

## Lecture 10 Implicit Regularization for Neural Networks

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## 1 Overview

Continuing the theme of implicit regularization from the previous four lectures, we use the tools developed in the last lecture to show that a non-smooth version of gradient flow (using the Clarke subdifferential) yields non-decreasing “soft” margin for homogeneous predictors on separable data. In particular this applies to neural networks since ReLU networks are homogeneous. To perform this analysis, we first prove a useful lemma about Clarke subdifferentials of homogeneous functions and generalize margin beyond linear classifiers.

## 2 Review

First we recall the definition of the Clarke subdifferential from last lecture.

**Definition 1.** For a locally-Lipschitz function  $f : \mathcal{X} \rightarrow \mathbb{R}$ , the Clarke subdifferential of  $f$  at  $w \in \mathcal{X}$  is

$$\partial f(w) = \text{conv}\{s : \exists (w_n)_n \text{ such that } w_n \rightarrow w, \nabla f(w_n) \rightarrow s\}.$$

## 3 Subdifferential for Homogeneous Functions

Motivated by the observation last lecture that an  $L$ -hidden layer ReLU neural network is  $L$ -homogeneous, we prove the following lemma.

**Lemma 2.** If  $f : \mathbb{R}^d \rightarrow \mathbb{R}$  is locally-Lipschitz and  $L$ -homogeneous, then  $\forall w \in \mathbb{R}^d$  and  $\forall s \in \partial f(w)$ , we have

$$\langle s, w \rangle = Lf(w).$$

*Proof.* First, if  $w = 0$  then this is trivial, since  $f(0) = 0^L f(0) = 0$  by  $L$ -positive homogeneity. Now we handle  $w \neq 0$ . Let  $D = \{w : f \text{ is differentiable at } w\}$ . (This is almost everywhere by local-Lipschitzness and Radamacher’s theorem.) If  $w \in D \setminus \{0\}$ , then

$$\begin{aligned} 0 &= \lim_{\delta \downarrow 0} \frac{f(w + \delta w) - f(w) - \langle \nabla f(w), \delta w \rangle}{\delta \|w\|} \\ &= \lim_{\delta \downarrow 0} \frac{((1 + \delta)^L - 1) f(w)}{\delta \|w\|} - \frac{\langle \nabla f(w), w \rangle}{\|w\|} \\ &= \frac{Lf(w)}{\|w\|} - \frac{\langle \nabla f(w), w \rangle}{\|w\|} \end{aligned}$$

where we used  $L$ -positive homogeneity and the fact that  $\lim_{\delta \downarrow 0} \frac{((1+\delta)^L - 1)}{\delta}$  is the (right) derivative of  $z \mapsto z^L$  at 1. Now we can rearrange to conclude that  $\langle \nabla f(w), w \rangle = Lf(w)$ . This concludes this case, because since  $f$  is differentiable at  $w$ ,  $\partial f(w) = \{\nabla f(w)\}$ .

Now we handle the case that  $w \notin D \setminus \{0\}$  in two steps. Let  $s \in \partial f(w)$  be such that there exists a sequence  $(w_n) \rightarrow w$  such that  $\nabla f(w_n) \rightarrow s$  (not all  $s \in \partial f(w)$  are of this form so this is only the first step). Then since all  $(w_n)_n$  are contained in  $D$ , for each  $n$  it holds from previous cases that  $Lf(w_n) - \langle \nabla f(w_n), w_n \rangle = 0$ . Then by continuity of  $f$  and the inner product, as well as the fact that  $\nabla f(w_n) \rightarrow s$ , we may take the limit to conclude that  $Lf(w) - \langle s, w \rangle = 0$  as desired. Finally, all  $s \in \partial f(w)$  are by definition convex combinations of vectors  $s_1, \dots, s_k$  which are handled by the previous step, and thus writing  $s = \sum_{i=1}^k \alpha_i s_i$  where  $\sum_{i=1}^k \alpha_i = 1$ , using the result from the previous step we have that

$$\begin{aligned} \langle s, w \rangle &= \sum_{i=1}^k \alpha_i \langle s_i, w \rangle \\ &= \sum_{i=1}^k \alpha_i Lf(w) \\ &= Lf(w). \end{aligned}$$

□

## 4 Margin of Homogeneous Predictors

Now we move towards our main result on implicit regularization for neural networks. We will show for  $L$ -homogeneous predictors that a “soft” version of the margin is non-decreasing along the (non-smooth analogue of) gradient flow. Before we can do so, we first generalize the margin beyond linear classifiers.

**Definition 3.** For an  $L$ -homogeneous predictor  $f(\cdot; w)$  we define the margin on a single point  $(x_i, y_i)$  as

$$m_i(w) = y_i f(x_i; w).$$

The (overall) margin of  $f(\cdot; w)$  is

$$\gamma(w) = \min_i m_i \left( \frac{w}{\|w\|} \right) = \min_i \frac{m_i(w)}{\|w\|^L}.$$

Note that if  $f$  is a linear predictor then we recover the same definition as we have seen before. The margin of the maximum-margin predictor is

$$\bar{\gamma} = \max_{w: \|w\|=1} \gamma(w).$$

Instead of analyzing this “hard” version of margin, we will analyze the soft margin. For a (non-averaged) loss  $\mathcal{L}(w) = \sum_{i=1}^n \ell(y_i f(x_i; w))$  where  $\ell(\cdot)$  is monotonic, we define the soft margin as

$$\tilde{\gamma}(w) = \frac{\ell^{-1}(\mathcal{L}(w))}{\|w\|^L}.$$

In the sequel we will focus on the exponential loss  $\ell(z) = \exp(-z)$ . In this case the soft margin becomes

$$\tilde{\gamma}(w) = \frac{-\ln \sum_{i=1}^n \exp(-y_i f(x_i; w))}{\|w\|^L} = \frac{-\ln \sum_{i=1}^n \exp(-m_i(w))}{\|w\|^L}.$$

Our separability assumption on the dataset will be that there exists  $w$  such that  $\tilde{\gamma}(w) > 0$ .

## 5 Main Result

We will analyze the flow given by the differential inclusion equation  $\dot{w}(t) \in -\partial \ln \sum_{i=1}^n \exp(-m_i(w(t)))$ , but first we prove a final useful lemma.

**Lemma 4.** For all  $w \in \mathbb{R}^d$ , if  $v \in -\partial \ln \sum_{i=1}^n \exp(-m_i(w))$  and if the chain rule holds, then

$$-L \ln \sum_{i=1}^n \exp(-m_i(w)) \leq \langle v, w \rangle.$$

*Proof.* Fix such a  $v$ . Then by the chain rule, for each  $i = 1, \dots, n$  there exists  $v_i \in \partial m_i(w)$  such that

$$v = \sum_{i=1}^n \frac{\exp(-m_i(w)) v_i}{\sum_{j=1}^n \exp(-m_j(w))}.$$

Then we can calculate

$$\begin{aligned} \langle v, w \rangle &= \sum_{i=1}^n \frac{\exp(-m_i(w))}{\sum_{j=1}^n \exp(-m_j(w))} \langle v_i, w \rangle \\ &= \sum_{i=1}^n \frac{\exp(-m_i(w))}{\sum_{j=1}^n \exp(-m_j(w))} L m_i(w) \\ &= \sum_{i=1}^n \frac{\exp(-m_i(w))}{\sum_{j=1}^n \exp(-m_j(w))} (-L \ln(\exp(-m_i(w)))) \\ &\geq \sum_{i=1}^n \frac{\exp(-m_i(w))}{\sum_{j=1}^n \exp(-m_j(w))} \left( -L \ln \left( \sum_{k=1}^n \exp(-m_k(w)) \right) \right) \\ &= -L \ln \left( \sum_{k=1}^n \exp(-m_k(w)) \right) \sum_{i=1}^n \frac{\exp(-m_i(w))}{\sum_{j=1}^n \exp(-m_j(w))} \\ &= -L \ln \left( \sum_{k=1}^n \exp(-m_k(w)) \right) \end{aligned}$$

where the second step made use of lemma 2 and the inequality used the fact that  $-\ln$  is monotonically decreasing.  $\square$

**Theorem 5.** For the flow with  $w(0) = 0$ ,  $\dot{w}(t) \in -\partial \ln \sum_{i=1}^n \exp(-m_i(w(t)))$ , assuming that the chain rule holds for almost all  $t \geq 0$  and assuming that there exists  $t_0$  such that  $\tilde{\gamma}(w(t_0)) > 0$ , then  $\tilde{\gamma}(w(t))$  is non-decreasing for  $t \geq t_0$ .

*Proof.* For convenience let  $\tilde{\gamma}(t) = \tilde{\gamma}(w(t))$ . Appealing to the fundamental theorem of calculus, we want to show that  $\frac{d}{dt}\tilde{\gamma}(t) \geq 0 \forall t \geq t_0$ . Fix an arbitrary  $t \geq t_0$  and define

$$u(t) = -\ln \sum_{i=1}^n \exp(-m_i(w(t))), \quad v(t) = \|w(t)\|^L,$$

so that

$$\tilde{\gamma}(t) = \frac{u(t)}{v(t)}.$$

Then

$$\frac{d}{dt}\tilde{\gamma}(t) = \frac{\dot{u}(t)v(t) - u(t)\dot{v}(t)}{v(t)^2}.$$

Note that when  $\tilde{\gamma}(t) > 0$  we must have  $w \neq 0$  so  $v(t) > 0$ . Now we analyze both  $\dot{u}(t)$  and  $\dot{v}(t)$ . Since  $\dot{w}(t) \in \partial u(t)$  and we assume the chain rule holds, we have for almost all  $t$  that

$$\begin{aligned} \dot{u}(t) &= \|\dot{w}(t)\|^2 \\ &\geq \|\dot{w}(t)\| \left\langle \frac{w(t)}{\|w(t)\|}, \dot{w}(t) \right\rangle \\ &\geq \frac{Lu(t)\|\dot{w}(t)\|}{\|w(t)\|} \end{aligned}$$

where the first inequality was by Cauchy-Schwarz and the second was by lemma 4. Next, again using Cauchy-Schwarz

$$\begin{aligned} \dot{v}(t) &= L\|w(t)\|^{L-1} \left\langle \frac{w(t)}{\|w(t)\|}, \dot{w}(t) \right\rangle \\ &\leq L\|w(t)\|^{L-1}\|\dot{w}(t)\|. \end{aligned}$$

Using these upper and lower bounds we have that

$$\begin{aligned} \dot{u}(t)v(t) - u(t)\dot{v}(t) &\geq \frac{Lu(t)\|\dot{w}(t)\|}{\|w(t)\|}v(t) - u(t)L\|w(t)\|^{L-1}\|\dot{w}(t)\| \\ &= u(t)L\|w(t)\|^{L-1}\|\dot{w}(t)\| - u(t)L\|w(t)\|^{L-1}\|\dot{w}(t)\| \\ &= 0 \end{aligned}$$

(where  $v(t) > 0$  as explained above and also  $u(t) > 0$  because  $\tilde{\gamma}(t) > 0$ ). □