

Solving nonlinear equations - continued

1/27/2011 L1

In the last lecture we presented Newton's method for solving a nonlinear equation $f(x) = 0$. This method, which assumes we know a formula for the derivative $f'(x)$, is summarized as follows:

- $x_0 = \langle \text{some initial guess} \rangle$
- for $k=1, 2, 3, \dots$ iterate

$$x_{k+1} = x_k - \frac{f(x_k)}{f'(x_k)}$$

We saw that Newton's method is just one example from a general family of methods, called fixed point iterations, and are defined as:

- $x_0 = \langle \text{initial guess} \rangle$
- $x_{k+1} = g(x_k)$.

Newton's method is simply the fixed point iteration obtained by using $g(x) = x - \frac{f(x)}{f'(x)}$ as the "iteration" function.

We also discussed the following properties:

- If g is continuous, and the equation $x = g(x)$ is equivalent (subject to algebraic manipulations) to the equation $f(x) = 0$, then:

If the sequence $\{x_k\}$ converges to the number a then $f(a) = 0$ (i.e. it is a solution)

- The sequence $\{x_k\}$ is not always guaranteed to converge. However if

$$|g(x) - g(y)| \leq L |x - y| \text{ for some } L \in [0, 1) \text{ and for any } x, y \in [a, b]$$

then g will be called a contraction. (in $[a, b]$)

When g is a contraction on an interval $(a - \delta, a + \delta)$ around an actual solution a to $f(x) = 0$, then if x_0 (or any subsequent iterate) falls within the interval $(a - \delta, a + \delta)$, the sequence $\{x_k\}$ will converge to a .

- In the case where g is differentiable, an easier criterion which can be used to ensure g is a contraction, is to ensure $|g'(x)| \leq L$ ($L \in [0, 1)$) with $x \in [a, b]$.

We will use these results to examine when Newton's method can be guaranteed to converge.

1/21/2011 L

For Newton, we have:

$$g(x) = x - \frac{f(x)}{f'(x)}$$

Assume that the second derivative $f''(x)$ exists. Then:

$$\begin{aligned} g'(x) &= 1 - \frac{f'(x)f'(x) - f(x)f''(x)}{[f'(x)]^2} \\ &= \frac{f(x)f''(x)}{[f'(x)]^2} \end{aligned}$$

We will now make some additional assumptions:

- If a is the solution $f(a) = 0$, assume $f'(a) \neq 0$.
- Assume that $\lim_{x \rightarrow a} f''(x) < \infty$ (the limit exists, and it is not infinite).

$$\text{Then } \lim_{x \rightarrow a} g'(x) = \frac{f(a)}{[f'(a)]^2} \lim_{x \rightarrow a} f''(x) = 0.$$

The fact that $\lim_{x \rightarrow a} g'(x) = 0$ implies that we can find an interval $(a-\delta, a+\delta)$ around a , such that $g'(x)$ can be arbitrarily small. In particular for any $0 \leq L < 1$ there is an appropriate δ that will guarantee that

$$\text{if } x \in (a-\delta, a+\delta) \Rightarrow |g'(x)| \leq L$$

As a consequence, g will be a contraction in $(a-\delta, a+\delta)$ and, if our initial guess is in that interval, then Newton's method will converge.

In some cases we can estimate what the radius δ has to be, in order to guarantee convergence; we will see examples later. A good heuristic however is to evaluate $|g'(x_n)|$ during the course of the iteration.

If the value is less than 1 , this is a reasonable indication (but, not a proof) that the iteration is headed to convergence.

However, a simple examination of $g'(x) = \frac{f(x) f''(x)}{[f'(x)]^2}$

can give us some clues about certain cases where convergence is more likely, or more difficult to secure:

- * If $f''(x) = \text{small}$, $g'(x)$ will also tend to be small. In particular when $f''(x) = 0$ convergence is certain. Unfortunately, this is only the case for linear functions $f(x) = ax + b$ which are a very limited sub-case of our general nonlinear problems.
- * If $f'(x)$ is large, convergence will typically occur more easily. Of course, sometimes $f' = \text{large}$ will happen at the same time $f'' = \text{large}$, so these 2 factors will compete with one another.

Another consequence is that, when $f'(x) \approx 0$ (i.e. the plot of f is mostly "flat") convergence will be quite more uncertain. Compare this with our intuitive explanation of "flat" tangents in Newton's method.

Order of convergence

1/21/2011 10

We previously used the hypothesis that g is a contraction to show that $|x_k - a| \xrightarrow[k \rightarrow \infty]{} 0$. Remember that the quantity $e = x_{\text{approximate}} - x_{\text{exact}}$ was previously defined as the (absolute) error. In this case, let us define $e_k = x_k - a$ (a is the solution $f(a) = 0$) as the error after the k -th iteration. If g is a contraction, we have

$$\begin{aligned} |e_{k+1}| &= |x_{k+1} - a| = |g(x_k) - g(a)| \\ &\leq L |x_k - a| = L |e_k| \end{aligned}$$

Since $L < 1$, the error shrinks at least by a constant factor at each iteration.

In some cases, we can do even better.

Remember Taylor's theorem:

If a function g has k derivatives defined, then:

$$\begin{aligned} g(y) &= g(x) + g'(x)(y-x) + g''(x) \frac{(y-x)^2}{2} + g'''(x) \frac{(y-x)^3}{3!} \\ &\quad + \cdots + g^{(k-1)}(x) \frac{(y-x)^{k-1}}{(k-1)!} + g^{(k)}(c) \frac{(y-x)^k}{k!} \end{aligned}$$

Where c is a number between x & y .

For $k=1$ we simply obtain the mean value theorem:

$$g(y) = g(x) + g'(c)(y-x)$$

or $\frac{g(y)-g(x)}{y-x} = g'(c)$ for some c between x & y .

which we used before to show that $|g'(c)| \leq L$ implies that g is a contraction with constant $= L$.

We will now use the theorem in the case $k=2$

$$g(y) = g(x) + g'(x)(y-x) + g''(c) \frac{(y-x)^2}{2}$$

Let $g = x - f/f'$ (as in Newton's method).

Also take $x = a$ (the solution) and $y = x_k$.

If $f'(a) \neq 0$ and $f''(a)$ is defined, then $g'(a) = \frac{f(a) f''(a)}{(f'(a))^2} = 0$.

Thus, the previous equation becomes:

$$g(x_k) = g(a) + g''(c) \frac{(x_k - a)^2}{2} \Rightarrow$$

$$\Rightarrow x_{k+1} = a + g''(c) \frac{|x_k - a|^2}{2}$$

$$\Rightarrow |x_{k+1} - a| = \underbrace{\frac{g''(c)}{2}}_C |x_k - a|^2$$

$$\Rightarrow |e_{k+1}| \leq C \cdot |e_k|^2 \quad \leftarrow \text{note the exponent!} \quad (1)$$

$$\text{where } C = \max \left\{ \frac{g''(x)}{2} \right\}_{x \in (a, x_k)}$$

Compare eq. (1) with the general guarantee

$$|e_{k+1}| \leq L |e_k| \quad (2) \quad \text{for contractions:}$$

• Eq (2) depends on $L < 1$ to reduce the error.

In Eq (1), even if C is larger, when e_k is small, then e_{k+1} will be reduced, e.g.

$$C = 10 \quad |e_k| = 10^{-3} \quad \Rightarrow \quad |e_{k+1}| \leq 10^{-5} !$$

• Eq (2) implies that every iteration adds a fixed number (or fraction) of correct significant digits.

e.g. Let $L = 0.3$

$$|e_{k+2}| \leq 0.3 |e_{k+1}| \leq 0.09 |e_k|$$

i.e. we gain 1 significant digit every 2 iterations.