

Lecture: Scheduling

(1)

Questions:

Difference between alloc / scheduling?

Pre-emptive vs. non?

Different policies: how behave?
(+'s, -'s)

Review

Processes + low-level mechanisms
how to preempt, sav/nestore ctxt

⇒ Resources: what OS's manage
things that a process needs/uses
(CPU, disk, memory)

Today: CPU ~ resource

Scheduling

Resources: Not all alike

Preemptible

Can take resource away, use for something else
give back later

e.g. CPU

Non-preemptible

Once given away, can't really take back
(until volunteered)

e.g. Disk block, terminal

Key: Given resource/demands ⇒ determine how to
manage it

create:
2 styles: Var/args =>
shown: NT
create Process
(clone: fork(), exec())
e.g. int c=3
int rc=fork();
if (rc < 0)
 // exit
else if (rc==c)
 exec()
else
 wait()

⇒ flexible
cat > file
close(standard-FILEs)
fd = open("file", mode)
goes

⇒ can be costly
huge key before
overhead

Decisions about Resources

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Allocation: which process gets which resource?

Space Sharing: [admission control] Divide up resource, give some to each when resources not easily preemptible

e.g. File space

Scheduling: how long process keeps resource
(best order)

Time sharing: more resources can be requested than available

Resource must be pre-emptible

e.g. CPU scheduling

Role of Dispatcher v. Role of Sched

Dispatcher: low-level mechanism

must ctxt switch

{ save state in PCB for old }
load state of new }

Scheduler: higher-level policy

which to run

could have both
space + time
sharing of CPU
in parallel
system,
memory

Performance Metrics

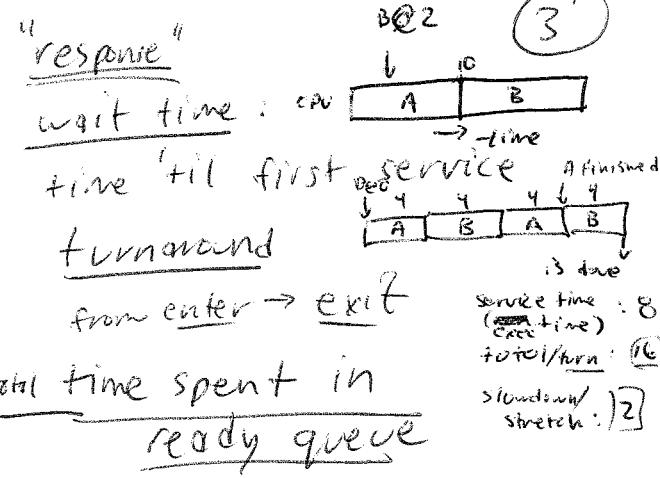
> Minimize waiting time: ^{cumulative} ready, not running
 init wait \rightarrow (response time)

> Minimize turn-around time

> Minimize "cumulative wait" \rightarrow total time spent in ready queue

> Minimize overhead
 \downarrow ctxt switches (costly?)

> Fairness
 maximize each process \Rightarrow same % of CPU



When does Sched make decisions?

Minimal: Non-preemptive

- 1) Process blocks on I/O
- 2) Process terminates
 \Rightarrow (remain scheduled until relinquished)

Also: Pre-emptive

- + (I/O interrupt)
 - 1) event completes: blocked \rightarrow ready
 - 2) timer interrupts
 \Rightarrow can run what it wants to

Algorithms: Overview

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① Process : CPU activity, I/O activity interleaved

if CPU bound: long CPU bursts }
I/O bound: short CPU bursts }

② might view
"job" as
□ □ □ □

Best

Algorithm depends on workload, environment

Specialized: only certain kinds of jobs,
much knowledge about them

general purpose: want to do well for
all types

Projects

Book

Discussion

FCFS

- > Simplest algorithm:
- > Not preemptive

> How to implement?
FIFO queues
⇒ simple

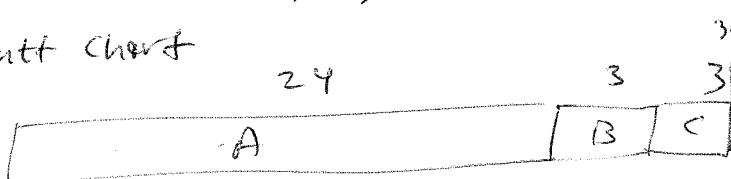
> why bad?

wait/service turnaround time depends on order of arrival

⇒ unfair to later jobs

e.g. 3 jobs (A, B, C) arrive @ same time

Gantt chart



What worked well here:
simple 2 job example

$$\text{Avg. cum. wait time} : (0 + 24 + 27) / 3 \Rightarrow 17$$

$$\text{Turnaround} : \frac{24 + 27 + 30}{3} \Rightarrow 27$$

A: 100
B: 20

use throughout

Note: in multiprogrammed world, can put job @ end of Q upon I/O

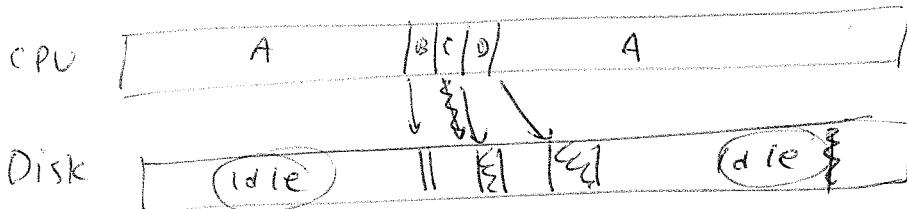
→ Instance of Convo Effect

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('slow truck in front of fast cars')

A: CPU bound

B,C,D: F/O bound



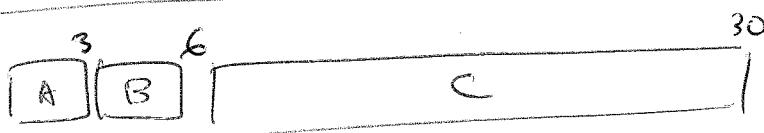
general problems

⇒ can also reduce I/O device utilization

⇒ has short job waiting time

SJF (Shortest Job First)

⇒ Should minimize wait/turnaround time



$$\text{Avg wait: } (0 + 3 + 6) / 3 = 3$$

$$\text{Avg Turn Around: } \frac{3+6+30}{3} = 13$$

⇒ if $T_A = T_B = T_C \Rightarrow \text{FCFS}$

⇒ Provably optimal (w/o preemption)

10/11

insight: moving short jobs up improves

(supermarket example)

their standing A LOT while only
hurting the long jobs A LITTLE

often

⇒ But, not practical

How to know job length?

(maybe can use past ⇒ predict future)

ST + CF (Shortest Time to Completion First)

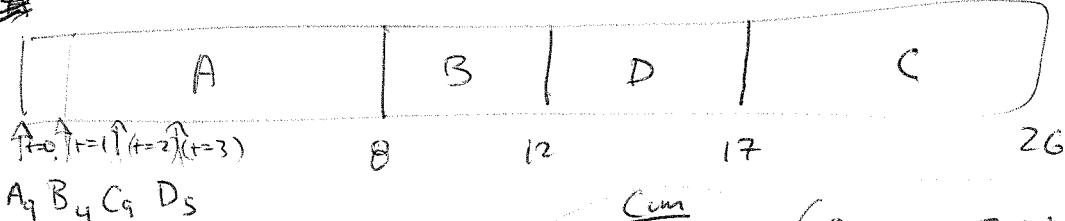
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STCF = SJF w/ preemption

Problem: SJF is fine, IF all jobs are in system

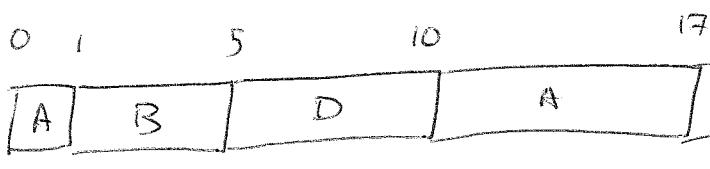
BUT, some arrive later!

SJF



$$\text{Avg Cum wait: } \frac{(0+7+9+15)}{4} \Rightarrow 7.75$$

w/ preemption!



$$\text{Avg wait: } \frac{(9+0+2+15)}{4} \Rightarrow 6.5$$

10/04
what worked well!
let them figure it out

A:100, B:20
A has run for:
{ 2 s }
{ 99 s }

Note: total time is always same
(no magic here)

Avg Cum wait

RR

⇒ more practical time sharing approach

⇒ run for time slice, then back of FIFO Q

⇒ preempted if still running @ end

Advantages

Fair, low average wait if job lengths very widely

⇒ good interactive perf

(low response time)

⇒ if N jobs time slice T_{ms}

longest wait for serial? $(N-1) T$

$$\frac{(N-1) T}{2}$$

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But, RR has problems

Poor when jobs nearly identical?



Even FCFS is better!

$$\text{Avg. turnaround time} = (10 + 20 + 30)/3 = \underline{\underline{20}}$$



A B C

$$= (28 + 29 + 30)/3 = \underline{\underline{29}}$$

But, avg wait/response time is good!

$$(0+1+2)/3 \Rightarrow \underline{\underline{1}}$$

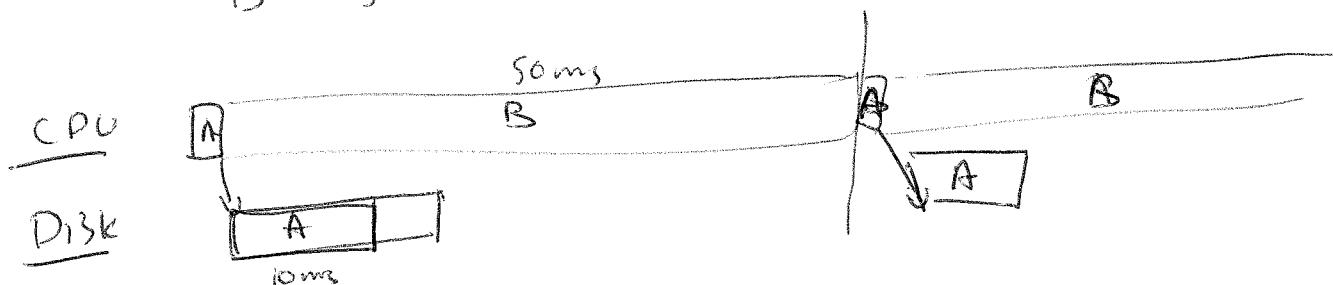
more interactive

$$\text{FCFS: } (0+10+20)/3 \Rightarrow \underline{\underline{10}}$$

Problem #2: Perf depends on length of the slice
if too high \Rightarrow FCFS

e.g. A 1 ms compute, 10 ms I/O

B just compute

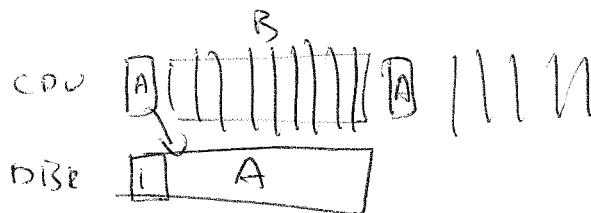


RR cont

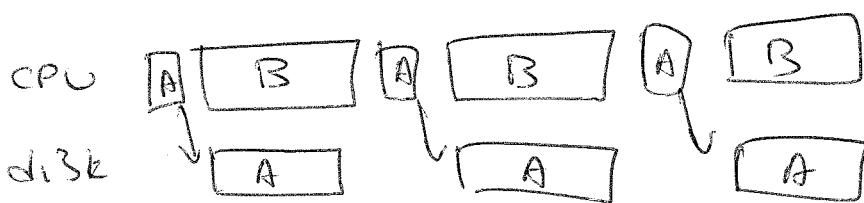
(c)

> if time-slice too low, ctxt switch overhead

$$TS = \underline{1 \text{ ms}}$$



But STCF is still better



> How to approximate? \Rightarrow PRIORITY

Dynamic
Adaptive
w/ priorities

> Each process has priority
run highest, RR among equal