

## Sun's Network File System (NFS)

One of the first uses of distributed client/server computing was in the realm of distributed file systems. In such an environment, there are a number of client machines and one server (or a few); the server stores the data on its disks, and clients request data through well-formed protocol messages. Figure 34.1 depicts the basic setup.

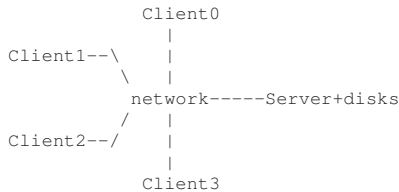


Figure 34.1: 4 clients, 1 Server (with disks), and yes, a network

As you can see from the (ugly) picture, the server has the disks; the clients communicate through the network to access their directories and files on those disks.

Why do we bother with this arrangement? (i.e., why don't we just let clients use their local disks?) Well, primarily this setup allows for easy **sharing** of data across clients. Thus, if

you access a file on one machine (Client0) and then later use another (Client2), you will have the same view of the file system. Your data is naturally shared across these different machines. A secondary benefit is **centralized administration**; for example, backing up files can be done from the few server machines instead of from the multitude of clients. Another advantage could be **security**; having all servers in a locked machine room prevents certain types of problems from arising.

### 34.1 A Basic Distributed File System

We now will study the architecture of a simplified distributed file system. A simple client/server distributed file system has more components than the file systems we have studied so far. On the client side, there are client applications which access files and directories through the **client-side file system**. A client application issues **system calls** to the client-side file system (such as `open()`, `read()`, `write()`, `close()`, `mkdir()`, etc.) in order to access files which are stored on the server. Thus, to client applications, the file system does not appear to be any different than a local (disk-based) file system, except perhaps for performance; in this way, distributed file systems provide **transparent** access to files, an obvious goal; after all, who would want to use a file system that required a different set of APIs or otherwise was a pain to use?

The role of the client-side file system is to execute the actions needed to service those system calls. For example, if the client issues a `read()` request, the client-side file system may send a message to the **server-side file system** (or, more commonly, the **file server**) to read a particular block; the file server will then read the block from disk (or its own in-memory cache), and send a message back to the client with the requested data. The client-side file system will then copy the data into the user buffer supplied to the `read()` system call and thus the request will complete. Note that a subsequent `read()` of the same block on the client may be **cached** in client memory or on the client's disk

even; in the best such case, no network traffic need be generated.



From this simple overview, you should get a sense that there are two important pieces of software in a client/server distributed file system: the client-side file system and the file server. Together their behavior determines the overall behavior of the distributed file system.

## 34.2 On To NFS

One of the earliest and most successful systems was developed by Sun Microsystems, and is known as the Sun Network File System (or NFS) [S86]. In defining NFS, Sun took an unusual approach: instead of building a proprietary and closed system, Sun instead developed an **open protocol** which simply specified the exact message formats that clients and servers would use to communicate. Different groups could develop their own NFS servers and thus compete in an NFS marketplace while preserving interoperability. It worked: today there are many companies that sell NFS servers (including Sun, NetApp [HLM94], EMC, IBM, and others), and the widespread success of NFS is likely attributed to this “open market” approach.

## 34.3 Focus: Simple and Fast Server Crash Recovery

In this note, we will discuss the classic NFS protocol (version 2, a.k.a. NFSv2), which was the standard for many years; small changes were made in moving to NFSv3, and larger-scale protocol changes were made in moving to NFSv4 (which is still

on-going). However, NFSv2 is both wonderful and frustrating and thus the focus of our study.

In NFSv2, one of the main goals of the design of the protocol was *simple and fast server crash recovery*. In a multiple-client, single-server environment, this goal makes a great deal of sense; any minute that the server is down (or unavailable) makes *all* the client machines (and their users) unhappy and unproductive. Thus, as the server goes, so goes the entire system.

#### 34.4 Key To Fast Crash Recovery: Statelessness

This simple goal is realized in NFSv2 by designing what we refer to as a **stateless** protocol. The server, by design, does not keep track of anything about what is happening at each client. For example, the server does not know which clients are caching which blocks, or which files are currently open at each client, or the current file pointer position for a file, etc. Simply put, the server does not track anything about what clients are doing; rather, the protocol is designed to deliver in each protocol request *all the information* that is needed in order to complete the request. If it doesn't now, this stateless approach will make more sense as we discuss the protocol in more detail below.

For an example of a **stateful** (not stateless) protocol, consider the `open()` system call. Given a pathname, `open()` returns a file descriptor (an integer). This descriptor is used on subsequent `read()` or `write()` requests to access various file blocks, as in this application code (note that proper error checking of the system calls is omitted for space reasons):

Now imagine that the client-side file system opens the file by sending a protocol message to the server saying "open the file 'foo' and give me back a descriptor". The file server then opens the file locally on its side and sends the descriptor back to the client. On subsequent reads, the client application uses that descriptor to call the `read()` system call; the client-side file system then passes the descriptor in a message to the file server, saying "read some bytes from the file that is referred to by the

```
char buffer[MAX];
int fd = open("foo", O_RDONLY); // get descriptor
read(fd, buffer, MAX);         // use descriptor to read MAX bytes from foo
read(fd, buffer, MAX);         // use descriptor to read MAX bytes from foo
...
read(fd, buffer, MAX);         // use descriptor to read MAX bytes from foo
close(fd);                     // close file (done with descriptor)
```

Figure 34.2: Client Code: Reading from a File

descriptor I am passing you here”.

In this example, the file descriptor is a piece of **shared state** between the client and the server (Ousterhout calls this **distributed state** [O91]). Shared state, as we hinted above, complicates crash recovery. Imagine the server crashes after the first read completes, but before the client has issued the second one. After the server is up and running again, the client then issues the second read. Unfortunately, the server has no idea to which file `fd` is referring; that information was ephemeral (i.e., in memory) and thus lost when the server crashed. To handle this situation, the client and server would have to engage in some kind of **recovery protocol**, where the client would make sure to keep enough information around in its memory to be able to tell the server what it needs to know (in this case, that file descriptor `fd` refers to file `foo`).

It gets even worse when you consider the fact that a stateful server has to deal with client crashes. Imagine, for example, a client that opens a file and then crashes. The `open()` uses up a file descriptor on the server; how can the server know it is OK to close a given file? In normal operation, a client would eventually call `close()` and thus inform the server that the file should be closed. However, when a client crashes, the server never receives a `close()`, and thus has to notice the client has crashed in order to close the file.

For these reasons, the designers of NFS decided to pursue a stateless approach: each client operation contains all the information needed to complete the request. No fancy crash recov-

ery is needed; the server just starts running again, and a client, at worst, might have to retry a request.

#### ASIDE: WHY SERVERS CRASH

Before getting into the details of the NFSv2 protocol, you might be wondering: why do servers crash? Well, as you might guess, there are plenty of reasons. Servers may simply suffer from a **power outage** (temporarily); only when power is restored can the machines be restarted. Servers are often comprised of hundreds of thousands or even millions of lines of code; thus, they have **bugs** (even good software has a few bugs per hundred or thousand lines of code), and thus they eventually will trigger a bug that will cause them to crash. They also have memory leaks; even a small memory leak will cause a system to run out of memory and crash. And, finally, in distributed systems, there is a network between the client and the server; if the network acts strangely (for example, if it becomes **partitioned** and clients and servers are working but cannot communicate), it may appear as if a remote machine has crashed, but in reality it is just not currently reachable through the network.

## 34.5 The NFSv2 Protocol

We thus arrive at the NFSv2 protocol definition. Our problem statement is simple:

#### THE CRUX OF THE PROBLEM

How can we define the network protocol to enable stateless operation? Clearly, stateful calls like `open()` can't be a part of the discussion (as it would require the server to track open files); however, the client application will want to call `open()`, `read()`, `write()`, `close()` and other standard API calls to access files and directories. Thus, as a refined question, how do we define the

protocol to both be stateless *and* support the POSIX file system API?

One key to understanding the design of the NFS protocol is understanding the **file handle**. File handles are used to uniquely describe the file or directory a particular operation is going to operate upon; thus, many of the protocol requests include a file handle.

You can think of a file handle as having three important components: a *volume identifier*, an *inode number*, and a *generation number*; together, these three items comprise a unique identifier for a file or directory that a client wishes to access. The volume identifier informs the server which file system the request refers to (an NFS server can export more than one file system); the inode number tells the server which file within that partition the request is accessing. Finally, the generation number is needed when reusing an inode number; by incrementing it whenever an inode number is reused, the server ensures that a client with an old file handle can't accidentally access the newly-allocated file.

Here is a summary of some of the important pieces of the protocol; the full protocol is available elsewhere (see Callaghan's book for an excellent and detailed overview of NFS [Sun89]).

We'll briefly highlight some of the important components of the protocol. First, the LOOKUP protocol message is used to obtain a file handle, which is then subsequently used to access file data. The client passes a directory file handle and name of a file to look up, and the handle to that file (or directory) plus its attributes are passed back to the client from the server.

For example, assume the client already has a directory file handle for the root directory of a file system (/) (indeed, this would be obtained through the NFS **mount protocol**, which is how clients and servers first are connected together; we do not discuss the mount protocol here for sake of brevity). If an application running on the client tries to open the file `/foo.txt`, the

```

NFSPROC_GETATTR
  expects: file handle
  returns: attributes
NFSPROC_SETATTR
  expects: file handle, attributes
  returns: nothing
NFSPROC_LOOKUP
  expects: directory file handle, name of file/directory to look up
  returns: file handle
NFSPROC_READ
  expects: file handle, offset, count
  returns: data, attributes
NFSPROC_WRITE
  expects: file handle, offset, count, data
  returns: attributes
NFSPROC_CREATE
  expects: directory file handle, name of file to be created, attributes
  returns: nothing
NFSPROC_REMOVE
  expects: directory file handle, name of file to be removed
  returns: nothing
NFSPROC_MKDIR
  expects: directory file handle, name of directory to be created, attributes
  returns: file handle
NFSPROC_RMDIR
  expects: directory file handle, name of directory to be removed
  returns: nothing
NFSPROC_READDIR
  expects: directory handle, count of bytes to read, cookie
  returns: directory entries, cookie (which can be used to get more entries)

```

Figure 34.3: Some examples of the NFS Protocol

client-side file system will send a lookup request to the server, passing it the root directory's file handle and the name `foo.txt`; if successful, the file handle for `foo.txt` will be returned, along with its attributes.

If case you are wondering, attributes are just the metadata that the file system tracks about each file, including fields such as file creation time, last modification time, size, ownership and permissions information, and so forth. Basically, the same type of information that you would get back if you called the `stat()`

system call on a file.

Once a file handle is available, the client can issue READ and WRITE protocol messages on a file to read or write the file, respectively. The READ protocol message requires the protocol to pass along the file handle of the file along with the offset within the file and number of bytes to read. The server then will be able to issue the read (after all, the handle tells the server which volume and which inode to read from, and the offset and count tells it which bytes of the file to read) and return the data to the client (or an error if there was a failure). WRITE is handled similarly, except the data is passed from the client to the server, and just a success code is returned.

One last interesting protocol message is the GETATTR request; given a file handle, it simply fetches the attributes for that file, including the last modified time of the file. We will see why this protocol request is quite important in NFSv2 below when we discuss caching (see if you can guess why).

## 34.6 From Protocol to Distributed File System

Hopefully you are now getting some sense of how this protocol is turned into a file system across the client-side file system and the file server. The client-side file system tracks open files, and generally translates application requests into the relevant set of protocol messages. The server simply responds to each protocol message, each of which has all the information needed to complete request.

For example, let us consider the a simple application which reads a file. In the diagram (Figure 34.4, we show what system calls the application makes, and what the client-side file system and file server do in responding to such calls.

A few comments about the interaction above. First, notice how the client tracks all relevant **state** for the file access, including the mapping of the integer file descriptor to an NFS file handle as well as the current file pointer. This enables the client to turn each read request (which you may have noticed

```

App fd = open("/foo", ...);
Cli  Send LOOKUP (root dir file handle, "foo")
Server      Receive LOOKUP request
Server      look for "foo" in root dir
Server      if successful, pass back foo's file handle/attributes
Cli  Receive LOOKUP reply
Cli  use attributes to do permissions check
Cli  if OK to access file, allocate file desc. in "open file table";
Cli  store NFS file handle therein
Cli  store current file position (0 to begin)
Cli  return file descriptor to application
App read(fd, buffer, MAX);
Cli  Use file descriptor to index into open file table
Cli  thus find the NFS file handle for this file
Cli  use the current file position as the offset to read from
Cli  Send READ (file handle, offset=0, count=MAX)
Server      Receive READ request
Server      file handle tells us which volume/inode number we need
Server      may have to read the inode from disk (or cache)
Server      use offset to figure out what block to read,
Server      and inode (and related structures) to find it
Server      issue read to disk (or get from server memory cache)
Server      return data (if successful) to client
Cli  Receive READ reply
Cli  Update file position to current + bytes read
Cli  set current file position = MAX
Cli  return data and error code to application
App read(fd, buffer, MAX);
      (Same as above, except offset=MAX and set current file position = 2*MAX)
App read(fd, buffer, MAX);
      (Same as above, except offset=2*MAX and set current file position = 3*MAX)
App read(fd, buffer, MAX);
      (Same as above, except offset=3*MAX and set current file position = 4*MAX)
App close(fd);
Client  Just need to clean up local structures
Client  Free descriptor "fd" in open file table for this process
Client  (No need to talk to server)

```

Figure 34.4: Reading A File: Client-side and File Server Actions

do *not* specify the offset to read from explicitly) into a properly-formatted read protocol message which tells the server exactly which bytes from the file to read. Upon every successful read,

the client updates the current file position in its table and thus subsequent reads are issued with the same file handle but a different offset.

Second, you may notice where server interactions occur. When the file is opened for the first time, the client-side file system sends a LOOKUP request message. Indeed, if a long pathname must be traversed (e.g., `/home/remzi/foo.txt`), the client would send three LOOKUPS: one to look up `home` in the directory `/`, one to look up `remzi` in `home`, and finally one to look up `foo.txt` in `remzi`.

Third, you may notice how each server request has all the information needed to complete the request in its entirety. This design point is critical to be able to gracefully recover from server failure, as we will now discuss.

### 34.7 Handling Server Failure with Idempotent Operations

When a client sends a message to the server, it sometimes does not receive a reply. There are many possible reasons for this failure to respond. In some cases, the message may be dropped by the network; networks do lose messages, and thus either the request or the reply could be lost and thus the client would never receive a response.

It is also possible that the server has crashed, and thus is not currently responding to messages. After a bit, the server will be rebooted and start running again, but in the meanwhile all requests have been lost. In all of these cases, clients are left with a question: what should they do when the client does not reply in a timely manner?

In NFSv2, a client handles all of these failures in a single, uniform, and elegant way: it simply *retries* the request. Specifically, after sending the request, the client sets a timer to go off after a specified time period. If a reply is received before the timer goes off, the timer is canceled and all is well. If, however, the timer goes off *before* any reply is received, the client assumes the

request has not been processed and resends the request. If this time the server replies, all is well and the client has neatly handled the problem.

The key to the ability of the client to simply retry the request regardless of what caused the failure is due to an important property of most NFS requests: they are **idempotent**. An operation is called idempotent when the effect of performing the operation multiple times is equivalent to the effect of performing the operation a single time. For example, if you store a value to a memory location three times, it is the same as doing so once; thus “store value to memory” is an idempotent operation. If, however, you increment a counter three times, it results in a different amount than doing so just once; thus, “increment counter” is not idempotent. More generally, any operation that just reads data is obviously idempotent; an operation that updates data must be more carefully considered to determine if it has this property.

#### DESIGN TIP: IDEMPOTENCY

**Idempotency** is a useful property when building reliable systems. When an operation can be issued more than once, it is much easier to handle failure of the operation; you can just retry it. If an operation is *not* idempotent, life becomes more difficult.

The key to the design of crash recovery in NFS is the idempotency of most of the common operations. LOOKUP and READ requests are trivially idempotent, as they only read information from the file server and do not update it. More interestingly, WRITE requests are also idempotent. If, for example, a WRITE fails, the client can simply retry it. Note how the WRITE message contains the data, the count, and (importantly) the exact offset to write the data to. Thus, it can be repeated with the knowledge that the outcome of multiple writes is the same as the outcome of a single write.

In this way, the client can handle all timeouts in a unified

```

** Case 1: Request lost on way to server **

                request
[send request] C -----> X           S
                    (request lost)

** Case 2: Server down **

                request
[send request] C -----\
                        \----->X S (down)

** Case 3: Reply lost on way back from server **

                request
[send request] C -----\
                        \-----> S [receive request]
                        \-----> S [handle request]
                        X <----- S [send reply]
                          reply
                    (reply lost)

** Client action in all three cases: Just retry the request **

```

Figure 34.5: The Three Cases of Retry

way. If a WRITE request was simply lost (Case 1 above), the client will retry it, the server will perform the write, and all will be well. The same will happen if the server happened to be down while the request was sent, but back up and running when the second request is sent, and again all works as desired (Case 2). Finally, the server may in fact receive the WRITE request, issue the write to its disk, and send a reply. This reply may get lost (Case 3), again causing the client to resend the request. When the server receives the request again, it will simply do the exact same thing: write the data to disk and reply that it has done so. If the client this time receives the reply, all is again well, and thus the client has handled both message loss and server failure in a uniform manner. Neat!

A small aside: some operations are hard to make idempotent.

For example, when you try to make a directory that already exists, you are informed that the `mkdir` request has failed. Thus, in NFS, if the file server receives a `MKDIR` protocol message and executes it successfully but the reply is lost, the client may repeat it and encounter that failure when in fact the operation at first succeeded and then only failed on the retry. Thus, life is not perfect.

### 34.8 Improving Performance: Client-side Caching

Distributed file systems are good for a number of reasons, but sending all read and write requests across the network can lead to a big performance problem: the network generally isn't that fast, especially as compared to local memory or disk. Thus, another problem: how can we improve the performance of a distributed file system?

The answer, as you might guess from reading the big bold words in the sub-heading above, is client-side **caching**. The NFS client-side file system caches file data (and metadata) that it has read from the server in client memory. Thus, while the first access is expensive (i.e., it requires network communication), subsequent accesses are serviced quite quickly out of client memory.

The cache also serves as a temporary buffer for writes. When a client application first writes to a file, the client buffers the data in client memory (in the same cache as the data it read from the file server) before writing the data out to the server. Such **write buffering** is useful because it decouples application `write()` latency from actual write performance, i.e., the application's call to `write()` succeeds immediately (and just puts the data in the client-side file system's cache); only later does the data get written out to the file server.

Thus, NFS clients cache data and performance is usually great and we are done, right? Unfortunately, not quite. Adding caching into any sort of system with multiple client caches introduces a big and interesting challenge which we will refer to as the **cache**

consistency problem.

### 34.9 The Cache Consistency Problem

The cache consistency problem is best illustrated with two clients and a single server. Imagine client C1 reads a file F, and keeps a copy of the file in its local cache. Now imagine a different client, C2, overwrites the file F, thus changing its contents; let's call the new version of the file F (version 2), or F[v2] and the old version F[v1] so we can keep the two distinct (but of course the file has the same name, just different contents). Finally, there is a third client, C3, which has not yet accessed the file F.

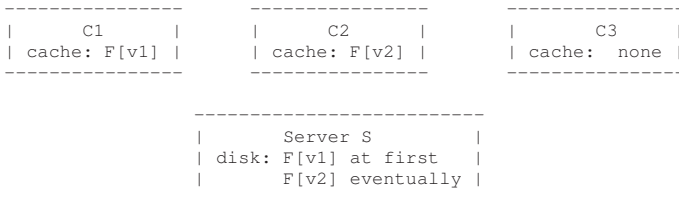


Figure 34.6: The Cache Consistency Problem

You can probably see the problem that is upcoming. In fact, there are two subproblems. The first subproblem is that the client C2 may buffer its writes in its cache for a time before propagating them to the server; in this case, while F[v2] sits in C2's memory, any access of F from another client (say C3) will fetch the old version of the file (F[v1]). Thus, by buffering writes at the client, other clients may get stale versions of the file, which may be undesirable; indeed, imagine the case where you log into machine C2, update F, and then log into C3 and try to read the file, only to get the old copy! Certainly this could be frustrating. Thus, let us call this aspect of the cache consistency problem **update visibility**; when do updates from one client become visible at other clients?

The second subproblem of cache consistency is a **stale cache**; in this case, C2 has finally flushed its writes to the file server, and thus the server has the latest version (F[v2]). However, C1 still has F[v1] in its cache; if a program running on C1 reads file F, it will get a stale version (F[v1]) and not the most recent copy (F[v2]). Again, this may result in undesirable behavior.

NFSv2 implementations solve these cache consistency problems in two ways. First, to address update visibility, clients implement what is sometimes called **flush-on-close** consistency semantics; specifically, when a file is written to and subsequently closed by a client application, the client flushes all updates (i.e., dirty pages in the cache) to the server. With flush-on-close consistency, NFS tries to ensure that an `open()` from another node will see the latest version of the file.

Second, to address the stale-cache problem, NFSv2 clients first check to see whether a file has changed before using its cached contents. Specifically, when opening a file, the client-side file system will issue a `GETATTR` request to the server to fetch the file's attributes. The attributes, importantly, include information as to when the file was last modified on the server; if the time-of-modification is more recent than the time that the file was fetched into the client cache, the client **invalidates** the file, thus removing it from the client cache and ensuring that subsequent reads will go to the server and retrieve the latest version of the file. If, on the other hand, the client sees that it has the latest version of the file, it will go ahead and use the cached contents, thus increasing performance.

When the original team at Sun implemented this solution to the stale-cache problem, they realized a new problem; suddenly, the NFS server was flooded with `GETATTR` requests. A good engineering principle to follow is to design for the **common case**, and to make it work well; here, although the common case was that a file was accessed only from a single client (perhaps repeatedly), the client always had to send `GETATTR` requests to the server to make sure no one else had changed the file. A client thus bombards the server, constantly asking "has anyone changed this file?" when more of the time, no one had.

To remedy this situation (somewhat), an **attribute cache** was added to each client. A client would still validate a file before accessing it, but most often would just look in the attribute cache to fetch the attributes. The attributes for a particular file were placed in the cache when the file was first accessed, and then would timeout after a certain amount of time (say 3 seconds). Thus, during those three seconds, all file accesses would determine that it was OK to use the cached file and thus do so with no network communication with the server.

### 34.10 Assessing NFS Cache Consistency

A few final words about NFS cache consistency. The flush-on-close behavior was added to “make sense”, but introduced a certain performance problem. Specifically, if a temporary or short-lived file was created on a client and then soon deleted, it would still be forced to the server. A more ideal implementation might keep such short-lived files in memory until they are deleted and thus remove the server interaction entirely, perhaps increasing performance.

More importantly, the addition of an attribute cache into NFS made it very hard to understand or reason about exactly what version of a file one was getting. Sometimes you would get the latest version; sometimes you would get an old version simply because your attribute cache hadn't yet timed out and thus the client was happy to give you what was in client memory. Although this was fine most of the time, it would (and still does!) occasionally lead to odd behavior.

And thus we have described the oddity that is NFS client caching. Whew!

### 34.11 Implications on Server-Side Write Buffering

Our focus so far has been on client caching, and that is where most of the interesting issues arise. However, NFS servers tend to be well-equipped machines with a lot of memory too, and

thus they have caching concerns as well. When data (and meta-data) is read from disk, NFS servers will keep it in memory, and subsequent reads of said data (and metadata) will not have to go to disk, a potential (small) boost in performance.

More intriguing is the case of write buffering. NFS servers absolutely may *not* return success on a WRITE protocol request until the write has been forced to stable storage (e.g., to disk or some other persistent device). While they can place a copy of the data in server memory, returning success to the client on a WRITE protocol request could result in incorrect behavior; can you figure out why?

The answer lies in our assumptions about how clients handle server failure. Imagine the following sequence of writes as issued by a client:

```
write(fd, a_buffer, size); // fill first block with a's
write(fd, b_buffer, size); // fill second block with b's
write(fd, c_buffer, size); // fill third block with c's
```

These writes overwrite the three blocks of a file with a block of a's, then b's, and then c's. Thus, if the file initially looked like this:

```
xxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxx
yyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyy
zzzzzzzzzzzzzzzzzzzzzzzzzzzzzzzzzzzzzzzzzzzzzzzzzzzzzzzzzzzz
```

we might expect the final result after these writes to be like this:

```
aaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaa
bbbbbbbbbbbbbbbbbbbbbbbbbbbbbbbbbbbbbbbbbbbbbbbbbbbbbbbbbbbb
cccccccccccccccccccccccccccccccccccccccccccccccccccccccccccc
```

The x's, y's, and z's, would be overwritten with a's, b's, and c's, respectively.

Now let's assume for the sake of the example that these three client writes were issued to the server as three distinct WRITE protocol messages. Assume the first WRITE message is received by the server and issued to the disk, and the client informed

of its success. Now assume the second write is just buffered in memory, and the server also reports it success to the client *before* forcing it to disk; unfortunately, the server crashes before writing it to disk. The server quickly restarts and receives the third write request, which also succeeds.

Thus, to the client, all the requests succeeded, but we are surprised that the file contents look like this:

```
aaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaa
yyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyyy <--- oops
ccccccccccccccccccccccccccccccccccccccccccccccccccccccccccc
```

Yikes! Because the server told the client that the second write was successful before committing it to disk, an old chunk is left in the file, which, depending on the application, might result in a completely useless file.

To avoid this problem, NFS servers *must* commit each write to stable (persistent) storage before informing the client of success; doing so enables the client to detect server failure during a write, and thus retry until it finally succeeds. Doing so ensures we will never end up with file contents intermingled as in the above example.

The problem that this requirement gives rise to in NFS server implementation is that write performance, without great care, can be *the* major performance bottleneck. Indeed, some companies (e.g., Network Appliance) came into existence with the simple objective of building an NFS server that can perform writes quickly; one trick they use is to first put writes in a battery-backed memory, thus enabling to quickly reply to WRITE requests without fear of losing the data and without the cost of having to write to disk right away; the second trick is to use a file system design specifically design to write to disk quickly when one finally needs to do so [HLM94,RO91].

### 34.12 Summary

We have seen the introduction of a distributed file system known as NFS. NFS is centered around the idea of simple and fast recovery in the face of server failure, and achieves this end through careful protocol design. Idempotency of operations is essential; because a client can safely replay a failed operation, it is OK to do so whether or not the server has executed the request.

We also have seen how the introduction of caching into a multiple-client, single-server system can complicate things. In particular, the system must resolve the cache consistency problem in order to behave reasonably; however, NFS does so in a slightly ad hoc fashion which can occasionally result in observably weird behavior. Finally, we saw how caching on the server can be tricky; in particular, writes to the server must be forced to stable storage before returning success (otherwise data can be lost).

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