MEMORY VIRTUALIZATION

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CS 537, Fall 2024

ADMINISTRIVIA

- Project 2 is due Sept 24th Tuesday
- Project I grading in progress (soon?)

- Midterm I: Oct 15th at 5.45pm
- Conflict form

AGENDA / LEARNING OUTCOMES

Memory virtualization

What are main techniques to virtualize memory?

What are their benefits and shortcomings?

RECAP

MEMORY VIRTUALIZATION

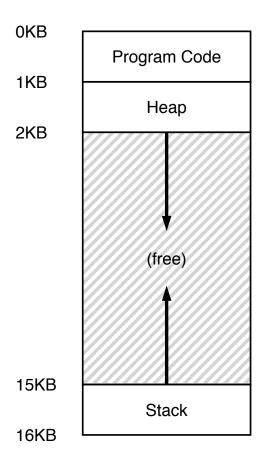
Transparency: Process is unaware of sharing

Protection: Cannot corrupt OS or other process memory

Efficiency: Do not waste memory or slow down processes

Sharing: Enable sharing between cooperating processes

RECAP: WHAT IS IN ADDRESS SPACE?



the code segment: where instructions live

the heap segment: contains malloc'd data dynamic data structures (it grows downward)

Static: Code and some global variables

Dynamic: Stack and Heap

(it grows upward) the stack segment: contains local variables arguments to routines, return values, etc.

HOW TO VIRTUALIZE MEMORY

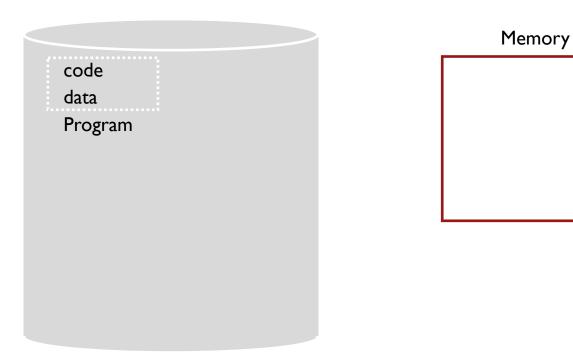
Problem: How to run multiple processes simultaneously?

Addresses are "hardcoded" into process binaries

How to avoid collisions?

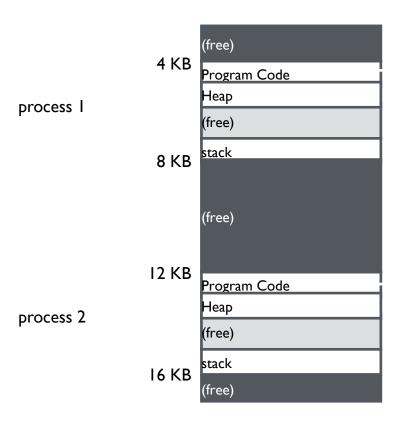
Possible Solutions for Mechanisms:

- I. Time Sharing
- 2. Static Relocation
- 3. Base
- 4. Base+Bounds



1) TIME SHARING MEMORY

2) STATIC: LAYOUT IN MEMORY



0x1010: movl 0x8(%rbp), %edi
0x1013: addl \$0x3, %edi
0x1019: movl %edi, 0x8(%rbp)

0x3010:movl 0x8(%rbp), %edi
0x3013:addl \$0x3, %edi
0x3019:movl %edi, 0x8(%rbp)

3) DYNAMIC RELOCATION

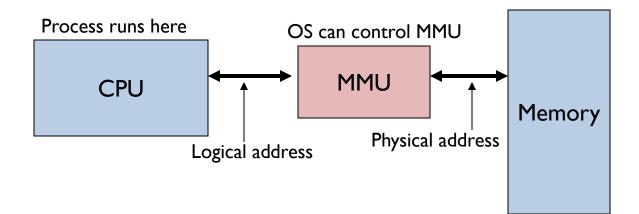
Goal: Protect processes from one another

Requires hardware support

Memory Management Unit (MMU)

MMU dynamically changes process address at every memory reference

- Process generates logical or virtual addresses (in their address space)
- Memory hardware uses physical or real addresses



HARDWARE SUPPORT FOR DYNAMIC RELOCATION

Privileged (protected, kernel) mode: OS runs

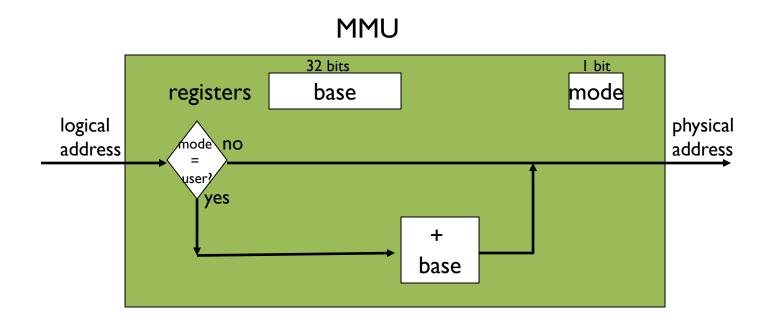
- When enter OS (trap, system calls, interrupts, exceptions)
- Allows certain instructions to be executed (Can manipulate contents of MMU)
- Allows OS to access all of physical memory

User mode: User processes run

Perform translation of logical address to physical address

IMPLEMENTATION OF DYNAMIC RELOCATION: BASE REG

Translation on every memory access of user process MMU adds base register to logical address to form physical address

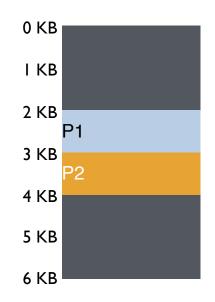


DYNAMIC RELOCATION WITH BASE REGISTER

Translate virtual addresses to physical by adding a fixed offset each time. Store offset in base register

Each process has different value in base register

Dynamic relocation by changing value of base register!



Base Register for PI = 2048

Base Register for P2 = 3072

Virtual

PI: load 10, RI

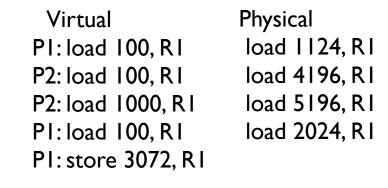
PI: load 200, RI

P2: load 500, R1

Physical

VISUAL EXAMPLE OF DYNAMIC RELOCATION: BASE REGISTER





Can PI hurt P2?

4) DYNAMIC WITH BASE+BOUNDS

Idea: limit the address space with a bounds register

Base register: smallest physical addr (or starting location)

Bounds register: size of this process's virtual address space

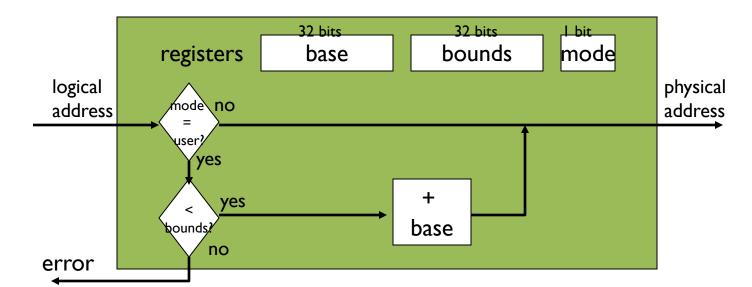
Sometimes defined as largest physical address (base + size)

OS kills process if process loads/stores beyond bounds

IMPLEMENTATION OF BASE+BOUNDS

Translation on every memory access of user process

- MMU compares logical address to bounds register if logical address is greater, then generate error
- MMU adds base register to logical address to form physical address



MANAGING PROCESSES WITH BASE AND BOUNDS

Context-switch: Add base and bounds registers to proc struct Steps

- Change to privileged mode
- Save base and bounds registers of old process
- Load base and bounds registers of new process
- Change to user mode and jump to new process

Protection requirement

- User process cannot change base and bounds registers
- User process cannot change to privileged mode

BASE AND BOUNDS

Advantages

Provides protection (both read and write) across address spaces
Supports dynamic relocation

Can place process at different locations initially and move address spaces

Simple, inexpensive implementation: Few registers, little logic in MMU

Disadvantages

Each process must be allocated contiguously in physical memory Must allocate memory that may not be used by process No partial sharing: Cannot share parts of address space

QUIZ 4

https://tinyurl.com/cs537-fa24-q4

```
unsigned long A = 3;
int main(int argc, char *argv[]) {
   int B = 7;
   short *P = malloc(5 * sizeof(short));
}
```



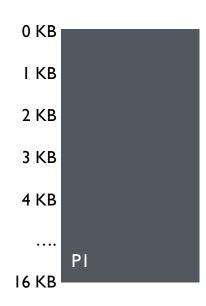
QUIZ 4

https://tinyurl.com/cs537-fa24-q4

Address space size IK
Physical memory of size I6K

Base: 0x00003cb5 (decimal 15541)

Limit: 492

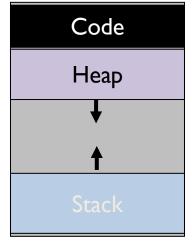


5) **SEGMENTATION**

Divide address space into logical segments

 Each segment corresponds to logical entity in address space (code, stack, heap)

Each segment has separate base + bounds register



SEGMENTED ADDRESSING

Process now specifies segment and offset within segment

How does process designate a particular segment?

- Use part of logical address
 - Top bits of logical address select segment
 - Low bits of logical address select offset within segment

What if small address space, not enough bits?

- Implicitly by type of memory reference
- Special registers

SEGMENTATION IMPLEMENTATION

MMU contains Segment Table (per process)

- Each segment has own base and bounds, protection bits
- Example: 14 bit logical address, 4 segments;

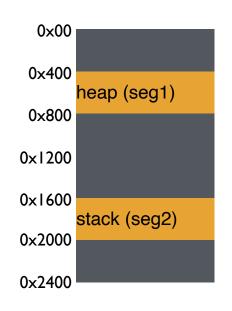
How many bits for segment?

How many bits for offset?

Segment	Base	Bounds	R W
0	0x2000	0x6ff	1 0
1	0x0000	0x4ff	1 1
2	0x3000	0xfff	1 1
3	0x0000	0x000	0 0

remember: I hex digit \rightarrow 4 bits

VISUAL INTERPRETATION



Virtual (hex) load 0x2010, R1

Physical

load 0x1010, R1

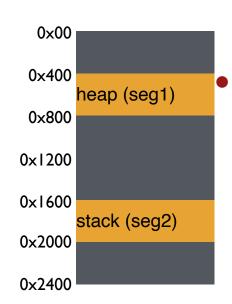
load 0x1100, R1

Segment numbers:

0: code+data

I: heap

2: stack



Virtual Physical $0 \times 1600 + 0 \times 010 = 0 \times 1610$ load 0×1010 , RI $0 \times 400 + 0 \times 010 = 0 \times 410$ load 0×1100 , RI $0 \times 400 + 0 \times 100 = 0 \times 500$

Segment numbers:
0: code+data
1: heap
2: stack

HOW DOES THIS LOOK IN X86

Stack Segment (SS): Pointer to the stack

Code Segment (CS): Pointer to the code

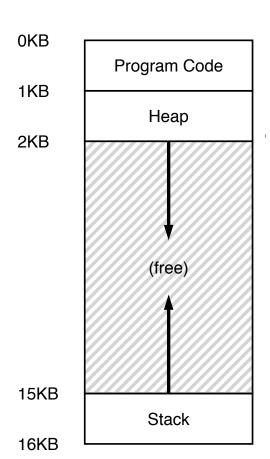
Data Segment (DS): Pointer to the data

Extra Segment (ES): Pointer to extra data

F Segment (FS): Pointer to more extra data

G Segment (GS): Pointer to still more extra data

NOTE: HOW DO STACKS GROW?



Stack goes 16K \rightarrow 12K, in physical memory is 28K \rightarrow 24K Segment base is at 28K

Virtual address 0x3C00 = 15K

→ top 2 bits (0x3) segment ref, offset is 0xC00 = 3K

How do we make CPU translate that ?

Negative offset = subtract max segment from offset = 3K - 4K = -1KAdd to base = 28K - 1K = 27K

ADVANTAGES OF SEGMENTATION

Enables sparse allocation of address space

Stack and heap can grow independently

- Heap: If no data on free list, dynamic memory allocator requests more from OS
 (e.g., UNIX: malloc calls sbrk())
- Stack: OS recognizes reference outside legal segment, extends stack implicitly

Different protection for different segments

- Enables sharing of selected segments
- Read-only status for code

Supports dynamic relocation of each segment

DISADVANTAGES OF SEGMENTATION

Not Compacted 0KB Each segment must be allocated contiguously **Operating System** 8KB May not have sufficient physical memory for large segments? 16KB (not in use) 24KB **External Fragmentation** Allocated 32KB (not in use) Allocated 40KB 48KB (not in use) 56KB Allocated 64KB

NEXT STEPS

Project 2: Due soon!

Next class: Paging, TLBs and more!