# Automatic Image Colorization - ○ ○ 

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## Problem Definition



## Previous Work

- User assisted
- Fully automated


## User assisted Scribble based

- User provides scribbles that give reference colors.
- The system extends the colors to the rest of the image.
- However, the colors have to be given as input, they are not learnt.


Photo: Levin et. al (2004)

## User assisted Reference based

- User provides reference image with similar features.
- The system transfers colors to the given image.
- However, providing/selecting suitable reference images is vital to this method.


Photos: Welsh et. al (2002)

## Fully Automated

Feature Engineering

- Image features created via pre-processing.
- Feature engineering plays a major role.

Neural Networks

- Convolutional Neural Networks are the current state of the art.
- Features are automatically learned.


## Setup

Infrastructure

- Google Cloud
- Nvidia Tesla K80 GPU


## Framework

- Keras

Training Data

- Imagenet
- Geological formation synset

Design

## Lab Color Space

- Euclidean distance in the a-b space corresponds to visually perceived differences
- L is the lightness channel
- 0 - black, 100 - white
- a, b are color components
- Range from -128 to +127 (or scaled to -100 to +100 )

Our task : predict the channels a, b using input L

## Network architecture



## Convolution

## Conv Unit

Conv Unit

## Loss Function MSE

- Not robust to inherent ambiguity
- Predicts mean of possible colorizations
- Results in desaturated color predictions



## Loss Function Multinomial classification

- Divide a , b space into K bins
- Predict probability distribution over these bins


$$
\operatorname{Loss}(Z, \hat{Z})=\sum_{p} \sum_{k=1}^{K} Z_{p, k} \log \left(\hat{Z}_{p, k}\right)
$$

## Problem : Desaturated output



## Solution: Color Rebalancing

- Distribution of a,b values strongly biased towards low (desaturated) values
- Reweight each pixel loss based on pixel color rarity
- Integrated into the loss function


## Desaturated output



## Color rebalanced



## Problem : Color patches



## Solution : Segmentation

- Intuition: Neighboring pixels that have similar intensities tend to have similar colors
- Introduce the notion of spatial locality into the loss function

$$
\begin{gathered}
\text { Loss }+=\lambda\left(\sum_{p}\left(\hat{a}_{p}-\sum_{q \in N(p)} w_{p q} \hat{a}_{q}\right)^{2}\right) \\
\text { Loss }+=\lambda\left(\sum_{p}\left(\hat{b}_{p}-\sum_{q \in N(p)} w_{p q} \hat{b}_{q}\right)^{2}\right) \\
w_{p q} \propto e^{-\left(L_{p}-L_{q}\right)^{2}}
\end{gathered}
$$

## Color patches



## Segmented



Results




## Failure cases



## Future Work

Tune the trade-off of vibrancy vs. realism in color re-balancing weights.
Explicitly control the colors used in a picture
Loss function - ambiguity invariant
Visualize network's intermediate layers
Applications to other underconstrained problems? E.g. Depth of field etc.

## References

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