HASH INDEXES

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WHAT IS THIS LECTURE ABOUT?

Hash indexes

- Static Hashing
 - what is the I/O cost?
 - problems with static hashing
- Extendible Hashing
 - insertion
 - deletion

HOW TO EVALUATE AN INDEX?

- What access types does it support?
 - *e.g.* equalitiy search, range search, etc.
- Time to access a record
- Time to insert a record
- Time to delete a record
- How much **space** does it use?

HASH INDEXES

- efficient for equality search
- not appropriate for range search
- Types of hash indexes:
 - static hashing
 - extendible (dynamic) hashing

STATIC HASHING

- A **hash index** is a collection of **buckets**
 - bucket = primary page + overflow pages
 - each bucket contains one or more data entries
- To find the bucket for each record, we use a hash function *h* applied on the search key *k*
 - N = number of buckets
 - $h(k) \mod N$ = bucket in which the data entry belongs
- Records with different search key may belong in the same bucket

STATIC HASHING: EXAMPLE



OPERATIONS ON HASH INDEXES

Equality search (*search-key = value*)

- apply the hash function on the search key to locate the appropriate bucket
- search through the primary page (plus overflow pages) to find the record(s)

I/O cost = 1 + #overflow pages

OPERATIONS ON HASH INDEXES

• Deletion

find the appropriate bucket, delete the record

Insertion

- find the appropriate bucket, insert the record
- if there is no space, create a new overflow page

HASH FUNCTIONS

- An *ideal* hash function must be uniform: each bucket is assigned the same number of key values
- A *bad* hash function maps all search key values to the same bucket
- Examples of good hash functions:
 - -h(k) = a * k + b, where *a* and *b* are constants
 - a random function

BUCKET OVERFLOW

- Bucket *overflow* can occur because of
 - insufficient number of buckets
 - skew in distribution of records
 - many records have the same search-key value
 - the hash function results in a non-uniform distribution of key values
- Bucket overflow is handled using *overflow buckets*

PROBLEMS OF STATIC HASHING

- In static hashing, there is a **fixed** number of buckets in the index
- Issues with this:
 - if the database grows, the number of buckets will be too small: long overflow chains degrade performance
 - if the database shrinks, space is wasted
 - reorganizing the index is expensive and can block query execution

EXTENDIBLE HASHING

Extendible Hashing

- **Extendible hashing** is a type of *dynamic* hashing
- It keeps a directory of pointers to buckets
- On overflow, it reorganizes the index by doubling the directory (and not the number of buckets)

EXTENDIBLE HASHING



EXTENDIBLE HASHING: INSERT



EXTENDIBLE HASHING: INSERT



each page can hold at most two records



We always have: global depth >= local depth

- The catalog doubles in size
- Global depth becomes 2





There is space in the bucket so nothing changes!





Since local depth is smaller than global, no need to change the directory size!





EXTENDIBLE HASHING: DELETE

- Locate the bucket of the record and remove it
- If the bucket becomes empty, it can be removed (and update the directory)
- Two buckets can also be coalesced together if the sum of the entries fit in a single bucket
- Decreasing the size of the directory can also be done, but it is expensive

MORE ON EXTENDIBLE HASHING

- How many disk accesses for equality search?
 One if directory fits in memory, else two
- Directory grows in spurts, and, if the distribution of hash values is skewed, the directory can grow very large
- We may need overflow pages when multiple entries have the same hash value!