

# CS 764: Topics in Database Management Systems Lecture 9: B-tree Locking

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#### Today's Paper: B-tree Locking

#### Efficient Locking for Concurrent Operations on B-Trees

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The B-tree and its variants have been found to be highly useful (both theoretically and in practice) for storing large amounts of information, especially on secondary storage devices. We examine the problem of overcoming the inherent difficulty of concurrent operations on such structures, using a practical storage model. A single additional "link" pointer in each node allows a process to easily recover from tree modifications performed by other concurrent processes. Our solution compares favorably with earlier solutions in that the locking scheme is simpler (no read-locks are used) and only a (small) constant number of nodes are locked by any update process at any given time. An informal correctness proof for our system is given.

Key Words and Phrases: database, data structures, B-tree, index organizations, concurrent algorithms, concurrency controls, locking protocols, correctness, consistency, multiway search trees CR Categories: 3.73, 3.74, 4.32, 4.33, 4.34, 5.24

#### 1. INTRODUCTION

The B-tree [2] and its variants have been widely used in recent years as a data structure for storing large files of information, especially on secondary storage devices [7]. The guaranteed small (average) search, insertion, and deletion time for these structures makes them quite appealing for database applications.

A topic of current interest in database design is the construction of databases that can be manipulated concurrently and correctly by several processes. In this

#### ACM Trans. Database Syst. 1981

### Agenda

Index in OLTP database

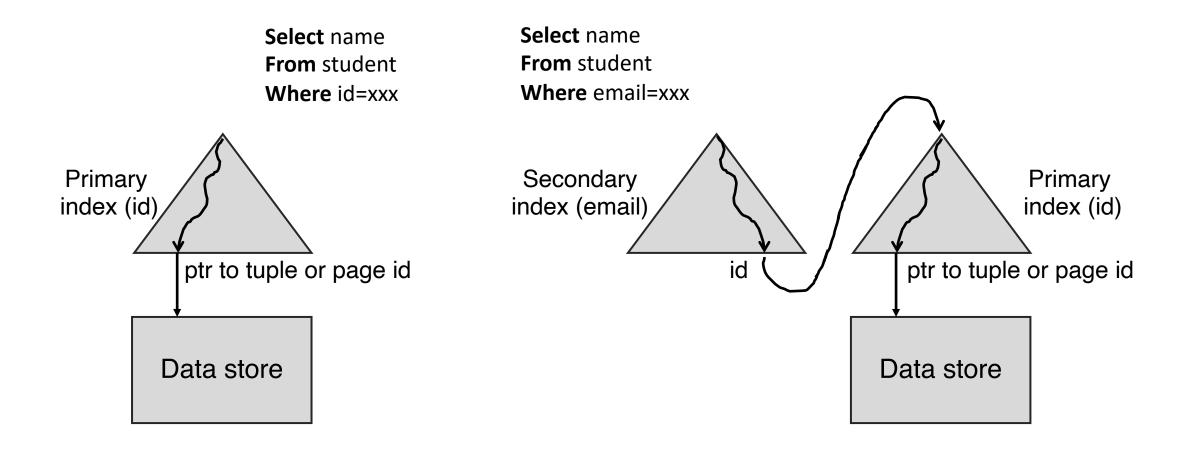
B tree, B+ tree, and B\* tree

B<sup>link</sup>-tree

#### Index in an OLTP Database

Select name **From** student Where id=xxx Primary index (id) ptr to tuple or page id Data store

## Index in an OLTP Database

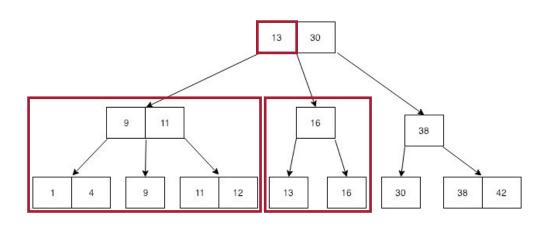


#### **B-tree**

#### Balanced tree data structure

- Data is sorted
- Supports: search, sequential scan, insets, and deletes

Algorithm	Average	Worst case
Space	O(n)	O(n)
Search	O(log n)	O(log n)
Insert	O(log n)	O(log n)
Delete	O(log n)	O(log n)



#### **B-tree**

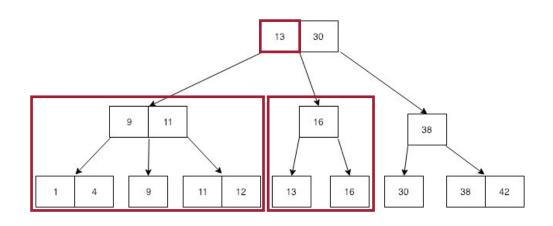
#### Balanced tree data structure

- Data is sorted
- Supports: search, sequential scan, inserts, and deletes

Properties

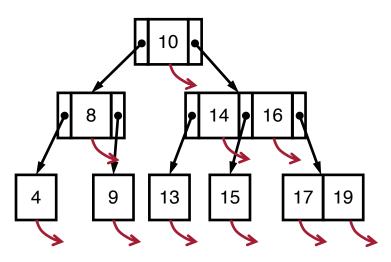
- Every node has at most *m* children.
- Every non-leaf node (except root) has at least [m/2] child nodes.
- All the leaf nodes of the B-tree must be at the same level.

Algorithm	Average	Worst case
Space	O(n)	O(n)
Search	O(log n)	O(log n)
Insert	O(log n)	O(log n)
Delete	O(log n)	O(log n)



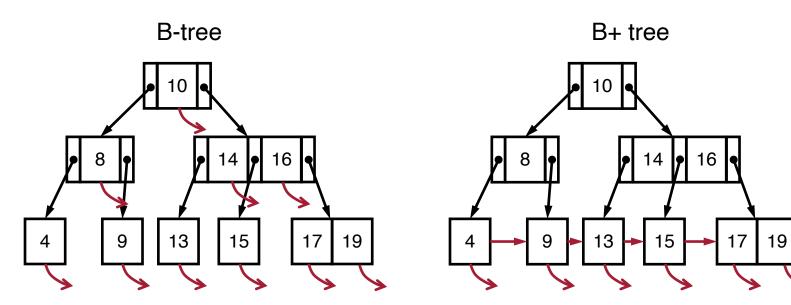
#### B-tree vs. B+ Tree vs. B\* Tree

**B-tree** 



B-tree: data pointers stored in all nodes

#### B-tree vs. B+ Tree vs. B\* Tree

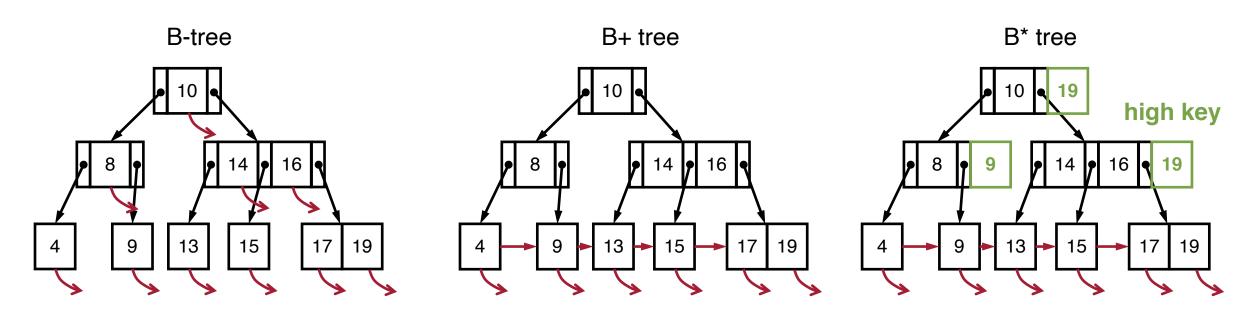


B-tree: data pointers stored in all nodes

B+ tree:

- Data pointers stored only in leaf nodes
- The leaf nodes are linked

#### B-tree vs. B+ Tree vs. B\* Tree



B-tree: data pointers stored in all nodes

B+ tree:

- Data pointers stored only in leaf nodes
- The leaf nodes are linked

B\* tree is a misused term in B-tree literature

- Typically means a variant of B+ tree in which each node is least 2/3 full
- In this paper: B+ tree with high key appended to non-leaf nodes (upper bound on values)

#### **B\* Tree Structure**

Within each node, keys in ascending order

Each node contains at least k keys and at most 2k keys (k is a tree parameter)

Values stored in a subtree are bounded by the the two key values

 $K_{i-1} < v \leq K_i$ 

Example: search key 53

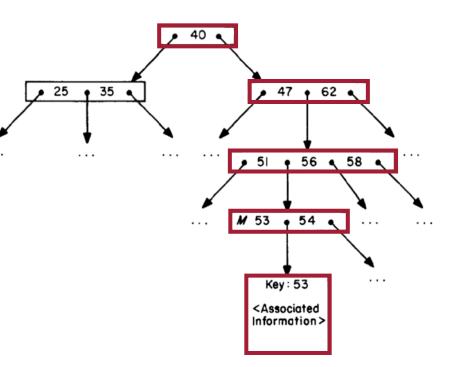
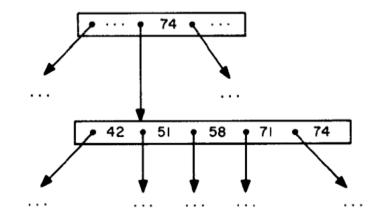


Fig. 2. An example B<sup>\*</sup>-tree (with parameter k = 2).

#### **B\*** Tree Insertion

Insert to leaf if the leaf node has fewer than *2k* entries

If leaf has 2k entries, split the node into two nodes (split may happen recursively)



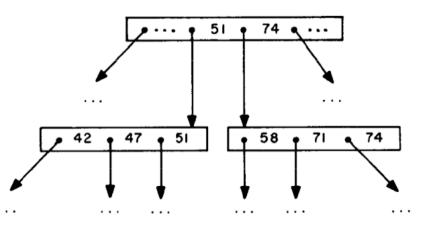
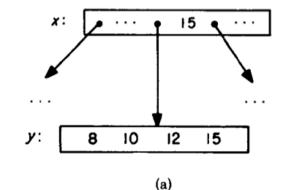


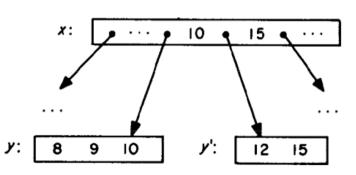
Fig. 4. Splitting a node after adding "47" (k = 2).

# **Challenge of Concurrent Operations**

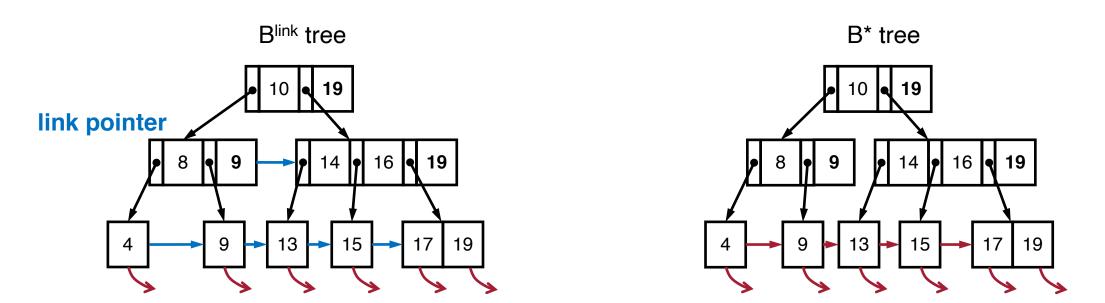
Concurrent search and insert operations may cause problems

	search(15)	insert(9)
1.	$\overline{C} \leftarrow \operatorname{read}(x)$	i
2.		$A \leftarrow \operatorname{read}(x)$
3.	examine C; get ptr to y	
4.		examine $A$ ; get ptr to $y$
5.		$A \leftarrow \operatorname{read}(y)$
6.		insert 9 into $A$ ; must split into $A, B$
7.		put(B, y')
8.		put(A, y)
9.		Add to node x a pointer to node $y'$ .
10.	$C \leftarrow \operatorname{read}(y)$	
11.	error: 15 not found!	





#### B<sup>link</sup>-Tree

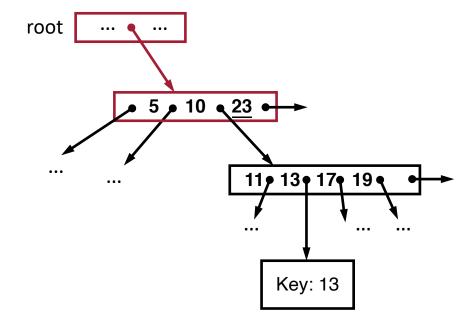


Adds a link field that points to the next node at the same level of the tree as the current node

The link pointer of the rightmost node on a level is a null pointer

# Blink-Tree: Search Algorithm

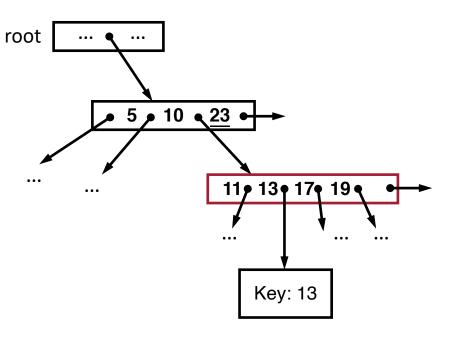
current $\leftarrow$ root;	/* Get ptr to root node */
$A \leftarrow \text{get(current)};$	/* Read node into memory */
while current is not a leaf do	
begin	/* Scan through tree */
current $\leftarrow$ scannode(v, A);	/* Find correct (maybe link) ptr */
$A \leftarrow \text{get(current)}$	/* Read node into memory */
end;	
	/* Now we have reached leaves. */
while $t \leftarrow \text{scannode}(v, A) = \text{link ptr of } A \text{ do}$	
	/* Keep moving right if necessary */
begin	
current $\leftarrow t$ ;	
$A \leftarrow \text{get}(\text{current})$	/* Get node */
end;	,,
	the leaf node in which $v$ should exist. */
if v is in A then done "success" else done "failu	



Example: search Key=13

# Blink-Tree: Search Algorithm

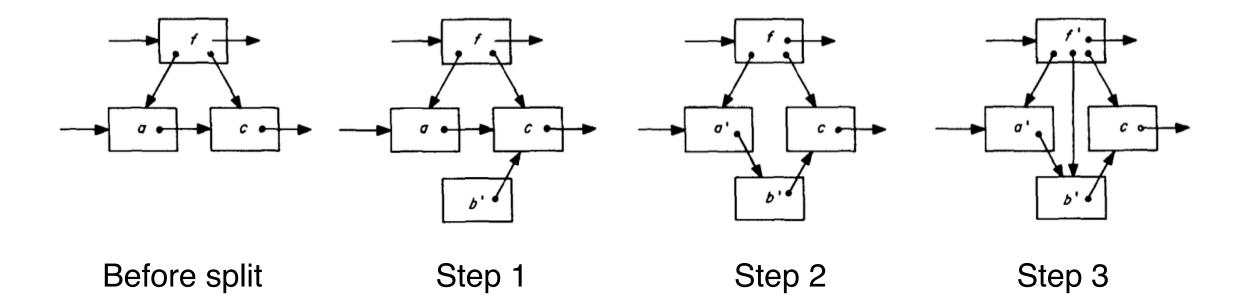
<b>procedure</b> search(v)	
current $\leftarrow$ root;	/* Get ptr to root node */
$A \leftarrow \text{get(current)};$	/* Read node into memory */
while current is not a leaf do	,
begin	/* Scan through tree */
current $\leftarrow$ scannode(v, A);	/* Find correct (maybe link) ptr */
$A \leftarrow \text{get}(\text{current})$	/* Read node into memory */
end;	
	/* Now we have reached leaves. */
while $t \leftarrow \text{scannode}(v, A) = \text{link ptr of } A$	A do
	/* Keep moving right if necessary */
begin	
current $\leftarrow t$ ;	
$A \leftarrow \text{get}(\text{current})$	/* Get node */
end;	
/* Now	we have the leaf node in which $v$ should exist. */
if $v$ is in A then done "success" else don	ne "failure"

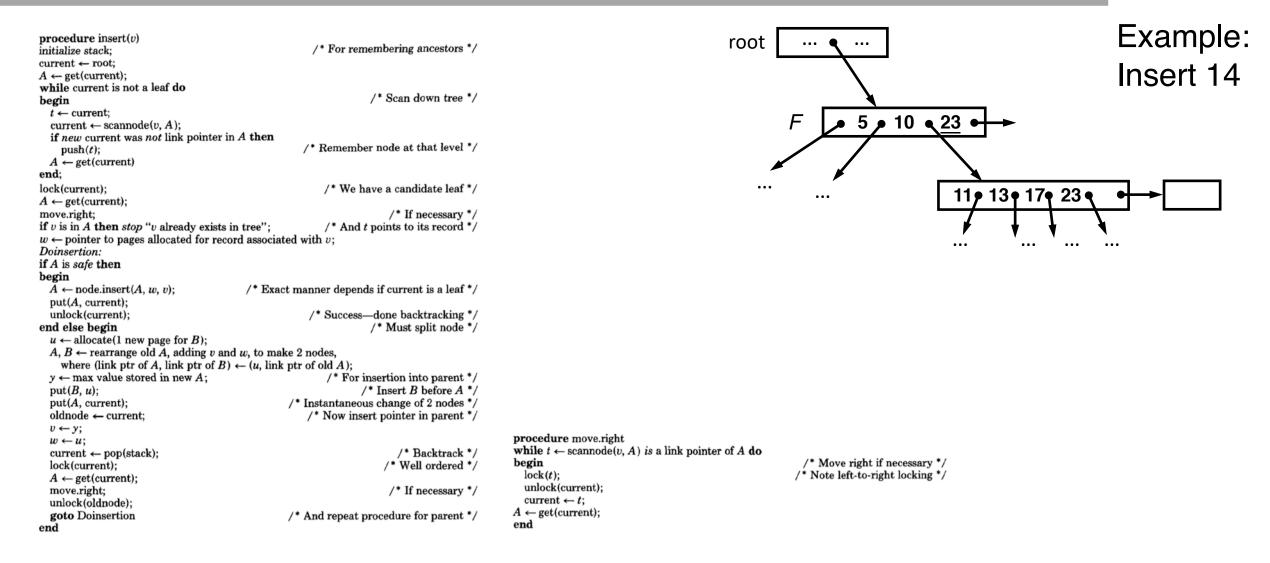


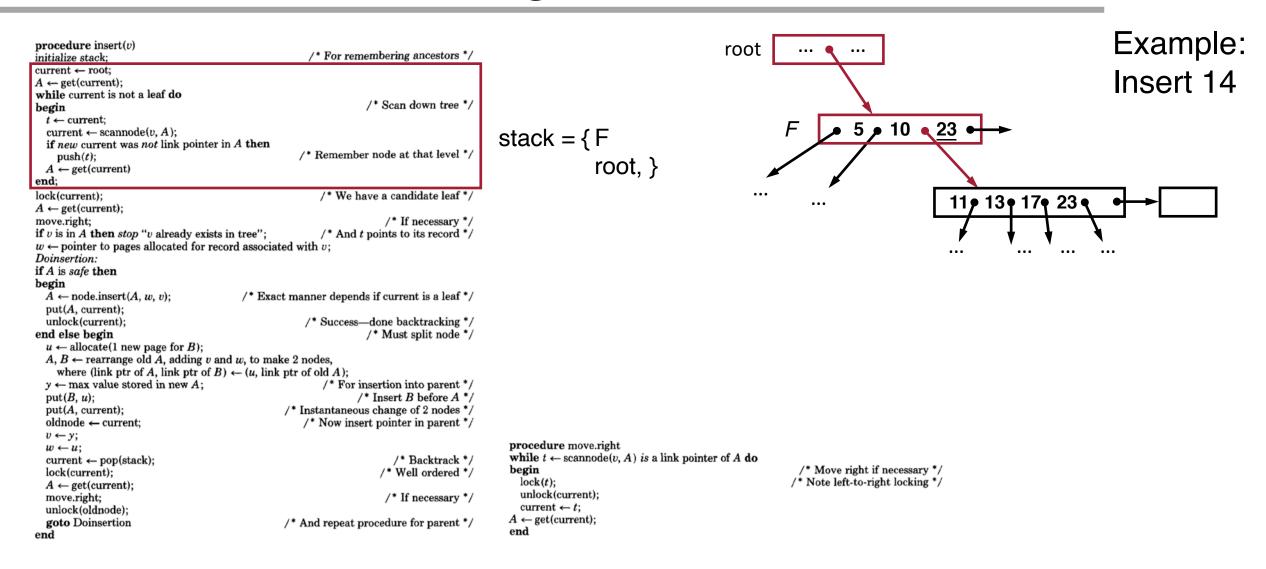
#### Example: search Key=13

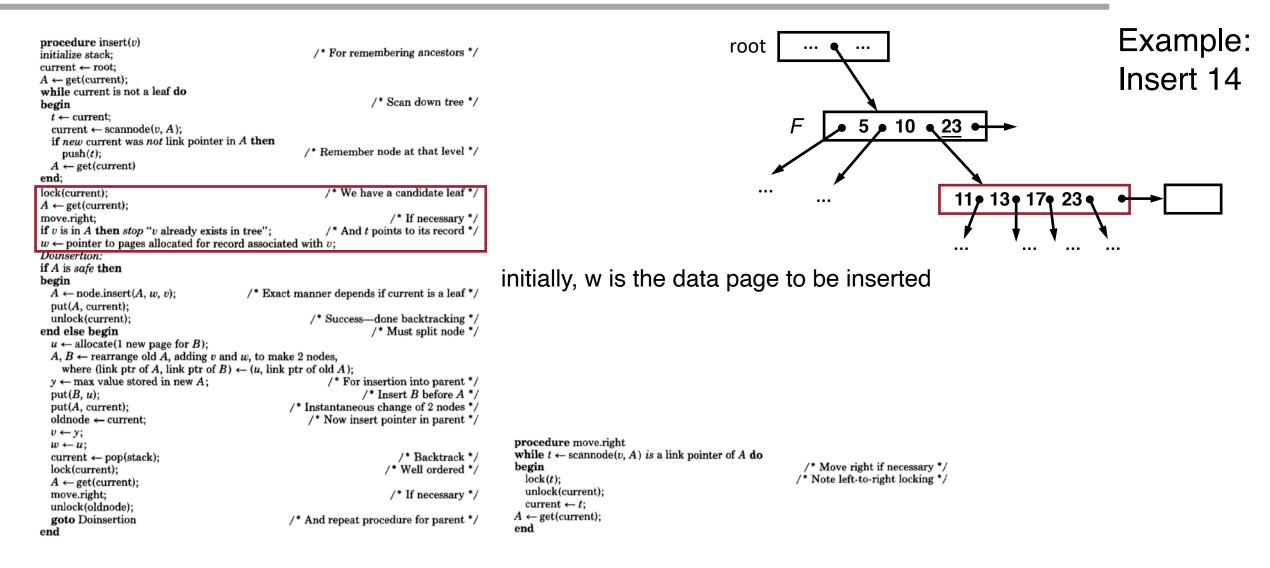
Insert to leaf if the leaf node if not full

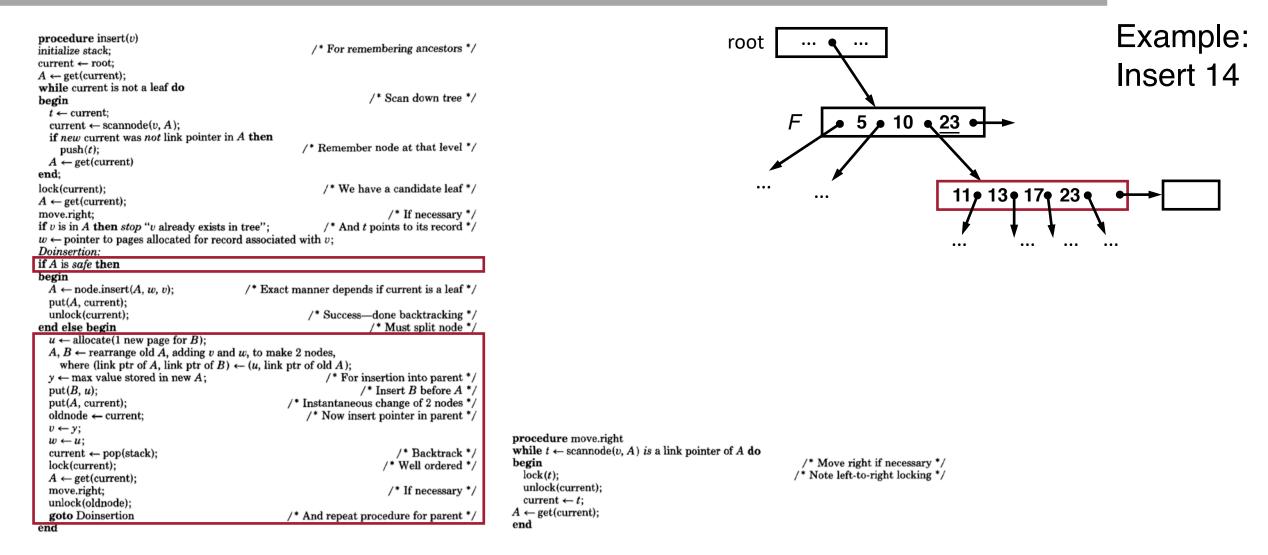
Illustration of node split (node *a* is split into *a*' and *b*')

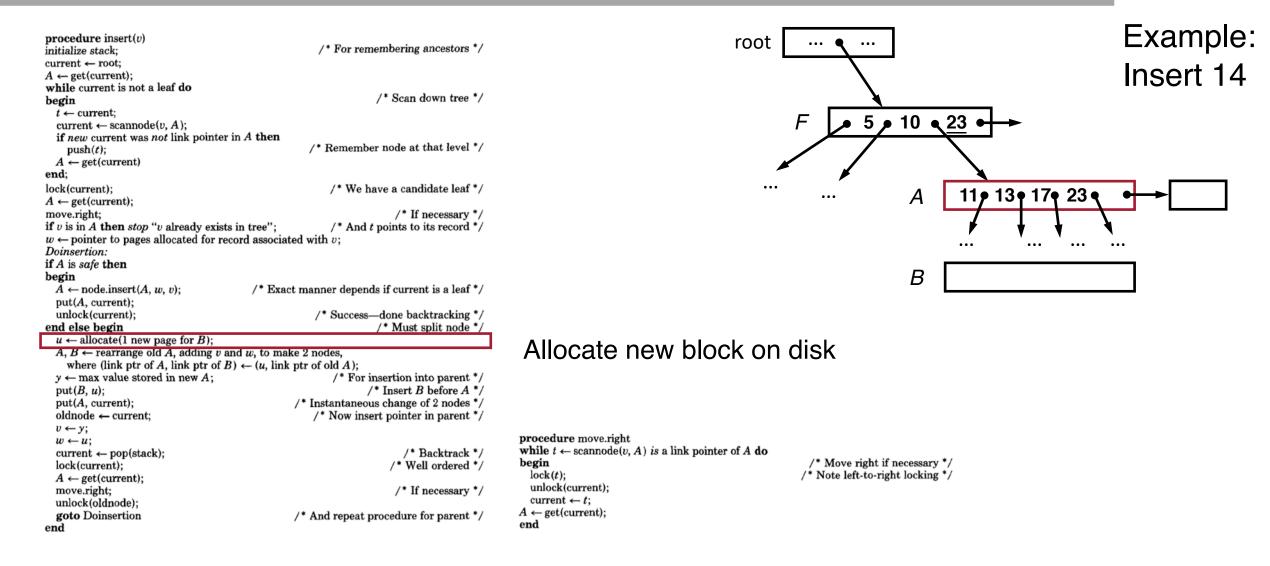


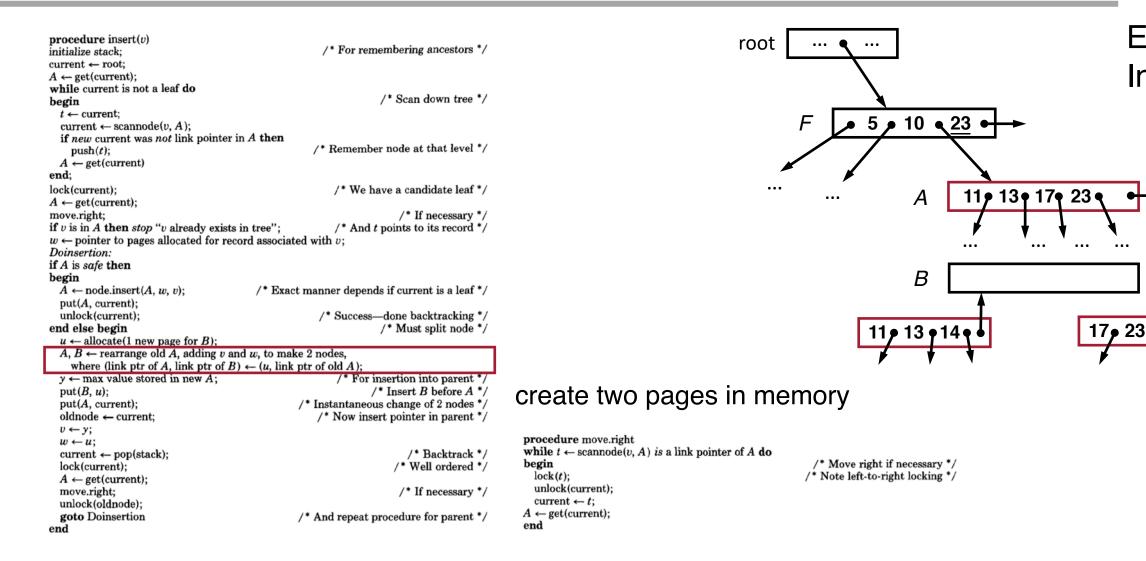










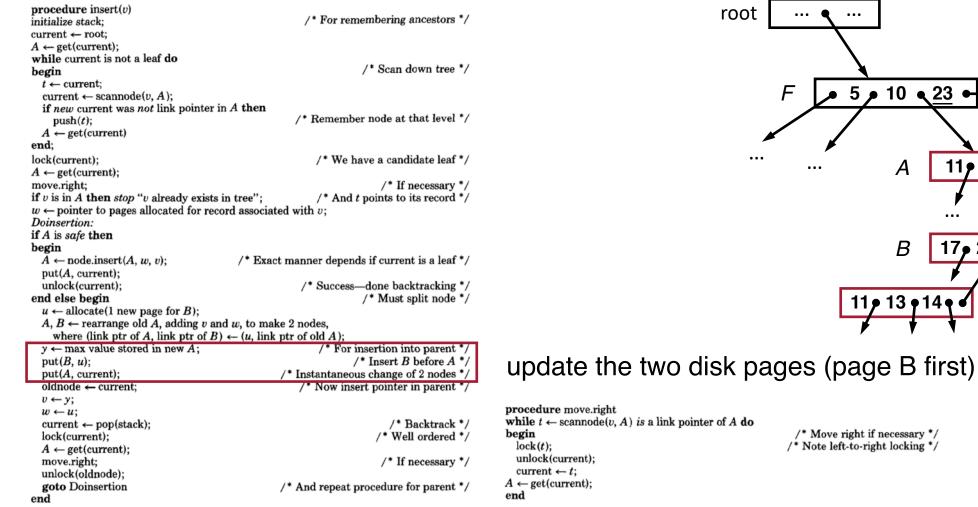


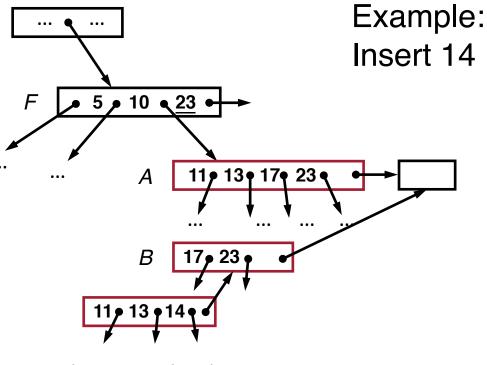
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Example:

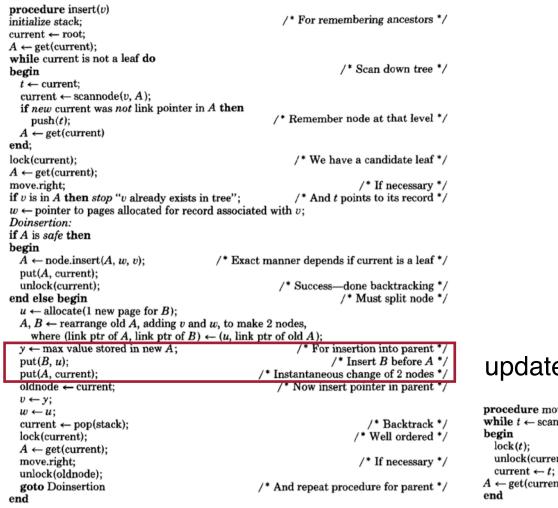
Insert 14

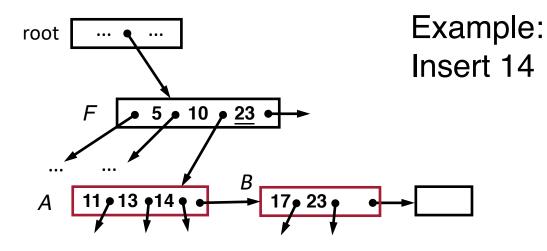
...





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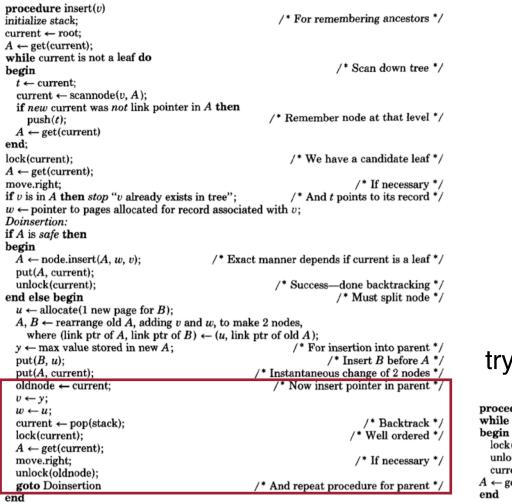


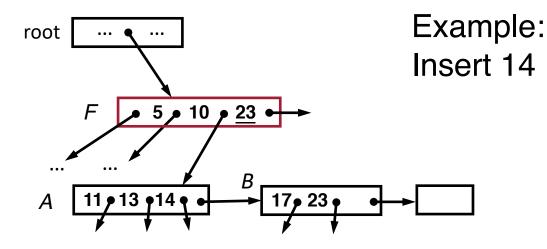


procedure move.right while  $t \leftarrow \text{scannode}(v, A)$  is a link pointer of A do

unlock(current);  $A \leftarrow get(current);$ 

#### /\* Move right if necessary \*/ /\* Note left-to-right locking \*/





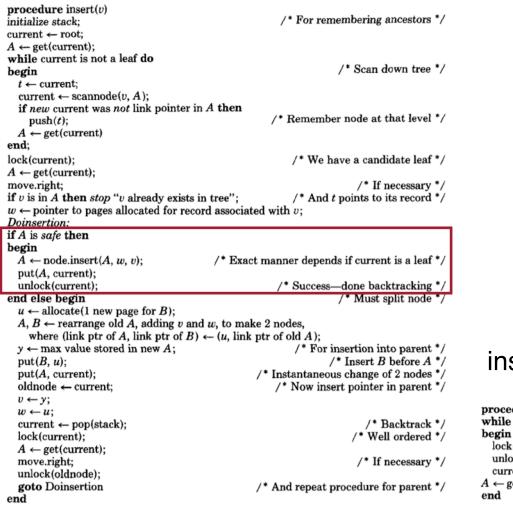
try to insert (key=14, ptr=B) to F

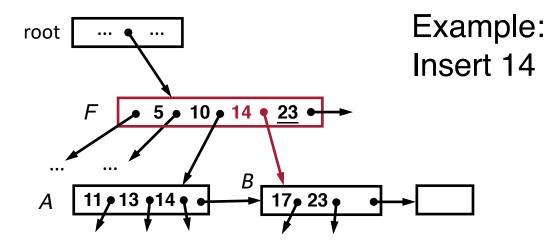
procedure move.right while  $t \leftarrow \text{scannode}(v, A)$  is a link pointer of A do

lock(t); unlock(current); current  $\leftarrow t$ ;  $A \leftarrow get(current);$ 

#### /\* Move right if necessary \*/

/\* Note left-to-right locking \*/

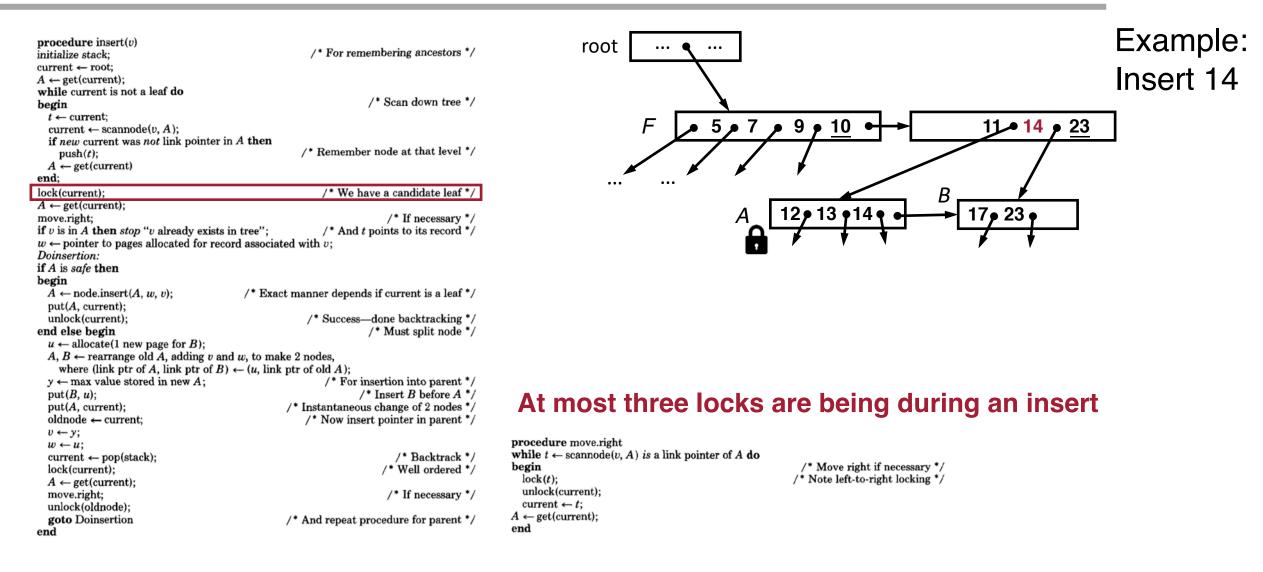


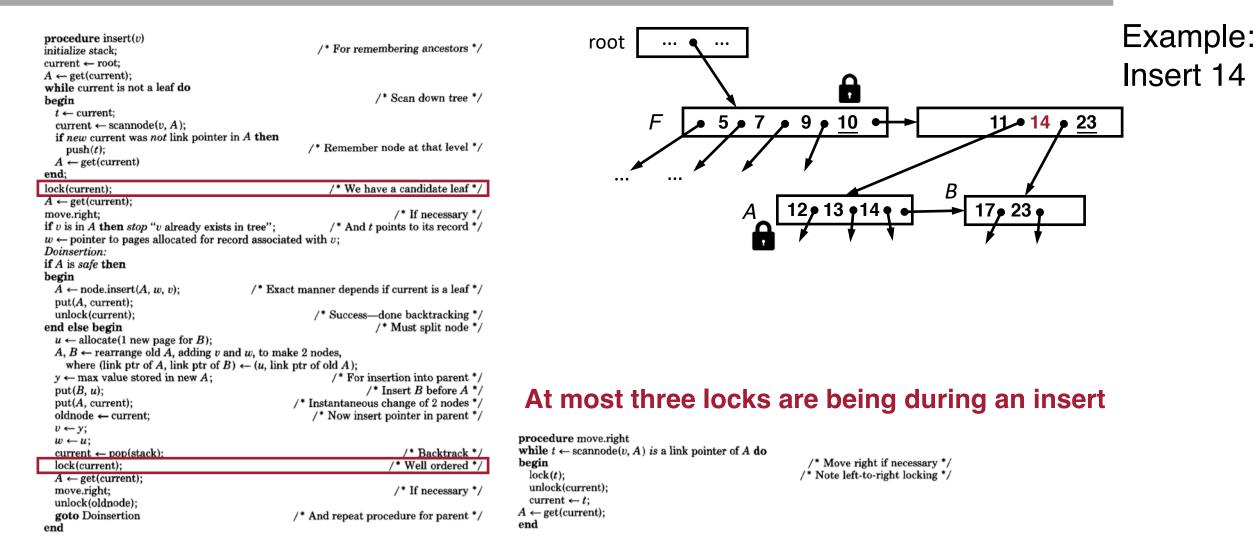


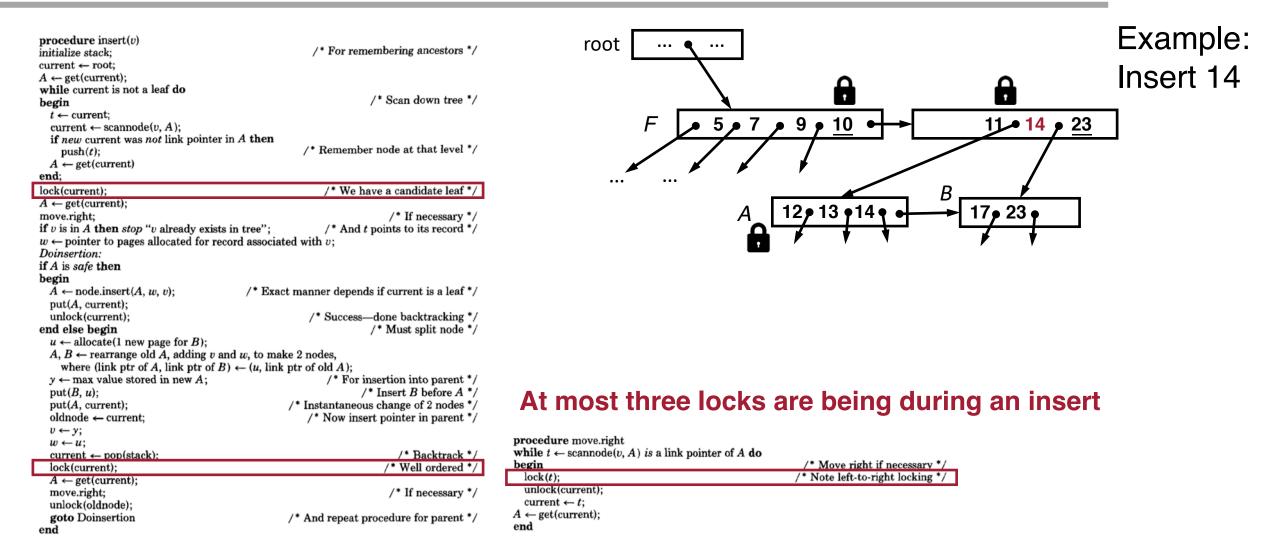
insert (key=14, ptr=B) to F

**procedure** move.right while  $t \leftarrow \text{scannode}(v, A)$  is a link pointer of A do

lock(t); unlock(current); current  $\leftarrow t$ ;  $A \leftarrow get(current);$  /\* Move right if necessary \*/ /\* Note left-to-right locking \*/





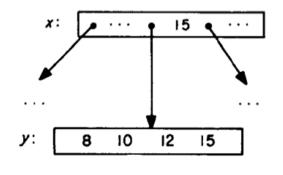


# **Revisit Concurrent Operations**

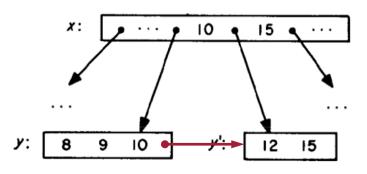
1. $\frac{\text{search}(15)}{C \leftarrow \text{read}(x)}$	insert(9)
2.	$A \leftarrow \operatorname{read}(x)$
3. examine C; get ptr to y	
4. 5.	examine $A$ ; get ptr to $y$
5.	$A \leftarrow \operatorname{read}(y)$
6.	insert 9 into $A$ ; must split into $A, B$
7.	put(B, y')
8.	put(A, y)
9	Add to node x a pointer to node $y'$ .
10. $C \leftarrow \text{read}(y)$	
11. error: 15 not found!	

key=15 is less than max key in node y

# Follow the link ptr to the next leaf node and 15 is found!







# **Other Issues**

Delete: allow fewer than k entries in a leaf node

• Observations: insertions are much more frequent than deletions

Deadlock freedom: locks are acquired bottom-up and left to right => total order

Livelock: keep following the link pointer due to node splits

# Q/A – B-tree Locking

B+ tree vs. B\* tree?

- Which variant of B-tree are modern DBMSs using?
- Would a left pointer add benefit?
- Experimental comparison
- What's the typical value of *k*?
- Binary search within a node?
- Disk utilization w.r.t. deletion

Deadlock vs. livelock?

### **Before Next Lecture**

Submit review before next lecture

C. Mohan, et al. <u>ARIES: A Transaction Recovery Method Supporting Fine-Granularity Locking and Partial Rollbacks Using Write-Ahead Logging</u>. ACM Trans. Database Syst. 1992.