Welcome back!

### MEMORY VIRTUALIZATION

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### **ADMINISTRIVIA**

- Project 2 is due Sept 24<sup>th</sup> Tuesday
- Project I grading in progress (soon?)

- Midterm I: Oct 15<sup>th</sup> at 5.45pm
- Conflict form Piazza

### AGENDA / LEARNING OUTCOMES

Memory virtualization

What are main techniques to virtualize memory?

What are their benefits and shortcomings?

# **RECAP**

### MEMORY VIRTUALIZATION

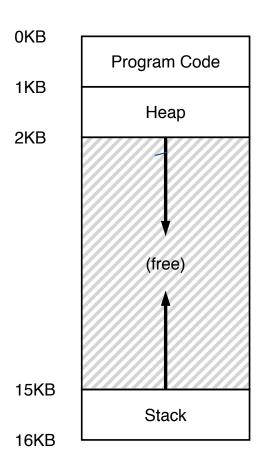
Transparency: Process is unaware of sharing

Protection: Cannot corrupt OS or other process memory

Efficiency: Do not waste memory or slow down processes

Sharing: Enable sharing between cooperating processes

### RECAP: WHAT IS IN ADDRESS SPACE?



the code segment: where instructions live

the heap segment: contains malloc'd data dynamic data structures (it grows downward)

Static: Code and some global variables

Dynamic: Stack and Heap

(it grows upward) the stack segment: contains local variables arguments to routines, return values, etc.

### HOW TO VIRTUALIZE MEMORY

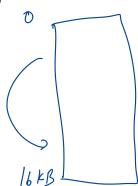
Problem: How to run multiple processes simultaneously?

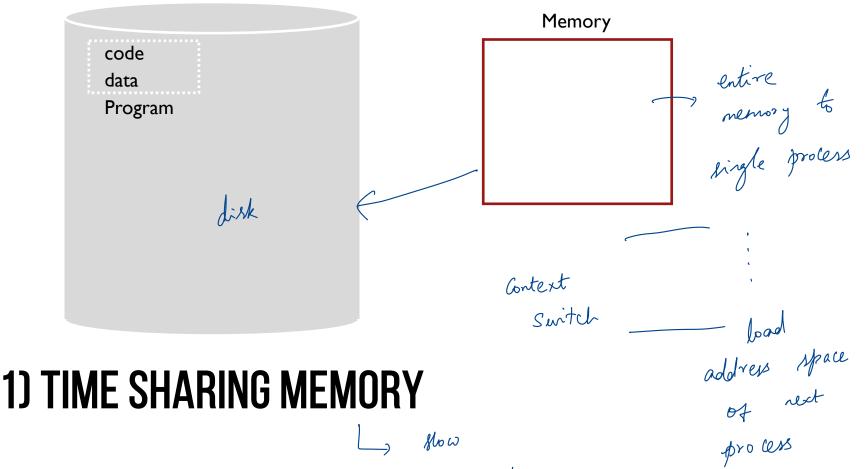
Addresses are "hardcoded" into process binaries

How to avoid collisions?



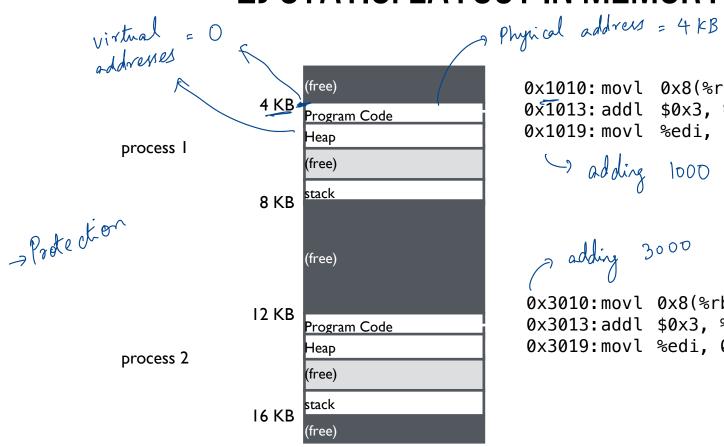
- I. Time Sharing
- 2. Static Relocation
- 3. Base
- 4. Base+Bounds





Now ire ficient

# 2) STATIC: LAYOUT IN MEMORY



```
0x1010: movl 0x8(%rbp), %edi
0x1013: addl $0x3, %edi
0x1019: movl %edi, 0x8(%rbp)
 adding 1000
```

adding 3000

```
0x3010:movl 0x8(%rbp), %edi
0x3013:addl $0x3, %edi
0x3019:movl %edi, 0x8(%rbp)
```

### 3) DYNAMIC RELOCATION

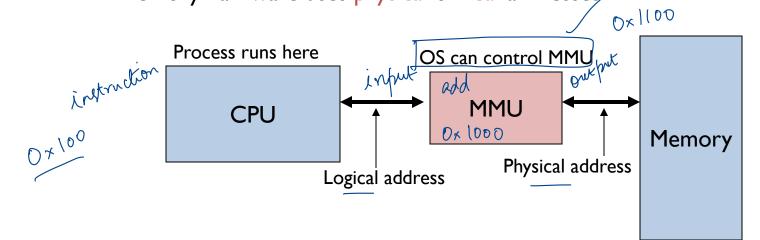
Goal: Protect processes from one another

Requires hardware support

Memory Management Unit (MMU)

MMU dynamically changes process address at every memory reference

- Process generates logical or virtual addresses (in their address space)
- Memory hardware uses physical or real addresses.



### HARDWARE SUPPORT FOR DYNAMIC RELOCATION

instructions only mode

Privileged (protected, kernel) mode: OS runs

- When enter OS (trap, system calls, interrupts, exceptions)
- Allows certain instructions to be executed (Can manipulate contents of MMU)
- Allows OS to access all of physical memory

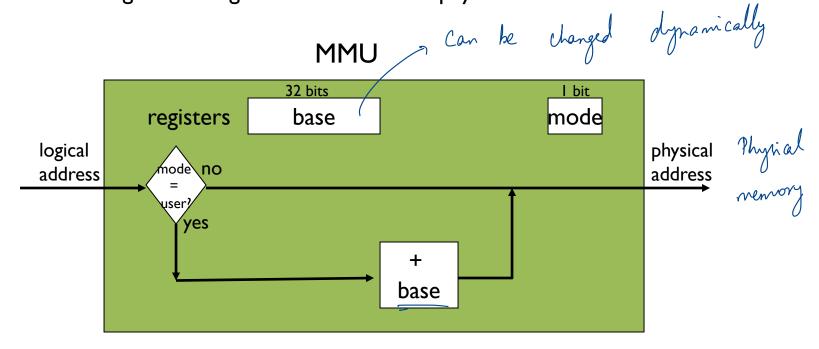
User mode: User processes run

Perform translation of logical address to physical address

wing the MMU

### IMPLEMENTATION OF DYNAMIC RELOCATION: BASE REG

Translation on every memory access of user process MMU adds base register to logical address to form physical address

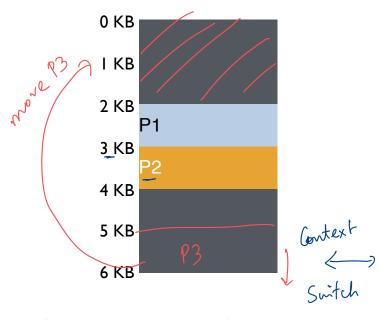


### DYNAMIC RELOCATION WITH BASE REGISTER

Translate virtual addresses to physical by adding a fixed offset each time. Store offset in base register

Each process has different value in base register

Dynamic relocation by changing value of base register!



Base Register for PI = 2048

Base Register for P2 = 3072

Virtual

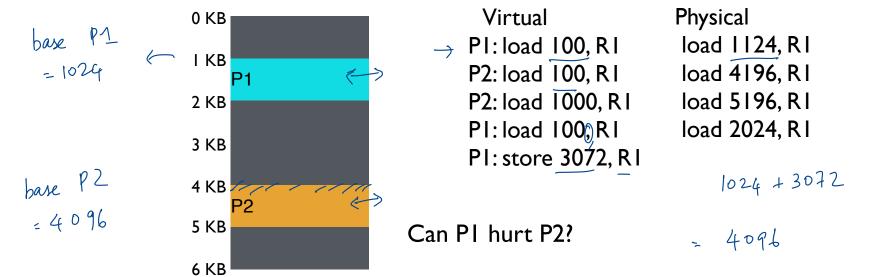
PI: load IQ, RI

PI: load 200, RI

P2: load 500, R1

**Physical** 

### VISUAL EXAMPLE OF DYNAMIC RELOCATION: **BASE REGISTER**



### 4) DYNAMIC WITH BASE+BOUNDS

Idea: limit the address space with a bounds register

Base register: smallest physical addr (or starting location)

Bounds register: size of this process's virtual address space

Sometimes defined as largest physical address (base + size)

→ OS kills process if process loads/stores beyond bounds

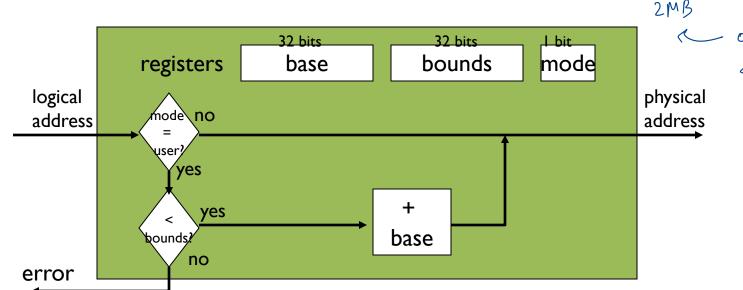
bose bounds

both are configured by OS

### IMPLEMENTATION OF BASE+BOUNDS

Translation on every memory access of user process

- MMU compares logical address to bounds register if logical address is greater, then generate error
- MMU adds base register to logical address to form physical address



### MANAGING PROCESSES WITH BASE AND BOUNDS

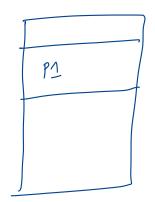
Context-switch: Add base and bounds registers to proc struct Steps

- Change to privileged mode
- Save base and bounds registers of old process
- Load base and bounds registers of new process
- Change to user mode and jump to new process

#### Protection requirement

- User process cannot change base and bounds registers
- User process cannot change to privileged mode

every process
add shace
reeds to be
contiguous



### BASE AND BOUNDS

#### Advantages

Provides protection (both read and write) across address spaces Supports dynamic relocation

Can place process at different locations initially and move address spaces

Simple, inexpensive implementation: Few registers, little logic in MMU

#### **Disadvantages**

Each process must be allocated contiguously in physical memory Must allocate memory that may not be used by process No partial sharing: Cannot share parts of address space

Efficiency Sharing

# QUIZ 4

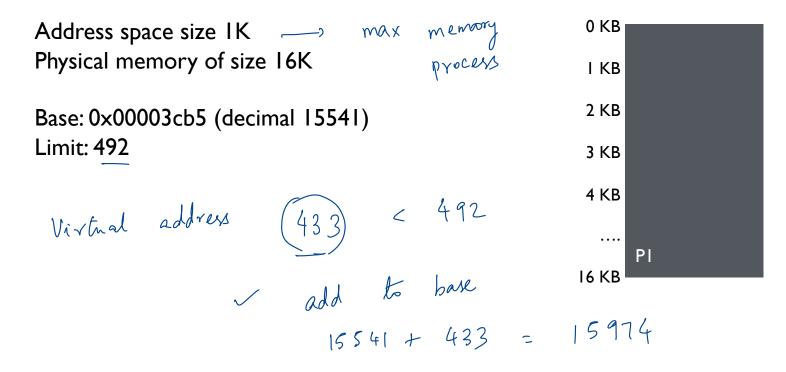
#### https://tinyurl.com/cs537-fa24-q4

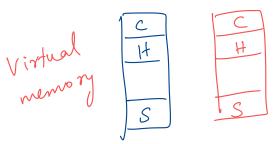
```
unsigned long A = 3;
     int main(int argc, char *argv[]) {
        int B = 7;
short *P = malloc(5 * sizeof(short));
static data / code
```

# QUIZ 4

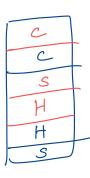
VA: 913 X

#### https://tinyurl.com/cs537-fa24-q4





# 5) **SEGMENTATION**



Divide address space into logical segments

- Each segment corresponds to logical entity in address space

(code, stack, heap)

Code Each segment has separate base + bounds register Heap bounds -> contiguous bare stack

2<sup>n</sup>-1

### SEGMENTED ADDRESSING

Process now specifies segment and offset within segment

How does process designate a particular segment?

- Use part of logical address (virtual address)
  - Top bits of logical address select segment
  - Low bits of logical address select offset within segment

segment offset which within that segment

What if small address space, not enough bits?

- Implicitly by type of memory reference
- Special registers

### SEGMENTATION IMPLEMENTATION

MMU contains Segment Table (per process)

- Each segment has own base and bounds, protection bits
- Example: 14 bit logical address, 4 segments; number

How many bits for segment?

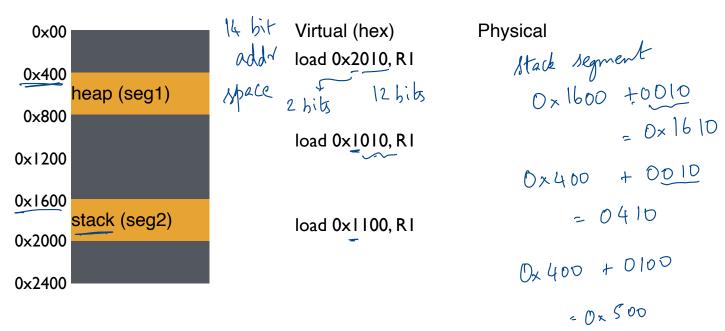
How many bits for offset?

Segment	Base	Bounds	R W
0 ,	0x2000	0x6ff	1 0
1 ,	0x0000	0x4ff	1 1
2 ·	0x3000	0xfff	1 1
3 ,	0x0000	0x000	0 0

remember:

I hex digit → 4 bits

# VISUAL INTERPRETATION

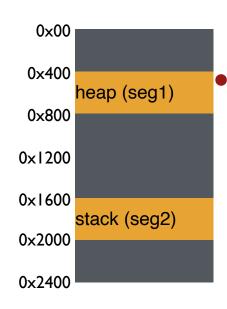


Segment numbers:

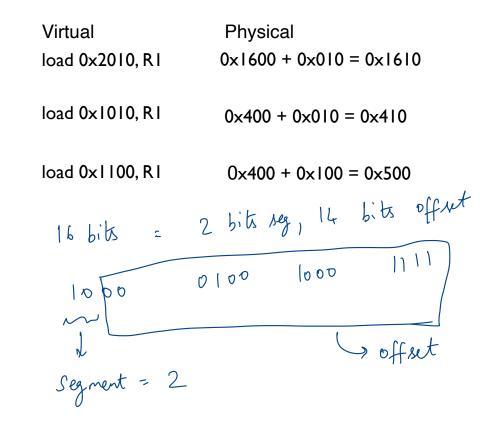
0: code+data

J: heap

2: stack



Segment numbers:
0: code+data
1: heap
2: stack



### HOW DOES THIS LOOK IN X86

Stack Segment (SS): Pointer to the stack

Code Segment (CS): Pointer to the code

Data Segment (DS): Pointer to the data

Extra Segment (ES): Pointer to extra data

F Segment (FS): Pointer to more extra data

G Segment (GS): Pointer to still more extra data

# NOTE: HOW DO STACKS GROW?

Physial 124kB

0KB **Program Code** 1KB Heap 2KB (free) 12 **\***KB Stack = 4 KB

**16KB** 

Stack goes 16K  $\rightarrow$  12K, in physical memory is 28K  $\rightarrow$  24K Segment base is at 28K

Virtual address 0x3C00 = 15K

 $\rightarrow$  top 2 bits (0x3) segment ref, offset is 0xC00 = 3K

How do we make CPU translate that ?

Negative offset = subtract max segment from offset

$$= 3K - 4K = -11$$

= 3K - 4K = -1KAdd to base = 28K - 1K = 27K

-> bound or size

# ADVANTAGES OF SEGMENTATION

Protection

Enables sparse allocation of address space

Stack and heap can grow independently

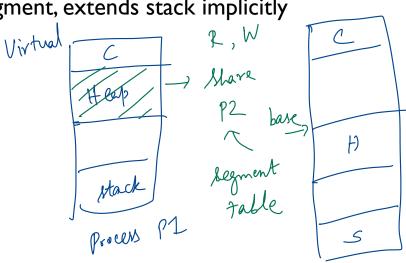
Heap: If no data on free list, dynamic memory allocator requests more from OS
 (e.g., UNIX: malloc calls sbrk())

• Stack: OS recognizes reference outside legal segment, extends stack implicitly

Different protection for different segments

- Enables sharing of selected segments
- Read-only status for code

Supports dynamic relocation of each segment



### DISADVANTAGES OF SEGMENTATION

Each segment must be allocated contiguously

May not have sufficient physical memory for large segments?

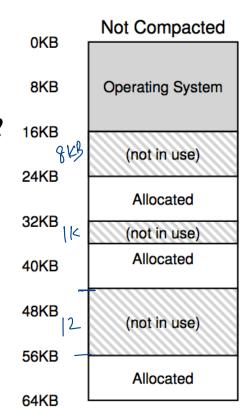
**External Fragmentation** 

Raging

24 KB in one segment

4 copying / moving

overhead



# **NEXT STEPS**

Project 2: Due soon!

Next class: Paging, TLBs and more!