

Neural Networks

Part 2

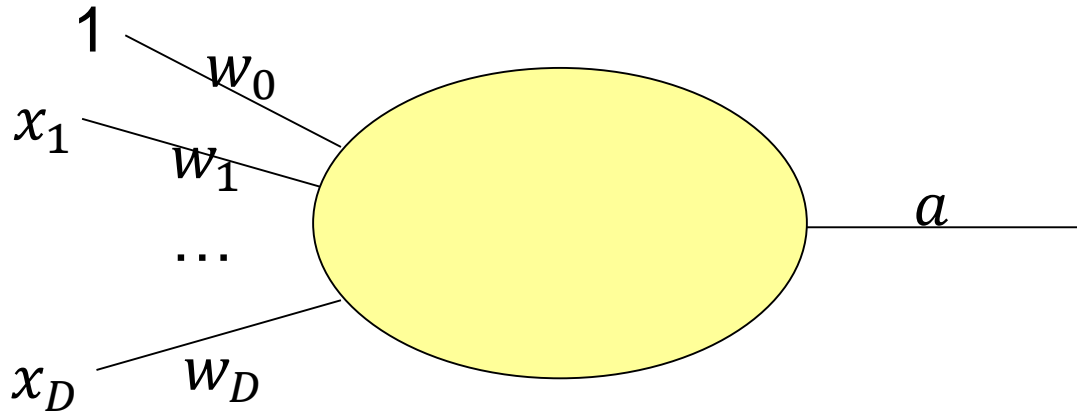
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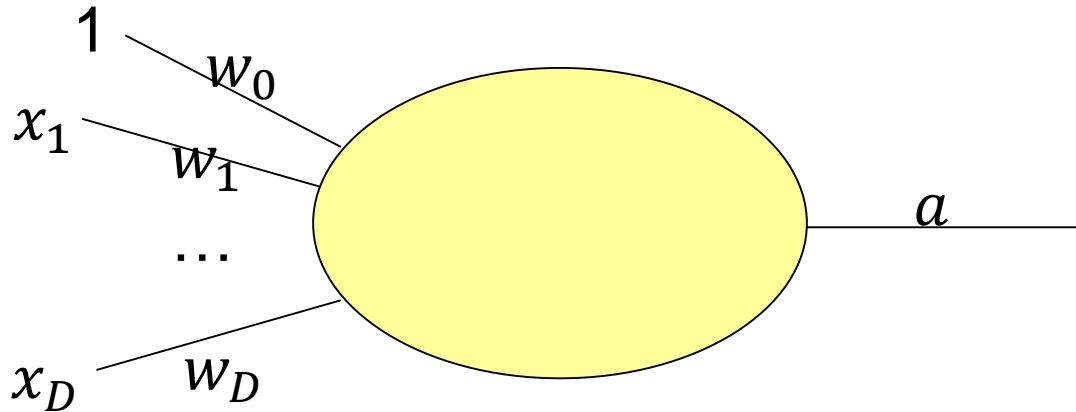
Limited power of one single neuron

- Perceptron: $a = g(\sum_d w_d x_d)$
- Activation function g : linear, step, sigmoid

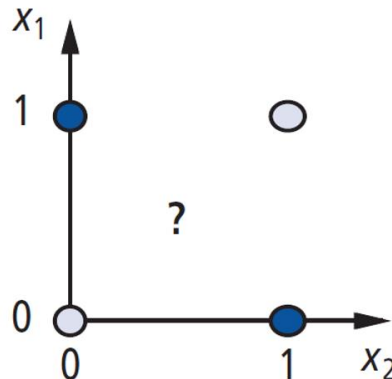


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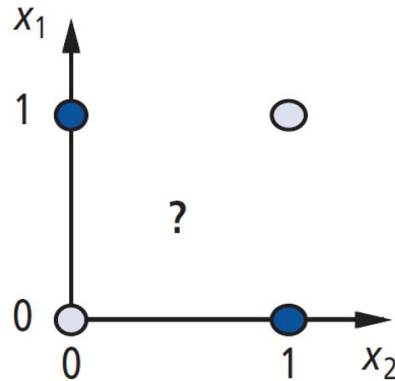


- Decision boundary **linear** even for nonlinear g
- **XOR** problem



Limited power of one single neuron

- XOR problem

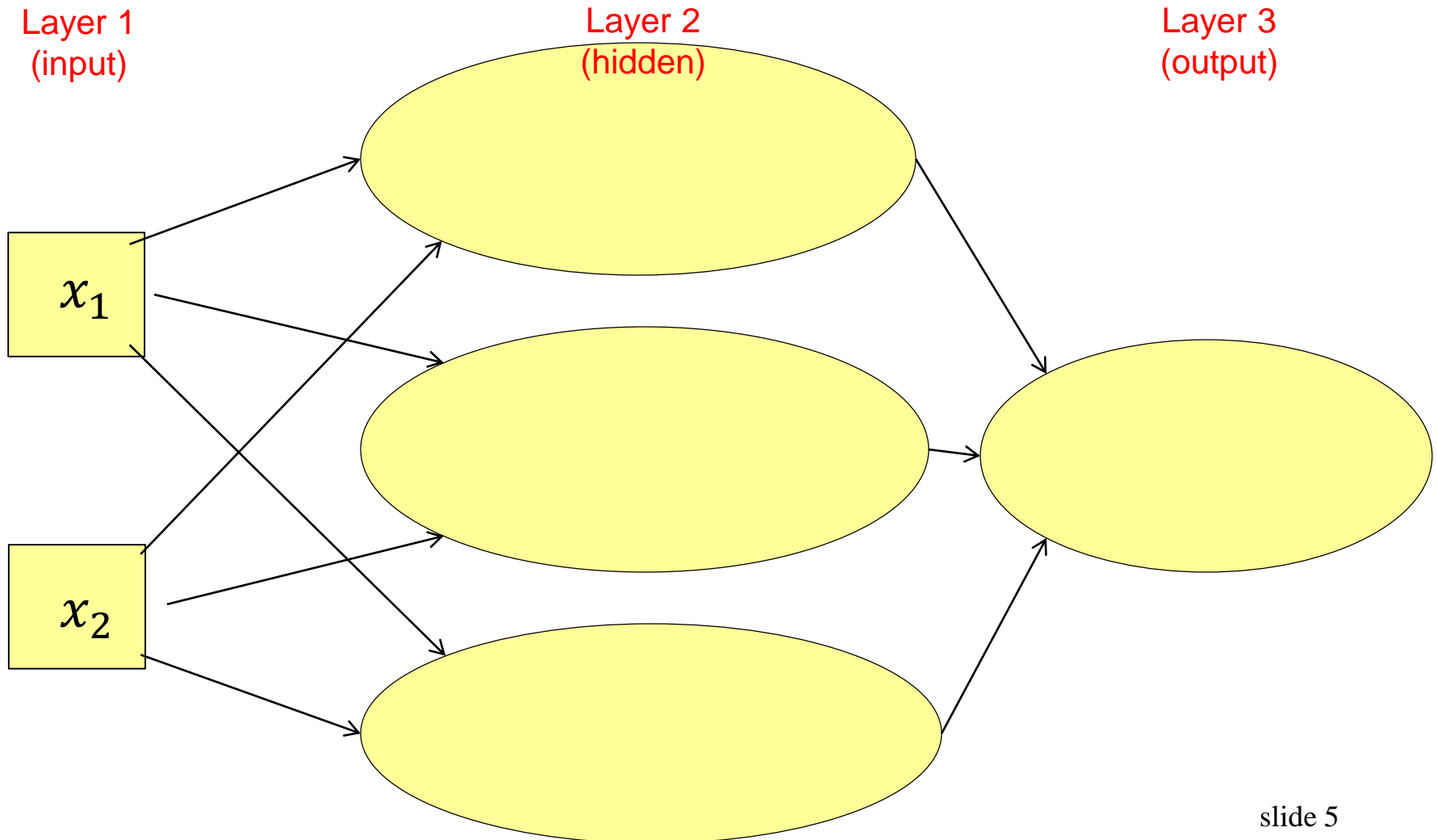


- **Wait!** If one can represent AND, OR, NOT, one can represent any logic circuit (including XOR), by **connecting them**

Question: how to?

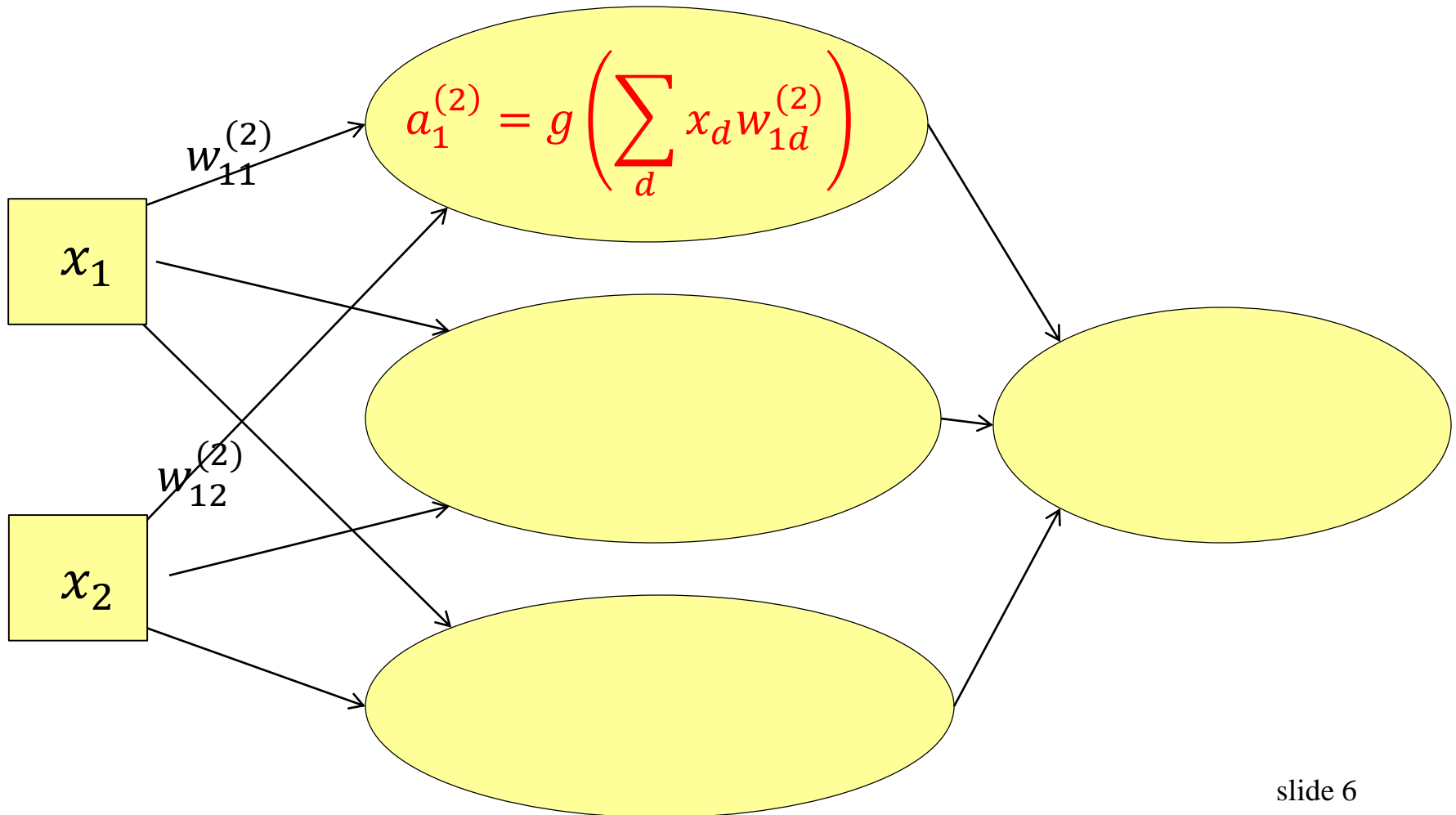
Multi-layer neural networks

- Standard way to connect Perceptrons
- Example: 1 hidden layer, 1 output layer



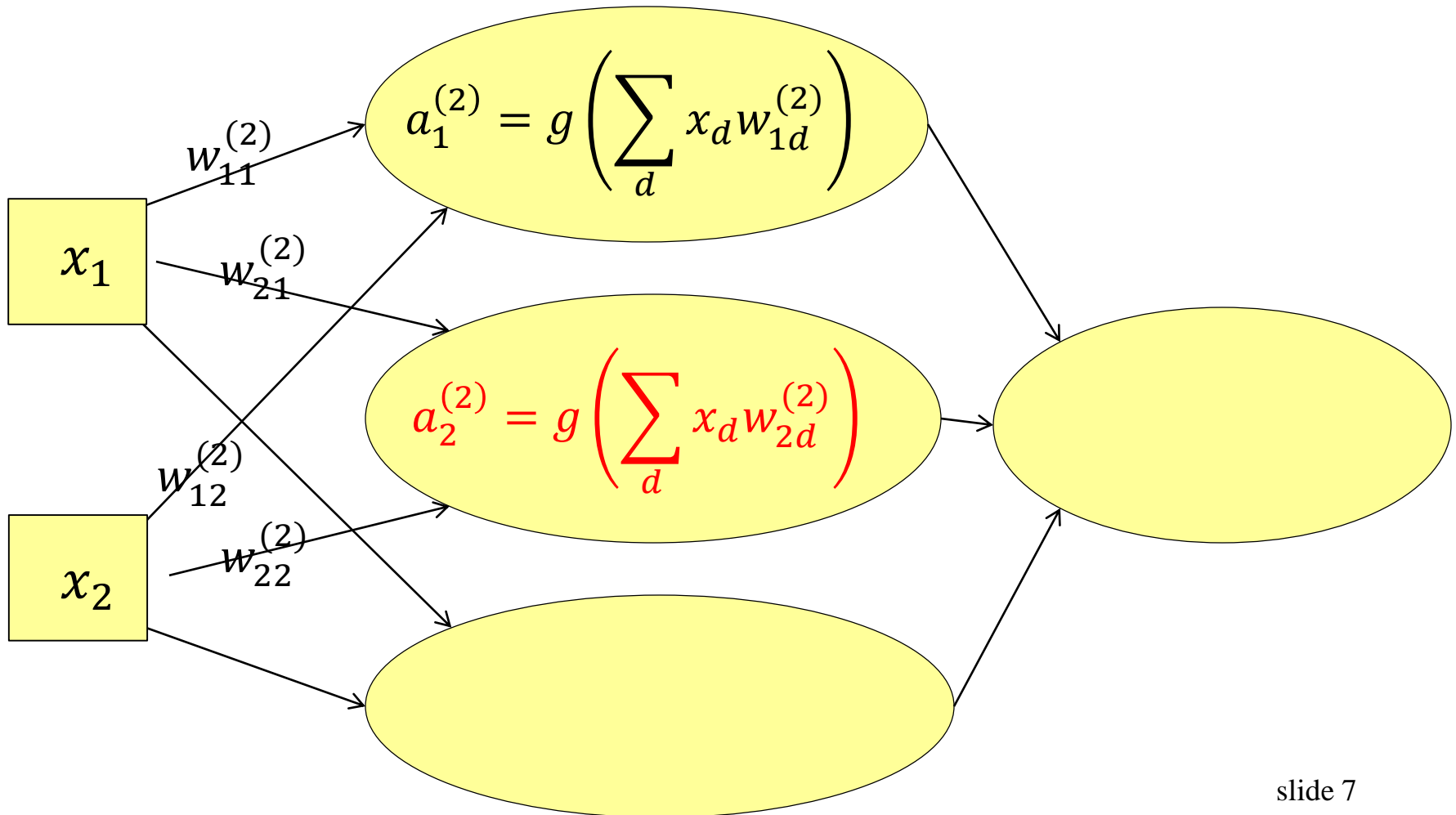
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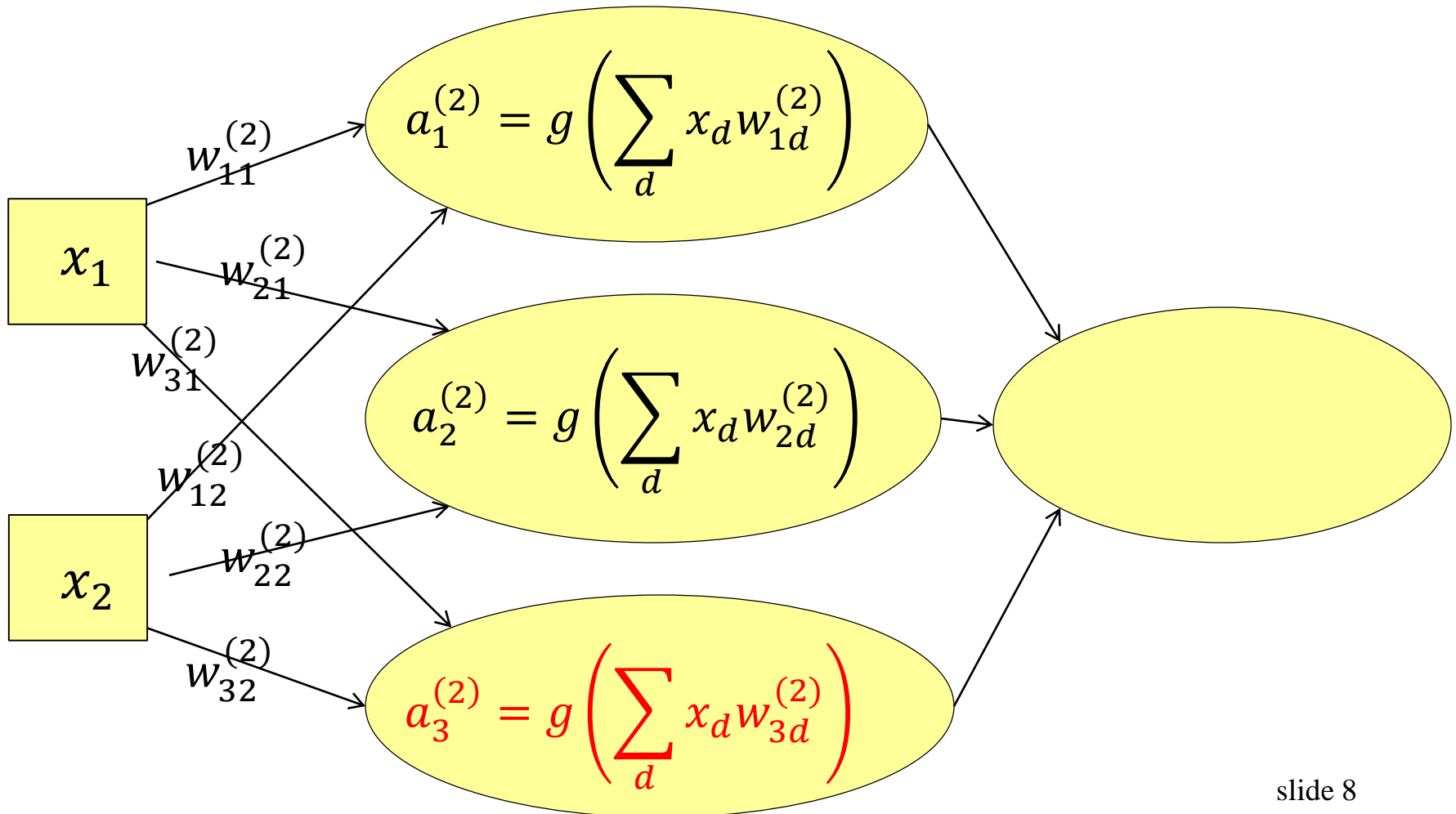
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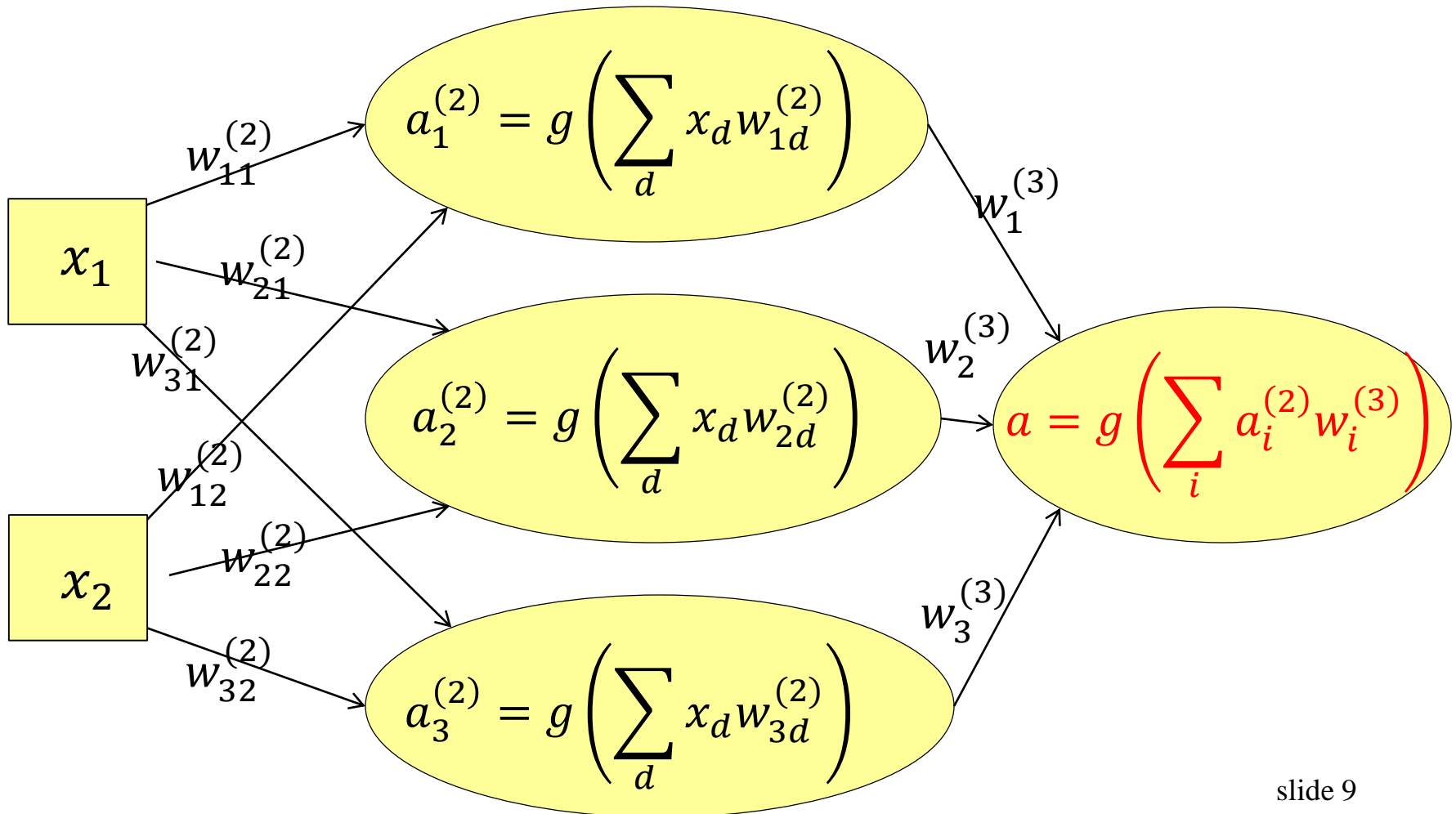
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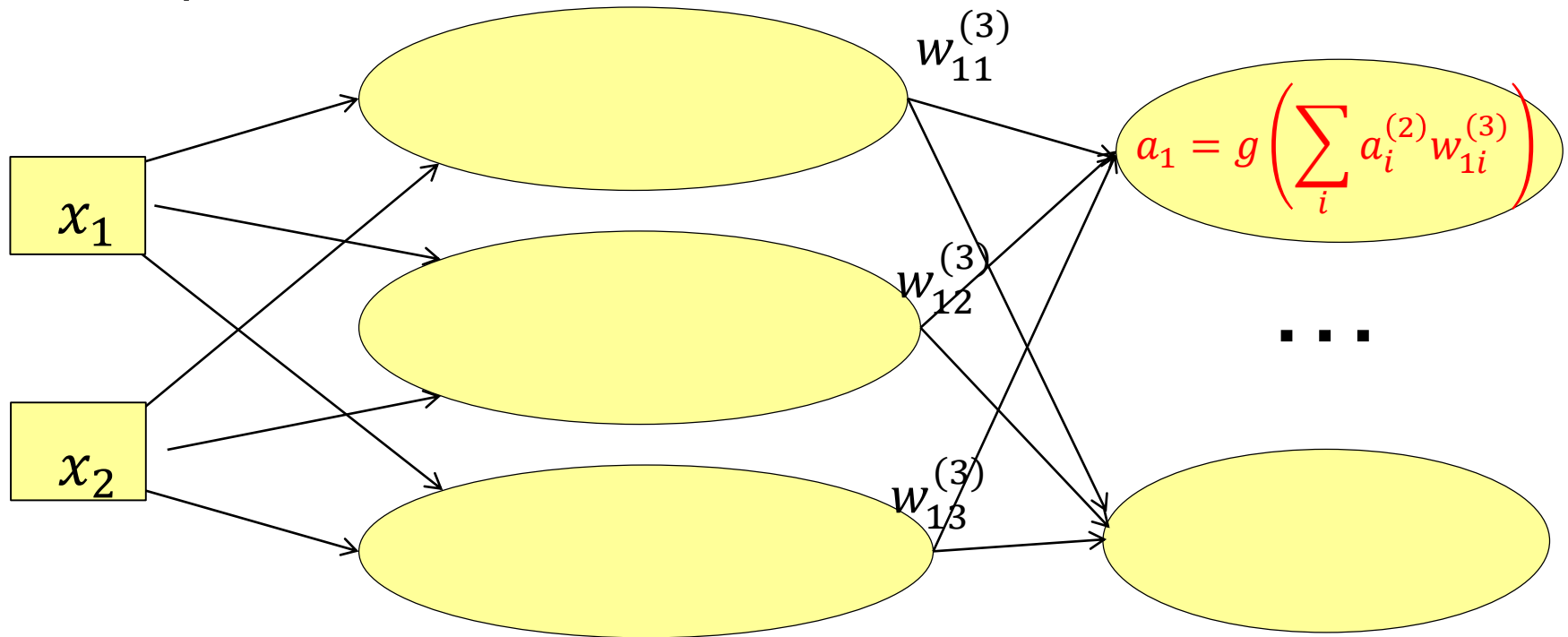
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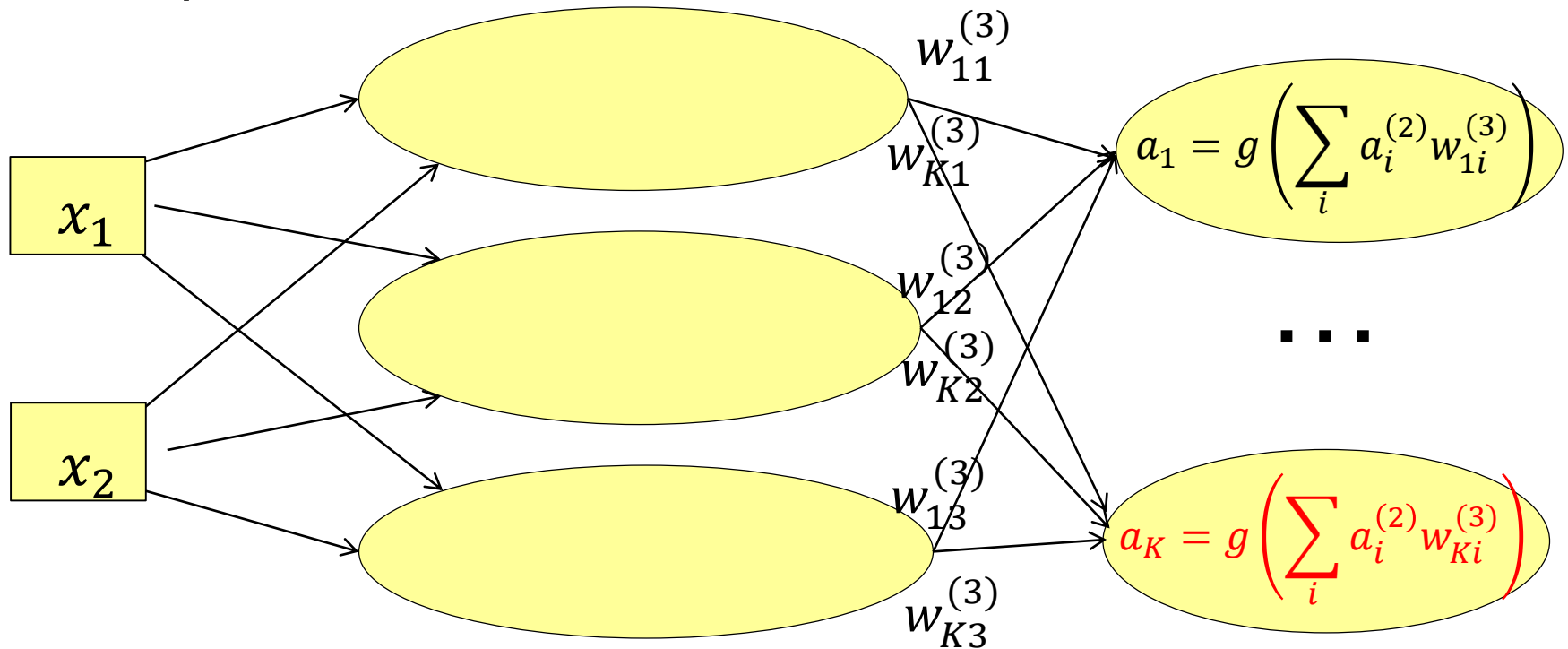
Neural net for K -way classification

- Use K output units
- Training: encode a label y by an indicator vector
 - class1=(1,0,0,...,0), class2=(0,1,0,...,0) etc.
- Test: choose the class corresponding to the largest output unit



Neural net for K -way classification

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The (unlimited) power of neural network

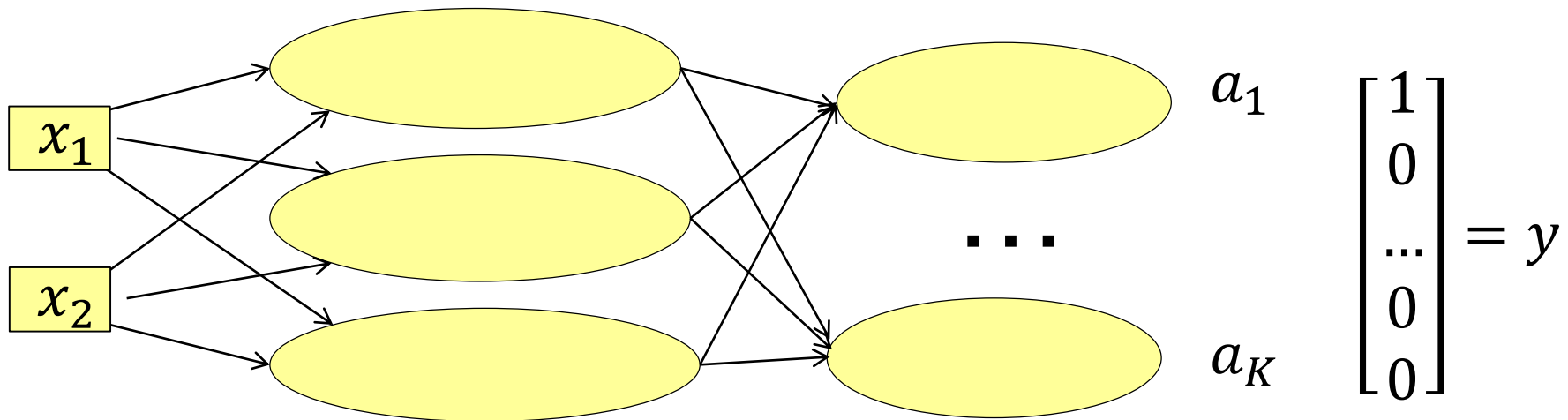
- In theory
 - we don't need too many layers:
 - 1-hidden-layer net with **enough hidden units** can represent any continuous function of the inputs with arbitrary accuracy
 - 2-hidden-layer net can even represent discontinuous functions

Learning in neural network

- Again we will minimize the error (K outputs):

$$E = \frac{1}{2} \sum_{x \in D} E_x, \quad E_x = \|y - a\|^2 = \sum_{c=1}^K (a_c - y_c)^2$$

- x : one training point in the training set D
- a_c : the c -th output for the training point x
- y_c : the c -th element of the label indicator vector for x



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 - Apparent difficulty: we don't know the 'correct' output of hidden units

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- Our variables are **all the weights w on all the edges**
 - Apparent difficulty: we don't know the 'correct' output of hidden units
 - It turns out to be OK: we can still do gradient descent. The trick you need is the **chain rule**
 - The algorithm is known as **back-propagation**

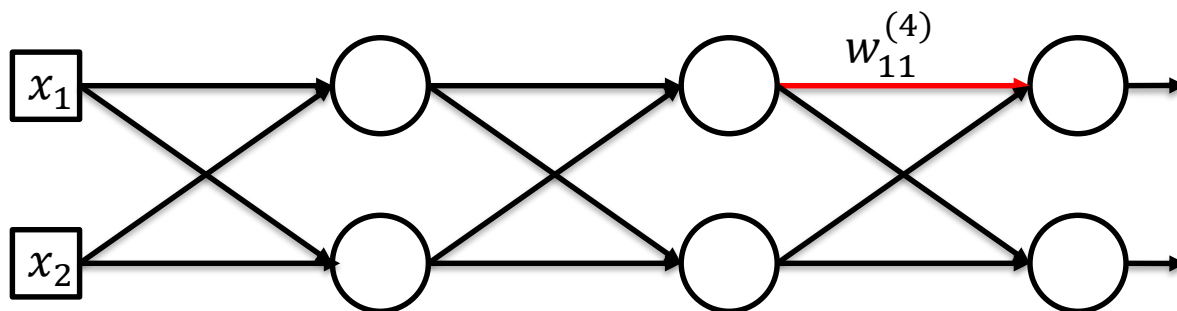
Gradient (on one data point)

Layer (1)

Layer (2)

Layer (3)

Layer (4)



E_x

want to compute $\frac{\partial E_x}{\partial w_{11}^{(4)}}$

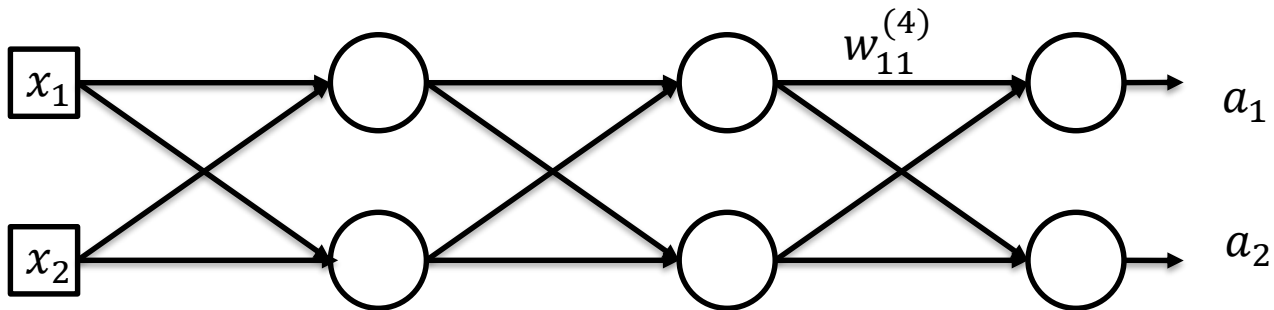
Gradient (on one data point)

Layer (1)

Layer (2)

Layer (3)

Layer (4)



$$E_x = \|y - a\|^2$$

$$a_1 \xrightarrow{\|y - a\|^2} E_x$$

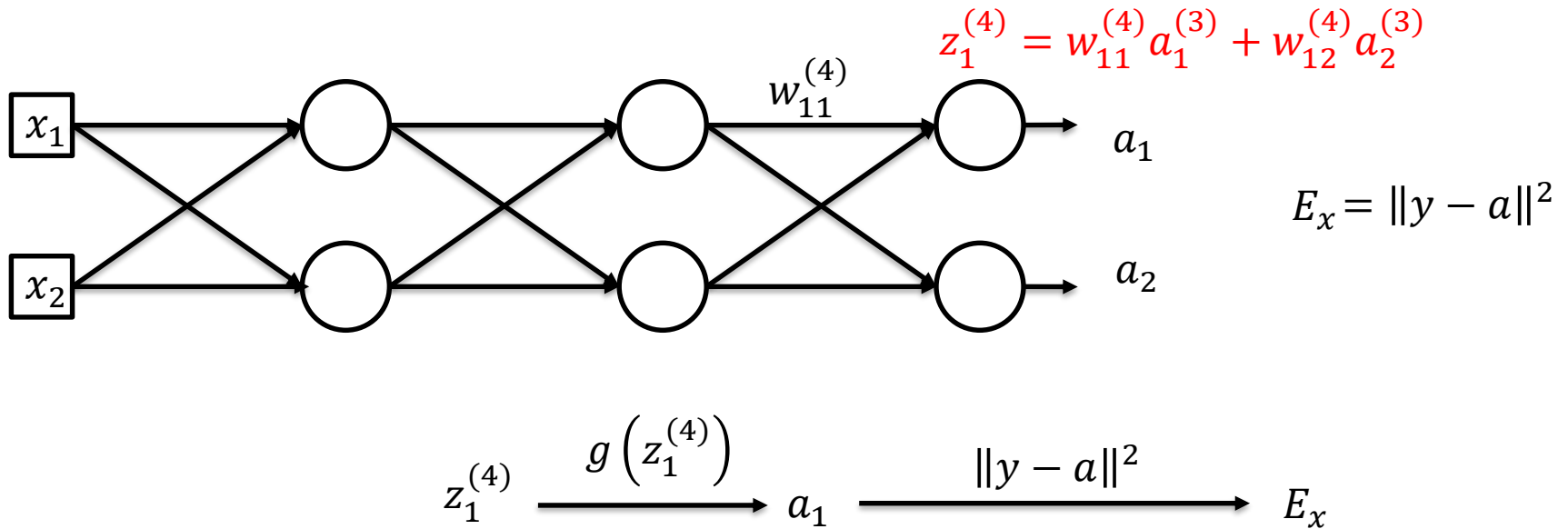
Gradient (on one data point)

Layer (1)

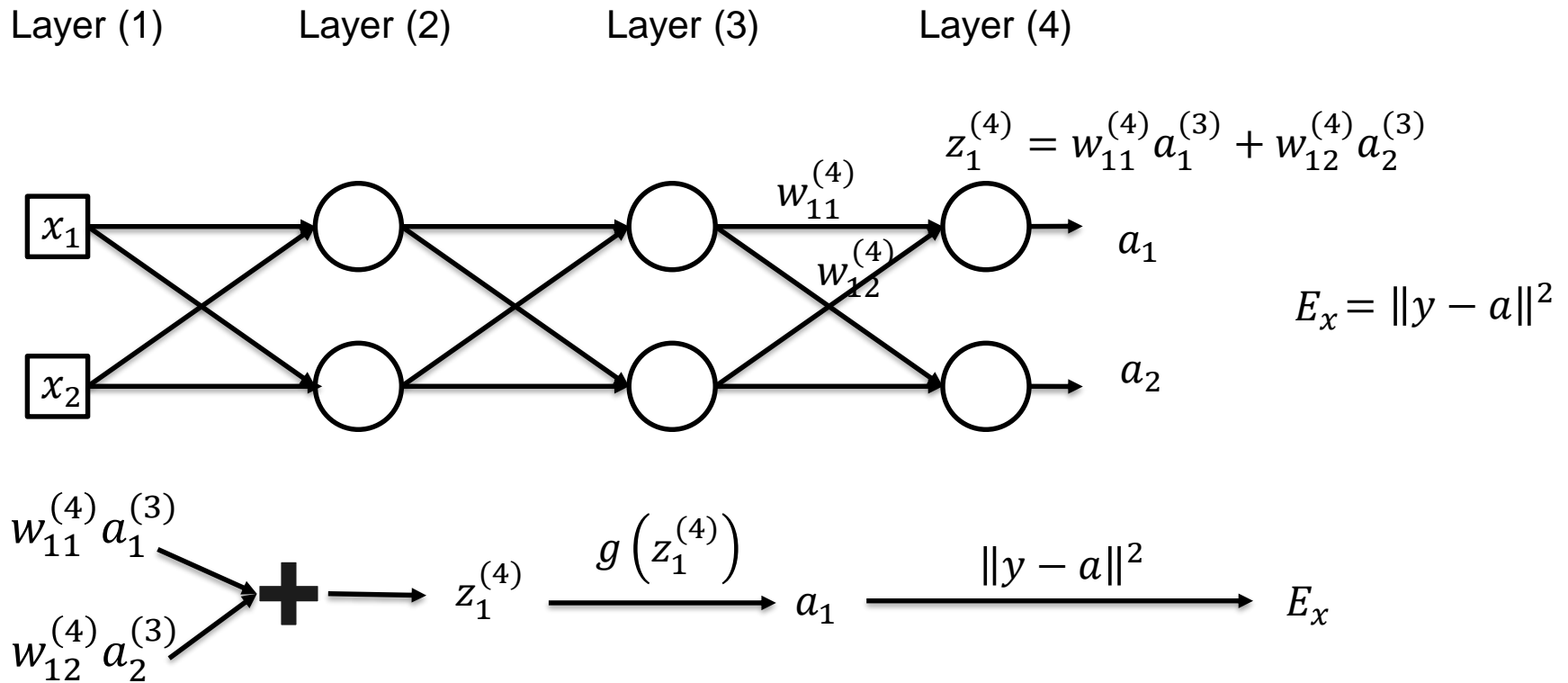
Layer (2)

Layer (3)

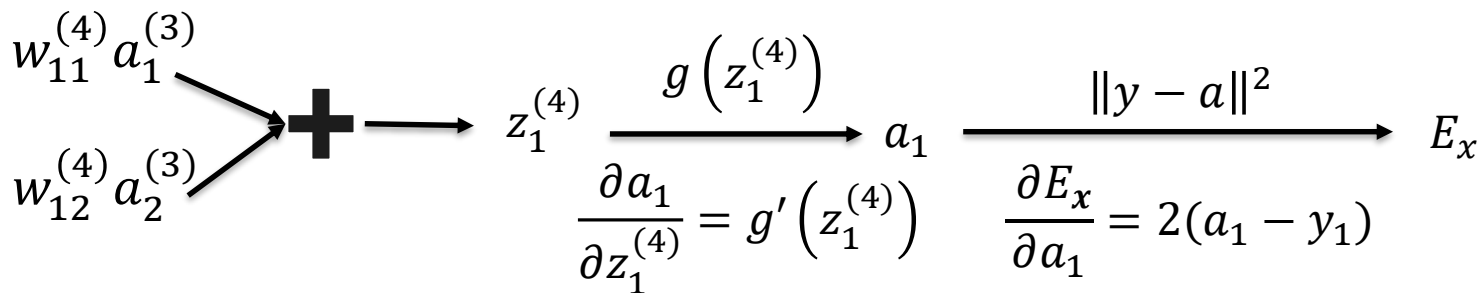
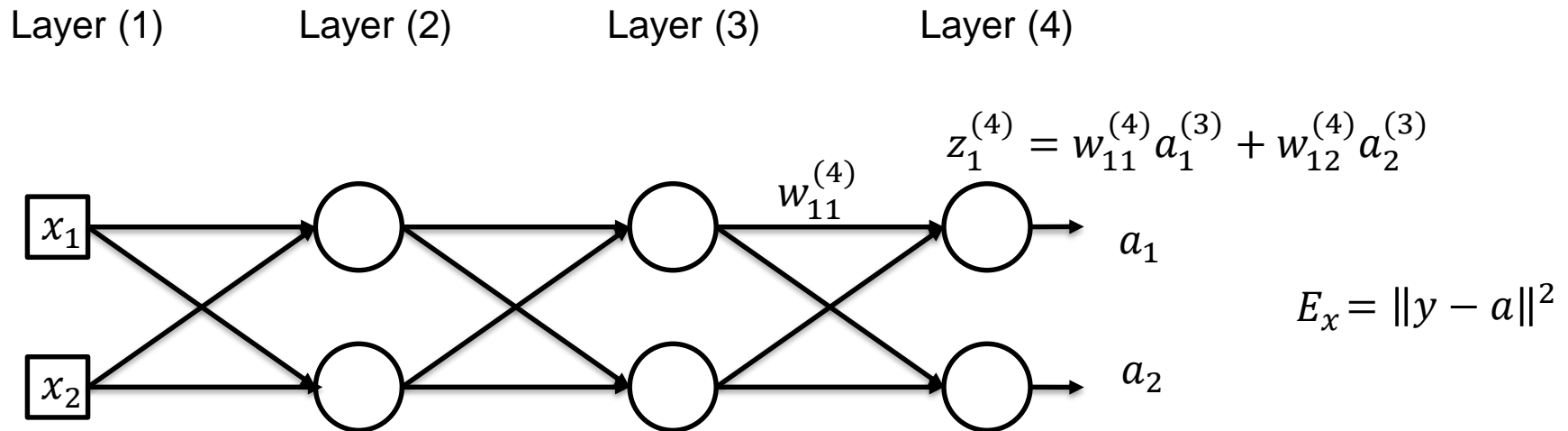
Layer (4)



Gradient (on one data point)



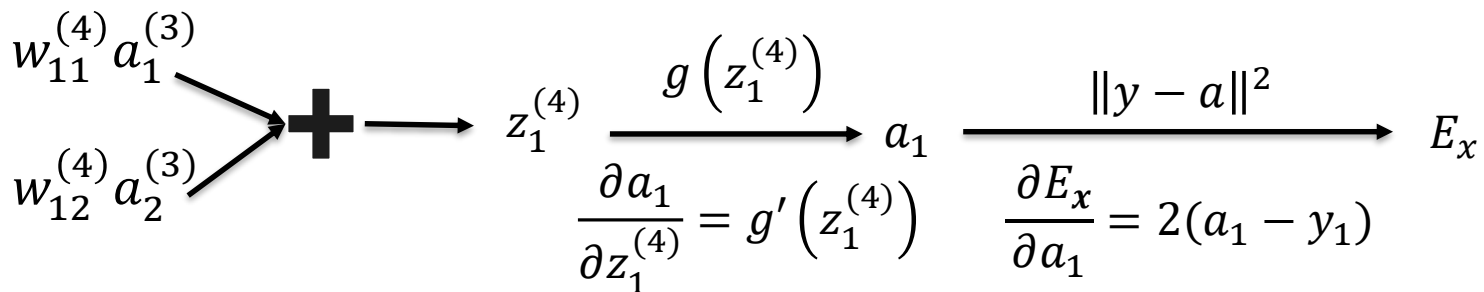
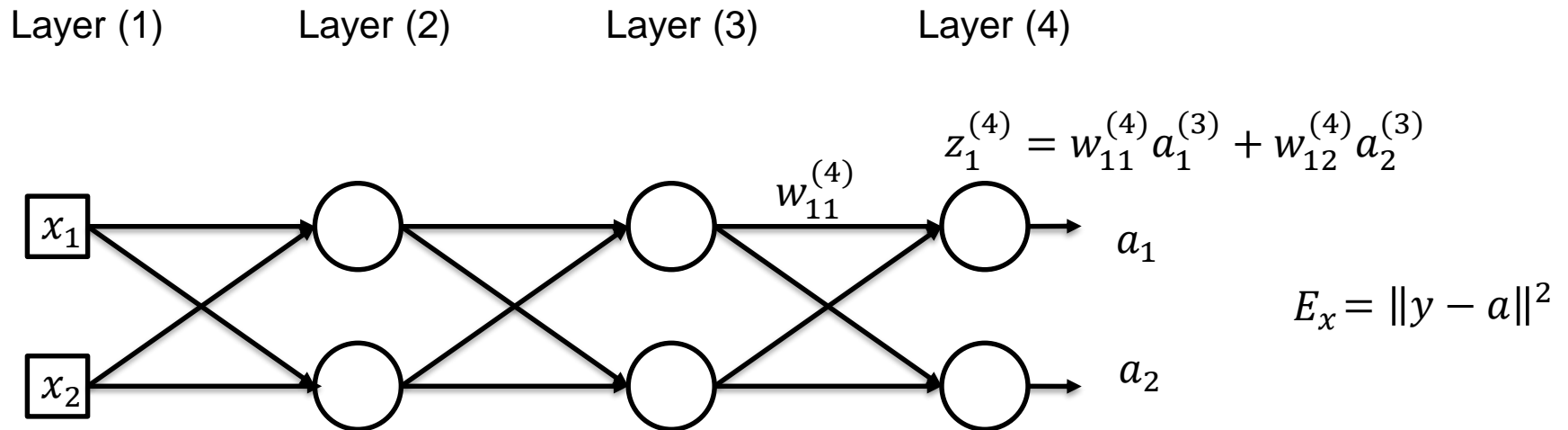
Gradient (on one data point)



By Chain Rule:

$$\frac{\partial E_x}{\partial w_{11}^{(4)}} = \frac{\partial E_x}{\partial a_1} \frac{\partial a_1}{\partial z_1^{(4)}} \frac{\partial z_1^{(4)}}{\partial w_{11}^{(4)}}$$

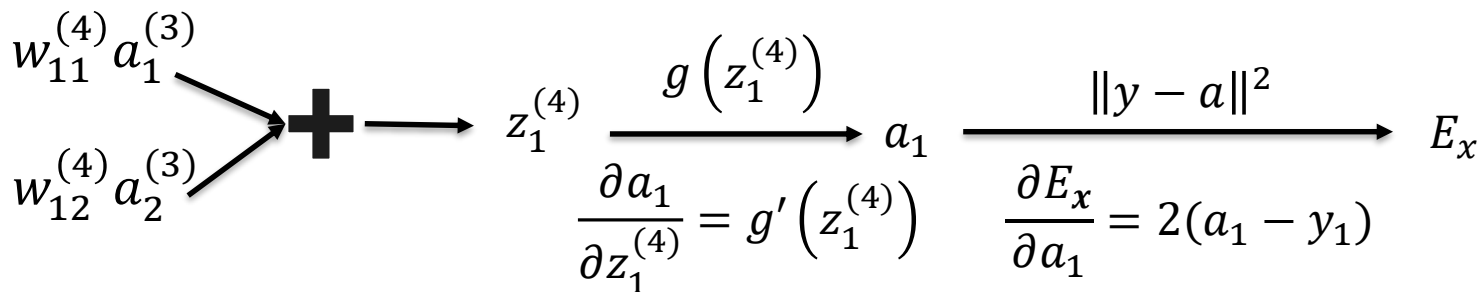
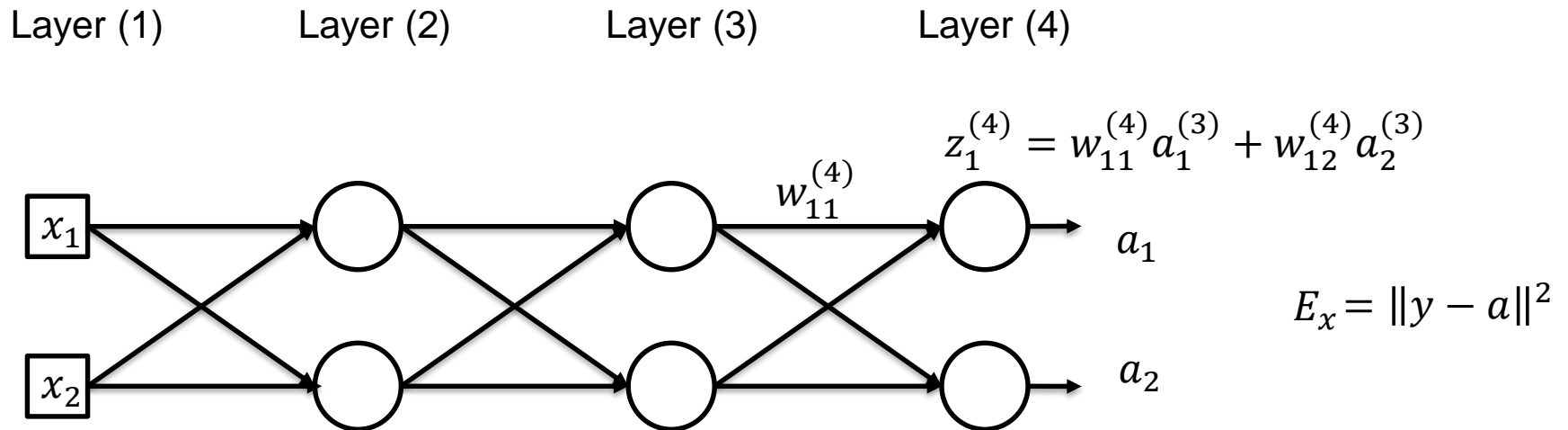
Gradient (on one data point)



By Chain Rule:

$$\frac{\partial E_x}{\partial w_{11}^{(4)}} = 2(a_1 - y_1) g'(z_1^{(4)}) \frac{\partial z_1^{(4)}}{\partial w_{11}^{(4)}}$$

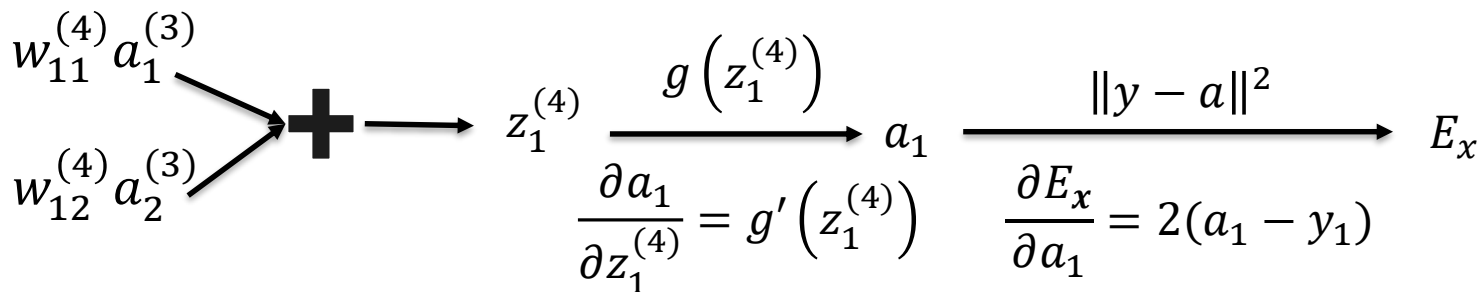
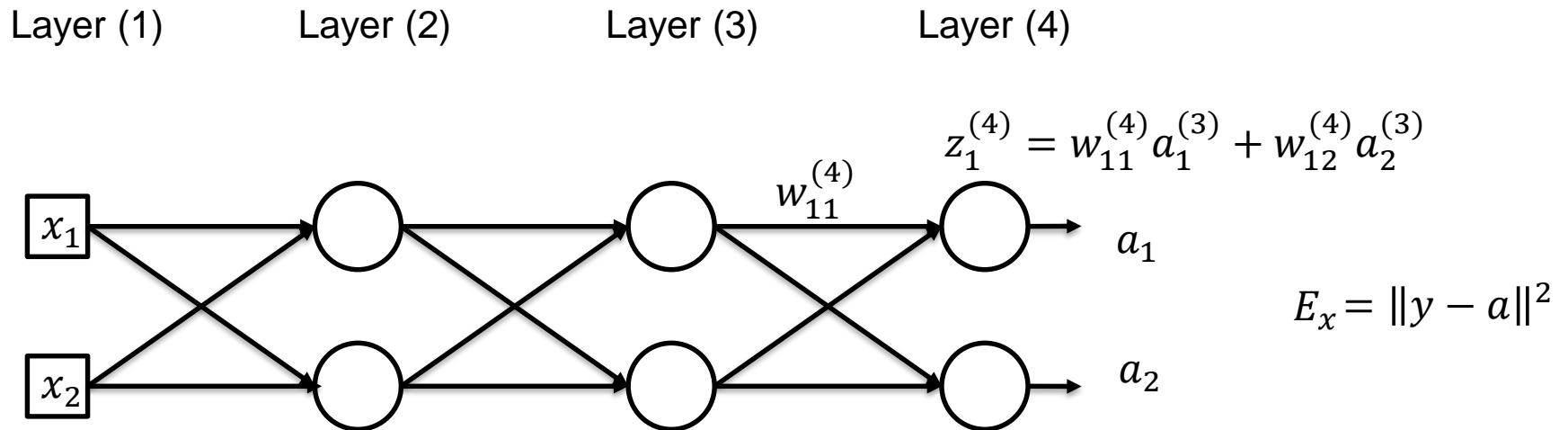
Gradient (on one data point)



By Chain Rule:

$$\frac{\partial E_x}{\partial w_{11}^{(4)}} = 2(a_1 - y_1) g'(z_1^{(4)}) a_1^{(3)}$$

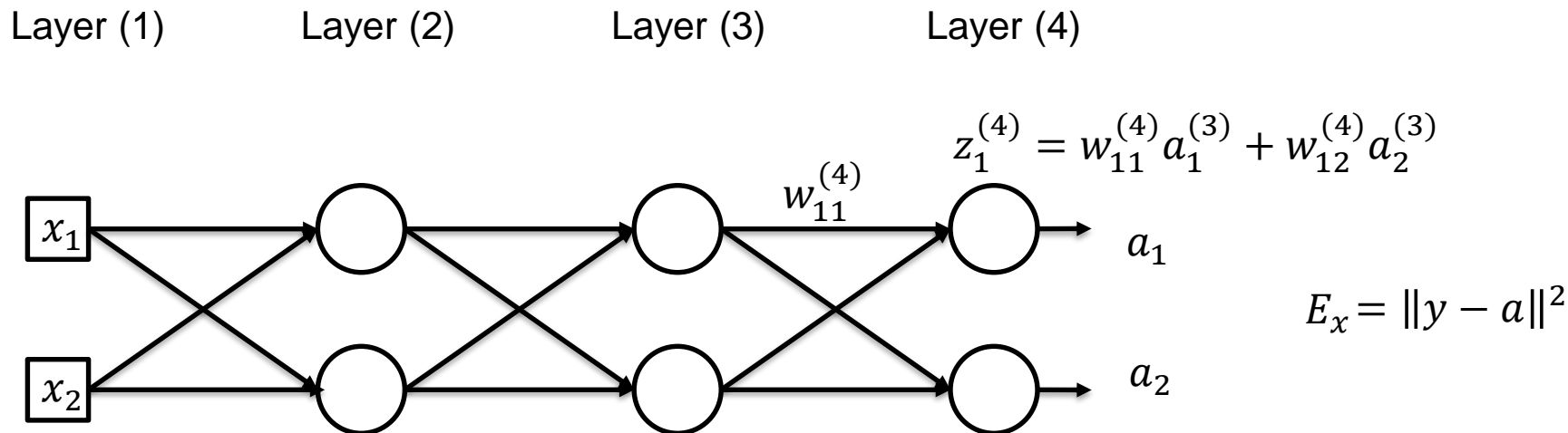
Gradient (on one data point)



By Chain Rule:

$$\frac{\partial E_x}{\partial w_{11}^{(4)}} = 2(a_1 - y_1) g(z_1^{(4)}) (1 - g(z_1^{(4)})) a_1^{(3)}$$

Gradient (on one data point)



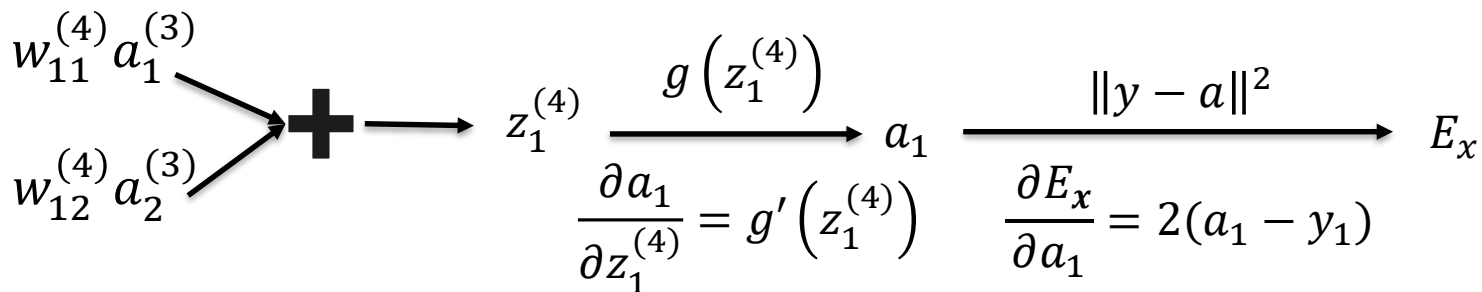
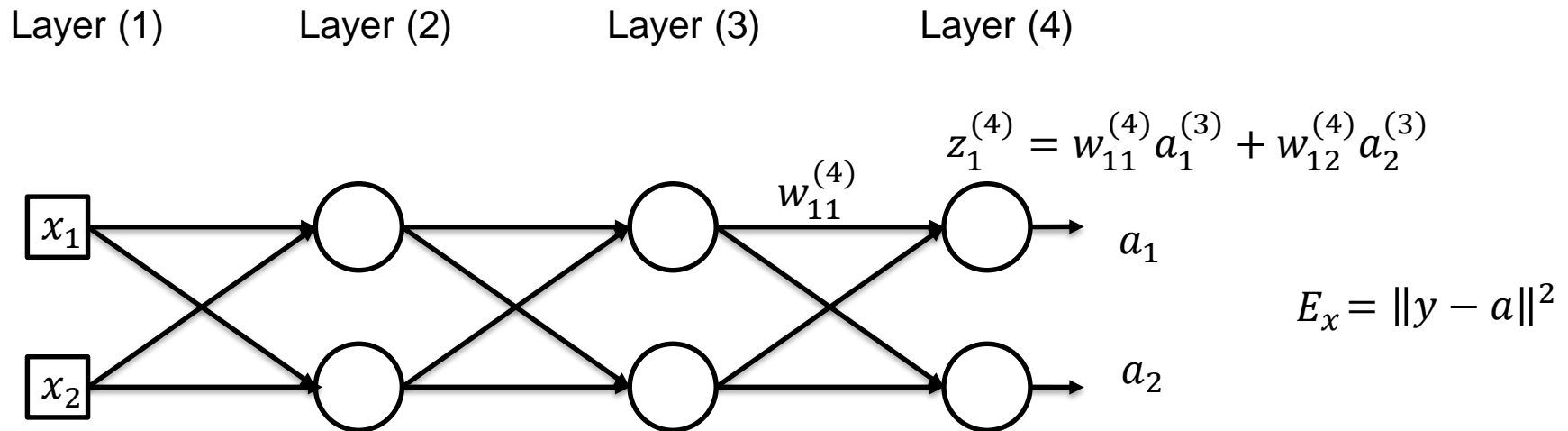
$$\begin{array}{c}
 w_{11}^{(4)} a_1^{(3)} \\
 w_{12}^{(4)} a_2^{(3)}
 \end{array}
 \rightarrow \text{+} \rightarrow z_1^{(4)} \xrightarrow{g(z_1^{(4)})} a_1 \xrightarrow{\|y - a\|^2} E_x$$

$$\frac{\partial a_1}{\partial z_1^{(4)}} = g'(z_1^{(4)}) \qquad \frac{\partial E_x}{\partial a_1} = 2(a_1 - y_1)$$

By Chain Rule:

$$\frac{\partial E_x}{\partial w_{11}^{(4)}} = 2(a_1 - y_1) a_1 (1 - a_1) a_1^{(3)}$$

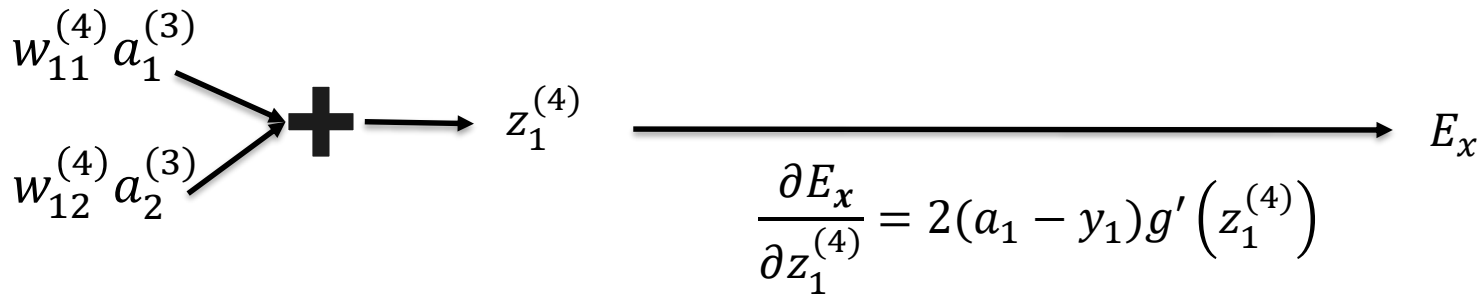
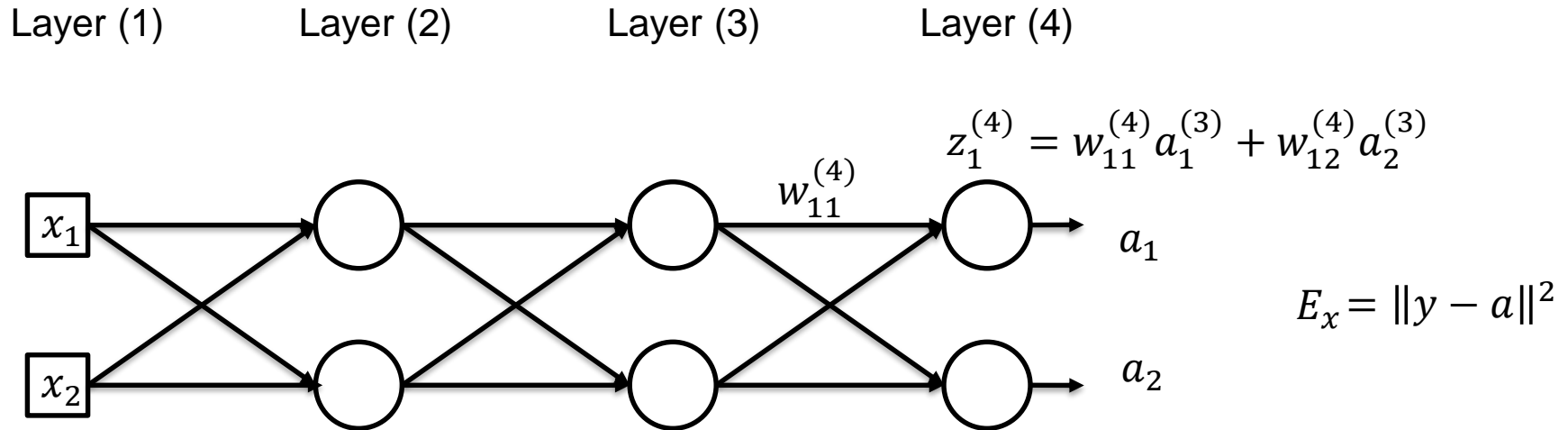
Gradient (on one data point)



By Chain Rule:
$$\frac{\partial E_x}{\partial w_{11}^{(4)}} = 2(a_1 - y_1) a_1 (1 - a_1) a_1^{(3)}$$

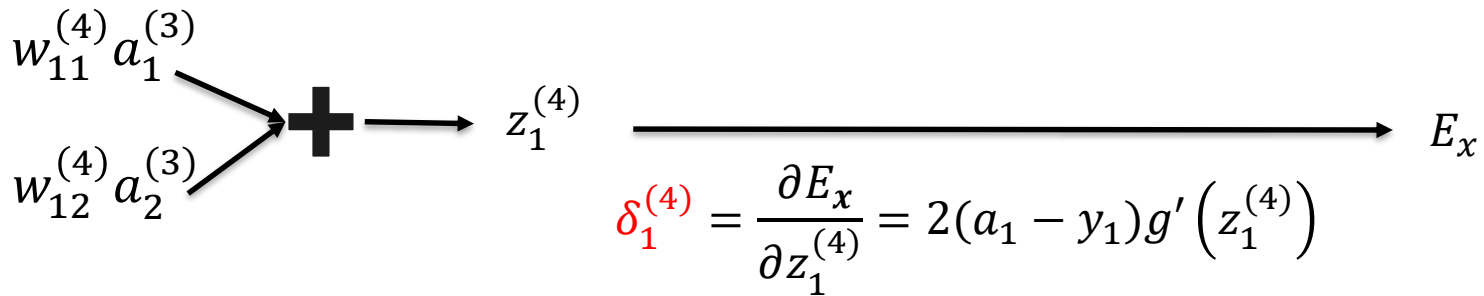
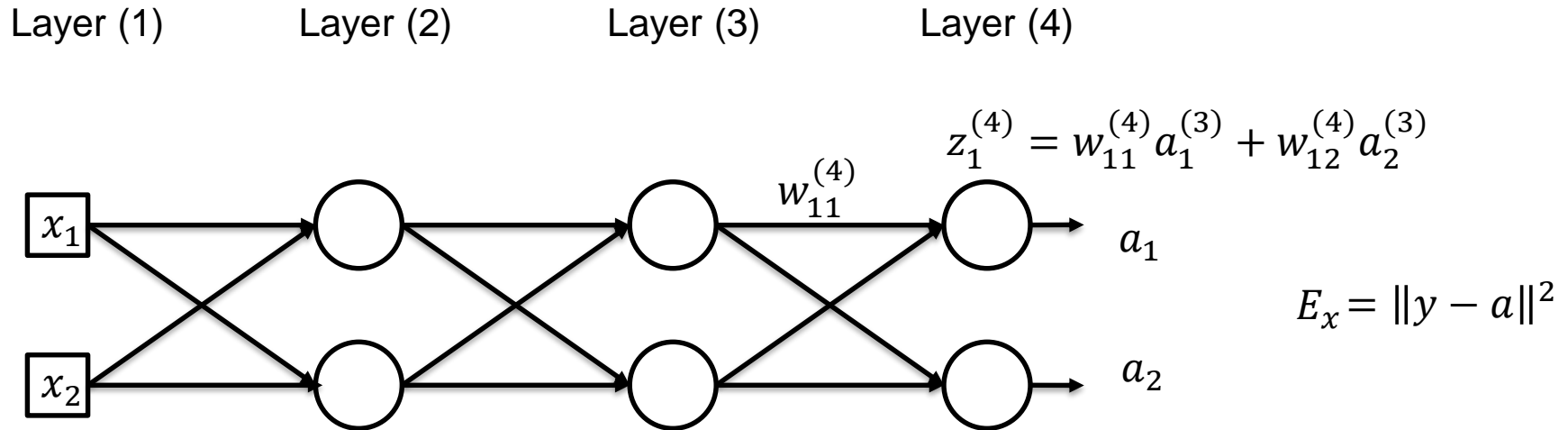
Can be computed by network activation

Backpropagation



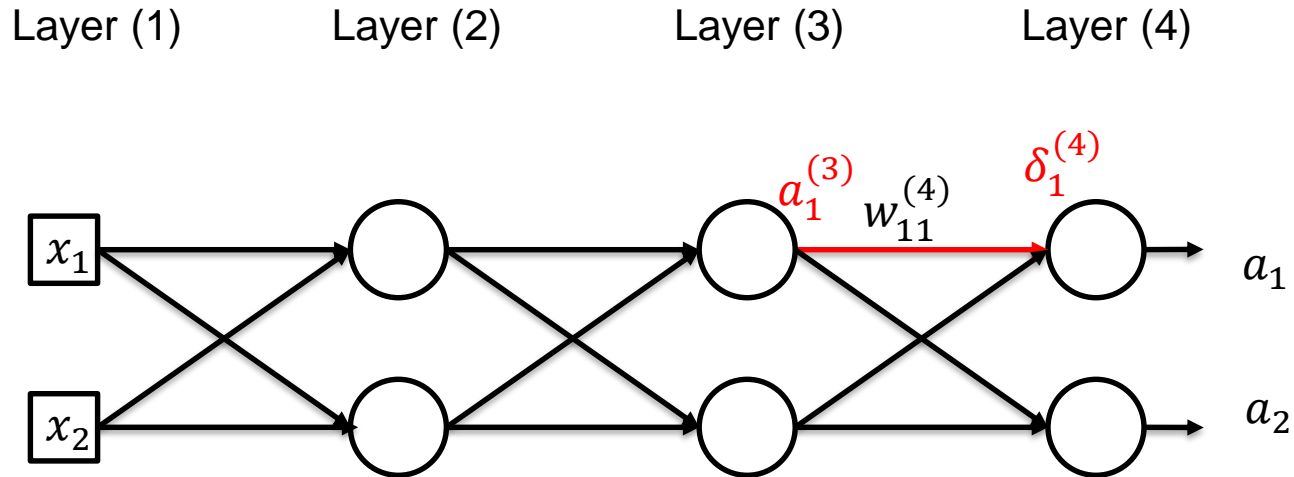
By Chain Rule:
$$\frac{\partial E_x}{\partial w_{11}^{(4)}} = 2(a_1 - y_1)a_1(1 - a_1)a_1^{(3)}$$

Backpropagation

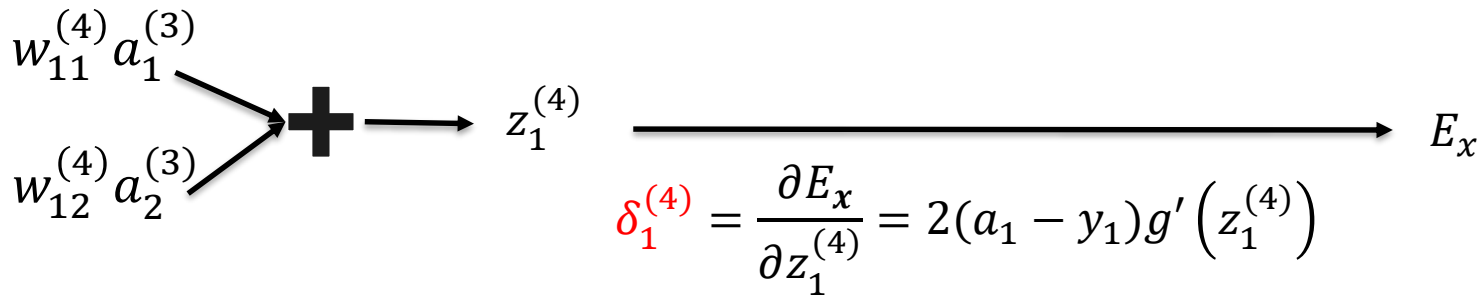


By Chain Rule: $\frac{\partial E_x}{\partial w_{11}^{(4)}} = 2(a_1 - y_1) a_1 (1 - a_1) a_1^{(3)}$

Backpropagation



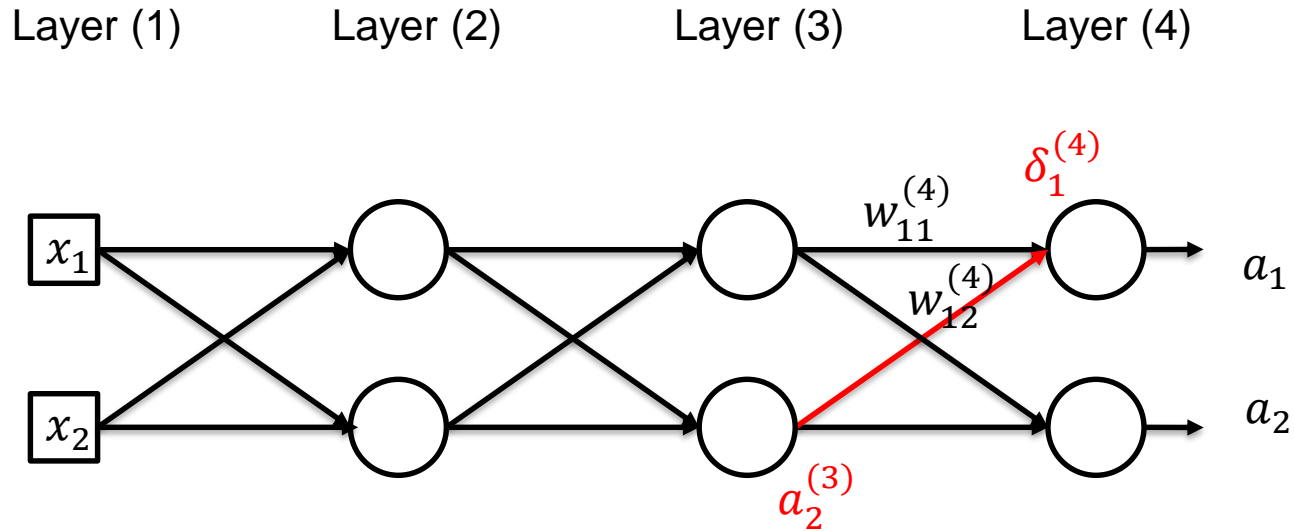
$$E_x = \|y - a\|^2$$



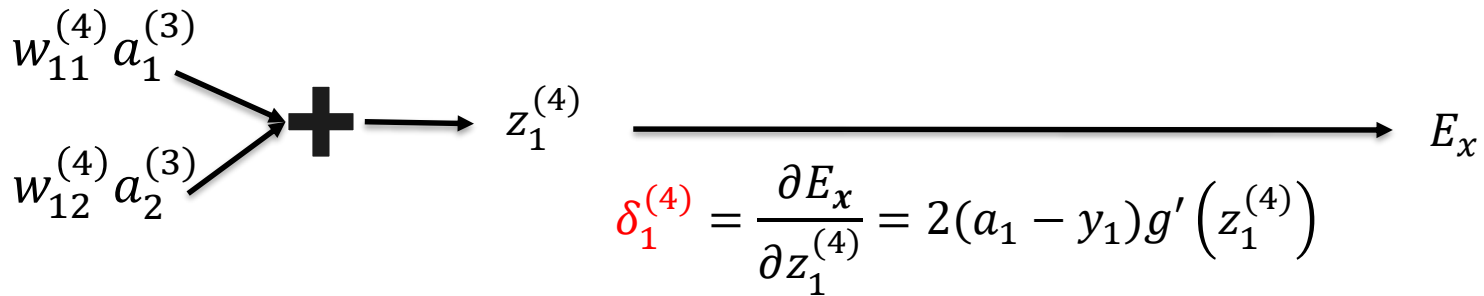
By Chain Rule:

$$\frac{\partial E_x}{\partial w_{11}^{(4)}} = \delta_1^{(4)} a_1^{(3)}$$

Backpropagation



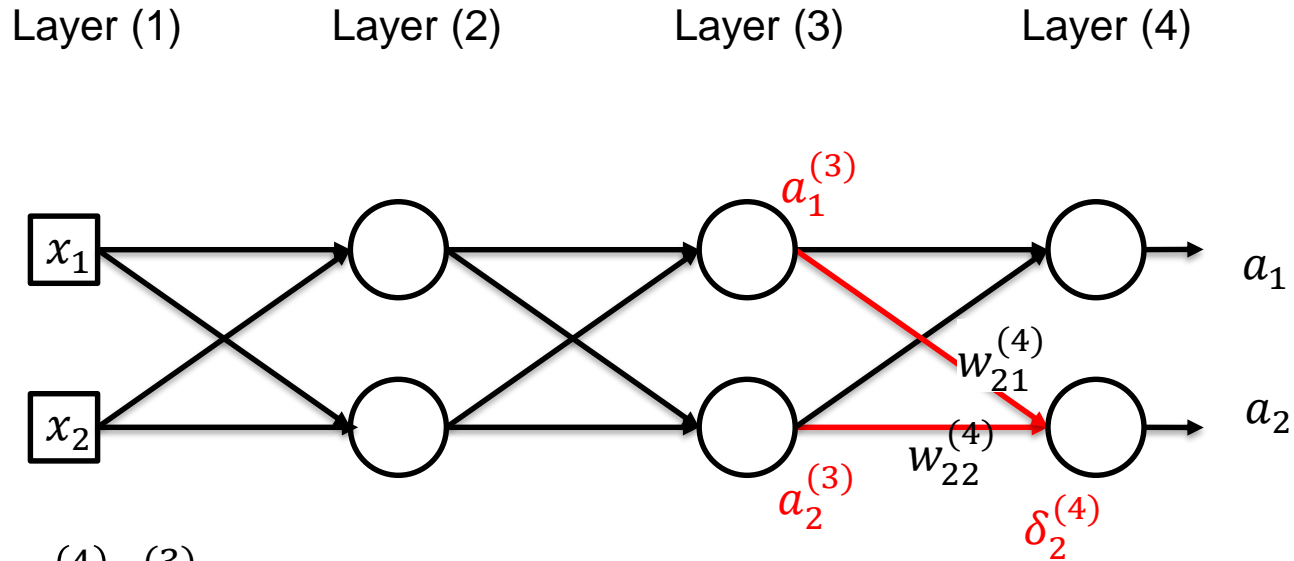
$$E_x = \|y - a\|^2$$



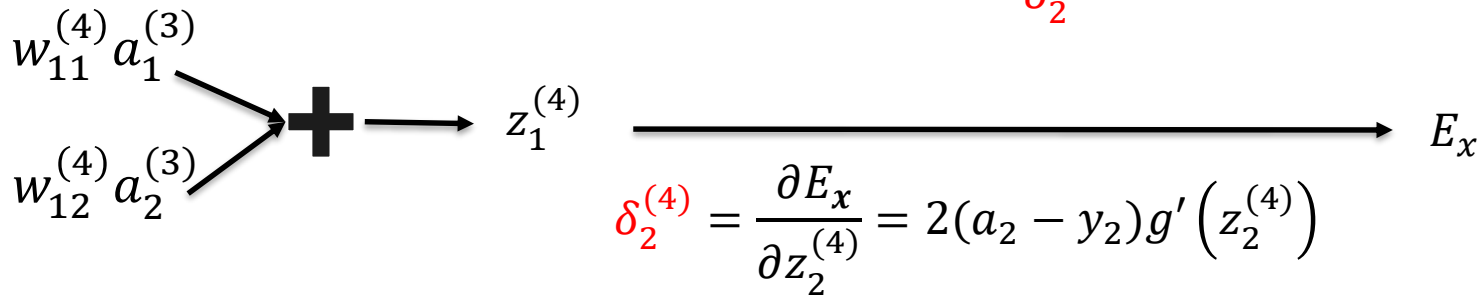
By Chain Rule:

$$\frac{\partial E_x}{\partial w_{11}^{(4)}} = \delta_1^{(4)} a_1^{(3)}, \quad \frac{\partial E_x}{\partial w_{12}^{(4)}} = \delta_1^{(4)} a_2^{(3)}$$

Backpropagation



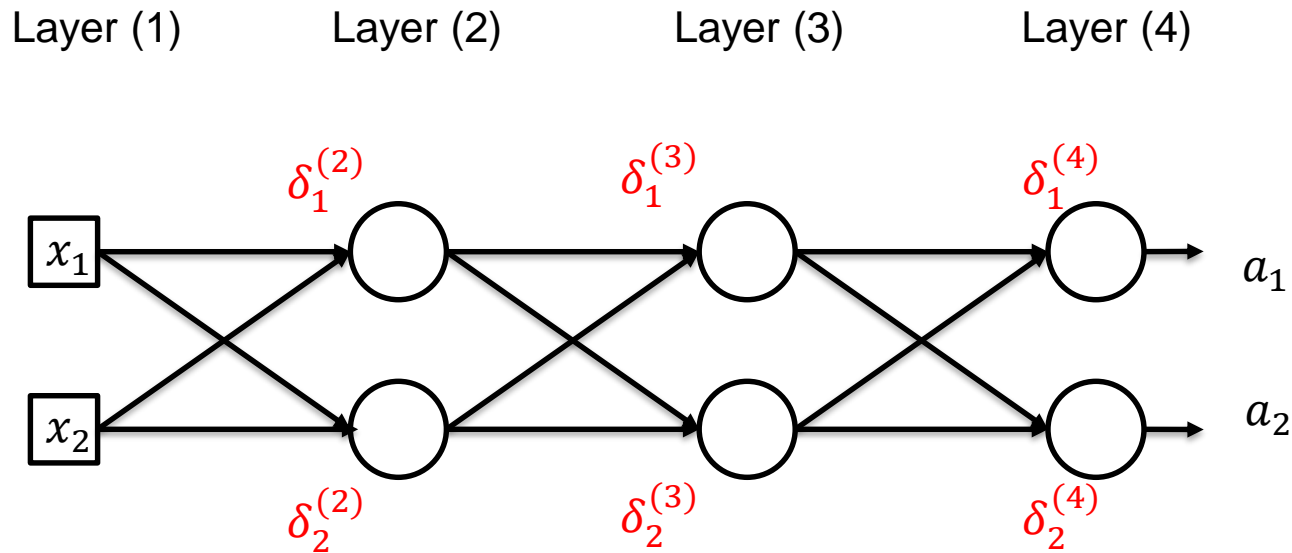
$$E_x = \|y - a\|^2$$



By Chain Rule:

$$\frac{\partial E_x}{\partial w_{21}^{(4)}} = \delta_2^{(4)} a_1^{(3)}, \quad \frac{\partial E_x}{\partial w_{22}^{(4)}} = \delta_2^{(4)} a_2^{(3)}$$

Backpropagation



$$E_x = \|y - a\|^2$$

Thus, for any weight in the network:

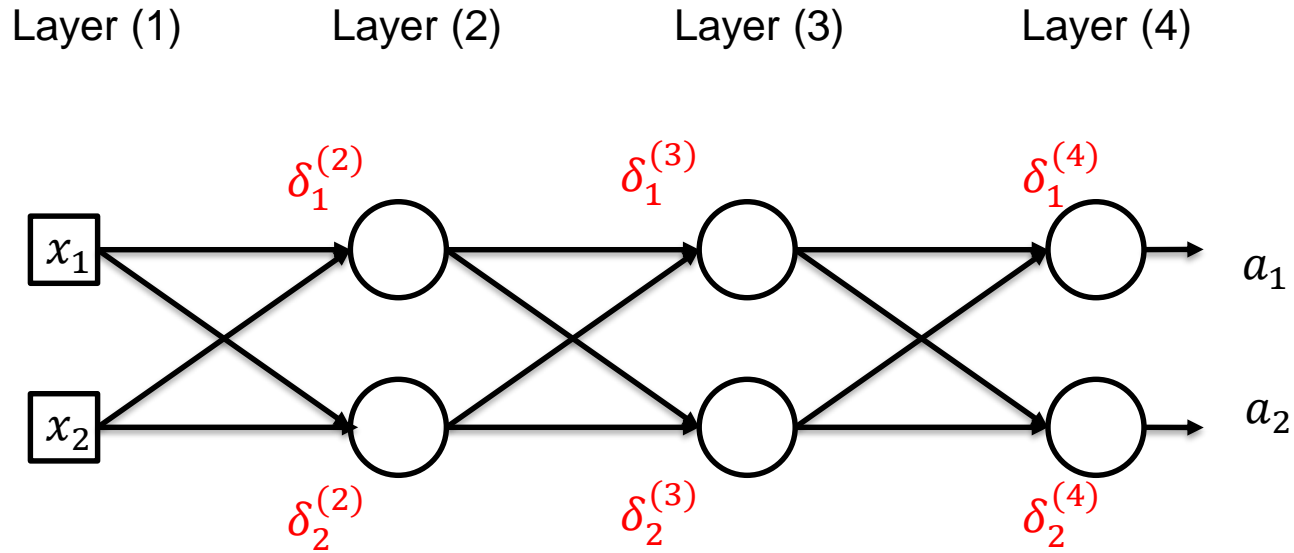
$$\frac{\partial E_x}{\partial w_{jk}^{(l)}} = \delta_j^{(l)} a_k^{(l-1)}$$

$\delta_j^{(l)}$: δ of j^{th} neuron in Layer l

$a_k^{(l-1)}$: Activation of k^{th} neuron in Layer $l - 1$

$w_{jk}^{(l)}$: Weight from k^{th} neuron in Layer $l - 1$ to j^{th} neuron in Layer l

Exercise



$$E_x = \|y - a\|^2$$

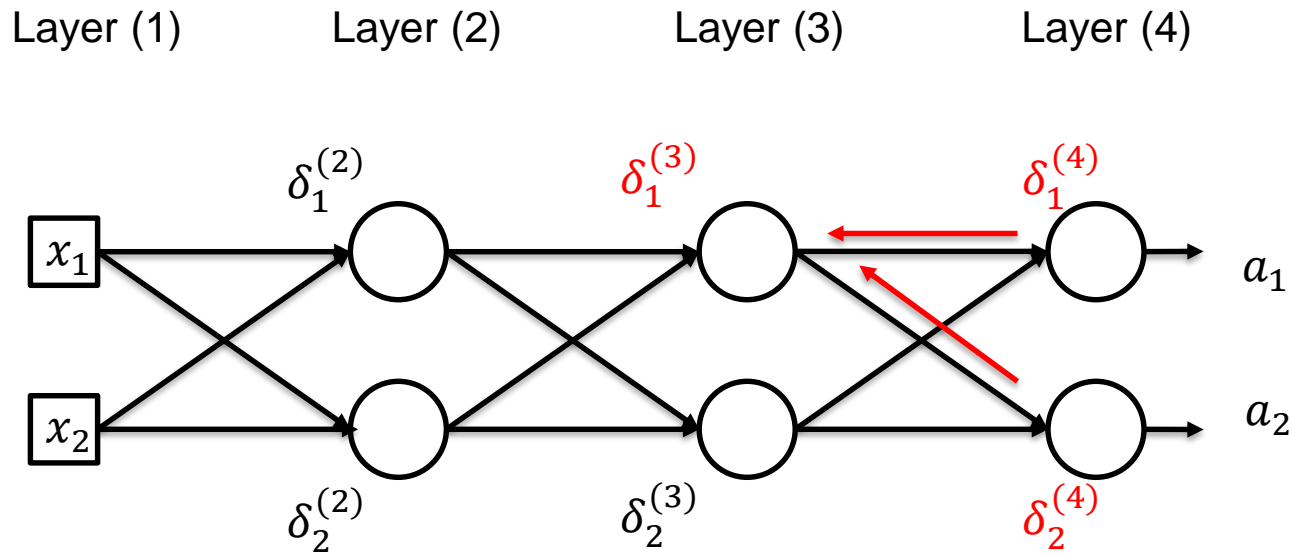
Show that for any bias in the network:

$$\frac{\partial E_x}{\partial b_j^{(l)}} = \delta_j^{(l)}$$

$\delta_j^{(l)}$: δ of j^{th} neuron in Layer l

$b_j^{(l)}$: bias for the j^{th} neuron in Layer l , i.e., $z_j^{(l)} = \sum_k w_{jk}^{(l)} a_k^{(l-1)} + b_j^{(l)}$

Backpropagation of δ



$$E_x = \|y - a\|^2$$

Thus, for any neuron in the network:

$$\delta_j^{(l)} = \sum_k \delta_k^{(l+1)} w_{kj}^{(l+1)} g'(z_j^{(l)})$$

$\delta_j^{(l)}$: δ of j^{th} Neuron in Layer l

$\delta_k^{(l+1)}$: δ of k^{th} Neuron in Layer $l + 1$

$g'(z_j^{(l)})$: derivative of j^{th} Neuron in Layer l w.r.t. its linear combination input

$w_{kj}^{(l+1)}$: Weight from j^{th} Neuron in Layer l to k^{th} Neuron in Layer $l + 1$

Gradient descent with Backpropagation

1. Initialize Network with Random Weights and Biases
2. For each Training Image:
 - a. Compute Activations for the Entire Network
 - b. Compute δ for Neurons in the Output Layer using Network Activation and Desired Activation

$$\delta_j^{(L)} = 2(y_j - a_j)a_j(1 - a_j)$$

- c. Compute δ for all Neurons in the previous Layers

$$\delta_j^{(l)} = \sum_k \delta_k^{(l+1)} w_{kj}^{(l+1)} a_j^{(l)} (1 - a_j^{(l)})$$

- d. Compute Gradient of Cost w.r.t each Weight and Bias for the Training Image using δ

$$\frac{\partial E_x}{\partial w_{jk}^{(l)}} = \delta_j^{(l)} a_k^{(l-1)}$$

$$\frac{\partial E_x}{\partial b_j^{(l)}} = \delta_j^{(l)}$$

Gradient descent with Backpropagation

3. Average the Gradient w.r.t. each Weight and Bias over the Entire Training Set

$$\frac{\partial E}{\partial w_{jk}^{(l)}} = \frac{1}{n} \sum \frac{\partial E_x}{\partial w_{jk}^{(l)}} \qquad \frac{\partial E}{\partial b_j^{(l)}} = \frac{1}{n} \sum \frac{\partial E_x}{\partial b_j^{(l)}}$$

4. Update the Weights and Biases using Gradient Descent

$$w_{jk}^{(l)} \leftarrow w_{jk}^{(l)} - \eta \frac{\partial E}{\partial w_{jk}^{(l)}} \qquad b_j^{(l)} \leftarrow b_j^{(l)} - \eta \frac{\partial E}{\partial b_j^{(l)}}$$

5. Repeat Steps 2-4 till Cost reduces below an acceptable level