

# Random Walks based Multi-Image Segmentation: Quasiconvexity Results and GPU-based Solutions

## COSEGMENTATION

*Cosegmentation* is the task of segmenting a common salient foreground object from two or more images.

We approach cosegmentation as an optimization problem of the form

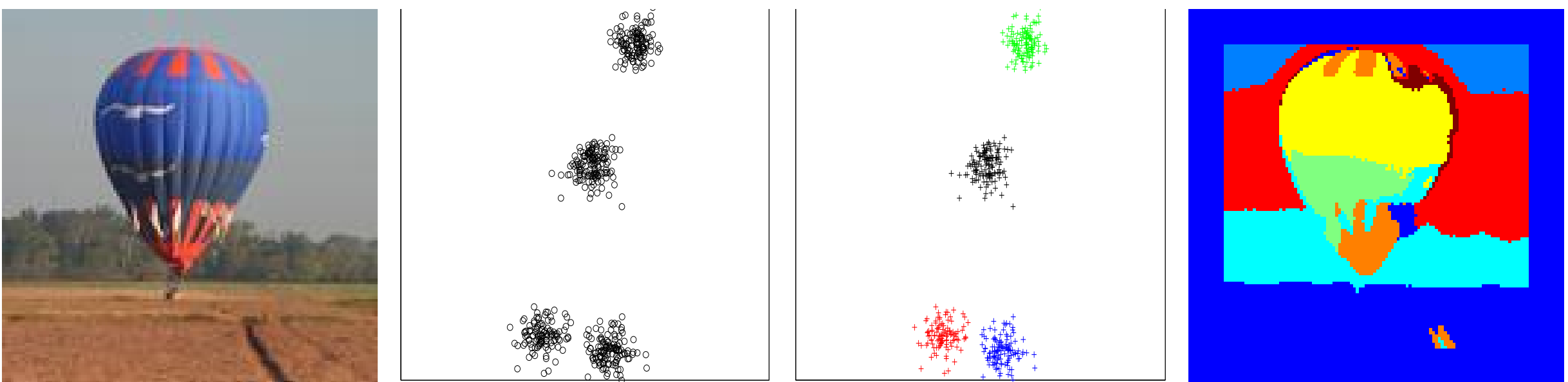
$$\min_{\mathbf{x}} \sum_{i \in \text{images}} E_{\text{segmentation}}(x_i) + E_{\text{cosegmentation}}(x_1, x_2, \dots)$$

**Random Walks based  $E_{\text{segmentation}}$  provides fast and effective nonparametric cosegmentation without entropy assumptions.**

## HISTOGRAM DISTANCE PENALTIES

A *histogram* gives a global description by binning/counting features.

Histograms bin similar pixels, and so provide a similarity measure in cosegmentation by comparing the histograms of subregions.



Use  $E_{\text{cosegmentation}}$  based on a distance measure between histograms.

## OPTIMIZATION MODEL

$E_{\text{segmentation}}(x_i) = x_i^T L_i x_i$ : Random walker energy with Laplacian matrix  $L_i$ .

Cosegmentation potential  $\|h_i - \bar{h}\|_2^2$ , the distance between foreground histogram  $h_i$  and common model histogram  $\bar{h}$ .

Given histogram matrices  $H_i$  and seeds  $s$  with values  $m_i$ , solve

$$\begin{aligned} \min_{x_i, h_i, \bar{h}} \quad & \sum_i x_i^T L_i x_i + \lambda \|h_i - \bar{h}\|_2^2 \\ \text{s.t.} \quad & x_i \in [0, 1]^{n_i}, \quad x_i^{(s)} = m_i^{(s)}, \quad H_i x_i = h_i, \quad i = 1 \dots m. \end{aligned}$$

to output segmentation potentials  $x_i$  for each image  $i$ .

## Box-QP

The model can be expressed as a QP with box constraints:

$$\begin{aligned} \min_{x_1, \dots, x_m, \bar{h}} \quad & \begin{bmatrix} x_1 \\ \vdots \\ x_m \\ \bar{h} \end{bmatrix}^T \begin{bmatrix} L_1 + \lambda H_1^T H_1 & & -\lambda H_1 \\ & \ddots & \\ & & L_m + \lambda H_m^T H_m - \lambda H_m \\ -\lambda H_1^T & \dots & -\lambda H_m^T & \lambda mI \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_m \\ \bar{h} \end{bmatrix} \\ \text{s.t.} \quad & l_i \leq x_i \leq u_i \quad x_i \text{ is of size } [0, 1]^{n_i} \quad i = 1, \dots, m \end{aligned}$$

where  $(l_i, u_i)$  is  $(1, 1)$  for foreground seeds,  $(0, 0)$  for background seeds, and  $(0, 1)$  otherwise.

Solved via GPCG, alternating gradient projection/conjugate gradient.

After distributing the multiplication

$$(L_i + H_i^T H_i) x_i = L x_i + H_i^T (H_i x_i).$$

we can calculate gradient with sparse matrix computations on GPU.

## SCALE-FREE SIMILARITIES

A metric distance between histogram vectors will be dependent on *scale* and only accurate segment foregrounds of the same size.

Cosegmentation can be robust to distances in scale by choosing an energy  $E$  such that

$$E(h, \bar{h}) = E(sh, \bar{h}) \quad \forall s \in \mathbb{R} \setminus \{0\}$$

This condition is met by a *normalized* histogram similarity, such as

$$-\frac{\langle h, \bar{h} \rangle}{\|h\|_2} = -\|\bar{h}\|_2 \cos(\angle h \bar{h})$$

## QUASICONVEXITY

A scale-free distance is not *convex* and used in  $E_{\text{coseg}}$  cannot efficiently be solved through traditional methods. It is however *quasiconvex* in  $h$ .

Quasiconvexity is the property of a function  $f$  such that its *sublevel sets* are convex:

$$f((1 - \lambda)x + \lambda x') \leq \max(f(x), f(x')) \quad \forall x, x' \in X, \lambda \in [0, 1]$$

## OPTIMIZATION SCHEME

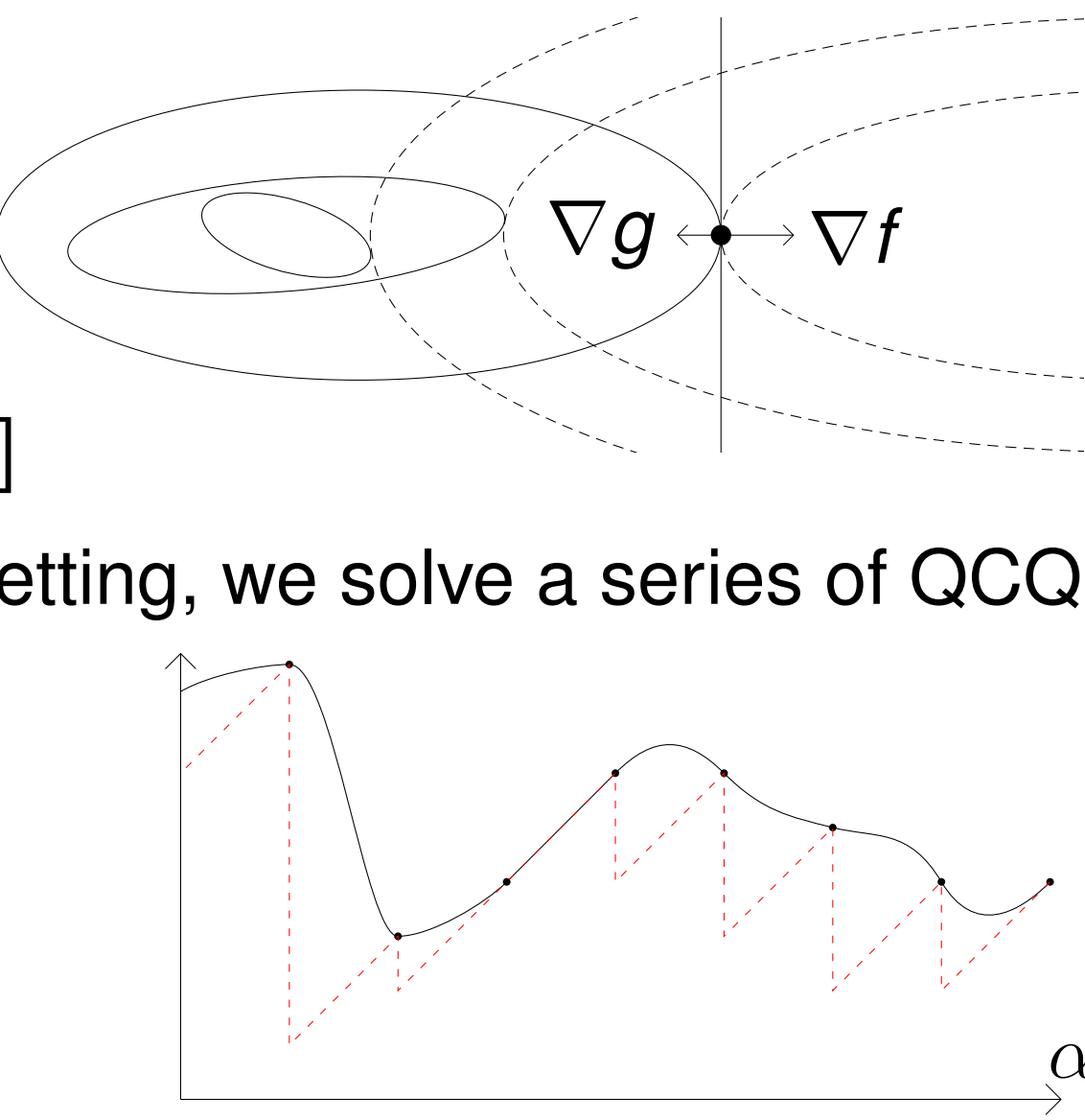
Given a pair of quasiconvex functions  $f, g$ , the solution to  $\min_x f(x) + g(x)$  is a solution to

$$\begin{aligned} \min_x \quad & f(x) \\ \text{s.t.} \quad & g(x) \leq \alpha \end{aligned}$$

for  $\alpha \in [\min_x g(x), g(\arg\min_x f(x))]$

In the epitome-based RWCoseg setting, we solve a series of QCQPs,

$$\begin{aligned} \min_{x, h} \quad & x^T L x \\ \text{s.t.} \quad & Hx = h, \quad 0 \leq x \leq 1 \\ & h^T (\bar{h} \bar{h}^T - \alpha I) h \leq 0 \end{aligned}$$

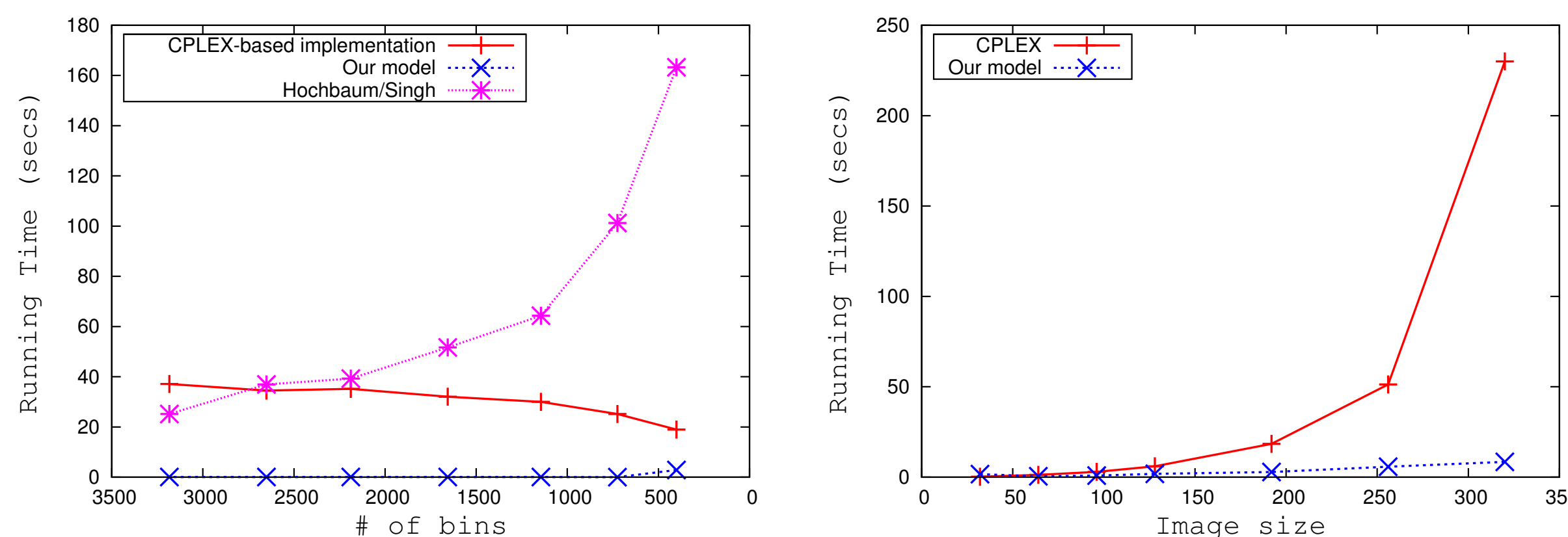


performing a grid search over  $\alpha$  to find the optimal segmentation.

$f + g$  restricted to the  $\alpha$  solutions will be *one-sided Lipschitz*.

Can therefore provide a lower bound on true minimum from solutions given a set of  $\alpha$ 's.

## RUNNING TIME



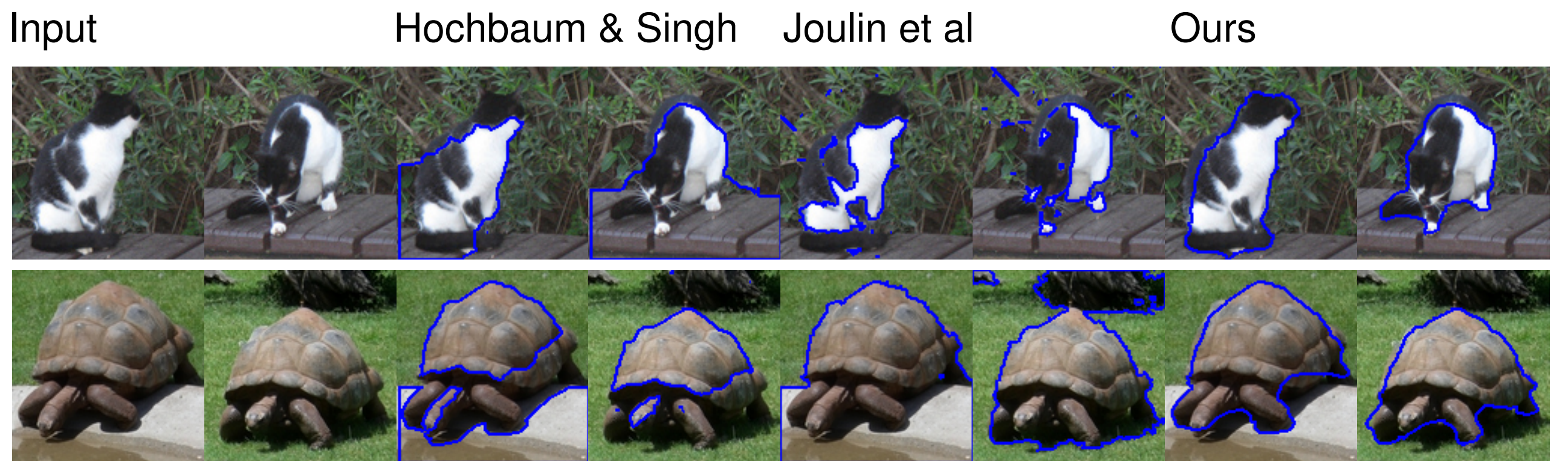
Running time varies with histogram complexity and image size.

## COMPARISON TO INDEPENDENT RW

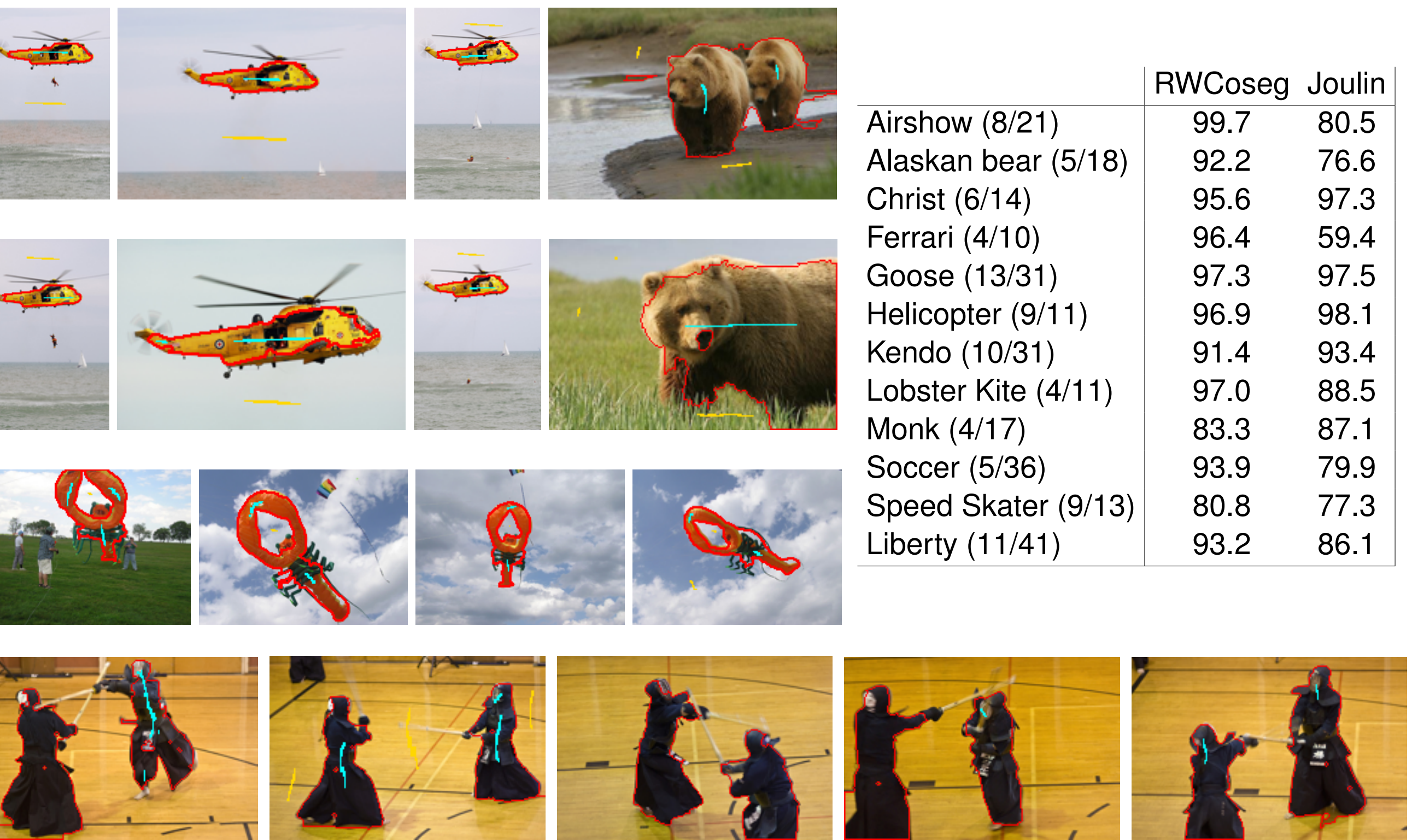


Segmentation potentials comparing Random Walks cosegmentation with independent runs on the same input.

## COSEGMENTATION COMPARISON



## ICOSEG DATASET



Segmentation accuracy for some iCoseg image sets. Subsets were chosen which have similar appearance under a histogram model.

## COSEGMENTATION FOR VIDEO



May be applied to video, with "histograms" based on optical flow and frame-by-frame penalties  $\|h_i - h_{i+1}\|_2^2$