CS 537 Lecture 19 Threads and Cooperation

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What's in a process?

- · A process consists of (at least):
 - User ID
 - state flags
 - an address space
 - the code for the running program
 - the data for the running program
 - an execution stack and stack pointer (SP)
 - · traces state of procedure calls made
 - the program counter (PC), indicating the next instruction
 - a set of general-purpose processor registers and their values
 - a set of OS resources
 - open files, network connections, sound channels, \dots
- · That's a lot of concepts bundled together!

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Questions answered in this lecture:

- · Why are threads useful?
- · How does one use POSIX pthreads?

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Organizing a Process

- · Scheduling / execution
 - state flags
 - an execution stack and stack pointer (SP)
 - the program counter (PC), indicating the next instruction
 - a set of general-purpose processor registers and their values
- · Resource ownership / naming
 - user ID
 - an address space
 - the code for the running program
 - the data for the running program
 - a set of OS resources
 - open files, network connections, sound channels, \dots

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Concurrency

- Imagine a web server, which might like to handle multiple requests concurrently
 - While waiting for the credit card server to approve a purchase for one client, it could be retrieving the data requested by another client from disk, and assembling the response for a third client from cached information
- Imagine a web client (browser), which might like to initiate multiple requests concurrently
 - The CS home page has 66 "src= ..." html commands, each of which is going to involve a lot of sitting around! Wouldn't it be nice to be able to launch these requests concurrently?
- Imagine a parallel program running on a multiprocessor, which might like to concurrently employ multiple processors
 - For example, multiplying a large matrix split the output matrix into k regions and compute the entries in each region concurrently using k processors

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 Image a program with two independent tasks: saving (or printing) data and editing text

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Common Programming Models

- Multi-threaded programs tend to be structured in one of three common models:
 - Manager/worker
 Single manager handles input and assigns work to the worker threads
 - Producer/consumer
 Multiple producer threads create data (or work) that is handled by one of the multiple consumer threads
 - Pipeline
 Task is divided into series of subtasks, each of which is handled in series by a different thread

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Why support Threads?

- Divide large task across several cooperative threads
- Multi-threaded task has many performance benefits
 - Adapt to slow devices
 One thread waits for device while other threads computes
 - Defer work
 One thread performs non-critical work in the background, when idle
 - Parallelism
 Each thread runs simultaneously on a multiprocessor
 - Modularity
 Independent tasks can be untangled

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What's needed?

- In each of these examples of concurrency (web server, web client, parallel program):
 - Everybody wants to run the same code
 - Everybody wants to access the same data
 - Everybody has the same privileges
 - Everybody uses the same resources (open files, network connections, etc.)
- But you'd like to have multiple hardware execution states:
 - an execution stack and stack pointer (SP)
 - · traces state of procedure calls made
 - the program counter (PC), indicating the next instruction
 - a set of general-purpose processor registers and their values

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How could we achieve this?

- · Given the process abstraction as we know it:
 - fork several processes
 - $\,-\,$ cause each to map to the same address space to share data
 - see the shmget () system call for one way to do this (kind of)
- This is like making a pig fly it's really inefficient
 - space: PCB, page tables, etc.
 - time: creating OS structures, fork and copy addr space, etc.
- Some equally bad alternatives for some of the cases:
 - Entirely separate web servers
 - Asynchronous programming in the web client (browser)

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Threads and processes

- Most modern OS's (Mach, Chorus, Windows XP, modern Unix (not Linux)) therefore support two entities:
 - the process, which defines the address space and general process attributes (such as open files, etc.)
 - the thread, which defines a sequential execution stream within a process
- · A thread is bound to a single process
 - processes, however, can have multiple threads executing within them
 - sharing data between threads is cheap: all see same address space
- · Threads become the unit of scheduling
 - processes are just containers in which threads execute

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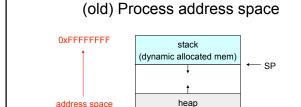
Can we do better?

- · Key idea:
 - separate the concept of a process (address space, etc.)
 - from that of a minimal "thread of control" (execution state: PC, etc.)
- This execution state is usually called a thread, or sometimes, a lightweight process

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0x00000000

(data segment)

code
(text segment)

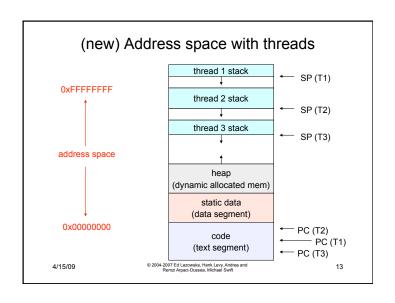
← PC

(dynamic allocated mem)

static data

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Process/thread separation

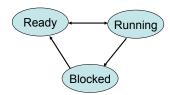
- · Concurrency (multithreading) is useful for:
 - handling concurrent events (e.g., web servers and clients)
 - building parallel programs (e.g., matrix multiply, ray tracing)
 - improving program structure (the Java argument)
- · Multithreading is useful even on a uniprocessor
 - even though only one thread can run at a time
- Supporting multithreading that is, separating the concept of a process (address space, files, etc.) from that of a minimal thread of control (execution state), is a big win
 - creating concurrency does not require creating new processes
 - "faster better cheaper"

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Thread states

· Threads have states like processes



· Example: a web server

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"Where do threads come from, Mommy?"

- Natural answer: the kernel is responsible for creating/ managing threads
 - for example, the kernel call to create a new thread would
 - · allocate an execution stack within the process address space
 - · create and initialize a Thread Control Block
 - stack pointer, program counter, register values
 - stick it on the ready queue
 - we call these kernel threads

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Kernel threads

- · OS now manages threads and processes
 - all thread operations are implemented in the kernel
 - OS schedules all of the threads in a system
 - if one thread in a process blocks (e.g., on I/O), the OS knows about it, and can run other threads from that process
 - possible to overlap I/O and computation inside a process
- · Kernel threads are cheaper than processes
 - less state to allocate and initialize
- But, they're still pretty expensive for fine-grained use (e.g., orders of magnitude more expensive than a procedure call)
 - thread operations are all system calls
 - · context switch
 - · argument checks
 - must maintain kernel state for each thread

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Performance example

- On a 3GHz Pentium running Linux 2.6.9:
 - Processes
 - fork/exit/waitpid: $120 \mu s$
 - Kernel threads
 - clone/waitpid: 13 μS

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Thread context switch

- Like process context switch
 - trap to kernel
 - save context of currently running thread
 - · push machine state onto thread stack
 - restore context of the next thread
 - · pop machine state from next thread's stack
 - return as the new thread
 - · execution resumes at PC of next thread
- What's not done:
 - change address space

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Thread interface

- · This is taken from the POSIX pthreads API:
 - t = pthread_create(attributes, start_procedure)
 - · creates a new thread of control
 - new thread begins executing at start_procedure
 - pthread_cond_wait(condition_variable)
 - the calling thread blocks, sometimes called thread block()
 - pthread signal(condition variable)
 - starts the thread waiting on the condition variable
 - pthread_exit()
 - terminates the calling thread
 - pthread wait(t)
 - · waits for the named thread to terminate

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How to keep a thread from hogging the CPU?

- Strategy 1: force everyone to cooperate
 - a thread willingly gives up the CPU by calling yield()
 - yield() calls into the scheduler, which context switches to another ready thread
 - what happens if a thread never calls yield()?
- Strategy 2: use preemption
 - scheduler requests that a timer interrupt be delivered by the OS periodically
 - usually delivered as a UNIX signal (man signal)
 - signals are just like software interrupts, but delivered to user-level by the OS instead of delivered to OS by hardware
 - at each timer interrupt, scheduler gains control and context switches as appropriate

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Multithreading Issues

- Semantics of fork() and exec() system calls
- · Thread cancellation
 - Asynchronous vs. Deferred Cancellation
- Signal handling
 - Which thread to deliver it to?
- Thread pools
 - Creating new threads, unlimited number of threads
- Thread specific data
- · Scheduler activations
 - Maintaining the correct number of scheduler threads

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Summary

- You really want multiple threads per address space
- Kernel threads are much more efficient than processes, but they're still not cheap
 - all operations require a kernel call and parameter verification
- User-level threads are:
 - fast as blazes
 - great for common-case operations
 - · creation, synchronization, destruction
 - can suffer in uncommon cases due to kernel obliviousness
 - I/O
 - · preemption of a lock-holder
- · Scheduler activations are the answer
 - pretty subtle though

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