

# Lecture 23: Minimal sufficiency

## Maximal reduction without loss of information

- There are many sufficient statistics for a given problem.
- In fact,  $X$  (the whole data set) is sufficient.
- If  $T$  is a sufficient statistic and  $T = \psi(S)$ , where  $\psi$  is a function and  $S$  is another statistic, then  $S$  is sufficient.

For instance, if  $X_1, \dots, X_n$  are iid with  $P(X_i = 1) = \theta$  and  $P(X_i = 0) = 1 - \theta$ , then  $(\sum_{i=1}^m X_i, \sum_{i=m+1}^n X_i)$  is sufficient for  $\theta$ , where  $m$  is any fixed integer between 1 and  $n$ .

- If  $T$  is sufficient and  $T = \psi(S)$  with a measurable function  $\psi$  that is not one-to-one, then  $T$  is more useful than  $S$ , since  $T$  provides a further reduction of the data without loss of information.
- Is there a sufficient statistics that provides “maximal” reduction of the data?

## Definition 6.2.11 (minimal sufficiency)

A sufficient statistic  $T(X)$  is a minimal sufficient statistic if, for any other sufficient statistic  $U(X)$ ,  $T(x)$  is a function of  $U(x)$ .

- $T(x)$  is a function of  $U(x)$  iff  $U(x) = U(y)$  implies that  $T(x) = T(y)$  for any pair  $(x, y)$ .
- In terms of the partitions of the range of the data set, if  $T(x)$  is a function of  $U(x)$ , then

$$\{x : U(x) = t\} \subset \{x : T(x) = t\}$$

Thus, a minimal sufficient statistic achieves the greatest possible data reduction as a sufficient statistic.

- If both  $T$  and  $S$  are minimal sufficient statistics, then by definition there is a one-to-one function  $\psi$  such that  $T = \psi(S)$ ; hence, the minimal sufficient statistic is unique in the sense that two statistics that are functions of each other can be treated as one statistic.
- For example, if  $T$  is minimal sufficient, then so is  $(T, e^T)$ , but no one is going to use  $(T, e^T)$ .
- If the range of  $X$  is  $\mathcal{R}^k$ , then there exists a minimal sufficient statistic.

### Example 6.2.15.

Let  $X_1, \dots, X_n$  be iid form the *uniform* $(\theta, \theta + 1)$  distribution, where  $\theta \in \mathcal{R}$  is an unknown parameter.

The joint pdf of  $(X_1, \dots, X_n)$  is

$$\prod_{i=1}^n I(\{\theta < x_i < \theta + 1\}) = I(\{x_{(n)} - 1 < \theta < x_{(1)}\}), \quad (x_1, \dots, x_n) \in \mathcal{R}^n,$$

where  $x_{(i)}$  denotes the  $i$ th ordered value of  $x_1, \dots, x_n$ .

By the factorization theorem,  $T = (X_{(1)}, X_{(n)})$  is sufficient for  $\theta$ .

Note that

$$x_{(1)} = \sup\{\theta : f_\theta(x) > 0\} \quad \text{and} \quad x_{(n)} = 1 + \inf\{\theta : f_\theta(x) > 0\}.$$

If  $S(X)$  is a statistic sufficient for  $\theta$ , then by the factorization theorem, there are functions  $h$  and  $g_\theta$  such that  $f_\theta(x) = g_\theta(S(x))h(x)$ .

For  $x$  with  $h(x) > 0$ ,

$$x_{(1)} = \sup\{\theta : g_\theta(S(x)) > 0\} \quad \text{and} \quad x_{(n)} = 1 + \inf\{\theta : g_\theta(S(x)) > 0\}.$$

Hence, there is a function  $\psi$  such that  $T(x) = \psi(S(x))$  when  $h(x) > 0$ .

Since  $P(h(X) > 0) = 1$ , we conclude that  $T$  is minimal sufficient.

In this example, the dimension of a minimal sufficient statistic is larger than the dimension of  $\theta$ .

Finding a minimal sufficient statistic by definition is not convenient.  
The next theorem is a useful tool.

### Theorem 6.2.13.

Let  $f_\theta(x)$  be the pmf or pdf of  $X$ . Suppose that  $T(x)$  is sufficient for  $\theta$  and that, for every pair  $x$  and  $y$  with at least one of  $f_\theta(x)$  and  $f_\theta(y)$  is not 0,  $f_\theta(x)/f_\theta(y)$  does not depend on  $\theta$  implies  $T(x) = T(y)$ . (Here, we define  $a/0 = \infty$  for any  $a > 0$ .) Then  $T(X)$  is minimal sufficient for  $\theta$ .

### Proof.

Let  $U(X)$  be another sufficient statistic.

By the factorization theorem, there are functions  $h$  and  $g_\theta$  such that  $f_\theta(x) = g_\theta(U(x))h(x)$  for all  $x$  and  $\theta$ .

For  $x$  and  $y$  such that at least one of  $f_\theta(x)$  and  $f_\theta(y)$  is not 0, i.e., at least one of  $h(x)$  and  $h(y)$  is not 0, if  $U(x) = U(y)$ , then

$$\frac{f_\theta(x)}{f_\theta(y)} = \frac{g_\theta(U(x))h(x)}{g_\theta(U(y))h(y)} = \frac{h(x)}{h(y)}$$

which does not depend on  $\theta$ .

By the assumption of the theorem,  $T(x) = T(y)$ .

This shows that there is a function  $\psi$  such that  $T(x) = \psi(S(x))$

Hence,  $T$  is minimal sufficient for  $\theta$

### Example 6.2.15.

We re-visit this example and show how to apply Theorem 6.2.13.

If  $X_1, \dots, X_n$  are iid form the  $uniform(\theta, \theta + 1)$  distribution, then the joint pdf is

$$f_{\theta}(x) = I(\{x_{(n)} - 1 < \theta < x_{(1)}\}), \quad x = (x_1, \dots, x_n) \in \mathcal{R}^n,$$

Let  $x$  and  $y$  be two data points.

Each of  $f_{\theta}(x)$  and  $f_{\theta}(y)$  only takes two possible values, 0 and 1.

Let  $A_x = (x_{(n)} - 1, x_{(1)})$  and  $A_y = (y_{(n)} - 1, y_{(1)})$ .

Then

$$\frac{f_{\theta}(x)}{f_{\theta}(y)} = \begin{cases} 0 & \theta \notin A_x, \theta \in A_y \\ 1 & \theta \in A_x, \theta \in A_y \\ \infty & \theta \in A_x, \theta \notin A_y \end{cases}$$

This depends on  $\theta$  unless  $A_x = A_y$ .

Thus, if the ratio does not depend on  $\theta$ , we must have  $x_{(1)} = y_{(1)}$  and  $X_{(n)} = Y_{(n)}$ .

Therefore, by Theorem 6.2.13,  $(X_{(1)}, X_{(n)})$  is minimal sufficient for  $\theta$ .

### Example 6.2.14.

Let  $X_1, \dots, X_n$  be iid from  $N(\mu, \sigma^2)$  with unknown  $\mu \in \mathcal{R}$  and  $\sigma > 0$ .

Earlier, we showed that  $T = (\bar{X}, S^2)$  is sufficient for  $\theta = (\mu, \sigma^2)$ .

Is  $T$  minimal sufficient?

Let  $f_\theta(x)$  be the joint pdf of the sample,  $x$  and  $y$  be two sample points. Then

$$\begin{aligned} \frac{f_\theta(x)}{f_\theta(y)} &= \frac{(2\pi\sigma^2)^{-n/2} \exp(-[(n(\bar{x} - \mu)^2 + (n-1)s_x^2]/(2\sigma^2))}{(2\pi\sigma^2)^{-n/2} \exp(-[(n(\bar{y} - \mu)^2 + (n-1)s_y^2]/(2\sigma^2))} \\ &= \exp([-n(\bar{x}^2 - \bar{y}^2) + 2n\mu(\bar{x} - \bar{y}) - (n-1)(s_x^2 - s_y^2)]/(2\sigma^2)) \end{aligned}$$

where  $\bar{x}$  and  $s_x^2$  are the sample mean and variance based on the sample point  $x$ , and  $\bar{y}$  and  $s_y^2$  are the sample mean and variance based on the sample point  $y$ .

This ratio does not depend on  $\theta = (\mu, \sigma^2)$  iff  $\bar{x} = \bar{y}$  and  $s_x^2 = s_y^2$ .

By Theorem 6.2.13,  $T = (\bar{X}, S^2)$  is minimal sufficient for  $\theta = (\mu, \sigma^2)$ .

Like the concept of sufficiency, minimal sufficiency also depends on the parameters we are interested in.

In Example 6.2.14, let us consider two sub-families.

- Suppose that it is known that  $\sigma = 1$ .  
Then  $T = (\bar{X}, S^2)$  is still sufficient but not minimal sufficient for  $\mu$ .  
In fact, using Theorem 6.2.13 we can show that  $\bar{X}$  is minimal sufficient for  $\mu$  when  $\sigma = 1$  and,  $T = (\bar{X}, S^2)$  is not a function of  $\bar{X}$  (why?).
- Suppose that it is known that  $\mu^2 = \sigma^2$  so that we only have one unknown parameter  $\mu \in \mathcal{R}, \mu \neq 0$ . (This is called a curved exponential family.)  
Is  $T = (\bar{X}, S^2)$  minimal sufficient for  $\theta = \mu$ ?  
Note that  $T$  is certainly sufficient for  $\theta$ .  
The answer can be found as a special case of the following result.

## Minimal sufficient statistics in exponential families

Let  $X_1, \dots, X_n$  be iid from an exponential family with pdf

$$f_{\theta}(x) = h(x)c(\theta) \exp(\eta(\theta)'T(x)), \quad \theta \in \Theta$$

where  $\eta(\theta)' = (w_1(\theta), \dots, w_k(\theta))$  and  $T(x)' = (t_1(x), \dots, t_k(x))$ .

Suppose that there exists  $\{\theta_0, \theta_1, \dots, \theta_k\} \subset \Theta$  such that the vectors  $\eta_i = \eta(\theta_i) - \eta(\theta_0)$ ,  $i = 1, \dots, k$ , are linearly independent in  $\mathcal{R}^k$ .

(This is true if the family is of full rank).

We have shown that  $T(X)$  is sufficient for  $\theta$ .

We now show that  $T$  is in fact minimal sufficient for  $\theta$ .

Note that we can focus on the points  $x$  at which  $h(x) > 0$ .

For any  $\theta$ ,

$$\frac{f_{\theta}(x)}{f_{\theta}(y)} = \exp(\eta(\theta)'[T(x) - T(y)]) \frac{h(x)}{h(y)}$$

If this ratio equals  $\phi(x, y)$  not depending on  $\theta$ , then

$$\eta(\theta)'[T(x) - T(y)] = \log(\phi(x, y)) + \log(h(y)/h(x))$$

which implies

$$[\eta(\theta_i) - \eta(\theta_0)]'[T(x) - T(y)] = 0 \quad i = 1, \dots, k.$$



Since  $\eta(\theta_i) - \eta(\theta_0)$ ,  $i = 1, \dots, k$ , are linearly independent, we must have  $T(x) = T(y)$ .

By Theorem 6.2.13,  $T$  is minimal sufficient for  $\theta$ .

## Application to curved normal family

We can now show that  $T = (\bar{X}, S^2)$  minimal sufficient for  $\theta = \mu$  when the sample is a random sample from  $N(\mu, \mu^2)$ ,  $\mu \in \mathcal{R}$ ,  $\mu \neq 0$ .

It can be shown that

$$\eta(\theta) = \left( \frac{n\mu}{\sigma^2}, -\frac{n-1}{2\sigma^2} \right)' = \left( \frac{n}{\mu}, -\frac{n-1}{2\mu^2} \right)'$$

Points  $\theta_0 = (1, 1)$ ,  $\theta_1 = (-1, 1)$ , and  $\theta_2 = (1/2, 1/2)$  are in the parameter space, and

$$\eta(\theta_1) - \eta(\theta_0) = \begin{pmatrix} -n \\ -(n-1)/2 \end{pmatrix} - \begin{pmatrix} n \\ -(n-1)/2 \end{pmatrix} = \begin{pmatrix} -2n \\ 0 \end{pmatrix}$$

$$\eta(\theta_2) - \eta(\theta_0) = \begin{pmatrix} n/2 \\ -2(n-1) \end{pmatrix} - \begin{pmatrix} n \\ -(n-1)/2 \end{pmatrix} = \begin{pmatrix} -n/2 \\ -3(n-1)/2 \end{pmatrix}$$

Are these two vectors linearly independent?

If there are  $c$  and  $d$  such that

$$c[\eta(\theta_1) - \eta(\theta_0)] + d[\eta(\theta_2) - \eta(\theta_0)] = 0$$

i.e.,

$$c \begin{pmatrix} -2n \\ 0 \end{pmatrix} + d \begin{pmatrix} -n/2 \\ -3(n-1)/2 \end{pmatrix} = 0$$

Then, we must have  $d = 0$  and then  $c = 0$ .

That means vectors  $\eta(\theta_1) - \eta(\theta_0)$  and  $\eta(\theta_2) - \eta(\theta_0)$  are linearly independent and the condition for the result of exponential family is satisfied.

Therefore,  $T = (\bar{X}, S^2)$  is minimal sufficient for  $\theta = \mu$ .

## Example.

Let  $(X_1, \dots, X_n)$  be a random sample from  $Cauchy(\mu, \sigma)$ , where  $\mu \in \mathcal{R}$  and  $\sigma > 0$  are unknown parameters.

The joint pdf of  $(X_1, \dots, X_n)$  is

$$f_{\mu, \sigma}(x) = \frac{\sigma^n}{\pi^n} \prod_{i=1}^n \frac{1}{\sigma^2 + (x_i - \mu)^2}, \quad x = (x_1, \dots, x_n) \in \mathcal{R}^n.$$

For any  $x = (x_1, \dots, x_n)$  and  $y = (y_1, \dots, y_n)$ , if

$$f_{\mu, \sigma}(x) = \psi(x, y) f_{\mu, \sigma}(y)$$

holds for any  $\mu$  and  $\sigma$ , where  $\psi$  does not depend on  $(\mu, \sigma)$ , then

$$\prod_{i=1}^n [1 + (y_i - \mu)^2] = \psi(x, y) \prod_{i=1}^n [1 + (x_i - \mu)^2] \quad \mu \in \mathcal{R}$$

Both sides of the above identity are polynomials of degree  $2n$  in  $\mu$ . Comparison of the coefficients to the highest terms gives  $\psi(x, y) = 1$  and hence

$$\prod_{i=1}^n [1 + (y_i - \mu)^2] = \prod_{i=1}^n [1 + (x_i - \mu)^2] \quad \mu \in \mathcal{R}$$

As a polynomial of  $\mu$ , the left-hand side of the above identity has  $2n$  complex roots  $x_i \pm i$ ,  $i = 1, \dots, n$ , while the right-hand side of the above identity has  $2n$  complex roots  $y_i \pm i$ ,  $i = 1, \dots, n$ .

Since the two sets of roots must agree, the ordered values of  $x_i$ 's are the same as the ordered values of  $y_i$ 's.

By Theorem 6.2.13, the order statistics of  $X_1, \dots, X_n$  is minimal sufficient for  $(\mu, \sigma)$ .

The following result may be useful in establishing minimal sufficiency outside of the exponential family.

### Theorem 6.6.5.

Let  $f_0, f_1, f_2, \dots$  be a sequence of pdf's or pmf's on the range of  $X$ , all have the same support.

a. The statistic

$$T(X) = \left( \frac{f_1(X)}{f_0(X)}, \frac{f_2(X)}{f_0(X)}, \dots \right)$$

is minimal sufficient for the family  $\{f_0, f_1, f_2, \dots\}$  of populations for  $X$ .

b. If  $\mathcal{P}$  is a family of pdf's or pmf's for  $X$  with common support, and

(i)  $f_i \in \mathcal{P}$ ,  $i = 0, 1, 2, \dots$

(ii)  $T(X)$  is sufficient for  $\mathcal{P}$ ,

then  $T$  is minimal sufficient for  $\mathcal{P}$ .

### Proof of part a.

Let  $g_i(T) = T_i$ , the  $i$ th component of  $T$ ,  $i = 0, 1, 2, \dots$ , and let  $g_0(T) = 1$ .

Then  $f_i(x) = g_i(T(x))f_0(x)$ ,  $i = 0, 1, 2, \dots$

By the factorization theorem,  $T$  is sufficient for  $\mathcal{P}_0 = \{f_0, f_1, f_2, \dots\}$ .

Suppose that  $S(X)$  is another sufficient statistic.

By the factorization theorem, there are Borel functions  $h$  and  $\tilde{g}_i$  such that

$$f_i(x) = \tilde{g}_i(S(x))h(x), \quad i = 0, 1, 2, \dots$$

Then

$$T_i(x) = \frac{f_i(x)}{f_0(x)} = \frac{\tilde{g}_i(S(x))}{\tilde{g}_0(S(x))}, \quad i = 0, 1, 2, \dots$$

Thus,  $T$  is a function of  $S$ .

By definition,  $T$  is minimal sufficient for  $\mathcal{P}_0$ .

## Proof of part b.

The two additional conditions are  $\mathcal{P}_0 \subset \mathcal{P}$  and  $T$  is sufficient for  $\mathcal{P}$ .

Let  $S$  be any sufficient statistic for  $\mathcal{P}$ .

Then  $S$  is also sufficient for  $\mathcal{P}_0$ .

From part a,  $T$  is minimal sufficient for  $\mathcal{P}_0$  so there is a function  $\psi$  such that  $T = \psi(S)$ .

By definition,  $T$  is minimal sufficient for  $\mathcal{P}$  since  $T$  is sufficient for  $\mathcal{P}$ .

- In fact, the result in Theorem 6.6.5 still holds if the common support condition is replaced by that the support of  $f_0$  contains the support of any pdf or pmf in  $\mathcal{P}$ .
- In most applications, we can choose  $\mathcal{P}_0$  containing finitely many elements.

## Example

Let  $X_1, \dots, X_n$  be a random sample from *double-exponential*( $\mu, 1$ ),  $\mu \in \mathcal{R}$ , i.e., the joint pdf of  $X$  is

$$f_{\mu}(x) = \frac{1}{2^n} \exp\left(-\sum_{i=1}^n |x_i - \mu|\right)$$

Consider  $\mathcal{P}_0 = \{f_0, f_1, \dots, f_n\}$ , where each  $f_j$  is the pdf with  $\mu = j$ ,  $j = 0, 1, \dots, n$ .

By Theorem 6.6.5a, a minimal sufficient statistic for  $\mathcal{P}_0$  is

$$T = \left( \exp\left(\sum_{i=1}^n |X_i| - \sum_{i=1}^n |X_i - j|\right), j = 1, \dots, n \right)$$

which is equivalent to

$$U = \left( \sum_{i=1}^n |X_i| - \sum_{i=1}^n |X_i - j|, j = 1, \dots, n \right)$$

We can further show that  $U$  is equivalent to  $S$ , the set of order statistics.

Since  $S$  is sufficient, by Theorem 6.6.5b,  $S$ ,  $U$ , and  $T$  are all minimal sufficient.

### Definition 6.6.3 (Necessity).

A statistic is said to be necessary if it can be written as a function of every sufficient statistic.

$T$  is necessary if, for every sufficient  $S$ , there is a function  $\psi$  such that  $T = \psi(S)$ .

From the definitions of the necessity and minimal sufficiency, we can reach the following conclusion.

### Theorem 6.6.4.

A statistic is minimal sufficient if and only if it is necessary and sufficient.