Q 1.1: Which of the following is **not** true?

- A. Adding more layers can improve the performance of a neural network.
- B. Residual connections help deal with vanishing gradients.
- C. CNN architectures use no more than ~20 layers to avoid problems such as vanishing gradients.
- D. It is usually easier to learn a zero mapping than the identity mapping.

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Q 1.1: Which of the following is **not** true?

- A. Adding more layers can improve the performance of a neural network. (Yes, as long as we're careful, e.g., ResNets.)
- B. Residual connections help deal with vanishing gradients. (Yes, this is an explicit consideration for residual connections.)
- C. CNN architectures use no more than ~20 layers to avoid problems such as vanishing gradients. (No, much deeper networks.)
- D. It is usually easier to learn a zero mapping than the identity mapping. (Yes: simple way to learn zero is to make weights zero)

- **Q 2.1**: If we apply data augmentation blindly, we might
- (i) Change the label of the data point
- (ii) Produce a useless training point
- A. (i) but not (ii)
- B. (ii) but not (i)
- C. Neither
- D. Both

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- (i) Change the label of the data point
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- A. (i) but not (ii) (Can do (ii): imagine turning up the contrast till the image is completely black and is unusable).
- B. (ii) but not (i) (Can change label: rotate a 6 into a 9).
- C. Neither (Can do either).
- D. Both

- **Q 2.2**: What are some consequences of data augmentation?
- (i) We have to store a much bigger dataset in memory
- (ii) For a fixed batch size, there will be more batches per epoch

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- (i) We have to store a much bigger dataset in memory
- (ii) For a fixed batch size, there will be more batches per epoch
- A. (i) but not (ii) ((i) is false: can store original points only, and then transform them on-the-fly).
- B. (ii) but not (i)
- C. Neither ((ii) is true: more points, same batch size means more batches).
- D. Both