VIRTUALIZATION: CPU TO MEMORY

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ADMINISTRIVIA

- Project I: DONE!?
- How to use slip days? (Piazza)

- Project 2 is out, due next Wednesday

AGENDA / LEARNING OUTCOMES

CPU virtualization

Recap of scheduling policies (Tue) Lottery Scheduling, Multi-CPU

Memory virtualization

What is the need for memory virtualization? How to virtualize memory?

RECAP: CPU VIRTUALIZATION

RECAP: SCHEDULING MECHANISM

Process: Abstraction to virtualize CPU

Use time-sharing in OS to switch between processes

Limited Direct Execution

Use system calls to run access devices etc. from user mode Context-switch using interrupts for multi-tasking

RECAP: METRICS \rightarrow POLICIES

Turnaround time = completion_time - arrival_time FIFO: First come, first served

SJF: Shortest job first

RECAP: METRICS \rightarrow POLICIES

Response time = first_run_time - arrival_time

Pre-emptive scheduling

RR: Round robin with time slice

Minimizes response time but could increase turnaround?

RECAP: MULTI-LEVEL FEEDBACK QUEUE

What if we don't know how long a job will run?

Support two job types with distinct goals

- "interactive" programs care about response time
- "batch" programs care about turnaround time

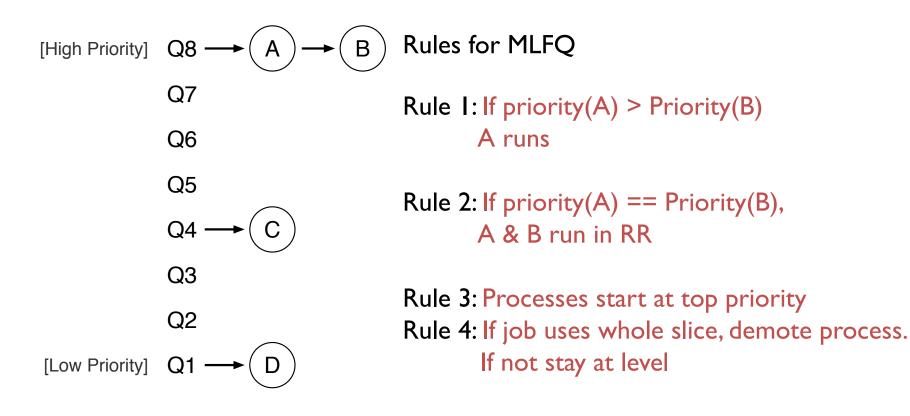
Approach:

Multiple levels of round-robin

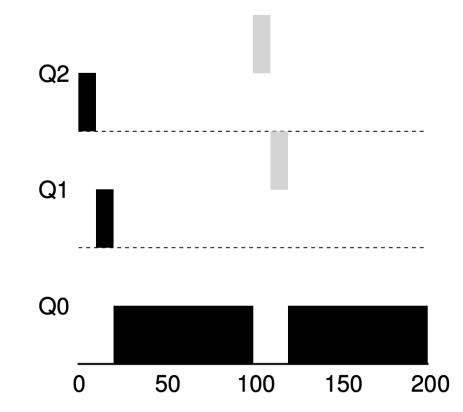
Each level has higher priority than lower level

Can preempt them

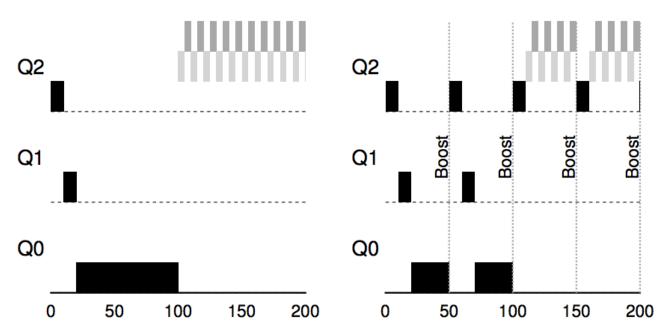
RECAP: MULTI-LEVEL FEEDBACK QUEUE



INTERACTIVE PROCESS JOINS



AVOID STARVATION



Priority Boost!

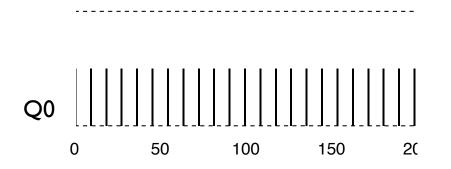
Rule 5: After some time period S, move all the jobs in the system to the topmost queue.

GAMING THE SCHEDULER ?



Job could trick scheduler by doing I/O just before time-slice end

QI



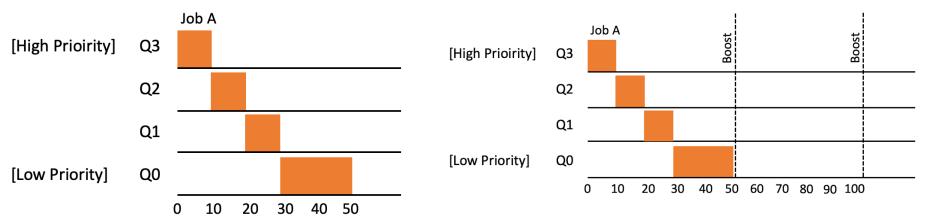
Rule 4*: Once a job uses up its time allotment at a given level (regardless of how many times it has given up the CPU), its priority is reduced

QUIZ 5 https://tinyurl.com/cs537-sp23-quiz5



| Jobs | Runtime | Arrival Time |
|-------|---------|--------------|
| Job A | 100 | 0 |
| Job B | 10 | 50 |

| Jobs | Runtime | Arrival Time |
|-------|---------|--------------|
| Job A | 100 | 0 |
| Job B | 10 | 50 |
| Job C | 20 | 70 |



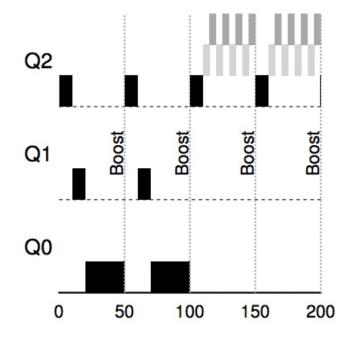
FAIRNESS IN SCHEDULING

Metrics so far: turn around time, response time.

New metric: Fairness!

3 users; each get 1/3rd of CPU no matter how long they run for

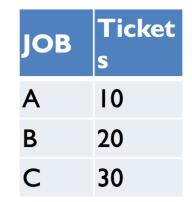
Is MLFQ fair?

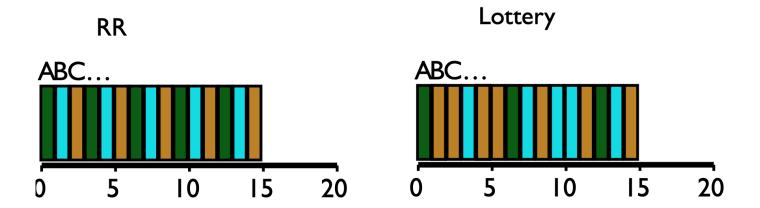


LOTTERY SCHEDULING

Approach:

Give processes lottery tickets
 Whoever wins the lottery runs
 Higher priority => more tickets

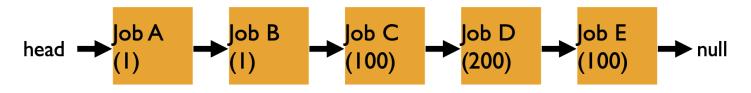




IMPLEMENTING LOTTERY SCHEDULING

```
int counter = 0;
int winner = getrandom(0, totaltickets);
node_t *current = head;
while (current) {
    counter += current->tickets;
    if (counter > winner) break;
    current = current->next;
}
```

// current gets to run



CPU SUMMARY

Mechanism

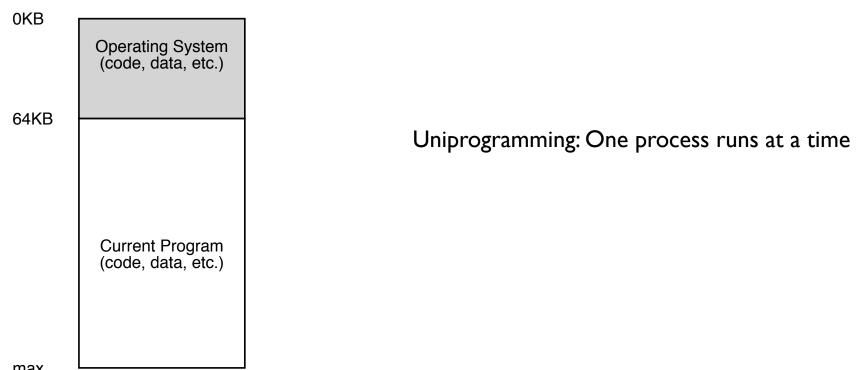
Process abstraction System call for protection Context switch to time-share

Policy

Metrics: turnaround time, response time Balance using MLFQ Fairness with Lottery Scheduling

VIRTUALIZING MEMORY

BACK IN THE DAY...



max

MULTIPROGRAMMING GOALS

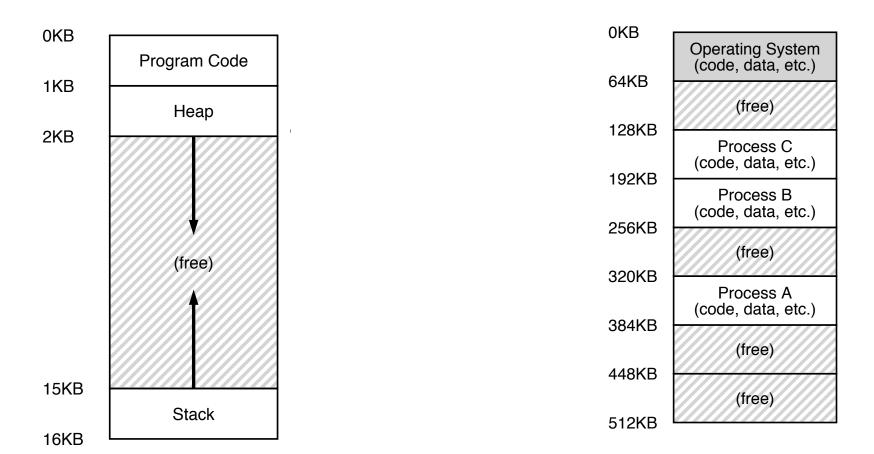
Transparency: Process is unaware of sharing

Protection: Cannot corrupt OS or other process memory

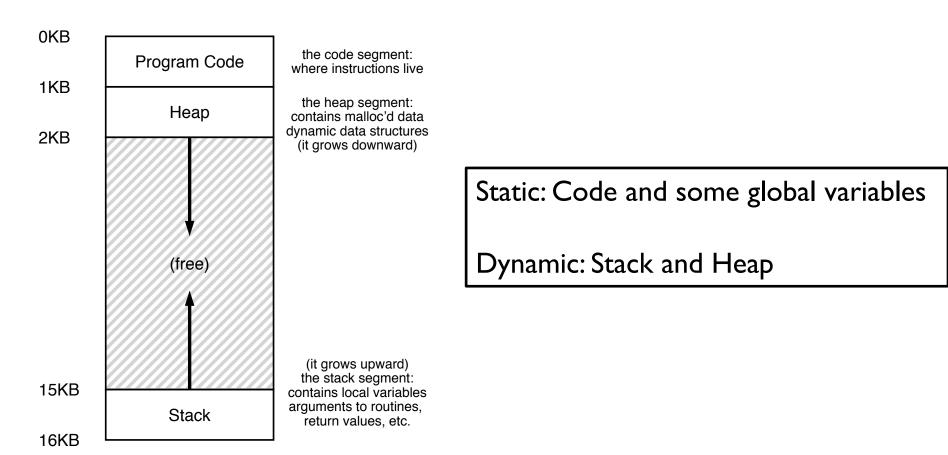
Efficiency: Do not waste memory or slow down processes

Sharing: Enable sharing between cooperating processes

ABSTRACTION: ADDRESS SPACE



WHAT IS IN ADDRESS SPACE?



ASIDE: HOW TO CREATE A PROCESS?

Unix-like OS use fork()

Fork() - Clones the calling process to create a child process

Make copy of code, data, stack etc.

Add new process to ready list

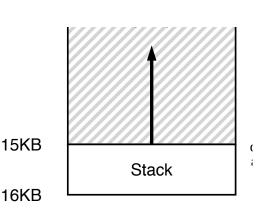
Exec(char *file): Replace current data and code with file

Advantages: Flexible, clean, simple

Disadvantages: Wasteful to perform copy and overwrite of memory

STACK ORGANIZATION

- alloc(A);
- alloc(B);
- alloc(C);
- free(C);
- alloc(D);
- free(D);
- free(B);
- free(A);



Pointer between allocated and free space Allocate: Increment pointer Free: Decrement pointer

No fragmentation!

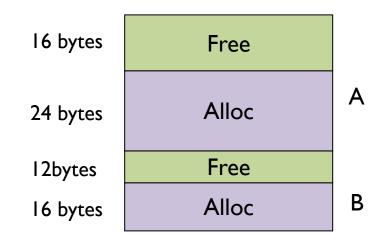
WHAT GOES ON STACK?

```
main () {
   int A = 0;
   foo(10);
   printf("A: %d\n", A);
}
void foo (int Z) {
   int A = 2;
   Z = 5;
   printf("A: %d Z: %d\n", A, Z);
}
```

HEAP ORGANIZATION

Allocate from any random location: malloc(), new() etc.

- Heap memory consists of allocated and free areas (holes)
- Order of allocation and free is unpredictable



MEMORY ACCESS

```
#include <stdio.h>
#include <stdlib.h>
```

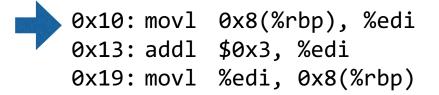
```
int main(int argc, char *argv[]) {
    int x;
    x = x + 3;
}
```

0x10:movl 0x8(%rbp), %edi
0x13:addl \$0x3, %edi
0x19:movl %edi, 0x8(%rbp)

%**rbp** is the base pointer: points to base of current stack frame

MEMORY ACCESS

Initial %rip = 0×10 %rbp = 0×200

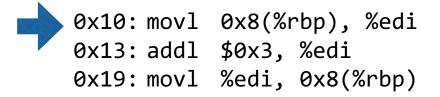


%**rbp** is the base pointer: points to base of current stack frame

%rip is instruction pointer (or program counter)

MEMORY ACCESS

Initial %rip = 0×10 %rbp = 0×200



%**rbp** is the base pointer: points to base of current stack frame

%rip is instruction pointer (or program counter)

Fetch instruction at addr 0x10 Exec:

load from addr 0x208

Fetch instruction at addr 0x13 Exec:

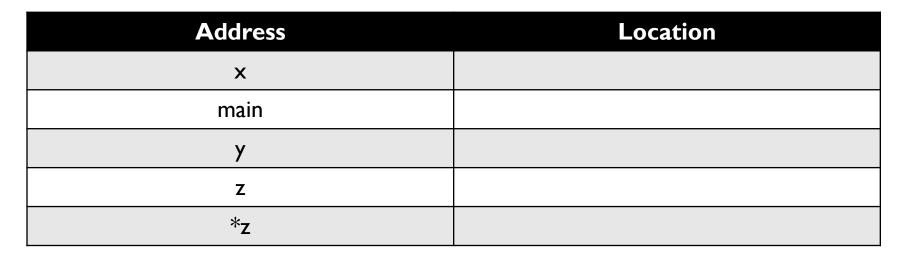
no memory access

Fetch instruction at addr 0x19 Exec:

store to addr 0x208

QUIZ 6 https://tinyurl.com/cs537-sp23-quiz6

```
int x;
int main(int argc, char *argv[]) {
    int y;
    int* z = malloc(sizeof(int));); Possible locations:
    static data/code, stack, heap
```

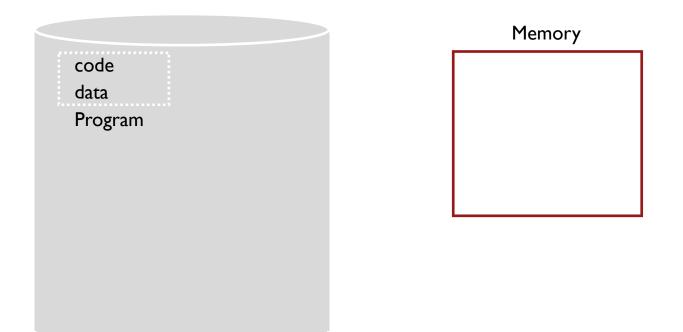


HOW TO VIRTUALIZE MEMORY

Problem: How to run multiple processes simultaneously? Addresses are "hardcoded" into process binaries How to avoid collisions?

Possible Solutions for Mechanisms (covered today):

- I. Time Sharing
- 2. Static Relocation
- 3. Base
- 4. Base+Bounds



TIME SHARE MEMORY: EXAMPLE

PROBLEMS WITH TIME SHARING?

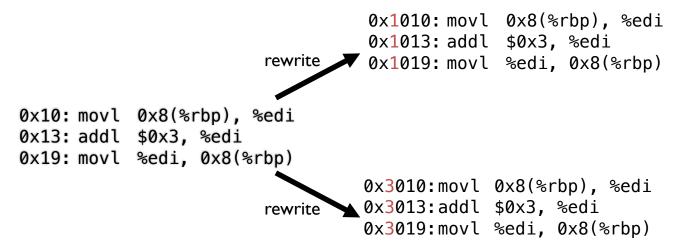
Ridiculously poor performance

Better Alternative: space sharing!

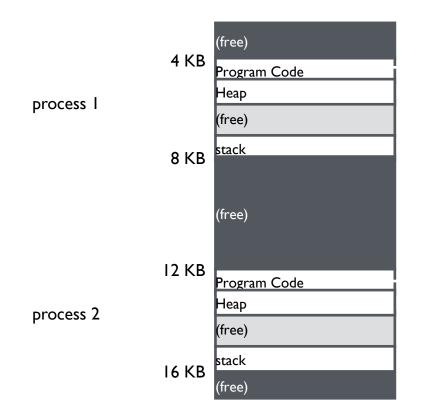
At same time, space of memory is divided across processes Remainder of solutions all use space sharing

2) STATIC RELOCATION

Idea: OS rewrites each program before loading it as a process in memory Each rewrite for different process uses different addresses and pointers Change jumps, loads of static data



STATIC: LAYOUT IN MEMORY



0x1010:movl 0x8(%rbp), %edi
0x1013:addl \$0x3, %edi
0x1019:movl %edi, 0x8(%rbp)

0x3010:movl 0x8(%rbp), %edi
0x3013:addl \$0x3, %edi
0x3019:movl %edi, 0x8(%rbp)

STATIC RELOCATION: DISADVANTAGES

No protection

- Process can destroy OS or other processes
- No privacy

Cannot move address space after it has been placed

- May not be able to allocate new process

3) DYNAMIC RELOCATION

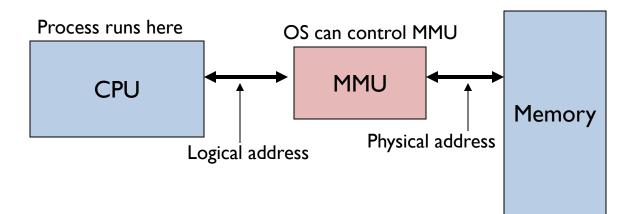
Goal: Protect processes from one another

Requires hardware support

Memory Management Unit (MMU)

MMU dynamically changes process address at every memory reference

- Process generates logical or virtual addresses (in their address space)
- Memory hardware uses physical or real addresses



HARDWARE SUPPORT FOR DYNAMIC RELOCATION

Privileged (protected, kernel) mode: OS runs

- When enter OS (trap, system calls, interrupts, exceptions)
- Allows certain instructions to be executed

(Can manipulate contents of MMU)

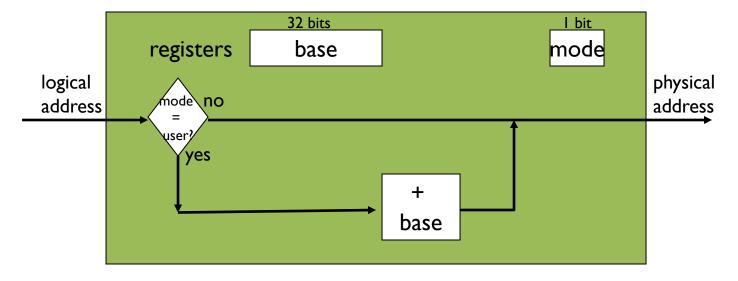
- Allows OS to access all of physical memory

User mode: User processes run

- Perform translation of logical address to physical address

IMPLEMENTATION OF DYNAMIC RELOCATION: BASE REG

Translation on every memory access of user process MMU adds base register to logical address to form physical address



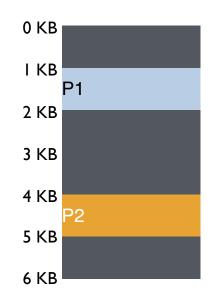
MMU

DYNAMIC RELOCATION WITH BASE REGISTER

Translate virtual addresses to physical by adding a fixed offset each time. Store offset in base register

Each process has different value in base register

Dynamic relocation by changing value of base register!



Virtual

PI: load 100, RI

P2: load 100, R1

P2: load 1000, R1

PI: load 100, RI

VISUAL EXAMPLE OF Dynamic relocation: Base register



| Virtual | Physical |
|-------------------|----------------|
| PI:load 100, RI | load 1124, R1 |
| P2: load 100, R1 | load 4196, R1 |
| P2: load 1000, R1 | load 5096, R I |
| PI: load 1000, R1 | load 2024, R I |

Can P2 hurt P1? Can P1 hurt P2?

How well does dynamic relocation do with base register for protection?



| Virtual | Physical | |
|--------------------|-------------------------|---------------|
| P1: load 100, R1 | load 1124, R1 | |
| P2: load 100, R1 | load 4196, R1 | |
| P2: load 1000, R1 | load 5096, R I | |
| P1: load 100, R1 | load 2024, R I | |
| PI: store 3072, RI | store 4096 , R I | (3072 + 1024) |

How well does dynamic relocation do with base register for protection?

4) DYNAMIC WITH BASE+BOUNDS

Idea: limit the address space with a bounds register

Base register: smallest physical addr (or starting location) Bounds register: size of this process's virtual address space

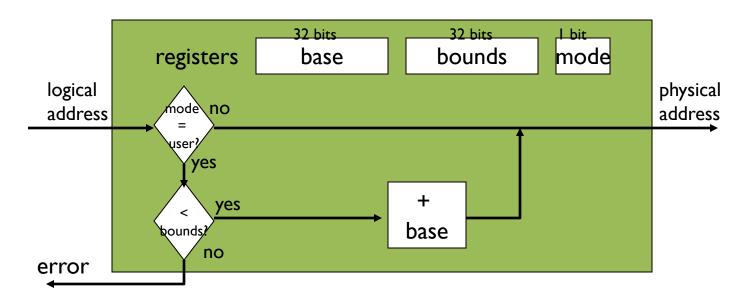
- Sometimes defined as largest physical address (base + size)

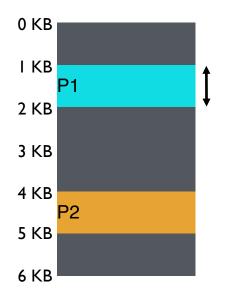
OS kills process if process loads/stores beyond bounds

IMPLEMENTATION OF BASE+BOUNDS

Translation on every memory access of user process

- MMU compares logical address to bounds register if logical address is greater, then generate error
- MMU adds base register to logical address to form physical address





base register bounds register



Virtual P1: load 100, R1 P2: load 100, R1 P2: load 1000, R1 P1: load 100, R1 P1: store 3072, R1

Can PI hurt P2?

Physical load 1124, R1 load 4196, R1 load 5196, R1 load 2024, R1

MANAGING PROCESSES WITH BASE AND BOUNDS

Context-switch: Add base and bounds registers to PCB Steps

- Change to privileged mode
- Save base and bounds registers of old process
- Load base and bounds registers of new process
- Change to user mode and jump to new process

Protection requirement

- User process cannot change base and bounds registers
- User process cannot change to privileged mode

BASE AND BOUNDS ADVANTAGES

Provides protection (both read and write) across address spaces Supports dynamic relocation

Can place process at different locations initially and also move address spaces

Advantages

Simple, inexpensive implementation: Few registers, little logic in MMU Fast: Add and compare in parallel

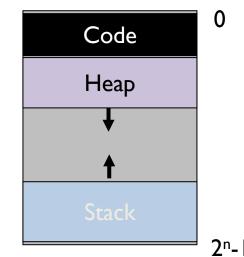
Disadvantages

- Each process must be allocated contiguously in physical memory
 Must allocate memory that may not be used by process
- No partial sharing: Cannot share parts of address space

BASE AND BOUNDS DISADVANTAGES

Disadvantages

- Each process must be allocated contiguously in physical memory Must allocate memory that may not be used by process
- No partial sharing: Cannot share parts of address space



NEXT STEPS

Project 2: Out now, due Feb 5th

Next week: Virtual memory segmentation, paging and more!