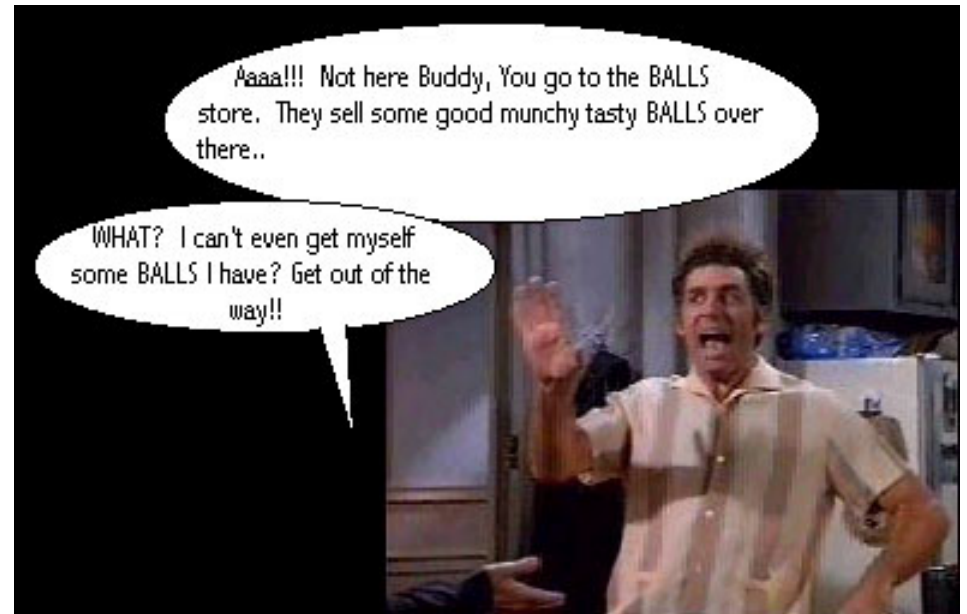
Exaggeration

- Get to the heart of the idea and emphasize it so the audience can see it.



Exaggeration

- Get to the heart of the idea and emphasize it so the audience can see it.



Appeal

- The character must interest the viewer.
- It doesn't have to be cute and cuddly.
- Design, simplicity, behavior all affect appeal.
- Example: Luxo, Jr. is made to appear childlike.

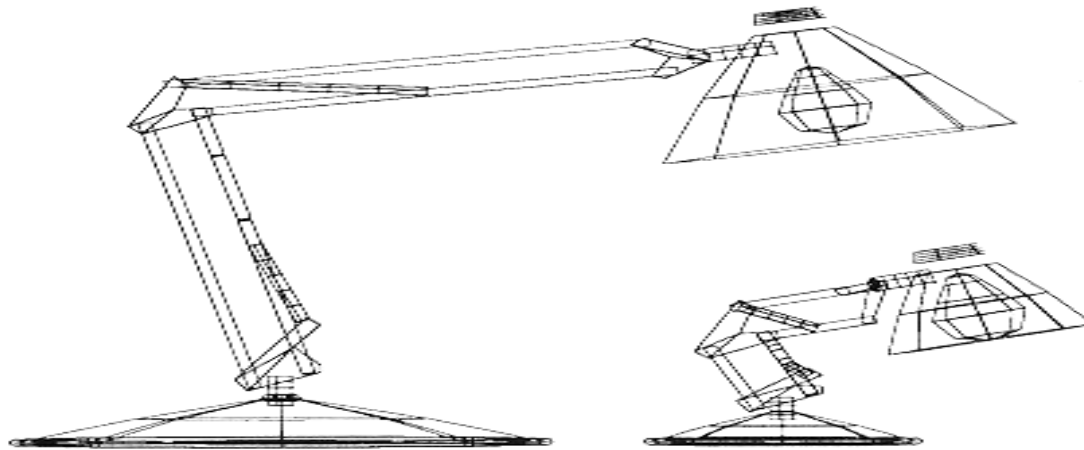


FIGURE 11. Varying the scale of different parts of Dad created the child-like proportions of Luxo Jr.

Appeal (cont'd)

- Note: avoid perfect symmetries.

THIS IS WHAT'S CALLED A "WOODEN" CHARACTER .

EACH EYE , EAR , ARM , HAND , FINGER , LEG , COLLAR , SHOE , ETC. LOOKS THE SAME AS ITS COUNTER-PART. THE RESULT IS A VERY STIFF LOOKING POSE .



PAGE 3

...THIS CHARACTER LOOKS MORE NATURAL SIMPLY BECAUSE EACH PART OF THE BODY VARIES IN SOME WAY FROM THE CORRESPONDING OPPOSITE PART.



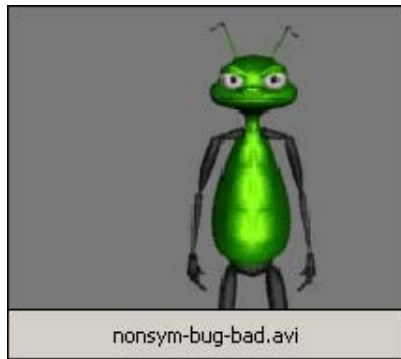
①①① EYES IN PERSPECTIVE



FINGERS THAT VARY GIVE THE HANDS A MORE DYNAMIC LOOK.

Appeal (cont'd)

- Note: avoid perfect symmetries.



Ray Tracing

Shirley Ch 4

Effects needed for Realism

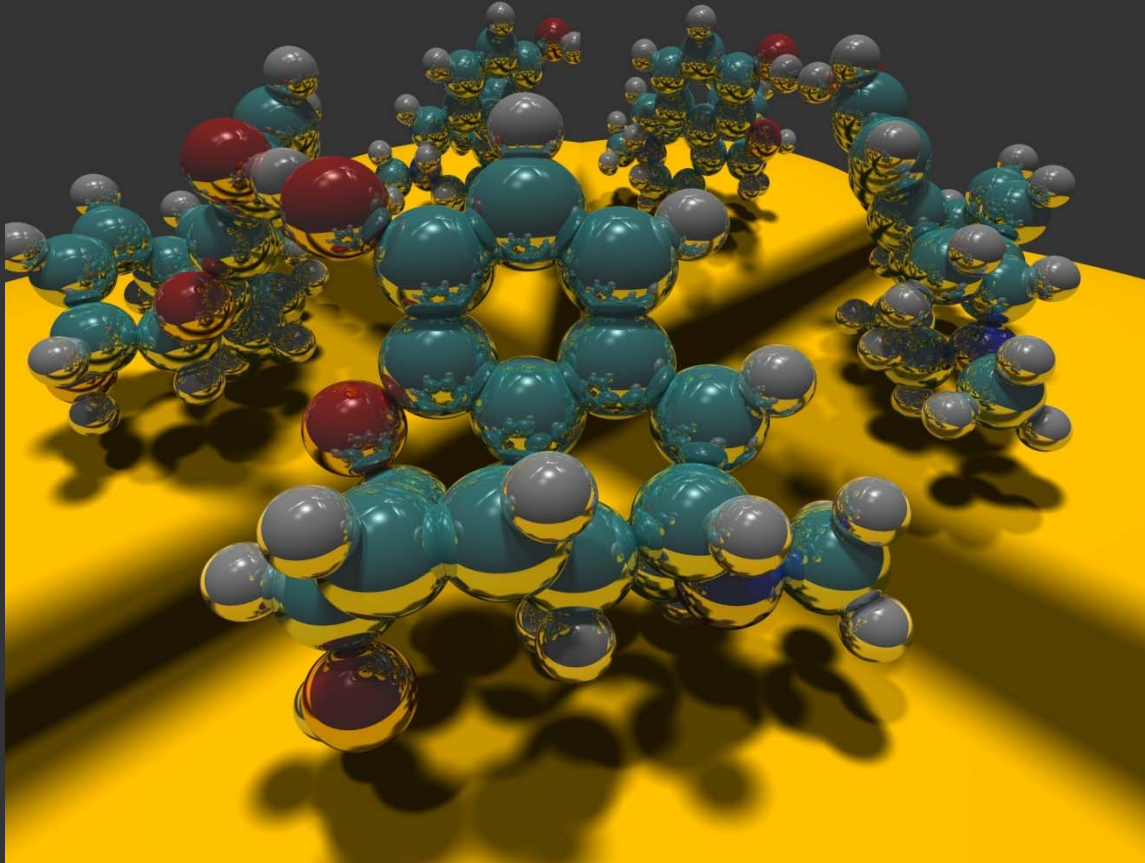


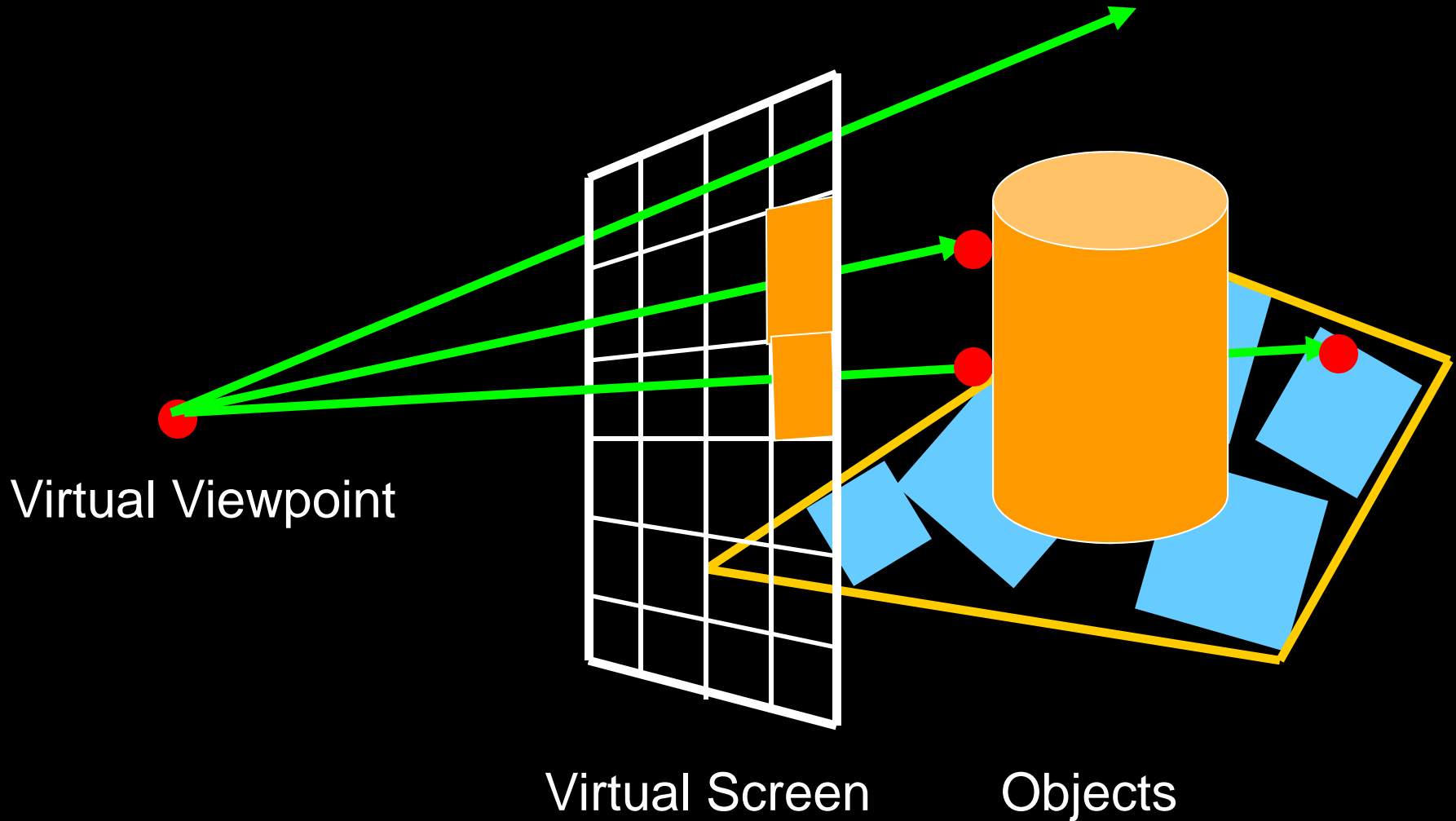
Image courtesy
Paul Heckbert 1983

- Reflections (Mirrors and Glossy)
- Transparency (Water, Glass)
- Interreflections (Color Bleeding)
- (Soft) Shadows
- Complex Illumination (Natural, Area Light)
- Realistic Materials (Velvet, Paints, Glass)
- And many more

Ray Tracing

- Different Approach to Image Synthesis as compared to Hardware pipeline (OpenGL)
 - OpenGL : Object by Object
 - Ray Tracing : Pixel by Pixel
- Advantage:
 - Easy to compute shadows/transparency/etc
- Disadvantage:
 - Slow (in early days)

Basic Version: Ray Casting



Raytracing sees the objects, finds out its geometry (lights, materials)

Ray Casting

Produce same images as with OpenGL

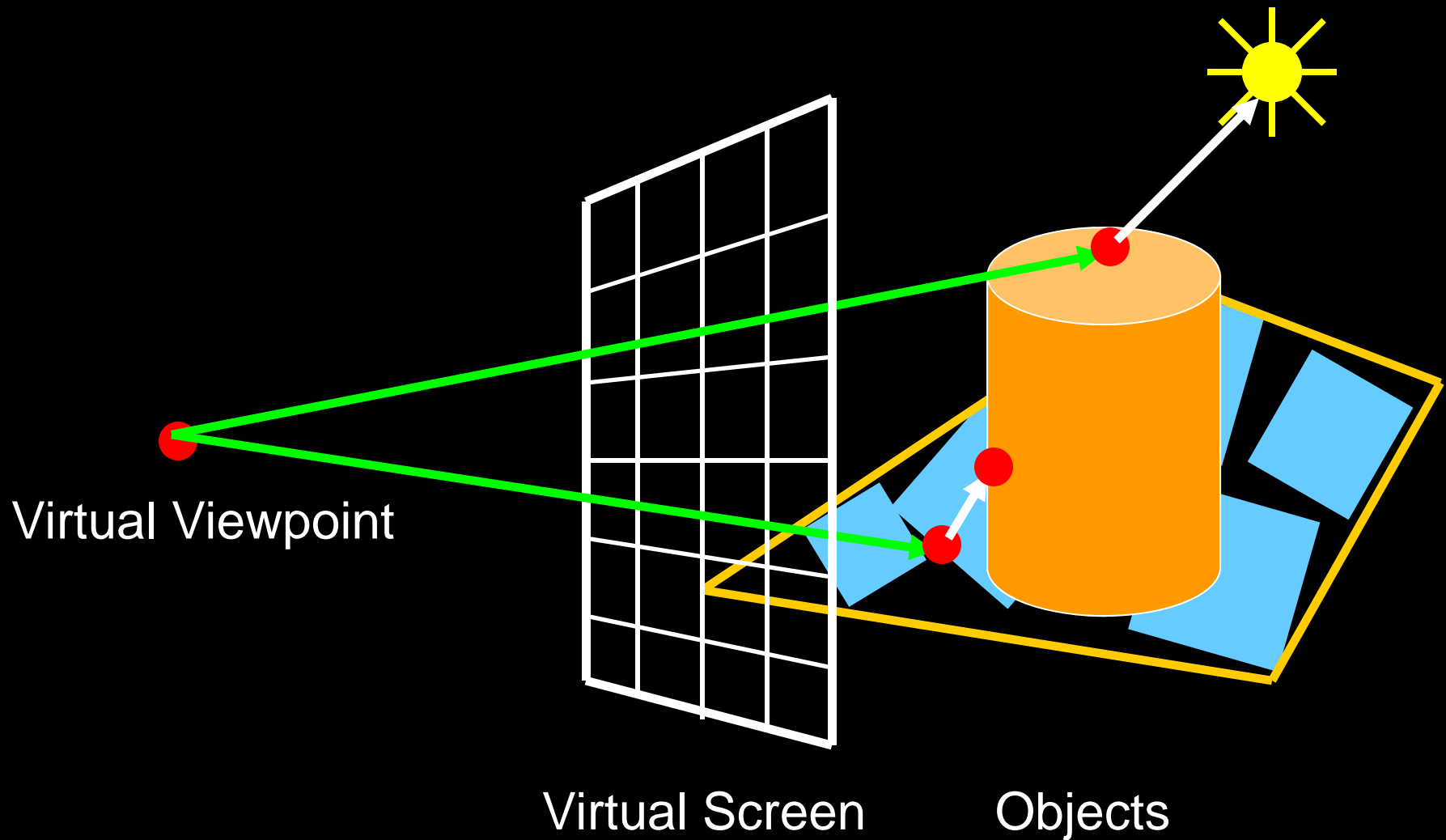
- Visibility per pixel instead of Z-buffer
- Find nearest object by shooting rays into scene
- Shade it as in standard OpenGL

Comparison to hardware scan-line

- Per-pixel evaluation, per-pixel rays (not scan-convert each object). On face of it, costly
- But good for walkthroughs of extremely large models (amortize preprocessing, low complexity)
- More complex shading, lighting effects possible

Shadows

Light Source



Virtual Screen

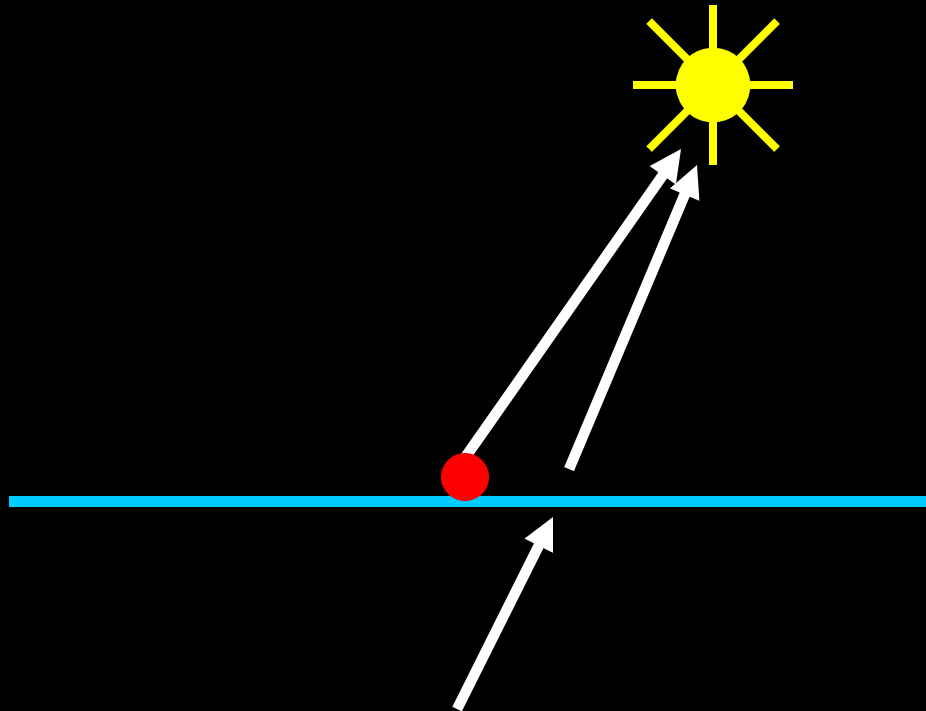
Objects

Shadow ray to light is blocked by object visible

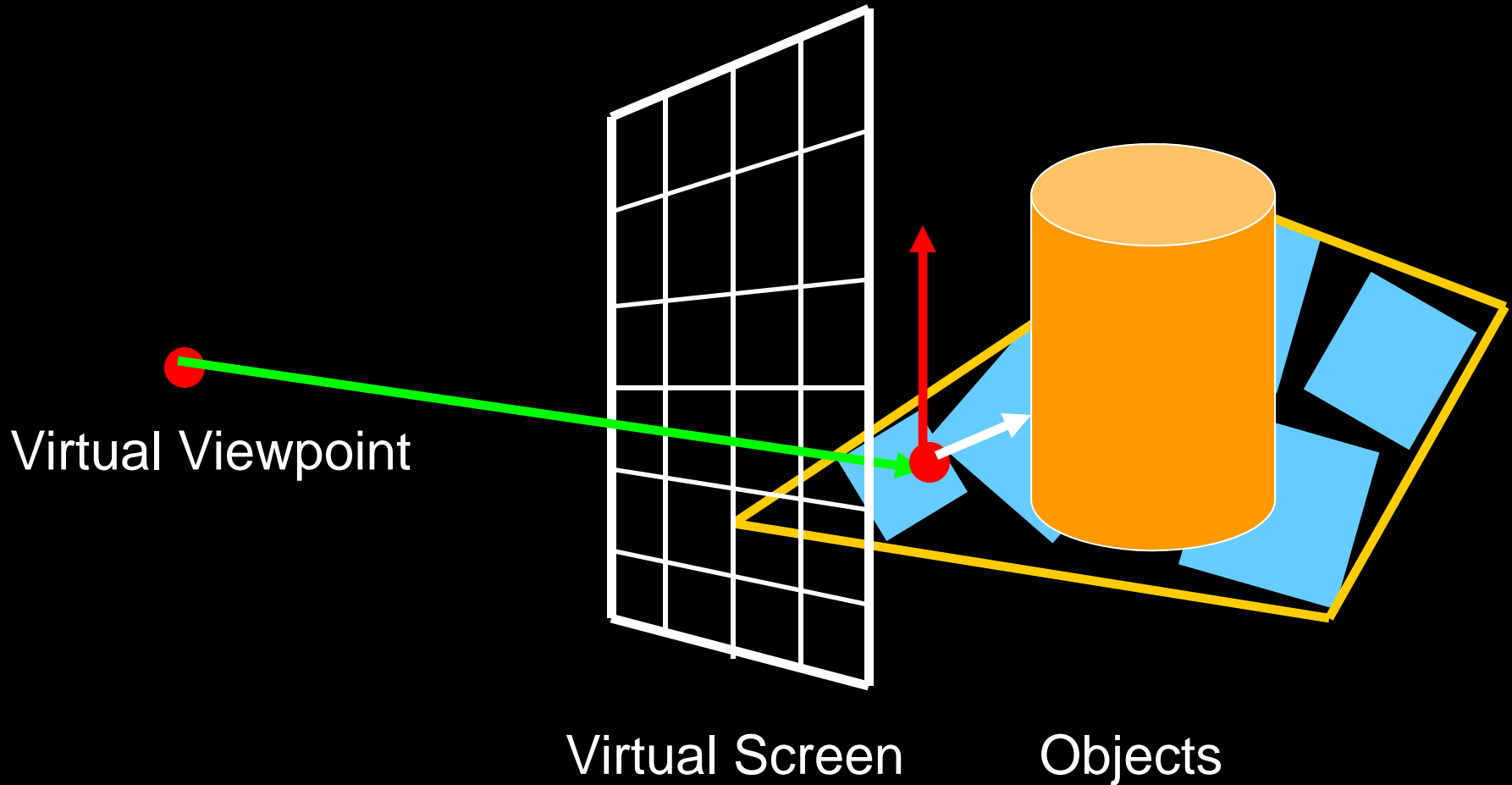
10.5 in textbook

Shadows: Numerical Issues

- Numerical inaccuracy may cause intersection to be below surface (effect exaggerated in figure)
- Causing surface to incorrectly shadow itself
- Move a little towards light before shooting shadow ray



Mirror Reflections/Refractions



Generate reflected ray in mirror direction,
Get reflections and refractions of objects

Recursive Ray Tracing (Core Idea)

For each pixel

- Trace Primary Eye Ray, find intersection
- Trace Secondary Shadow Ray(s) to all light(s)
 - `Color = Visible1 ? Illumination Model(light1) : 0 ;`
 - `Color += Visible2 ? Illumination Model(light2) : 0 ;`
 - ...

- Trace Reflected Ray

- `Color += reflectivity * Color of reflected ray`

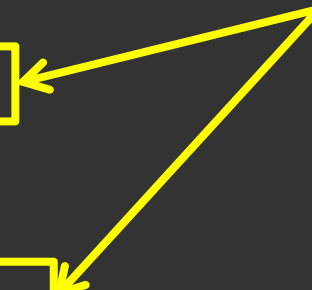
- Trace Refracted Ray

- `Color += transparency * Color of refracted ray`

Recursive function Calls

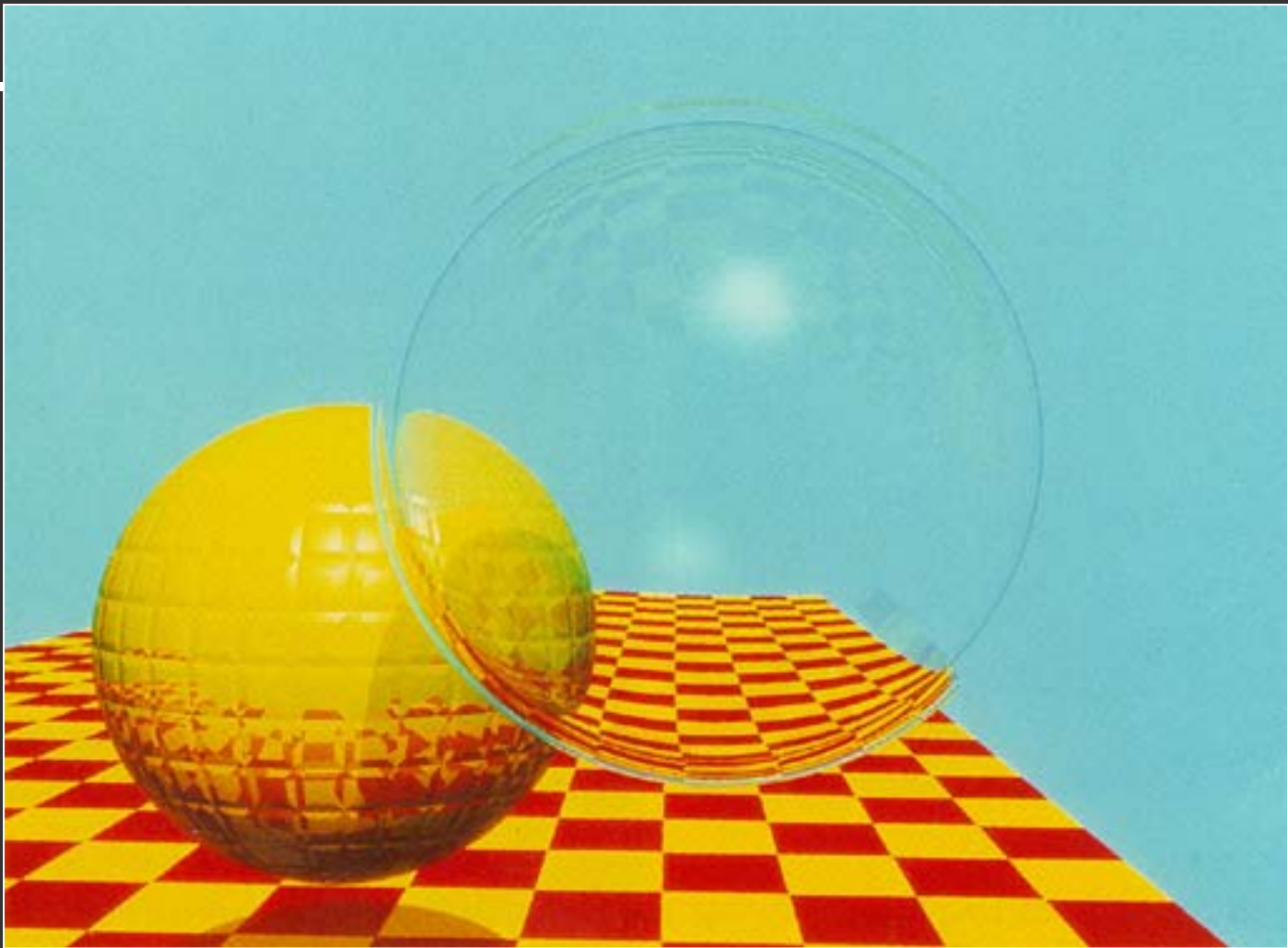
Color of reflected ray

Color of refracted ray

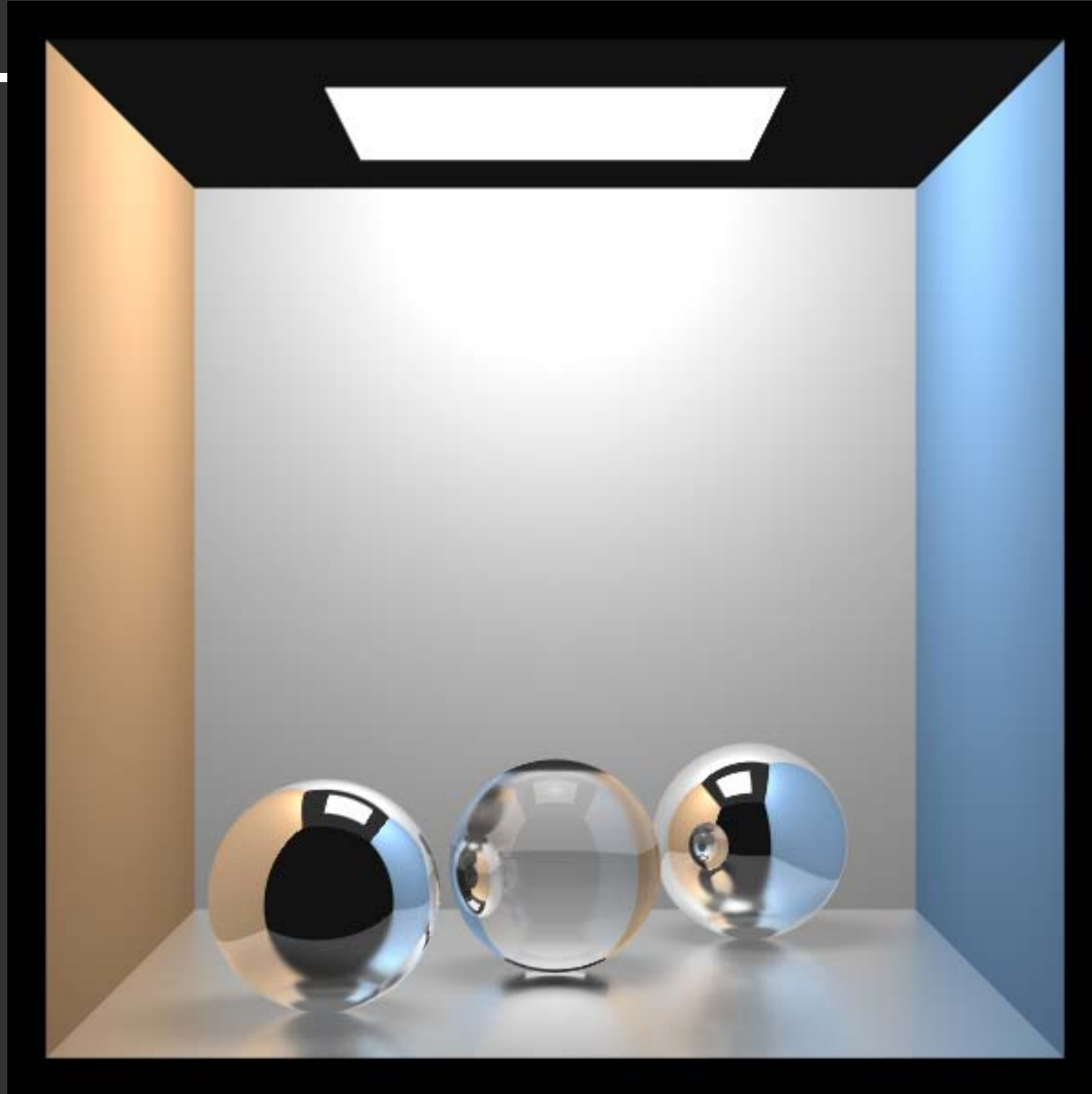


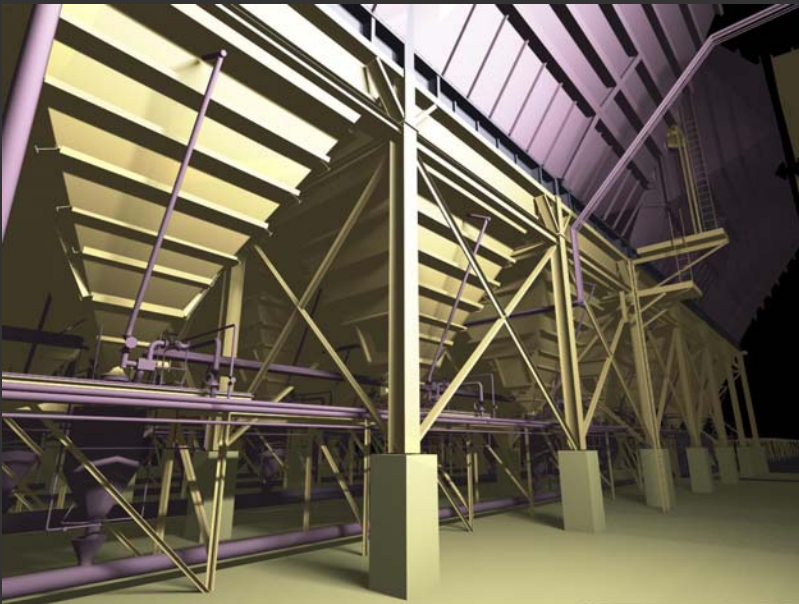
Problems with Recursion

- Reflection rays may be traced forever
- Generally, set maximum recursion depth



Turner Whitted 1980





Effects needed for Realism

- (Soft) Shadows
- Reflections (Mirrors and Glossy)
- Transparency (Water, Glass)
- Interreflections (Color Bleeding)
- Complex Illumination (Natural, Area Light)
- Realistic Materials (Velvet, Paints, Glass)

Discussed in this lecture

Not discussed so far but possible with distribution ray tracing
(13.4)

Hard (but not impossible) with ray tracing; radiosity methods

How to implement Ray tracing?

- Ray parameterization
- *Ray-Surface Intersection*

Ray/Object Intersections

- Heart of Ray Tracer
 - One of the main initial research areas
 - Optimized routines for wide variety of primitives
- Various types of info
 - Shadow rays: Intersection/No Intersection
 - Primary rays: Point of intersection, material, normals, Texture coordinates

Example

- Sphere
 - How to decide there is an intersection?
- Triangle
 - How to decide the intersection is inside?
- Polygon
 - How to decide the intersection is inside?
- How about an ellipsoid?

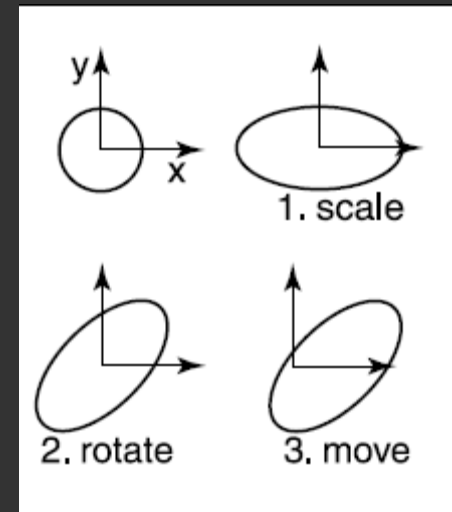
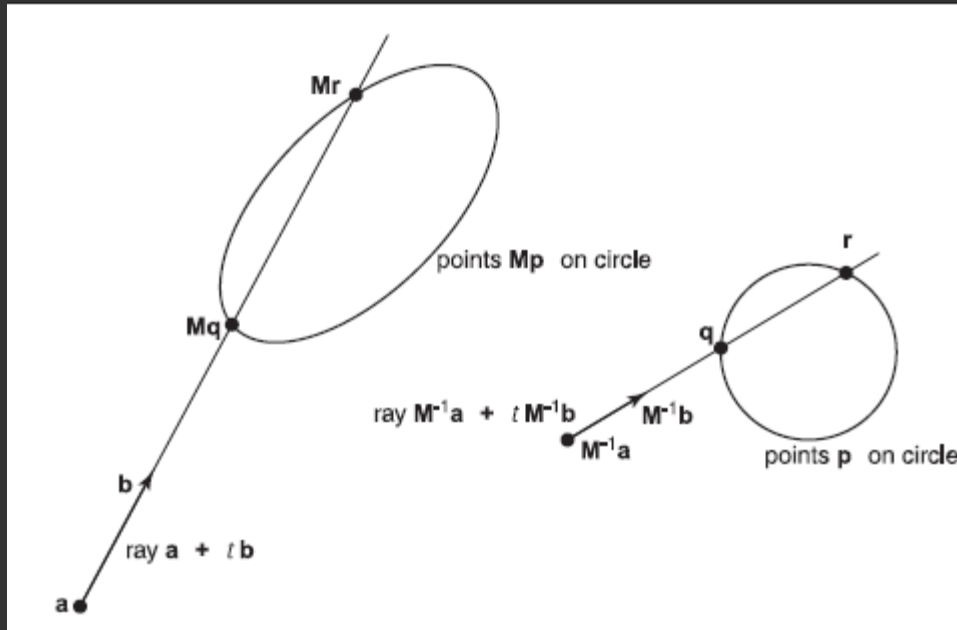
Ray-Tracing Transformed Objects

We have an optimized ray-sphere test

- But we want to ray trace an ellipsoid...

Solution: Ellipsoid transforms sphere

- Apply inverse transform to ray, use ray-sphere



Acceleration

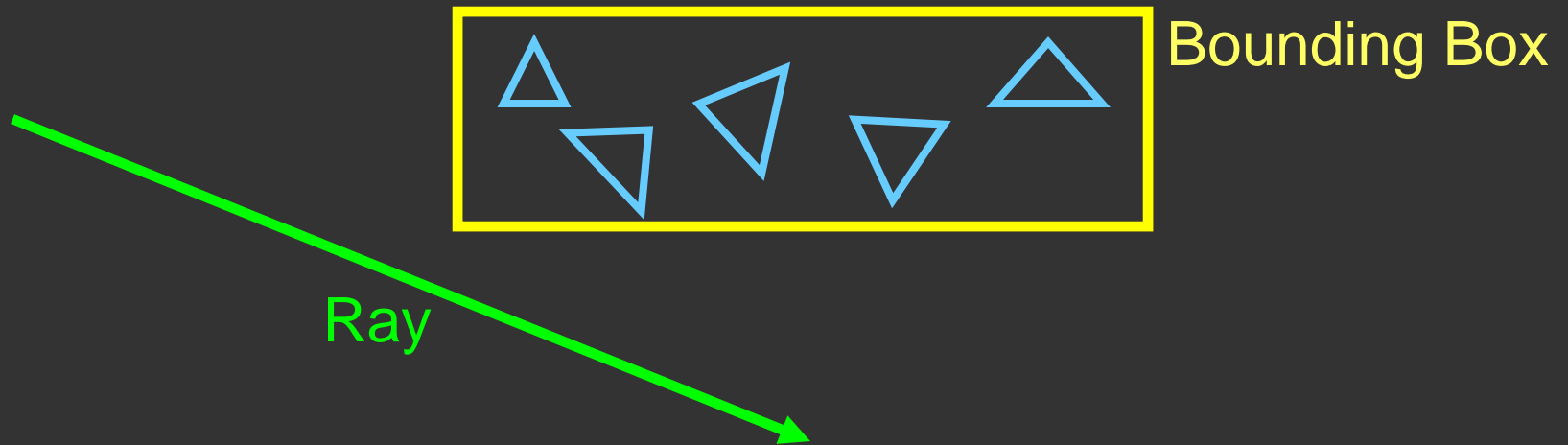
Testing each object for each ray is slow

- Faster Intersections
 - Optimized Ray-Object Intersections
 - *Fewer Intersections*

Acceleration Structures

Bounding boxes (possibly hierarchical)

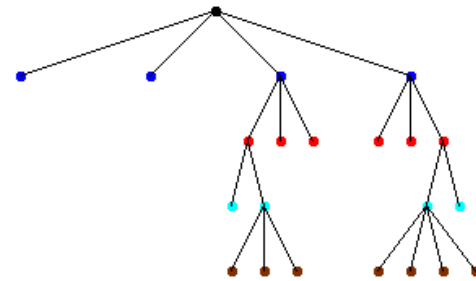
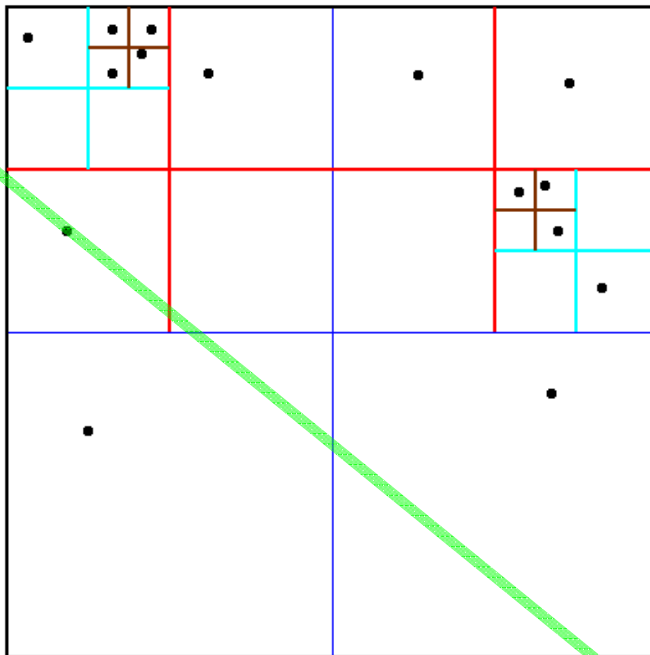
If no intersection bounding box, needn't check objects



Different Spatial Hierarchies (Oct-trees, kd trees, BSP trees)

Octree

Adaptive quadtree where no square contains more than 1 particle



K-d tree

