



CS 540 Introduction to Artificial Intelligence

Statistics & Math Review

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Announcements

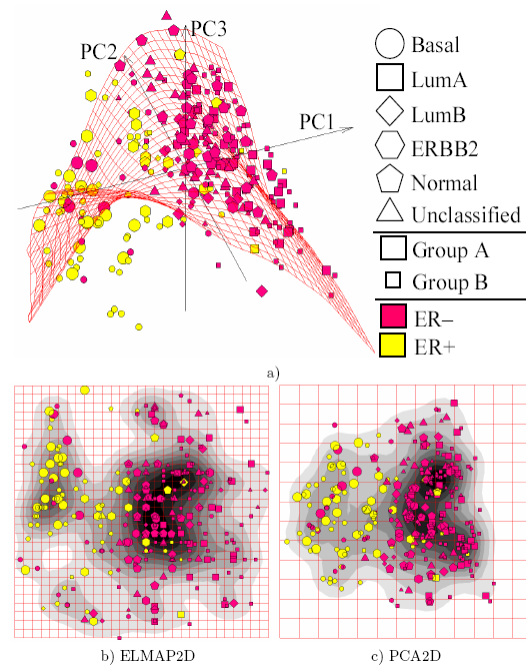
- **Homeworks:**
 - HW2 due Tuesday---get started early!
- **Class roadmap:**

Thursday, Jan 28	Probability
Tuesday, Feb 2	Linear Algebra and PCA
Thursday, Feb 4	Statistics and Math Review
Tuesday, Feb 9	Introduction to Logic
Thursday, Feb 11	Natural Language Processing

Fundamentals

Outline

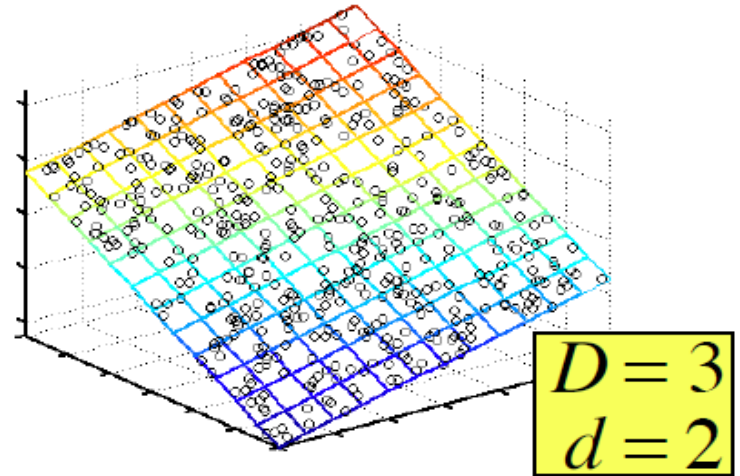
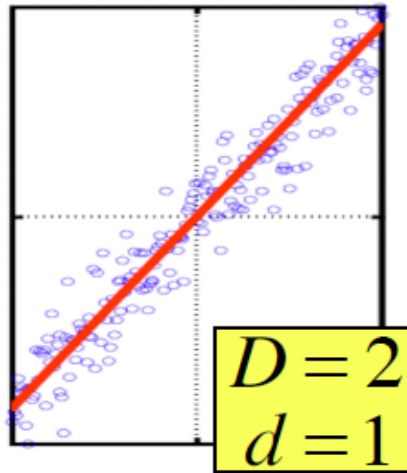
- Finish last lecture: **PCA**
- Review of probability
- Statistics: sampling & estimation



Wikipedia

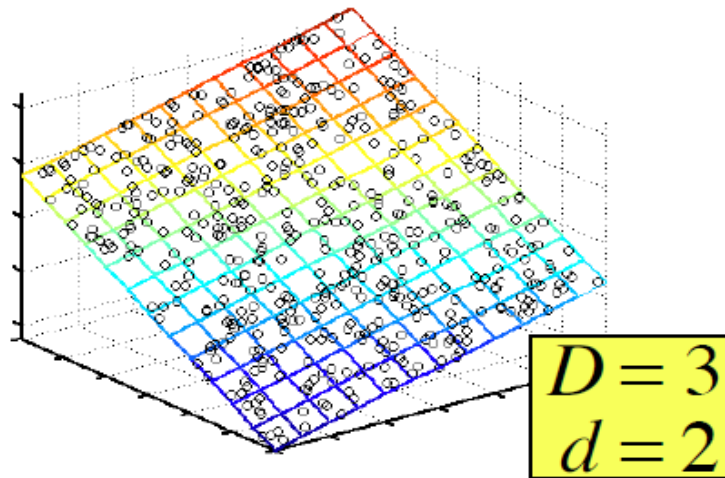
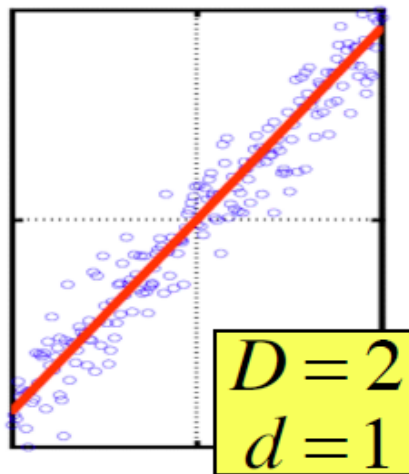
Principal Components Analysis (PCA)

- A type of dimensionality reduction approach
 - For when data is **approximately lower dimensional**



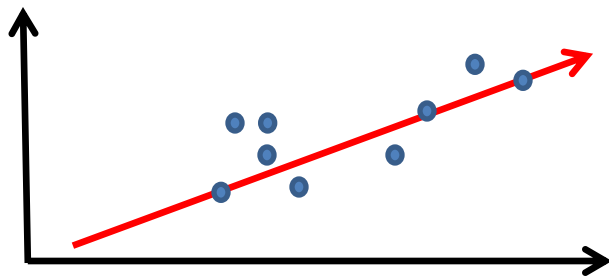
Principal Components Analysis (PCA)

- Goal: find **axes** of a subspace
 - Will project to this subspace; want to preserve data



Principal Components Analysis (**PCA**)

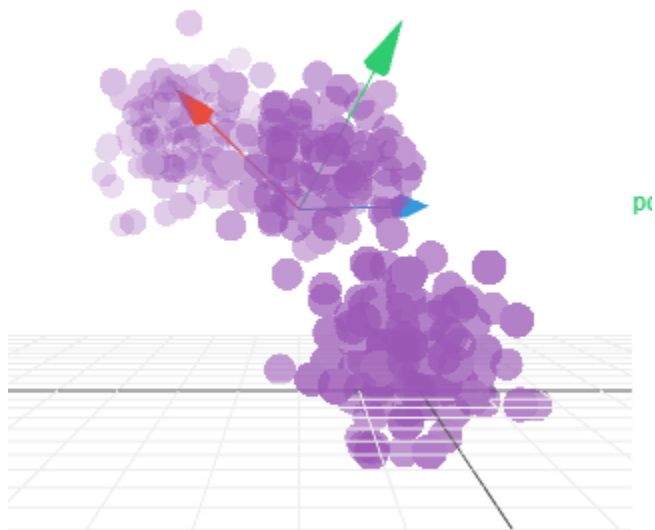
- From 2D to 1D:
 - Find a $v_1 \in \mathbb{R}^d$ so that we maximize “variability”
 - IE,



- New representations are along this vector (1D!)

Principal Components Analysis (PCA)

- From d dimensions to r dimensions
 - Sequentially get $v_1, v_2, \dots, v_r \in \mathbb{R}^d$
 - Orthogonal!
 - Still minimize the projection error
 - Equivalent to “**maximizing variability**”
 - The vectors are the **principal components**



Victor Powell

PCA Setup

- **Inputs**

- Data: $x_1, x_2, \dots, x_n, x_i \in \mathbb{R}^d$

- Can arrange into $X \in \mathbb{R}^{n \times d}$

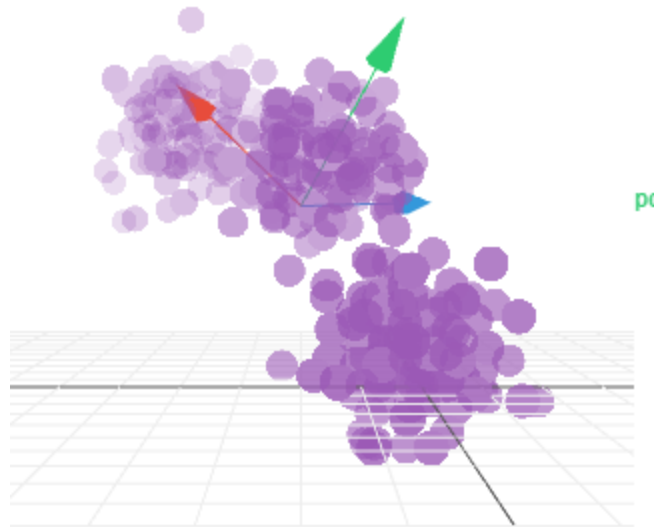
- **Centered!**

$$\frac{1}{n} \sum_{i=1}^n x_i = 0$$

- **Outputs**

- Principal components $v_1, v_2, \dots, v_r \in \mathbb{R}^d$

- Orthogonal!



Victor Powell

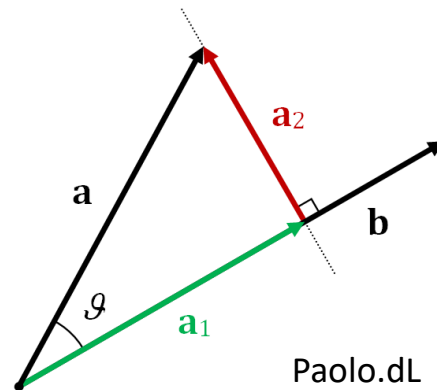
PCA Goals

- Want directions/components (unit vectors) so that
 - Projecting data maximizes variance
 - What's projection?
 - To project a onto unit vector b ,

$$\sum_{i=1}^n \langle x_i, v \rangle^2 = \|Xv\|^2$$

$\langle a, b \rangle b$ ← Direction

↑
Length



PCA Goals

- Want directions/components (unit vectors) so that
 - Projecting data maximizes variance
 - What's projection?

$$\sum_{i=1}^n \langle x_i, v \rangle^2 = \|Xv\|^2$$

- Do this **recursively**
 - Get orthogonal directions $v_1, v_2, \dots, v_r \in \mathbb{R}^d$

PCA First Step

- First component,

$$v_1 = \arg \max_{\|v\|=1} \sum_{i=1}^n \langle v, x_i \rangle^2$$

- Same as getting

$$v_1 = \arg \max_{\|v\|=1} \|Xv\|^2$$

PCA Recursion

- Once we have $k-1$ components, next?

$$\hat{X}_k = X - \sum_{i=1}^{k-1} X v_i v_i^T$$

- Then do the same thing

Deflation



$$v_k = \arg \max_{\|v\|=1} \|\hat{X}_k w\|^2$$

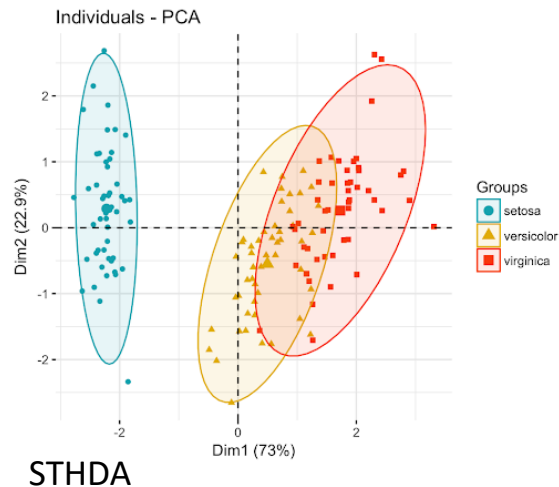
PCA Interpretations

- The v 's are eigenvectors of $X^T X$ (**Gram matrix**)
 - Show via Rayleigh quotient
- $X^T X$ (proportional to) sample covariance matrix
 - When data is 0 mean!
 - I.e., PCA is eigendecomposition of sample covariance
- Nested subspaces $\text{span}(v_1)$, $\text{span}(v_1, v_2)$, ...,



Lots of Variations

- PCA, Kernel PCA, ICA, CCA
 - Unsupervised techniques to extract structure from high dimensional dataset
- Uses:
 - **Visualization**
 - Efficiency
 - Noise removal
 - Downstream machine learning use



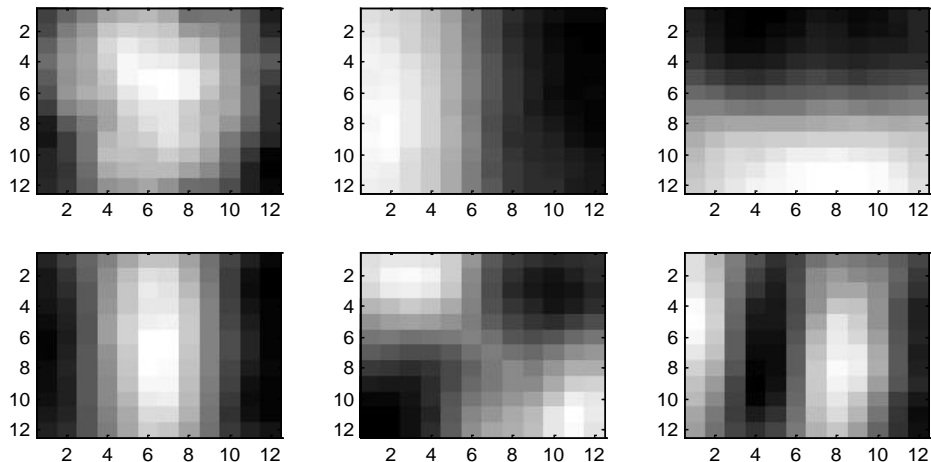
Application: Image Compression

- Start with image; divide into 12x12 patches
 - I.E., 144-D vector
 - **Original image:**



Application: Image Compression

- 6 most important components (as an image)



Application: Image Compression

- Project to 6D,



Compressed



Original

Probability Review: Outcomes & Events

- Outcomes: possible results of an **experiment**
- **Events**: subsets of outcomes we're interested in

$$\text{Ex: } \Omega = \{1, 2, 3, 4, 5, 6\}$$

outcomes

$$\mathcal{F} = \{\emptyset, \{1\}, \{2\}, \dots, \{1, 2\}, \dots, \Omega\}$$

events



Review: Probability Distribution

- We have outcomes and events.
- Now assign probabilities For $E \in \mathcal{F}$, $P(E) \in [0, 1]$

Back to our example:

$$\mathcal{F} = \underbrace{\{\emptyset, \{1, 3, 5\}, \{2, 4, 6\}, \Omega\}}_{\text{events}}$$

$$P(\{1, 3, 5\}) = 0.2, P(\{2, 4, 6\}) = 0.8$$



Review: Random Variables

- Map outcomes to real values $X : \Omega \rightarrow \mathbb{R}$
- Can still work with probabilities:

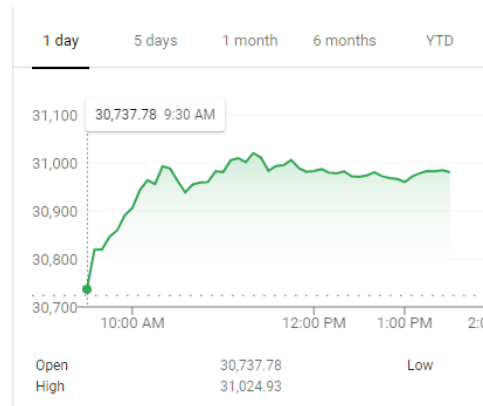
$$P(X = 3) := P(\{\omega : X(\omega) = 3\})$$

- Cumulative Distribution Function (CDF)

$$F_X(x) := P(X \leq x)$$

Review: Expectation & Variance

- Another advantage of RVs are “summaries”
- Expectation: $E[X] = \sum_a a \times P(x = a)$
 - The “average”
- Variance: $Var[X] = E[(X - E[X])^2]$
 - A measure of spread
- Higher moments: other parametrizations



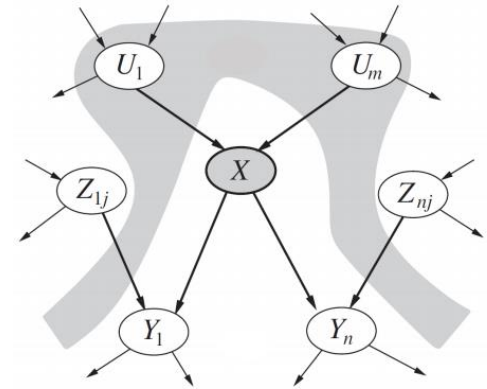
Review: Conditional Probability

- For when we know something,

$$P(X = a|Y = b) = \frac{P(X = a, Y = b)}{P(Y = b)}$$

- Leads to **conditional independence**

$$P(X, Y|Z) = P(X|Z)P(Y|Z)$$



Credit: **Devin Soni**

Review: Bayesian Inference

- Conditional Prob. & Bayes:

$$P(H|E_1, E_2, \dots, E_n) = \frac{P(E_1, \dots, E_n|H)P(H)}{P(E_1, E_2, \dots, E_n)}$$

- Has more evidence.
 - Likelihood is hard---but **conditional independence assumption**

$$P(H|E_1, E_2, \dots, E_n) = \frac{P(E_1|H)P(E_2|H) \cdots P(E_n|H)P(H)}{P(E_1, E_2, \dots, E_n)}$$

Review: Classification

- Expression

$$P(H|E_1, E_2, \dots, E_n) = \frac{P(E_1|H)P(E_2|H) \cdots P(E_n|H)P(H)}{P(E_1, E_2, \dots, E_n)}$$

- H : some class we'd like to infer from evidence
 - Estimate prior $P(H)$
 - Estimate $P(E_i|H)$ from data!
 - How?

Samples and Estimation

- Usually, we don't know the distribution (P)
 - Instead, we see a bunch of samples
- Typical statistics problem: **estimate parameters** from samples
 - Estimate probability $P(H)$
 - Estimate the mean $E[X]$
 - Estimate parameters $P_{\theta}(X)$



Samples and Estimation

- Typical statistics problem: **estimate parameters** from samples
 - Estimate probability $P(H)$
 - Estimate the mean $E[X]$
 - Estimate parameters $P_{\theta}(X)$
- Example: Bernoulli with parameter p
 - Mean $E[X]$ is p



Examples: Sample Mean

- Bernoulli with parameter p
- See samples x_1, x_2, \dots, x_n
 - Estimate mean with **sample mean**

$$\hat{\mathbb{E}}[X] = \frac{1}{n} \sum_{i=1}^n x_i$$

- No different from counting heads

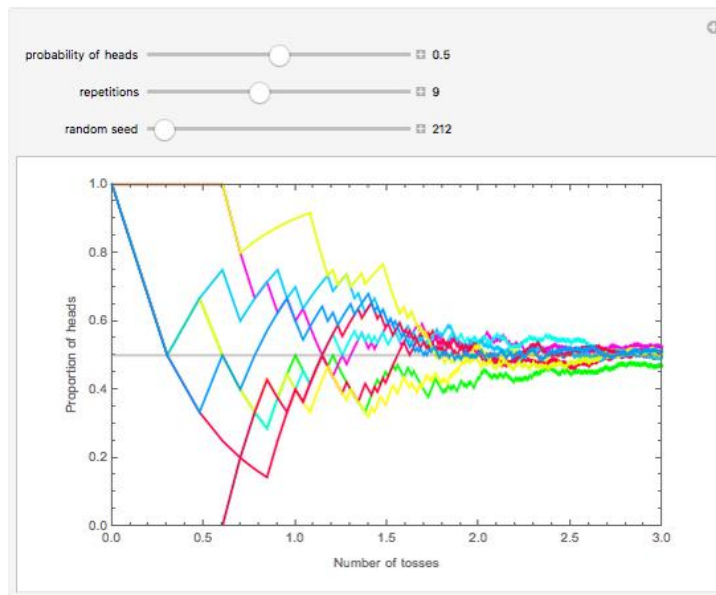


Estimation Theory

- How do we know that the sample mean is a good estimate of the true mean?
 - Concentration inequalities

$$P(|\mathbb{E}[X] - \hat{\mathbb{E}}[X]| \geq t) \leq \exp(-2nt^2)$$

- Law of large numbers
- Central limit theorems, etc.



Wolfram Demo