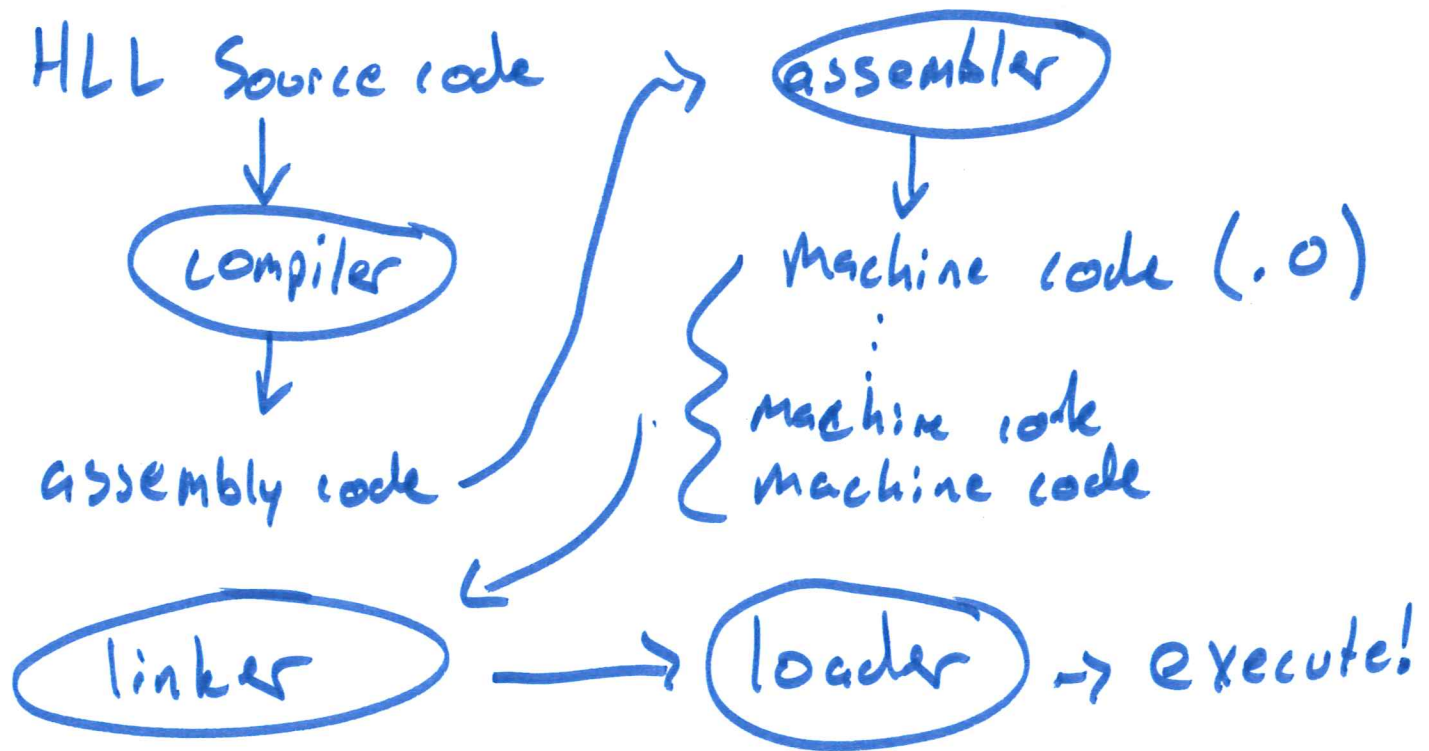


Linking and loading



Difference between assembly + machine code?

- Why do we need the assembler?

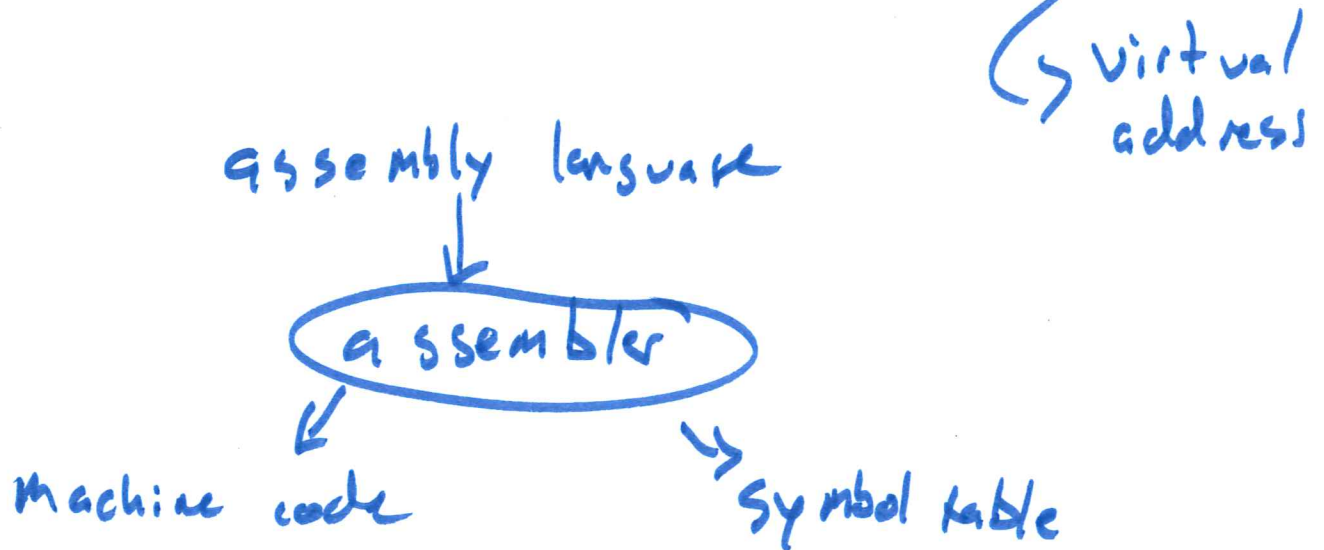
top:
addl ...
movl ...
jmp top

addresses

- convert from assembly to binary
- assign addresses to symbols

Assembler:

- Scan each line and convert to machine code
- assign each symbol (if can) an address
- these symbol → address "translations" are put in a symbol table



objdump -t

After assembling ~~the~~ into machine code

"Linking" - collects and combines machine code and data into a file that is

"Loaded" - copied into memory to be ready to execute

Addressing in machine code

- absolute - the actual (virtual) address

- relative - save space use PC + offset
(Indirect)

```
movl 0x5000000, %eax
```

```
while (...) {  
    ...  
}
```

```
jmp 0x80123AB - 10
```

need a linker to compute these addresses

mod1.c

```
int a = 12;  
main() {  
    f1();  
}
```

↳ assembler doesn't know address

later the linker fills in the missing addresses

mod2.c

```
f1() {  
    a++;  
}
```

↳ assembler can't know what address this is

```
int a = 12; global var
```

```
int main(int argc, char *argv[]) {
```

```
    for (int i=0; i<10; i++) {  
        a += 1;  
    }
```

```
10    return 0;  
    }
```

addressing: file format elf32-i386

Disassembly of section .text:

08048394 <main>:

```
8048394: 55                push   %ebp
8048395: 89 e5            mov    %esp,%ebp
10 8048397: 83 ec 10        sub    $0x10,%esp
804839a: c7 45 fc 00 00 00 00 movl   $0x0,-0x4(%ebp)
80483a1: eb 11            jmp    80483b4 <main+0x20>
80483a3: a1 2c 96 04 08    mov    0x804962c,%eax
80483a8: 83 c0 01        add    $0x1,%eax
20 80483ab: a3 2c 96 04 08    mov    %eax,0x804962c
80483b0: 83 45 fc 01    addl   $0x1,-0x4(%ebp)
80483b4: 83 7d fc 09    cmpl   $0x9,-0x4(%ebp)
80483b8: 7e e9 -17        jle    80483a3 <main+0xf>
80483ba: b8 00 00 00 00    mov    $0x0,%eax
30 80483bf: c9                leave
```

Disassembly of section .data:

```
08049628 <_data_start>:
8049628: 00 00            add %al,(%eax)
...
40 0804962c <a>:
804962c: 0c 00            or $0x0,%al
...
```



gcc -C → only do preprocessor + compiler + assembler

↳ .o file

ld → linker → links .o files together

→ CPP (pre processor)

CC (compiler)

AS (assembler)

ld (linker)

gcc → all these together

Linker fills in other missing info too

Creates the ELF → file format for executables

→ 15 + segments

adds -init;

.data .rodata

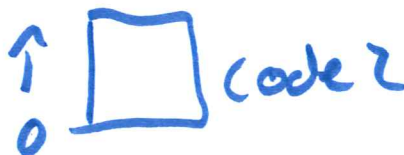
.text .bss

⊠

⋮

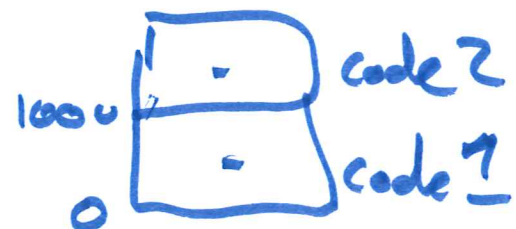
- exit;

mod 1.o syntab.



app

~~mod~~



fills in blanks, assigns addresses

- Relocate ~~at~~ object files
update any addresses of moved objects
-

Loading

- done (mostly) by the OS
- copy executable (created by linking) into memory
- OS allocates some space for stack
 - sets `%esp`
- OS allocates some space for heap
 - sets `brk` pointer
- Sets the PC to first instruction
 - ↳ Starts executing code
 - logically jumps to `main`.
 - actually goes to `init()` → (libraries initializes)

Previously, we assumed Static linking

Dynamic linking common

↳ parts of the linking step saved until execution / loading

Why dynamic?

- two programs both using same func.
 - save memory by having 1 copy
- lots of code never needed
- reduces executable size
- eliminates duplication in executables
- to dynamically choose which function