

Hello!

CONCURRENCY: CONDITION VARIABLES

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CS 537, Fall 2024

Grading updates → P2 , P3 grades out
Regrade forms on Piazza

Midterm
in progress

Project 4 out!
→ Discussion

TA Office hours



RECAP

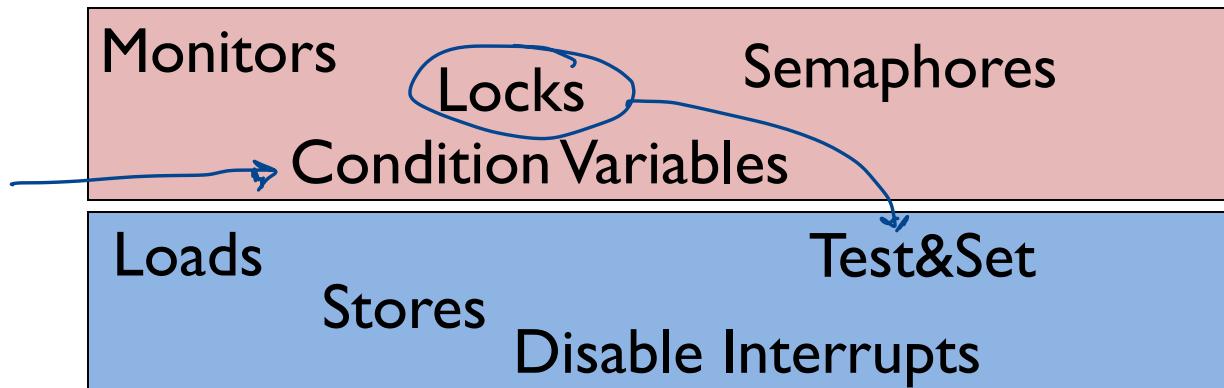
SYNCHRONIZATION

Build higher-level synchronization primitives in OS

Operations that ensure correct ordering of instructions across threads

Use help from hardware

Motivation: Build them once and get them right



CONCURRENCY OBJECTIVES

Mutual exclusion (e.g., A and B don't run at same time)

- solved with *locks*

—

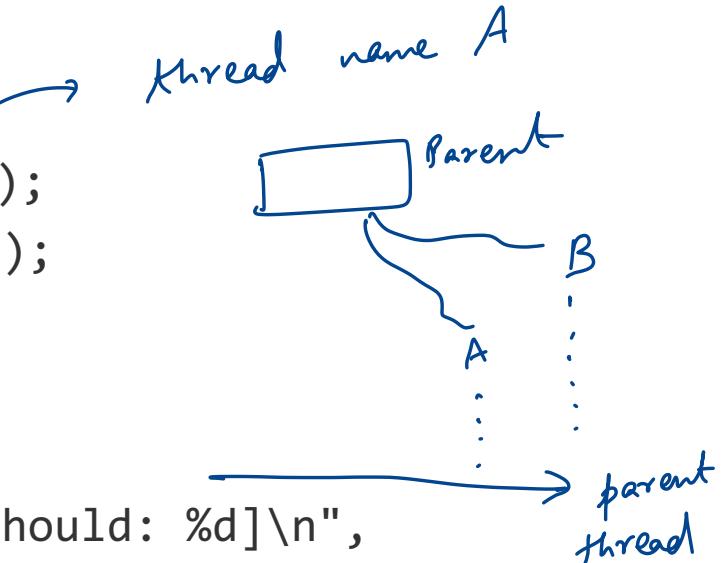
Ordering (e.g., B runs after A does something)

- solved with condition variables and semaphores

ORDERING EXAMPLE: JOIN

```
pthread_t p1, p2;  
Pthread_create(&p1, NULL, mythread, "A");  
Pthread_create(&p2, NULL, mythread, "B");  
// join waits for the threads to finish  
Pthread_join(p1, NULL);  
Pthread_join(p2, NULL);  
printf("main: done\n [balance: %d]\n [should: %d]\n",  
      balance, max*2);  
return 0;
```

Desire some ordering of execution
Thread A & Thread B will run
before Parent Printf



how to implement join()?

CONDITION VARIABLES

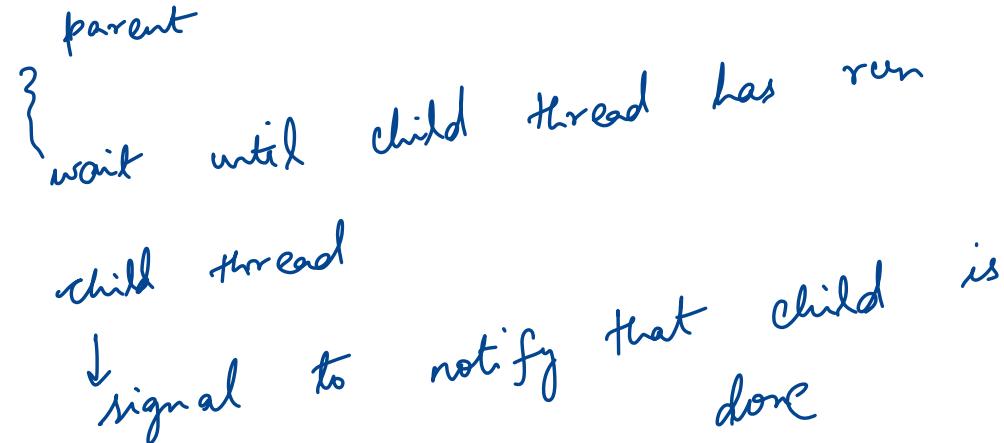
Condition Variable: queue of waiting threads

B waits for a signal on CV before running

- wait(CV, ...)

A sends signal to CV when time for **B** to run

- signal(CV, ...)



CONDITION VARIABLES

wait(cond_t *cv, mutex_t *lock)

- assumes the lock is held when wait() is called

- puts caller to sleep + releases the lock (atomically)

- when awoken, reacquires lock before returning

if multiple threads are calling
want

→ holds the lock after
returning

signal(cond_t *cv)

- wake a single waiting thread (if ≥ 1 thread is waiting)

- if there is no waiting thread, just return, doing nothing



JOIN IMPLEMENTATION: ATTEMPT 1

Parent:

```
void thread_join() {  
    Mutex_lock(&m);          // x  
    Cond_wait(&c, &m);       // y  
    Mutex_unlock(&m);        // z  
}
```

wakes up holds the lock

sleep, block until you
get a signal

Child:

```
void thread_exit() {  
    Mutex_lock(&m);          // a  
    Cond_signal(&c);         // b  
    Mutex_unlock(&m);        // c  
}
```

wake up Parent

Example schedule:

Parent:

x

y

z

Child:

a

b

c

time

JOIN IMPLEMENTATION: ATTEMPT 1

Parent:

```
void thread_join() {  
    Mutex_lock(&m);      // x  
    Cond_wait(&c, &m);   // y  
    Mutex_unlock(&m);   // z  
}
```

Child:

```
void thread_exit() {  
    Mutex_lock(&m);      // a  
    Cond_signal(&c);     // b  
    Mutex_unlock(&m);   // c  
}
```

Example broken schedule:

Parent:

x

y

→ go to sleep
never woken up!

Child:

a

b

c

RULE OF THUMB 1

Keep state in addition to CV's!



variable to indicate if
parent thread is
waiting

CV's are used to signal threads when state changes

If state is already as needed, thread doesn't wait for a signal!

JOIN IMPLEMENTATION: ATTEMPT 2

Parent:

```
void thread_join() {  
    Mutex_lock(&m); // w  
    if (done == 0) // x  
        Cond_wait(&c, &m); // y  
    Mutex_unlock(&m); // z  
}
```

int done = 0;

done = 1 \Rightarrow thread exit
has finished!

Child:

```
void thread_exit() {  
    done = 1; // a  
    Cond_signal(&c); // b  
}
```

lock ?

Parent:

w

x

z

Child:

a b

done is not zero

done = 1

JOIN IMPLEMENTATION: ATTEMPT 2

Parent: *atomically*

```
void thread_join() {  
    Mutex_lock(&m); // w  
    if (done == 0) // x  
        Cond_wait(&c, &m); // y  
    Mutex_unlock(&m); // z  
}
```

Child: *hold the lock when updating shared state*

```
void thread_exit() {  
    done = 1; // a  
    Cond_signal(&c); // b  
}
```

get stuck

Parent: w x

y

Child:

a b



JOIN IMPLEMENTATION: CORRECT

Parent:

```
void thread_join() {  
    Mutex_lock(&m);           // w  
    if (done == 0)             // x  
        Cond_wait(&c, &m);   // y  
    Mutex_unlock(&m);         // z  
}
```

- ① Keep shared state
② Hold the lock to access state

Child:

```
void thread_exit() {  
    Mutex_lock(&m);           // a  
    done = 1;                  // b  
    Cond_signal(&c);          // c  
    Mutex_unlock(&m);         // d  
}
```

Parent: w

x

y

z

Child:

a

b

c

Use mutex to ensure no race between interacting with state and wait/signal

QUIZ 11

<https://tinyurl.com/cs537-fa24-q11>



Assume a list L originally contains three nodes with keys 3, 4, and 5. Assume thread T calls List_Insert(L,2) and thread S calls List_Insert(L,6). Assume malloc() does not fail.

```
typedef struct __node_t {  
    int key;  
    struct __node_t *next;  
} node_t;  
typedef struct __list_t {  
    node_t *head;  
} list_t;  
Void List_Insert(list_t *L, int key) {  
    node_t *new = malloc(sizeof(node_t));  
    new->key = key;  
    new->next = L->head;  
    L->head = new;  
}
```



TTTTSSSS

6 → 2 → 3 → 4 → 5
↑

SSTTTTSS

6 → 2 → 3 → 4 → 5

??

T11 SSSS T

```
void add (int *val, int amt) {  
    mutex_lock(&m);  
    *val += amt;  
    mutex_unlock(&m);  
}
```

→ not
performant

```
void add (int *val, int amt) {  
    do {  
        int old = *val; ss  
    } while (CompareAndSwap(<Q1>, <Q2>, <Q3>) != <Q4>);  
}
```

```
int CAS(int *addr, int ex, int n) {  
    int actual = *addr;  
    if (actual == ex)  
        *addr = n;  
    return actual;  
}
```

if it is still *ss* → set it to 60
+ ↓ -
existing new

Q1 val

Q3 old + amt

Q2 old

Q4 old

PRODUCER/CONSUMER PROBLEM

EXAMPLE: UNIX PIPES

A pipe may have many writers and readers

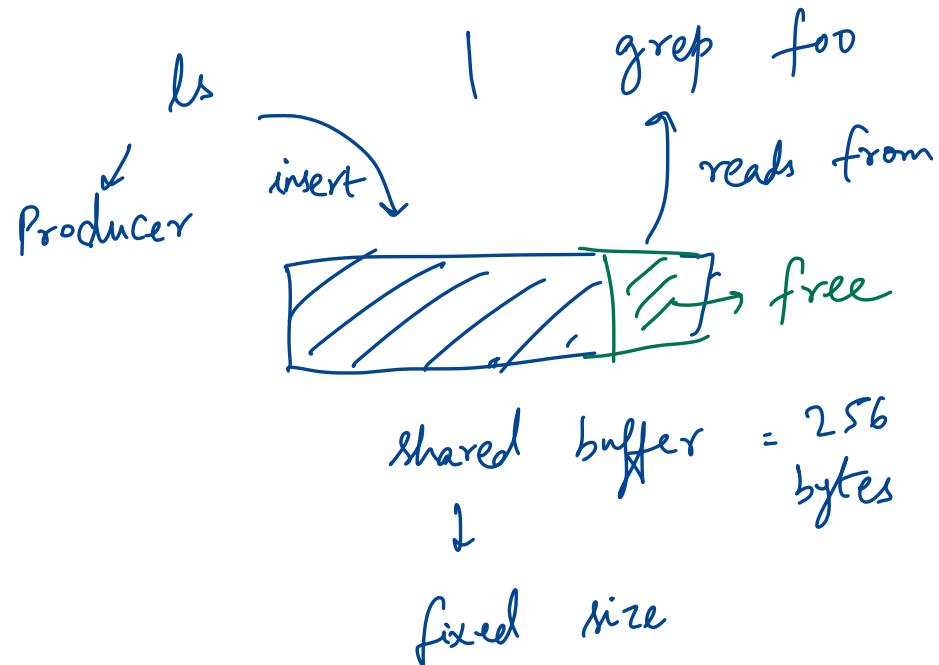
Internally, there is a finite-sized buffer

Writers add data to the buffer

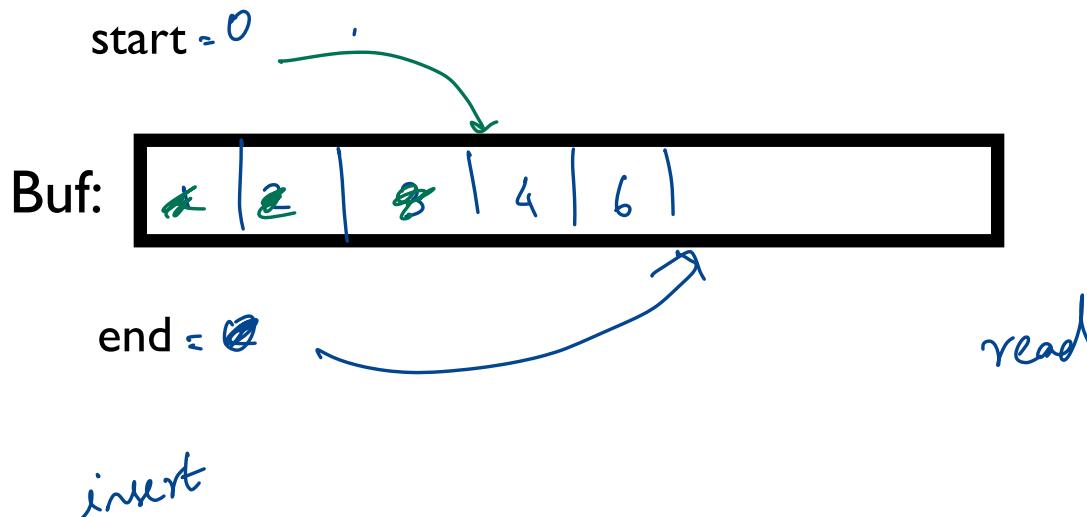
- Writers have to wait if buffer is full

Readers remove data from the buffer

- Readers have to wait if buffer is empty



EXAMPLE: UNIX PIPES



EXAMPLE: UNIX PIPES

Implementation:

- reads/writes to buffer require locking
- when buffers are full, writers must wait  or block until there is free space
- when buffers are empty, readers must wait  until there are items available

PRODUCER/CONSUMER PROBLEM

Producers generate data (like pipe writers)

Consumers grab data and process it (like pipe readers)

Producer/consumer problems are frequent in systems (e.g. web servers)

General strategy use condition variables to:

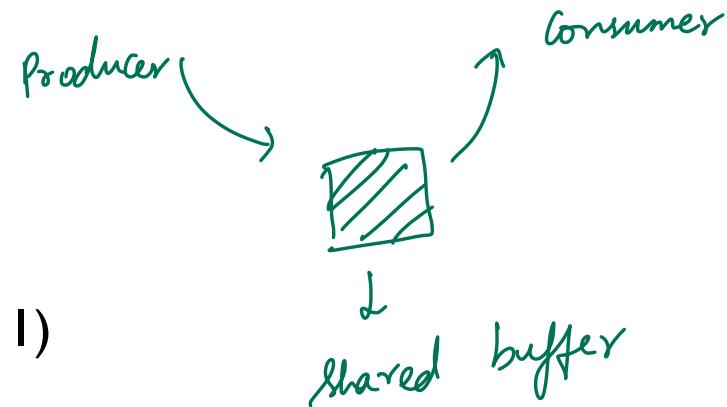
- make producers wait when buffers are full

- make consumers wait when there is nothing to consume

PRODUCE/CONSUMER EXAMPLE

Start with easy case:

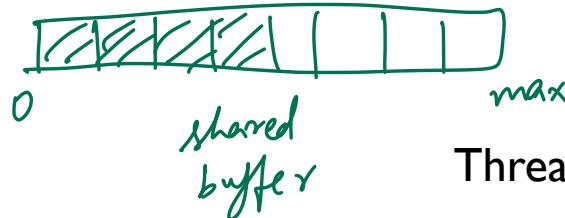
- 1 producer thread
- 1 consumer thread
- 1 shared buffer to fill/consume ($\text{max} = 1$)



Numfull = number of buffers currently filled

\downarrow
shared state or shared variable

numfull



Thread 1 state:

```
void *producer(void *arg) {  
    for (int i=0; i<loops; i++) {  
        Mutex_lock(&m);  
        if(numfull == max)  
            Cond_wait(&cond, &m);  
        do_fill(i);  
        Cond_signal(&cond);  
        some space  
        available  
        Mutex_unlock(&m);  
    }  
}  
wake up consumer
```

numfull = number
of entries
in buffer

Thread 2 state:

```
void *consumer(void *arg) {  
    while(1) {  
        Mutex_lock(&m);  
        if(numfull == 0)  
            Cond_wait(&cond, &m);  
        int tmp = do_get();  
        Cond_signal(&cond);  
        Mutex_unlock(&m);  
        printf("%d\n", tmp);  
    }  
}  
wake up producer
```

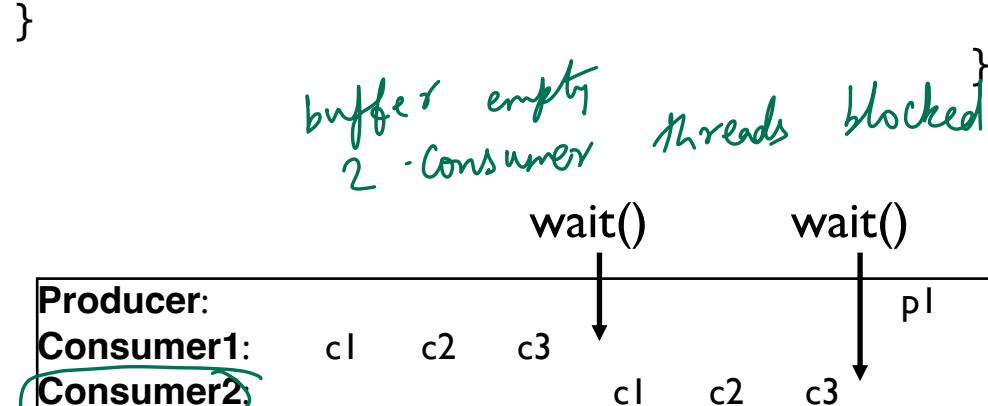
WHAT ABOUT 2 CONSUMERS?

Can you find a problematic timeline with 2 consumers (still 1 producer)?

```

void *producer(void *arg) {
    for (int i=0; i<loops; i++) {
        Mutex_lock(&m); // p1
        if(numfull == max) // p2
            Cond_wait(&cond, &m); // p3
        do_fill(i); // p4
        Cond_signal(&cond); // p5
        Mutex_unlock(&m); // p6
    }
}

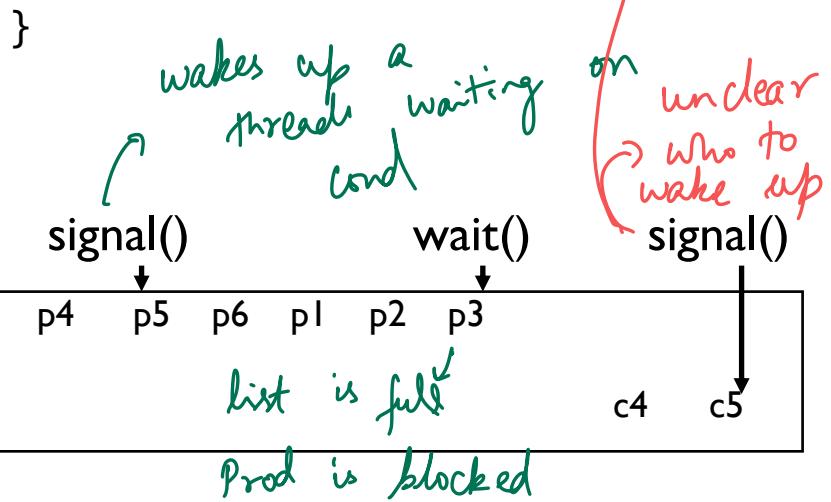
```



```

if Consumer1 woken up
buffer empty
void *consumer(void *arg) {
    while(1) {
        Mutex_lock(&m); // c1
        if(numfull == 0) // c2
            Cond_wait(&cond, &m); // c3
        int tmp = do_get(); // c4
        Cond_signal(&cond); // c5
        Mutex_unlock(&m); // c6
        printf("%d\n", tmp); // c7
    }
}

```



HOW TO WAKE THE RIGHT THREAD?

Wake all the threads!?

Better solution (usually): use two condition variables

PRODUCER/CONSUMER: TWO CVS

```
void *producer(void *arg) {  
    for (int i = 0; i < loops; i++) {  
        Mutex_lock(&m); // p1  
        if (numfull == max) // p2  
            Cond_wait(&empty, &m); // p3  
        do_fill(i); // p4  
        → Cond_signal(&fill); // p5  
        Mutex_unlock(&m); // p6  
    }  
}
```

```
void *consumer(void *arg) {  
    while (1) {  
        Mutex_lock(&m);  
        if (numfull == 0)  
            Cond_wait(&fill, &m);  
        int tmp = do_get();  
        → Cond_signal(&empty);  
        Mutex_unlock(&m);  
    }  
}
```

- Two cond vars
1. Producer waits on empty . Consumers signal when make space
 2. Consumer waits on fill

PRODUCER/CONSUMER: TWO CVS

```
void *producer(void *arg) {  
    for (int i = 0; i < loops; i++) {  
        Mutex_lock(&m); // p1  
        if (numfull == max) // p2  
            Cond_wait(&empty, &m); // p3  
        do_fill(i); // p4  
        Cond_signal(&fill); // p5  
        Mutex_unlock(&m); // p6  
    }  
}
```

C1: c1 c2 c3
P : p1 p2 p4 p5 p6
C2:

```
void *consumer(void *arg) {  
    while (1) {  
        c1 Mutex_lock(&m);  
        c2 if (numfull == 0)  
        c3 Cond_wait(&fill, &m);  
        c4 int tmp = do_get();  
        c5 Cond_signal(&empty);  
        c6 Mutex_unlock(&m);  
    }  
}
```

c1 c2 c4 c5 c6

C4

numfull
can change
between signal
thread run

1. consumer1 waits because numfull == 0
2. producer increments numfull, wakes consumer1
3. before consumer1 runs, consumer2 runs, grabs entry, sets numfull=0.
4. consumer2 then reads bad data.

PRODUCER/CONSUMER: TWO CVS AND WHILE

```
void *producer(void *arg) {  
    for (int i = 0; i < loops; i++) {  
        Mutex_lock(&m); // p1  
        while (numfull == max) // p2  
            Cond_wait(&empty, &m); // p3  
        do_fill(i); // p4  
        Cond_signal(&fill); // p5  
        Mutex_unlock(&m); // p6  
    }  
}  
  
void *consumer(void *arg) {  
    while (1) {  
        Mutex_lock(&m);  
        check numfull → while (numfull == 0)  
        Cond_wait(&fill, &m);  
        int tmp = do_get();  
        Cond_signal(&empty);  
        Mutex_unlock(&m);  
    }  
}
```

No concurrent access to shared state
Every time lock is acquired, assumptions are reevaluated
A consumer will get to run after every do_fill()
A producer will get to run after every do_get()

GOOD RULE OF THUMB 3

Whenever a lock is acquired, **recheck assumptions** about state!

Another thread could grab lock in between signal and wakeup from wait

Note that some libraries also have “spurious wakeups” (may wake multiple waiting threads at signal or at any time)

SUMMARY: RULES OF THUMB FOR CVS

1. Keep state in addition to CV's
2. Always do wait/signal with lock held
3. Whenever thread wakes from waiting, recheck state

NEXT STEPS

Next class: Semaphores