

CS 537 Lecture 11 Memory

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Memory Management Topics

- Goals of memory management
 - convenient abstraction for programming
 - isolation between processes
 - allocate scarce memory resources between competing processes, maximize performance (minimize overhead)
- Mechanisms
 - physical vs. virtual address spaces
 - page table management, segmentation policies
 - page replacement policies

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Virtual Memory from 10,000 feet

- The basic abstraction that the OS provides for memory management is **virtual memory** (VM)
 - VM enables programs to execute without requiring their entire address space to be resident in physical memory
 - program can also execute on machines with less RAM than it “needs”
 - many programs don’t need all of their code or data at once (or ever)
 - e.g., branches they never take, or data they never read/write
 - no need to allocate memory for it, OS should adjust amount allocated based on its **run-time** behavior
 - virtual memory **isolates** processes from each other
 - one process cannot name addresses visible to others; each process has its own isolated address space
- VM requires hardware and OS support
 - MMU’s, TLB’s, page tables, ...

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Virtualizing Resources

- Physical Reality:
Different Processes/Threads share the same hardware
 - Need to multiplex CPU (finished earlier: scheduling)
 - Need to multiplex use of Memory (Today)
 - Need to multiplex disk and devices (later in term)
- Why worry about memory sharing?
 - The complete working state of a process and/or kernel is defined by its data in memory (and registers)
 - Consequently, cannot just let different threads of control use the same memory
 - Physics: two different pieces of data cannot occupy the same locations in memory
 - Probably don’t want different threads to even have access to each other’s memory (protection)

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In the beginning...

- First, there was batch programming
 - programs used physical addresses directly
 - OS loads job, runs it, unloads it
- Then came multiprogramming
 - need multiple processes in memory at once
 - to overlap I/O and computation
 - memory requirements:
 - protection: restrict which addresses processes can use, so they can't stomp on each other
 - fast translation: memory lookups must be fast, in spite of protection scheme
 - fast context switching: when swap between jobs, updating memory hardware (protection and translation) must be quick

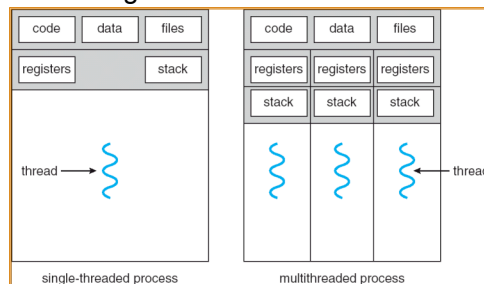
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Virtual Addresses

- To make it easier to manage memory of multiple processes, make processes use **virtual addresses**
 - virtual addresses are independent of location in physical memory (RAM) that referenced data lives
 - OS determines location in physical memory
 - instructions issued by CPU reference virtual addresses
 - e.g., pointers, arguments to load/store instruction, PC, ...
 - virtual addresses are translated by hardware into physical addresses (with some help from OS)
- The set of virtual addresses a process can reference is its **address space**
 - many different possible mechanisms for translating virtual addresses to physical addresses
 - we'll take a historical walk through them, ending up with our current techniques
- In reality, an address space is a **data structure** in the kernel

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Recall: Single and Multithreaded Processes



- Threads encapsulate concurrency
 - “Active” component of a process
- Address spaces encapsulate protection
 - Keeps buggy program from trashing the system
 - “Passive” component of a process

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Important Aspects of Memory Multiplexing

- Translation:
 - Ability to translate accesses from one address space (virtual) to a different one (physical)
 - When translation exists, processor uses virtual addresses, physical memory uses physical addresses
 - Side effects:
 - Can be used to avoid overlap
 - Can be used to give uniform view of memory to programs
- Protection:
 - Prevent access to private memory of other processes
 - Different pages of memory can be given special behavior (Read Only, Invisible to user programs, etc).
 - Kernel data protected from User programs
 - Programs protected from themselves

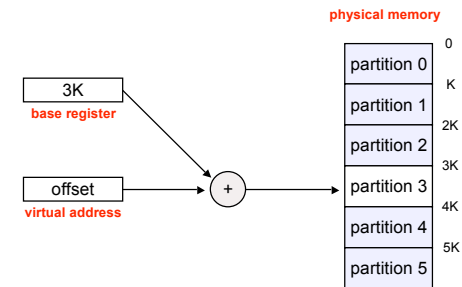
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Old technique #1: Fixed Partitions

- Physical memory is broken up into fixed partitions
 - all partitions are equally sized, partitioning never changes
 - hardware requirement: **base register**
 - physical address = virtual address + base register
 - base register loaded by OS when it switches to a process
 - how can we ensure protection?
- Advantages
 - simple, ultra-fast context switch
- Problems
 - internal fragmentation**: memory in a partition not used by its owning process isn't available to other processes
 - partition size** problem: no one size is appropriate for all processes
 - fragmentation vs. fitting large programs in partition

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Fixed Partitions (K bytes)



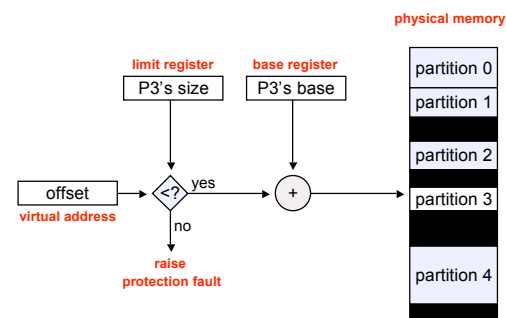
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Old technique #2: Variable Partitions

- Obvious next step: physical memory is broken up into variable-sized partitions
 - hardware requirements: **base register**, **limit register**
 - physical address = virtual address + base register
 - how do we provide protection?
 - if (physical address > base + limit) then... ?
- Advantages
 - no internal fragmentation
 - simply allocate partition size to be just big enough for process
 - (assuming we know what that is!)
- Problems
 - external fragmentation**
 - as we load and unload jobs, holes are left scattered throughout physical memory

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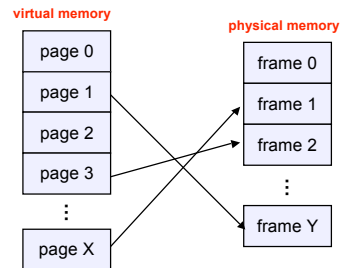
Variable Partitions



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Modern technique: Paging

- Solve the external fragmentation problem by using fixed sized units in both physical and virtual memory



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User's Perspective

- Processes view memory as a contiguous address space from bytes 0 through N
 - virtual address space (VAS)
- In reality, virtual pages are scattered across physical memory frames
 - virtual-to-physical mapping
 - this mapping is *invisible* to the program
- Protection is provided because a program cannot reference memory outside of its VAS
 - the virtual address 0xDEADBEEF maps to different physical addresses for different processes

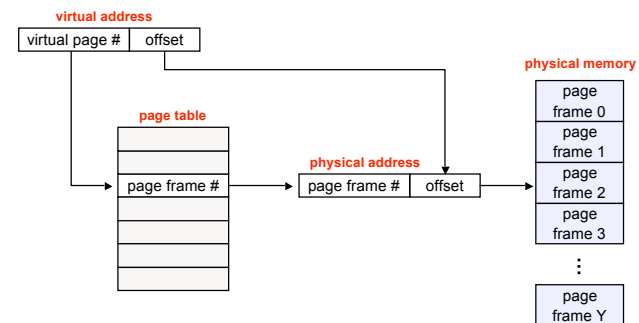
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Paging

- Translating virtual addresses
 - a virtual address has two parts: *virtual page number* & *offset*
 - virtual page number (VPN) is index into a *page table*
 - page table entry contains *page frame number* (PFN)
 - physical address is PFN::offset
- Page tables
 - managed by the OS
 - map virtual page number (VPN) to page frame number (PFN)
 - VPN is simply an index into the page table
 - one *page table entry* (PTE) per page in virtual address space
 - i.e., one PTE per VPN

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Paging



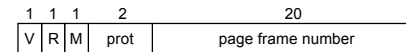
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Paging example

- assume 32 bit addresses
 - assume page size is 4KB (4096 bytes, or 2^{12} bytes)
 - VPN is 20 bits long (2^{20} VPNs), offset is 12 bits long
- let's translate virtual address $0x13325328$
 - VPN is $0x13325$, and offset is $0x328$
 - assume page table entry $0x13325$ contains value $0x03004$
 - page frame number is $0x03004$
 - VPN $0x13325$ maps to PFN $0x03004$
 - physical address = PFN::offset = $0x03004328$

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Page Table Entries (PTEs)



- PTE's control mapping
 - the **valid bit** says whether or not the PTE can be used
 - says whether or not a virtual address is valid
 - it is checked each time a virtual address is used
 - the **reference bit** says whether the page has been accessed
 - it is set when a page has been read or written to
 - the **modify bit** says whether or not the page is dirty
 - it is set when a write to the page has occurred
 - the **protection bits** control which operations are allowed
 - read, write, execute
 - the **page frame number** determines the physical page
 - physical page start address = PFN << (#bits/page)

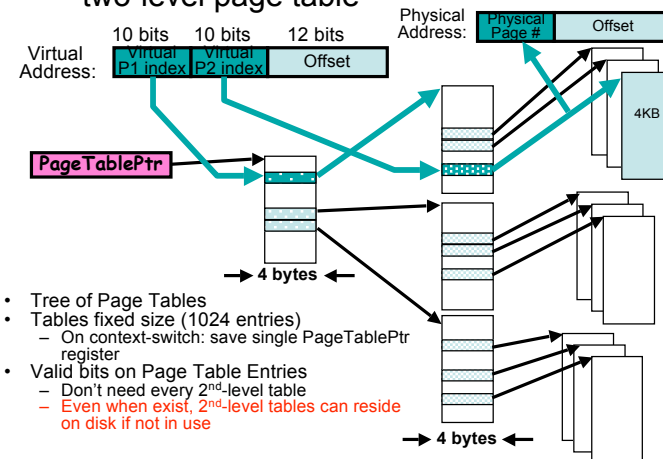
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Multi-level Translation

- What about a tree of tables?
 - Lowest level page table \Rightarrow memory still allocated with bitmap
- Could have any number of levels
 - x86 has 2
 - x64 has 4

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Another common example: two-level page table



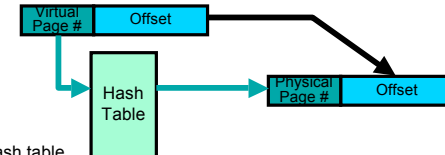
Multi-level Translation Analysis

- Pros:
 - Only need to allocate as many page table entries as we need for application
 - In other words, sparse address spaces are easy
 - Easy memory allocation
 - Easy Sharing
 - Share at segment or page level (need additional reference counting)
- Cons:
 - One pointer per page (typically 4K – 16K pages today)
 - Two (or more, if >2 levels) lookups per reference
 - Seems very expensive!

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Inverted Page Table

- With all previous examples ("Forward Page Tables")
 - Size of page table is at least as large as amount of virtual memory allocated to processes
 - Physical memory may be much less
 - Much of process space may be out on disk or not in use



- Answer: use a hash table
 - Called an "Inverted Page Table"
 - Size is independent of virtual address space
 - Directly related to amount of physical memory
 - Very attractive option for 64-bit address spaces
- Cons: Complexity of managing hash changes
 - Often in hardware!

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Paging Advantages

- Easy to allocate physical memory
 - physical memory is allocated from free list of frames
 - to allocate a frame, just remove it from its free list
 - external fragmentation is not a problem!
 - complication for kernel contiguous physical memory allocation
 - many lists, each keeps track of free regions of particular size
 - regions' sizes are multiples of page sizes
 - "buddy algorithm"
- Easy to "page out" chunks of programs
 - all chunks are the same size (page size)
 - use valid bit to detect references to "paged-out" pages
 - also, page sizes are usually chosen to be convenient multiples of disk block sizes

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Paging Disadvantages

- Can still have internal fragmentation
 - process may not use memory in exact multiples of pages
- Memory reference overhead
 - 2 references per address lookup (page table, then memory)
 - solution: use a hardware cache to absorb page table lookups
 - translation lookaside buffer (TLB) – next class
- Memory required to hold page tables can be large
 - need one PTE per page in virtual address space
 - 32 bit AS with 4KB pages = 2^{20} PTEs = 1,048,576 PTEs
 - 4 bytes/PTE = **4MB per page table**
 - OS's typically have separate page tables per process
 - 25 processes = 100MB of page tables
 - solution: page the page tables (!!!)
 - (ow, my brain hurts...more later)

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