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# ZigBee/IEEE 802.15.4

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# Outline of Talk

- Introduction
  - Evolution of LR-WPAN Standard
  - Zigbee and IEEE 802.15.4
  - Zigbee vs. Bluetooth
- IEEE 802.15.4 WPAN
  - 2 types of WPAN devices
  - Network Topologies
  - Architecture
- IEEE 802.15.4 PHY Layer
- IEEE 802.15.4 MAC Layer
- Experimental Evaluation of 802.15.4 Transmission Power Control and Interference Minimization
- Video Surveillance demo



# Evolution of WPAN

- Wired telephony network → Cellular Network
  - Need for mobility
  - Cost of laying new wires
- Cellular Network → WLAN
  - IEEE 802.11
  - Long range (100m), Data throughput of 2-11Mbps
- WLAN → WPAN
  - Even smaller wireless coverage area
  - Low-cost, low power, short range, and small size



# IEEE 802.15.4 (ZigBee)

- IEEE 802.15.4
  - Specifies the PHY and MAC layers
  - Low data rate
  - Low power
- ZigBee Alliance
  - Joined with IEEE to specify entire protocol stack
  - Targeted towards automation, sensor networks, and remote control applications
  - Provides for upper layer services
    - security services, data networking, compliance testing, marketing, and advanced engineering for the evolution of the standard



# ZigBee vs. Bluetooth

- ZigBee

- Smaller packets over large network
- Data rate 250 kbps @2.4 GHz
- Allows up to 254 nodes
- Simplified protocol stack
- Used in time critical applications (15msec wake up time)
- Mostly Static networks with many, infrequently used devices
- Home automation, toys, remote controls, etc.

- Bluetooth

- Larger packets over small network
- Data rate is 1Mbps @2.4 GHz
- Allows up to 8 nodes in piconet setup
- More complex protocol stack
- Not so time critical (3sec wake up time)
- Ad-hoc networks
- File transfer
- Screen graphics, pictures, hands-free audio, Mobile phones, headsets, PDAs, etc.



# Components of WPAN

- Full function device (**FFD**)
  - Any topology
  - PAN coordinator capable
  - Talks to any other device
  - Implements complete protocol set
- Reduced function device (**RFD**)
  - Limited to certain topologies
  - Cannot become a PAN coordinator
  - Talks only to a network coordinator
  - Very simple implementation
  - Reduced protocol set



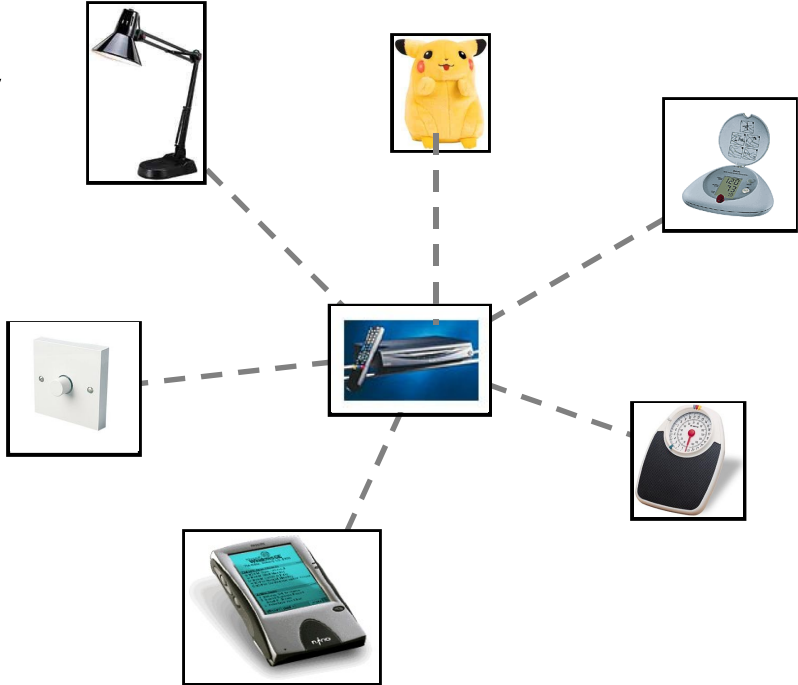
# IEEE 802.15.4 Definitions

- Network Device:
  - An RFD or FFD implementation containing an IEEE 802.15.4 medium access control and physical interface to the wireless medium.
- Coordinator:
  - An FFD with network device functionality that provides coordination and other services to the network.
- PAN Coordinator:
  - A coordinator that is the principal controller of the PAN. A network has exactly one PAN coordinator.



# Network Topologies

- ZigBee supports 3 types of network topologies
  - Star topology
  - Peer-to peer topology
  - Cluster tree topology

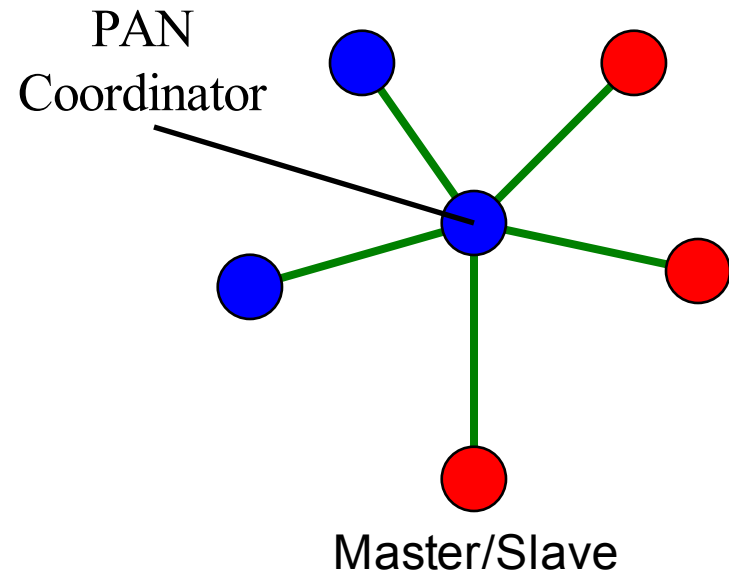






# Star Topology

- Communication is done through the PAN coordinator
- PAN usually mains powered
- Devices battery powered
- Applications include:
  - Home automation
  - PC peripherals



— Communications flow

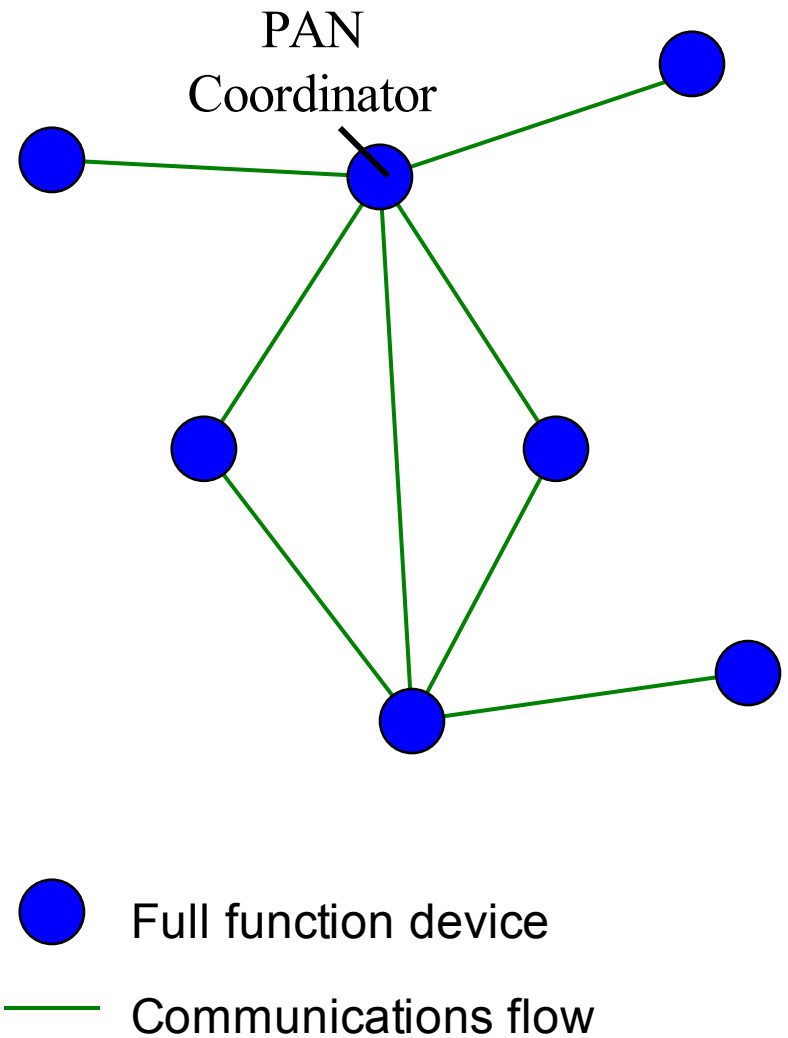
● Full function device

● Reduced function device



# Peer-to-peer Topology

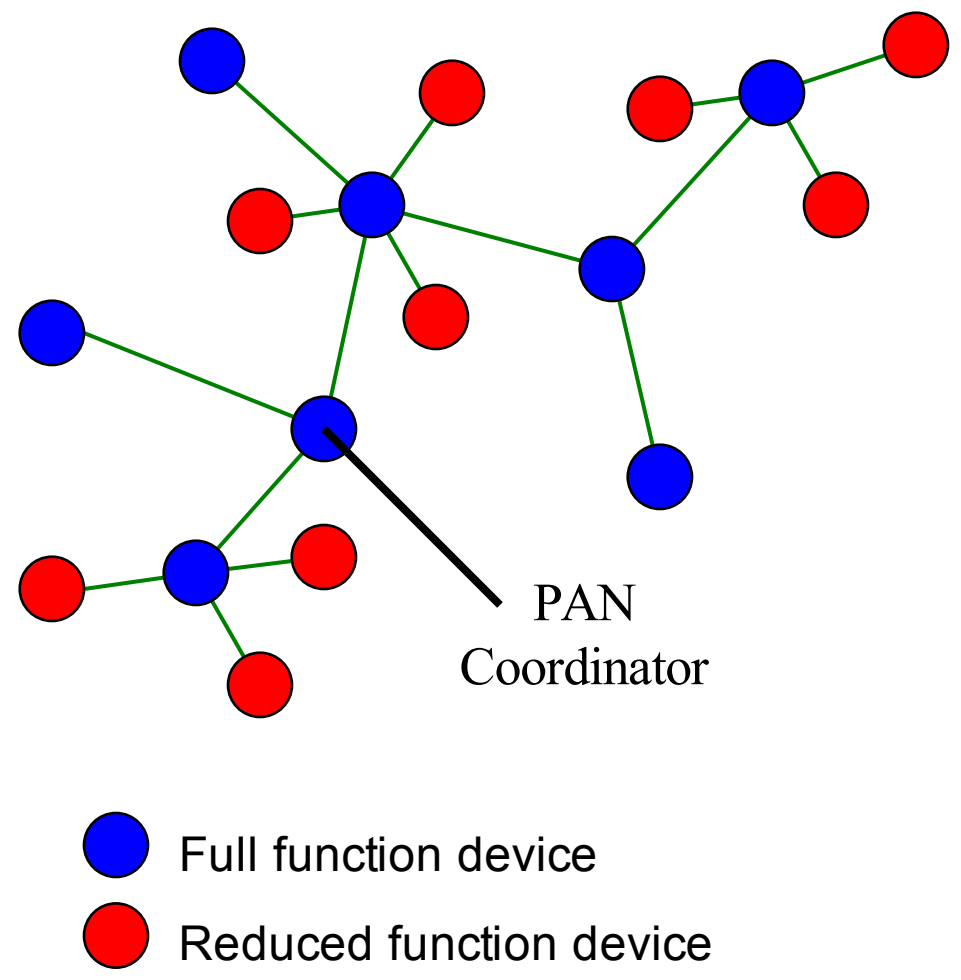
- Any device can communicate with any other device
  - Ad hoc
  - Self-organizing
- Allows for multiple hops to route messages
- Applications include:
  - Industrial control and monitoring
  - Wireless sensor networks
  - Inventory tracking





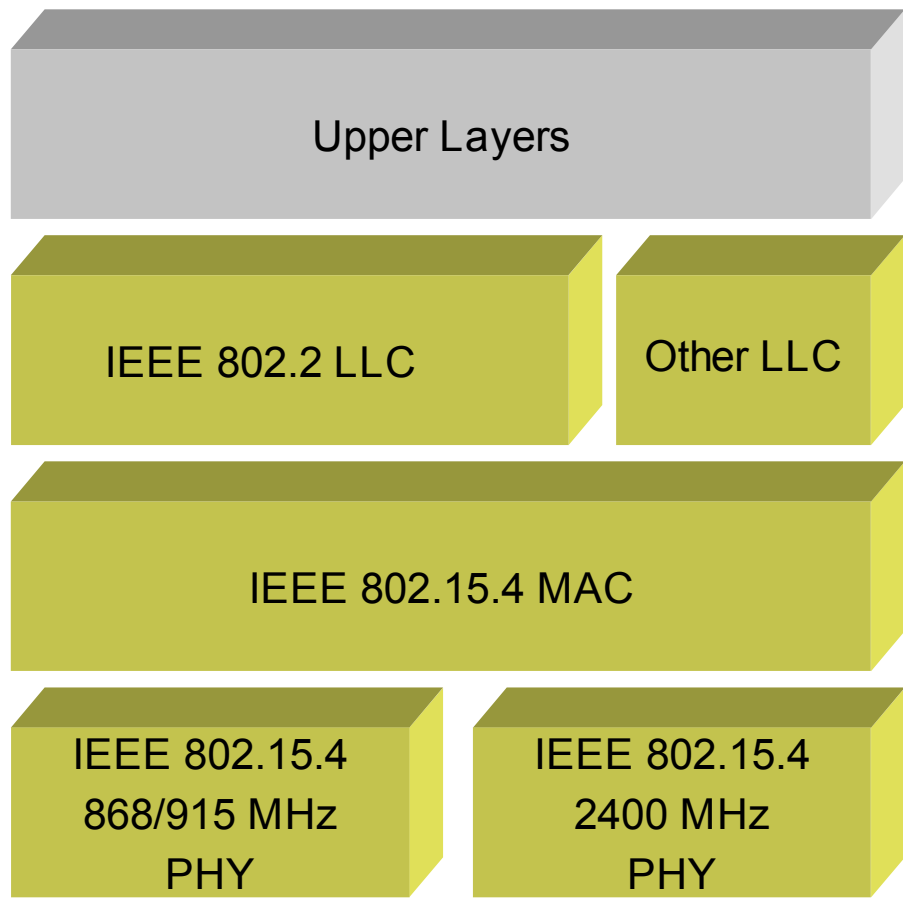
# Cluster tree Topology

- Special case of peer-to-peer
- PAN coordinator establishes itself as cluster head (CLH)
- Tree formed around PAN coordinator
- Advantage
  - Increased coverage area
- Disadvantage
  - Increased message latency





# 802.15.4 Architecture





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# 802.15.4 PHY LAYER





# 802.15.4 PHY Layer

- The standard offers two options based on the frequency band.
- Both based on direct sequence spread spectrum (DSSS).

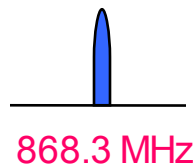
PHY (MHz)	Frequency band (MHz)	Spreading parameters		Data parameters		
		Chip rate (kchip/s)	Modulation	Bit rate (kb/s)	Symbol rate (ksymbol/s)	Symbols
868/915	868–868.6	300	BPSK	20	20	Binary
	902–928	600	BPSK	40	40	Binary
2450	2400–2483.5	2000	O-QPSK	250	62.5	16-ary Orthogonal



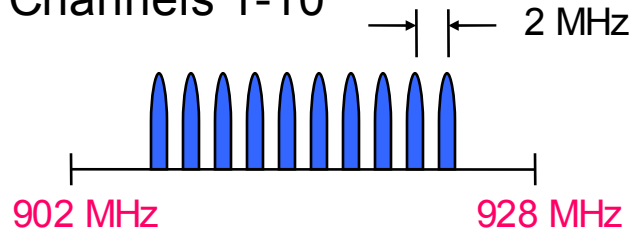
# Operating Frequency Bands

**868MHz / 915MHz  
PHY**

Channel 0

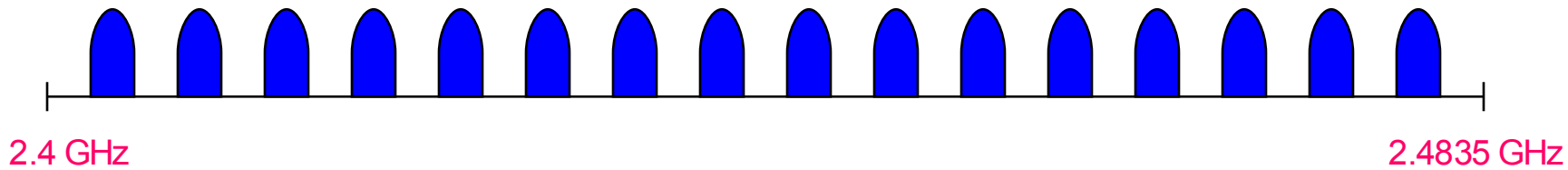


Channels 1-10



**2.4 GHz  
PHY**

Channels 11-26





# 802.15.4 PHY Layer

- Provides two services to physical layer management entity (PLME)
  - PHY data service
    - exchange data packets between MAC and PHY
  - PHY management service interface
    - Clear channel assessment (CCA)
      - 3 methods: Energy above threshold, Carrier sense only, or Carrier sense w/ energy above threshold
    - Energy detection (ED)
      - Used by network layer (channel selection)
    - Link Quality Indication (LQI)
      - Used by higher layers
      - Uses ED and/or SNR estimate



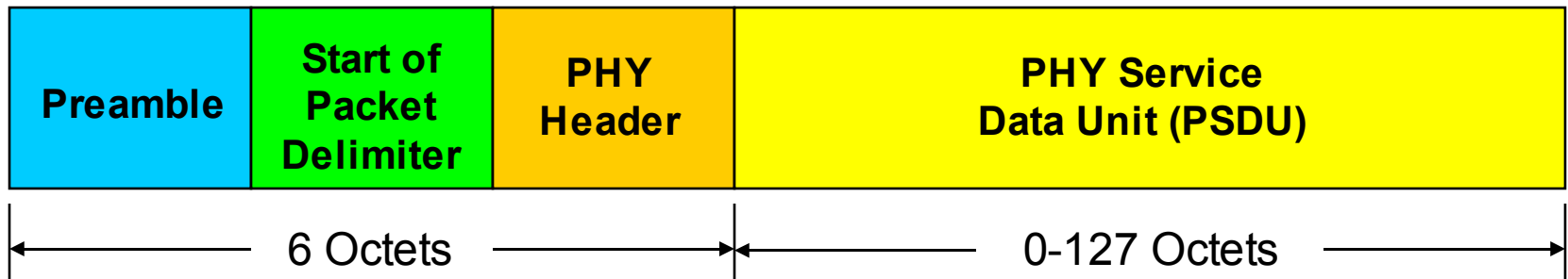


# 802.15.4 PHY Layer

## Packet Structure

### PHY Packet Fields

- Preamble (32 bits) – synchronization
- Start of Packet Delimiter (8 bits)
- PHY Header (8 bits) – PSDU length
- PSDU (0 to 1016 bits) – Data field





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# 802.15.4 MAC LAYER



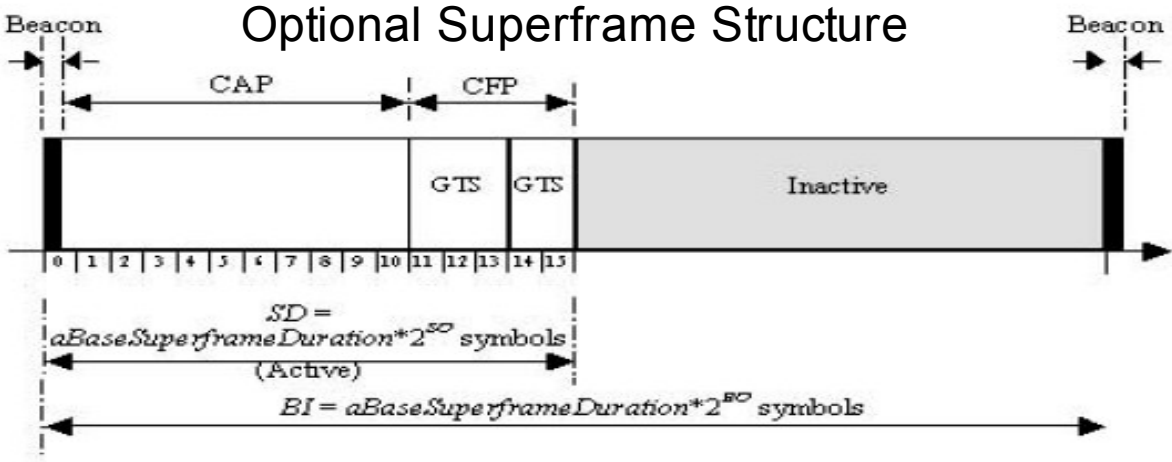


# 802.15.4 MAC Layer

- Provides two services to the MAC sublayer management entity (MLME)
  - MAC data service
    - Enables transmission and reception of MAC protocol data units (MPDU) across PHY data service
  - MAC management service
    - Beacon management
    - Channel access
    - GTS management
    - Frame validation
    - ACK frame delivery
    - Association and disassociation



# 802.15.4 MAC Layer



**Beacon** – sent by PAN coordinator in the first slot of the superframe

**Contention Access Period (CAP)**

- Communication using slotted CSMA-CA

**Contention Free Period (CFP)**

- Guaranteed time slots (GTS) given by coordinator (no CSMA)

**Beacon Order (BO)**

- Describes the interval at which the coordinator shall transmit its beacon frames
- if BO = 15, superframe is ignored

**Superframe Order (SO)**

- Describes the length of the active portion of the superframe
- if SO = 15, superframe should not remain active after the beacon



# CSMA-CA Algorithm

- Slotted CSMA-CA
  - Used in superframe structure
  - Backoff periods are aligned with superframe slot boundaries of PAN coordinator
  - Used in CAP, must locate boundary of the next backoff period to transmit data
- Un-slotted CSMA-CA
  - Non beacon enabled network
  - Backoff periods are not synchronized btw devices



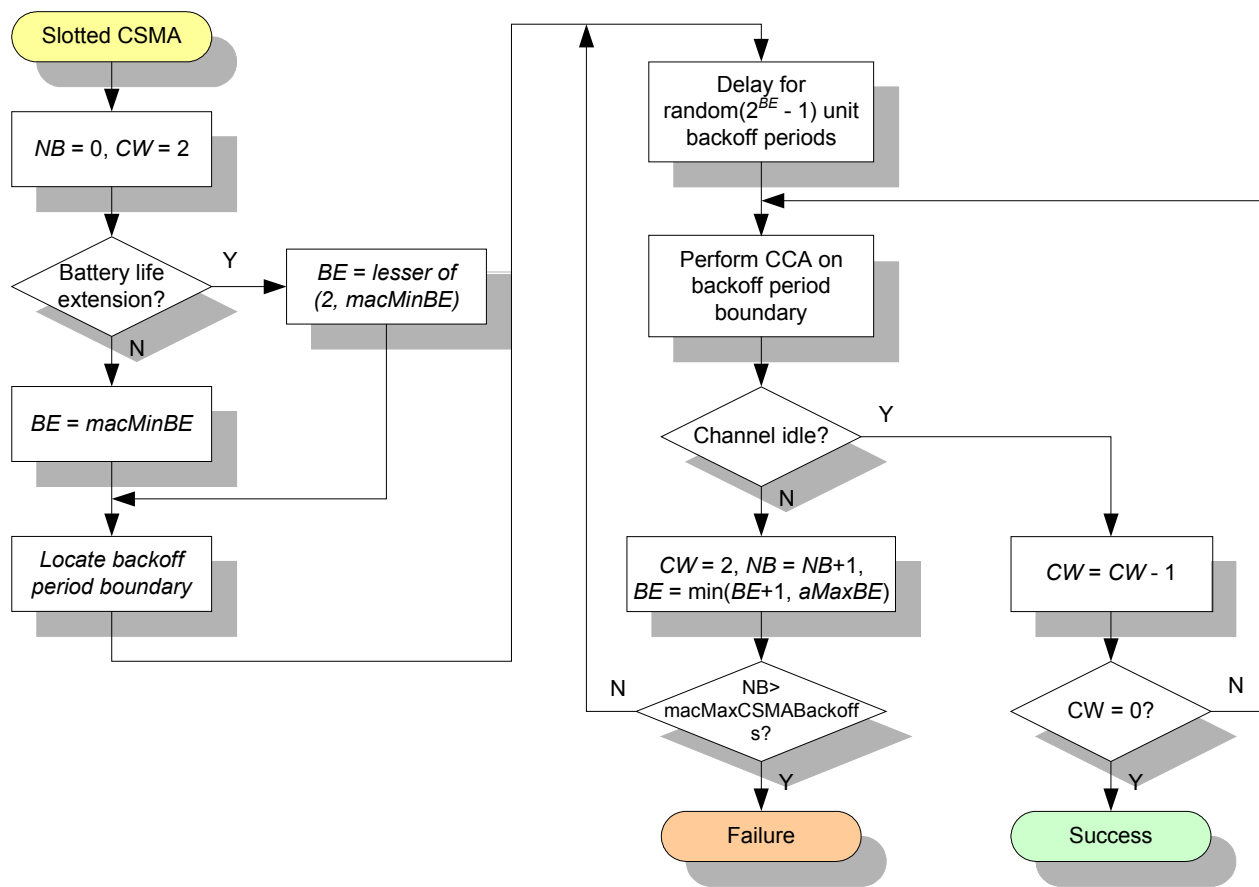
# CSMA-CA Algorithm

- Each device has three variables:
  - NB is the number of times the CSMA-CA was required to backoff while attempting a current transmission.
  - CW is the contention window length, which defines the number of backoff periods that needs to be clear of activity before a transmission can start.
  - BE is the backoff exponent, which is related to how many backoff periods a device shall wait before attempting to assess the channel.



# Slotted CSMA Procedure

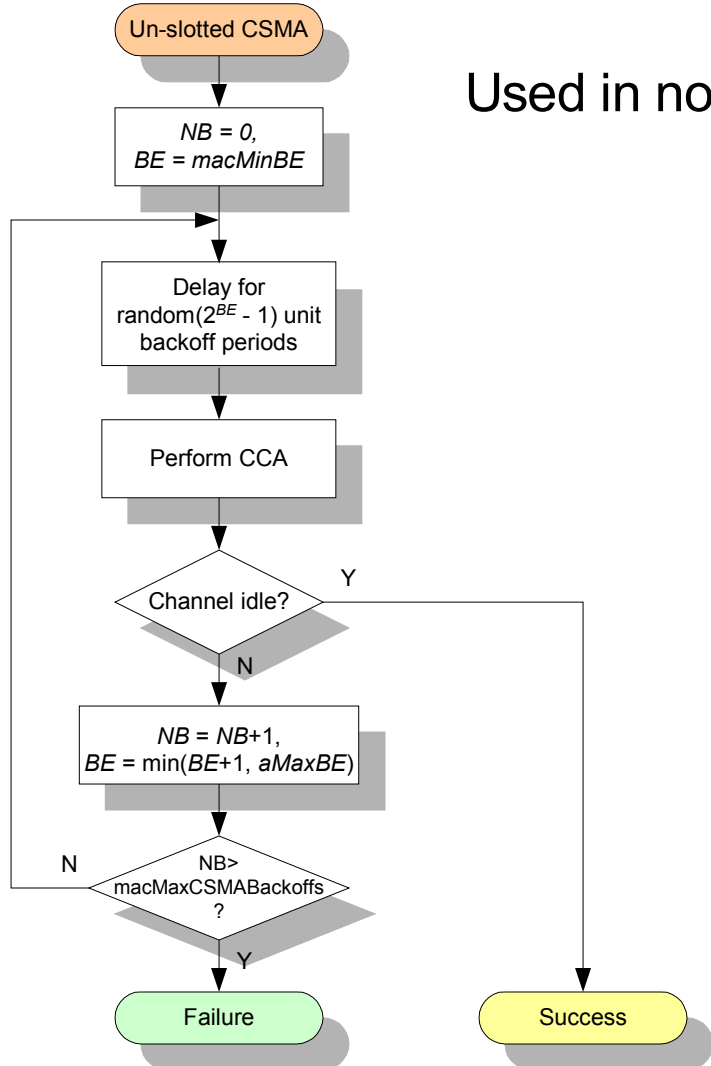
Used in beacon enabled networks.





# Unslotted CSMA Procedure

Used in non-beacon networks.

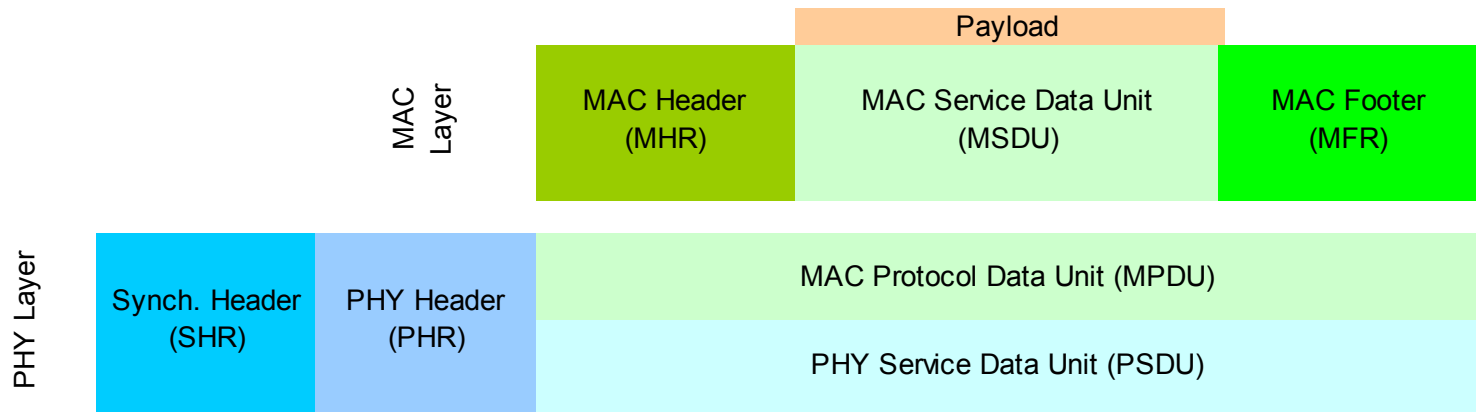






# 802.15.4 MAC Layer

## General Frame Structure



### 4 Types of MAC Frames:

- Data Frame
- Beacon Frame
- Acknowledgment Frame
- MAC Command Frame



# References

- IEEE 802.15.4-2003 standard.
- Tutorial .ppt “IEEE 802.15.4 Tutorial” by Jose Gutierrez, Eaton Corporation, Jan. 2003.
- Tutorial .ppt “IEEE 802.15.4 MAC Overview” by Marco Naeve, Eaton Corporation, May 2004.
- Tutorial .ppt “802.15.4 and ZigBee” by Kevin Klues, Washington University in St. Louis.



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# **Experimental Investigation of IEEE 802.15.4 Transmission Power Control and Interference Minimization**

Submitted to IEEE INFOCOM 2007

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# Research Motivation

- Communication interference can severely reduce the performance of wireless networks.
- Simple models such as circular communication and interference “range” model don’t work for every wireless node package.
- Sensor networks are becoming very popular with industry.
- Studying the interference characteristics of actual hardware nodes is a fundamental research problem.



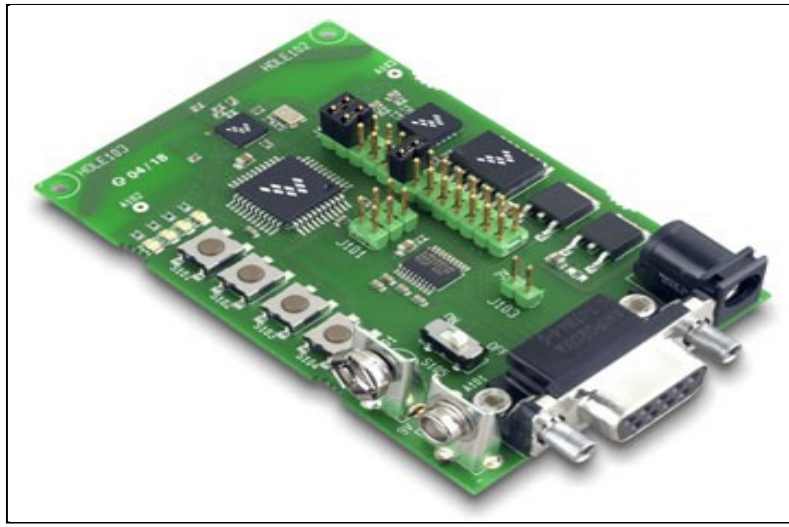
# Research Goals

- In depth experimental study of the interplay between interference and transmission power using 802.15.4 physical layer hardware.
- Investigate the impact between interference and the relative positions and orientations of the wireless nodes.
- Development of experimental models of interference, transmission power, and achievable reliable communication ranges.
- Using these models in higher level algorithms.



# Freescale Hardware Details

- Sensor Application Reference Design (SARD)
- MC13192 2.4 GHz RF transceiver
- MC9S08GT60 low-voltage, low-power 8-bit MCU
- Dipole antenna
- 3-axis accelerometers (-x,-y,-z)
- Interface RS-232 port



13192DSK board



# SARD 13192 Radio

- Runs complete 802.15.4 PHY layer
- Operates in 2.4 GHz band
- Has 16 selectable channels
- Power supply range of 2 – 3.4 Volts
- Transmit powers from –27dBm to 4 dBm
- Theoretical throughput of 250 kbps
- Receive sensitivity of <-92 dBm @ 1% PER.
- Supports 3 power saving modes.

PA Power Adjust Reg 12[7:0] (Hex)	Typical Differential Power at Output Con- tact (dBm)	Typical PA Current (mA)
00	-27.6	1.7
04	-20.6	2.5
08	-17.7	3.8
0C	-16.3	6
1C	-15.7	6.1
2C	-15.2	6.1
3C	-14.6	6.1
4C – PWR 4	-8.9	6.9
5C	-8.2	7
6C	-7.5	7.1
7C	-7.1	7.2
8C – PWR 8	-1.6	9.3
9C	-1.1	9.6
AC	-0.7	9.9
BC – PWR 11	-0.3	10.2
CC	1.3	12.2
DC	1.9	13.6
EC	2.5	16.3
FC	2.6	16.6
FD	3.2	16.8
FE	3.7	16.9
FF – PWR 15	4.1	17



# Freescal Development Flow

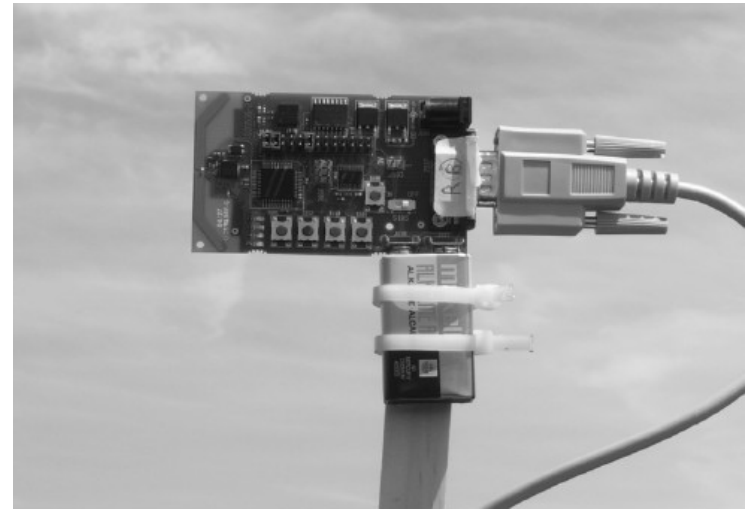
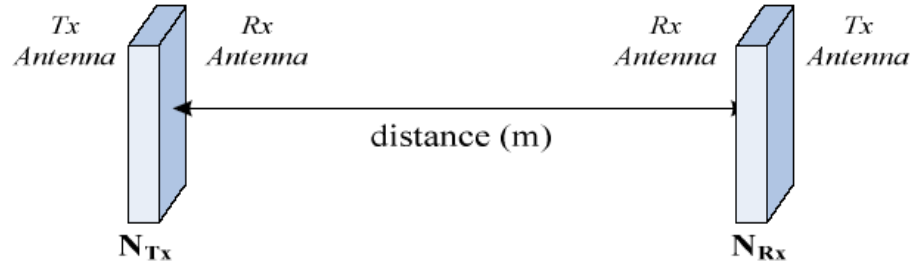
- Metrowerks Codewarrior 3.0 for HC08
  - Software debugger emulates CPU only
  - Supports on-chip debugging
- Programmed in C and assembly
  - Software floating point emulation available
  - Standard libraries supported
    - malloc, free, strlen, etc.
  - In line assembly used for “special” functionality
  - Interrupt driven coding style





# Range Experimental Setup

- Placed NRx in a fixed location connected to a PC through RS-232.
- NTx moved at different distances (LOS) from NRx.
- Varied transmit power at NTx as well as packet size.
- Sent 256 packets at each power level tested.
- Experiments were done both indoor and outdoor.
- Varied heights and orientations of the board.
- Measured packet loss at NRx.





# Range Results

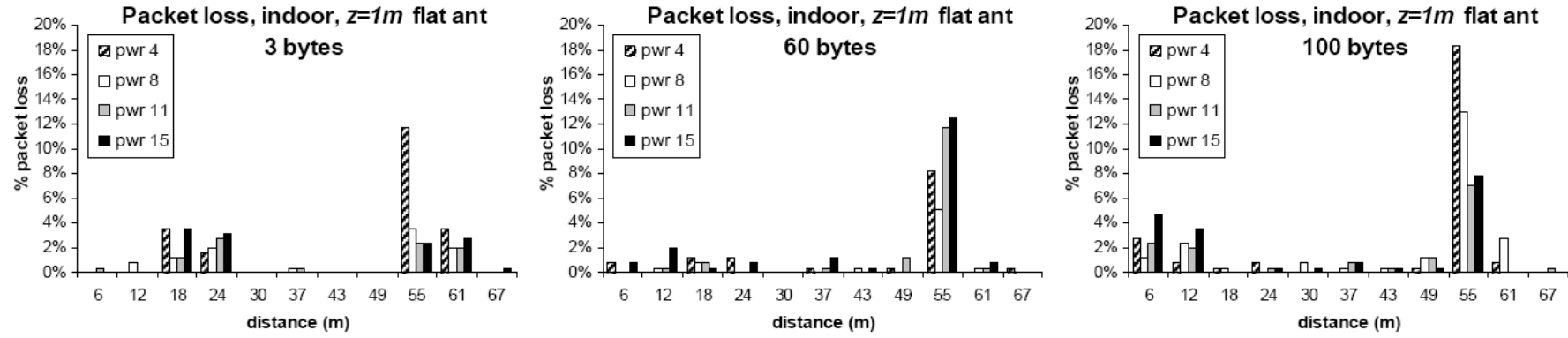


Figure 5. Indoor range test, 1m node height, flat antenna orientation, three packet sizes.

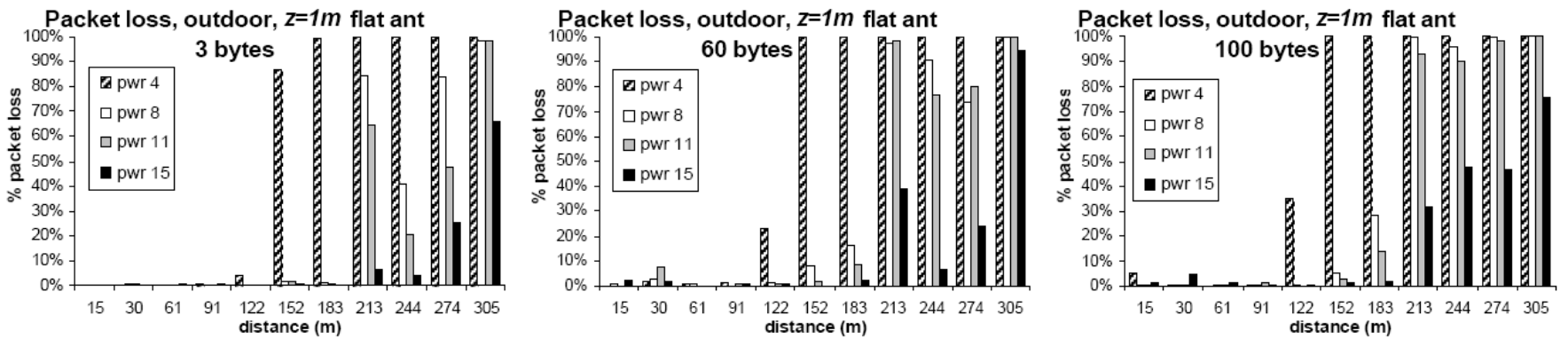


Figure 6. Outdoor range test, 1m node height, flat antenna orientation, three packet sizes.



# Range Results

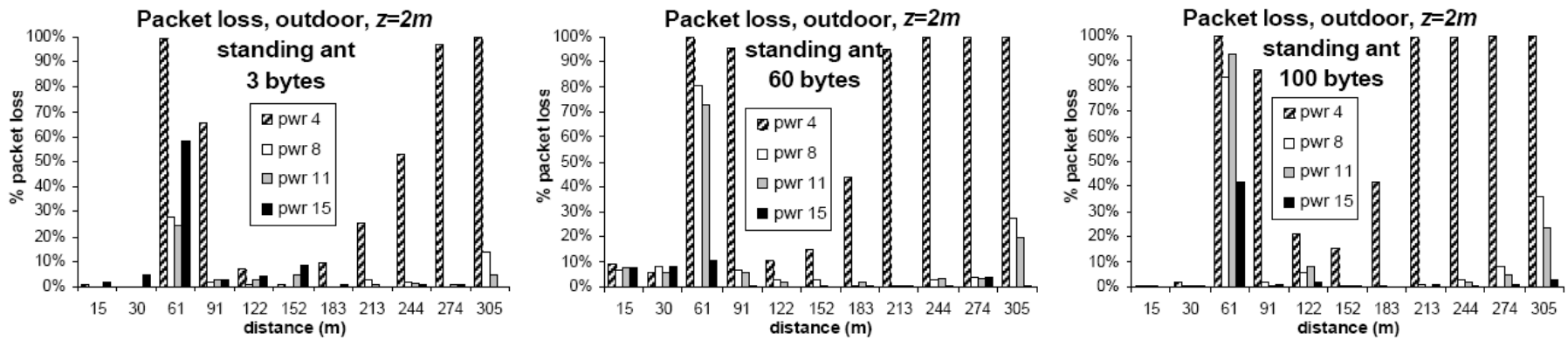


Figure 7. Outdoor range test, 2m node height, standing antenna orientation, three packet sizes.

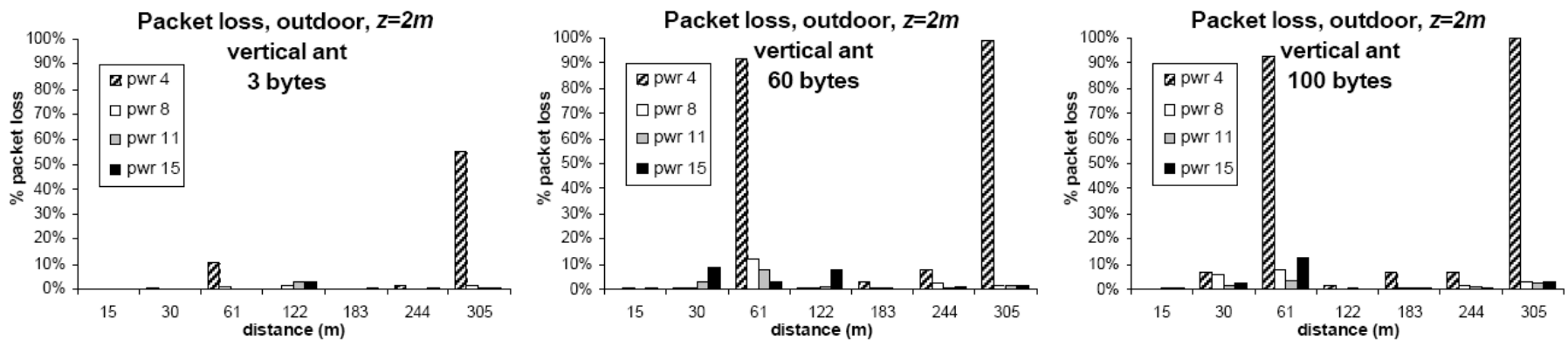


Figure 8. Outdoor range test, 2m node height, vertical antenna orientation, three packet sizes.



# Interference Experimental Setup

- NRx and NTx fixed at 6m in LOS.
- Nint placed at different locations based on the Rx/Tx link. (LOS of NRx)
- All nodes place only 15 cm from the ground.
- NTx sent 1024 packets at various packet sizes with fixed transmit power.
- Nint send 100 byte continuous packets with fixed transmit power.
- Varied orientation of interferer.
- Measured packet loss at NRx.

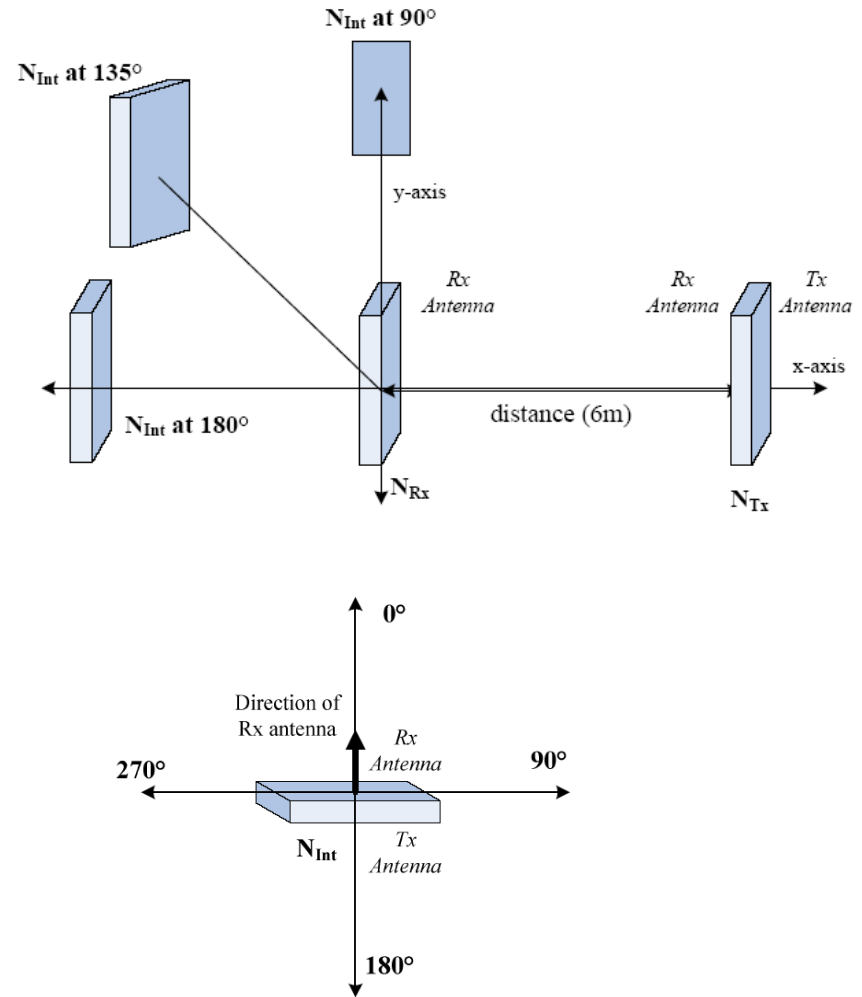


Figure 16. Orientations of the interferer  $N_{int}$ .



# Interference Results

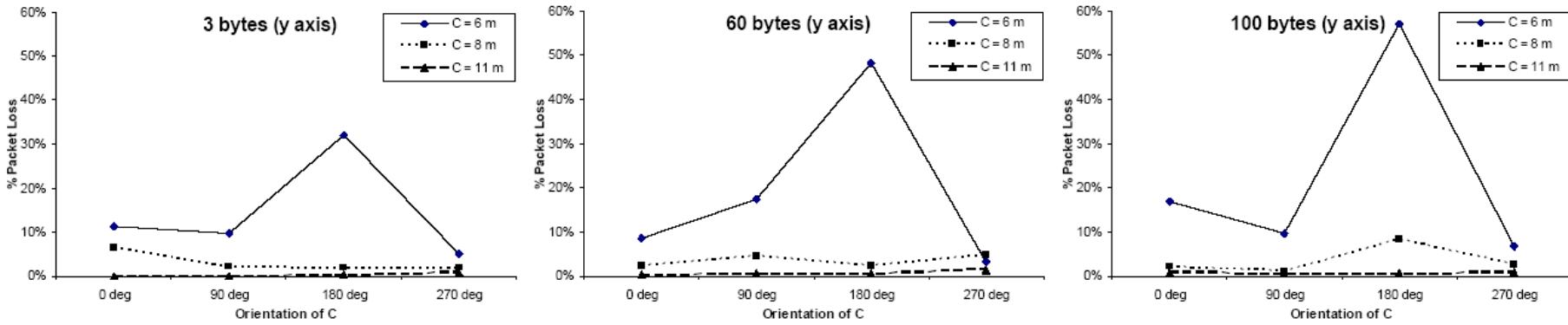


Figure 14. Effects of the positions and orientation of the interfering node on throughput at positions along the v axis.

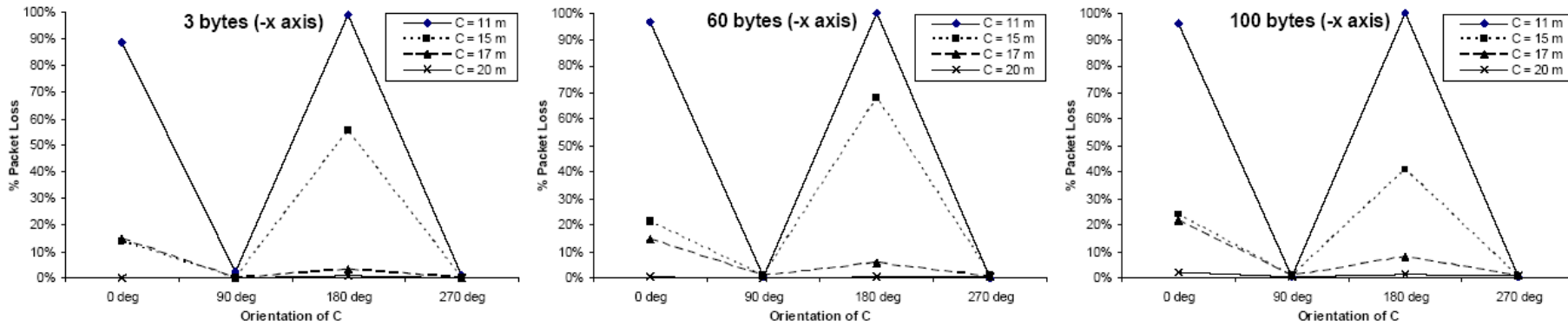


Figure 15. Effects of the orientation of the interfering node on throughput at positions along the -x axis.



# Future Work

- Now that we have range and interference models we need to find a way to use them.
  - Come up with scheduling algorithms to effectively schedule transmissions based on this link to node interference model
- Per packet channel switching to reduce interference.
- Also working on power minimization optimizations within different states of the radio and MCU. (ECE 751)



# Video Surveillance demo

- Funded by the Defense Advanced Research Projects Agency (DARPA)
  - **ELASTIC project:** Expendable Local Area Sensors in a Tactically Interconnected Cluster
    - Cheap ad hoc sensors to be deployed rapidly
      - Ballistic deployment
      - Disaster areas
      - Military surveillance
    - Images and video desired
    - Other sensors
    - Location awareness and target tracking
    - A number of challenging research issues



# Video Surveillance

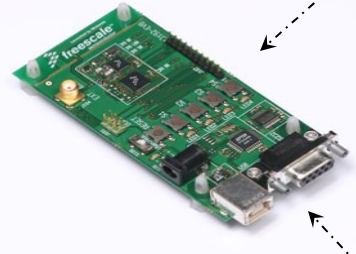
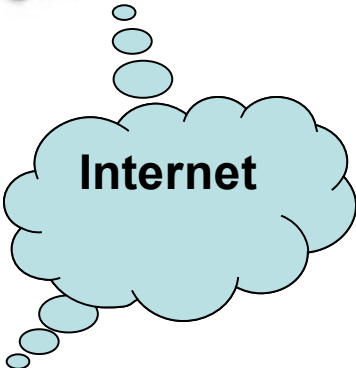
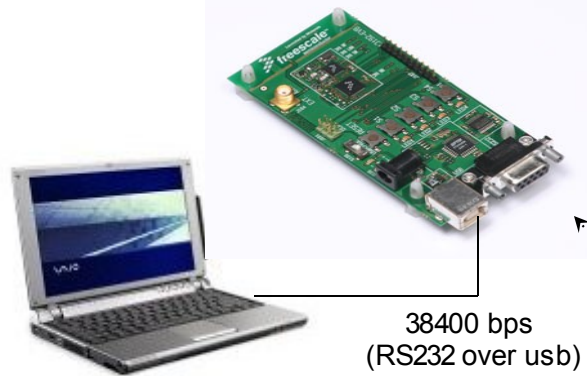
- CMUCam2+
  - Commercially available (~\$169)
  - SX52 microcontroller
  - OV6620 Omnivision CMOS imager
  - Track user-defined colors at up to 50 FPS
  - Track motion using frame differencing at 26 FPS
  - Find the centroid of any tracked data
  - Gather mean color and variance information
  - Gather a 28 bin histogram of each color channel
  - Arbitrary image windowing
  - Dump a raw image (single or multiple channels)
  - Up to 160 X 255 resolution
  - Supports multiple baudrates (RS232 interface)
  - Control 5 servo outputs
  - 6-12V at ~200mA current requirement
    - Consumes a lot of power if not power managed.







# Prototype Demo



250 kbps\*  
(ZigBee)

