Automatic Image Colorization

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Problem Definition



Previous Work

- User assisted
- Fully automated

User assisted Scribble based

- User provides scribbles that give reference colors.
- The system extends the colors to the rest of the image.
- However, the colors have to be given as input, they are not learnt.



Photo: Levin et. al (2004)

User assisted Reference based

- User provides reference image with similar features.
- The system transfers colors to the given image.
- However, providing/selecting suitable reference images is vital to this method.





Photos: Welsh et. al (2002)

Fully Automated

Feature Engineering

- Image features created via pre-processing.
- Feature engineering plays a major role.

Neural Networks

- Convolutional Neural Networks are the current state of the art.
- Features are automatically learned.



Infrastructure

- Google Cloud
- Nvidia Tesla K80 GPU

Framework

• Keras

Training Data

- Imagenet
 - \circ Geological formation synset



Lab Color Space

- Euclidean distance in the a-b space corresponds to visually perceived differences
- L is the lightness channel
 - 0 black, 100 white
- a, b are color components
 - Range from -128 to +127 (or scaled to -100 to +100)

Our task : predict the channels a, b using input L



Loss Function MSE

- Not robust to inherent ambiguity
- Predicts mean of possible colorizations
- Results in desaturated color predictions



Loss Function Multinomial classification

- Divide a, b space into K bins
- Predict probability distribution over these bins



$$Loss(Z, \hat{Z}) = \sum_{p} \sum_{k=1}^{K} Z_{p,k} log(\hat{Z}_{p,k})$$

Problem : Desaturated output







Solution : Color Rebalancing

- Distribution of a,b values strongly biased towards low (desaturated) values
- Reweight each pixel loss based on pixel color rarity
- Integrated into the loss function



Desaturated output







Color rebalanced







Problem : Color patches







Solution : Segmentation

- Intuition: Neighboring pixels that have similar intensities tend to have similar colors
- Introduce the notion of spatial locality into the loss function

 $Loss += \lambda \left(\sum_{p} (\hat{a}_{p} - \sum_{q \in N(p)} w_{pq} \hat{a}_{q})^{2} \right)$ $Loss += \lambda \left(\sum_{p} (\hat{b}_{p} - \sum_{q \in N(p)} w_{pq} \hat{b}_{q})^{2} \right)$ $w_{pq} \propto e^{-(L_{p} - L_{q})^{2}}$

Color patches







Segmented













































Failure cases













Future Work

Tune the trade-off of vibrancy vs. realism in color re-balancing weights.

Explicitly control the colors used in a picture

Loss function - ambiguity invariant

Visualize network's intermediate layers

Applications to other underconstrained problems? E.g. Depth of field etc.

References

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