

When do We Run a Compiler?

- **Prior to execution**

This is standard. We compile a program once, then use it repeatedly.

- **At the start of each execution**

We can incorporate values known at the start of the run to improve performance.

A program may be partially compiled, then completed with values set at execution-time.

- **During execution**

Unused code need not be compiled. Active or “hot” portions of a program may be specially optimized.

- **After execution**

We can profile a program, looking for heavily used routines, which can be specially optimized for later runs.

WHAT do COMPILERS PRODUCE?

Pure Machine Code

Compilers may generate code for a particular machine, not assuming any operating system or library routines. This is “pure code” because it includes nothing beyond the instruction set. This form is rare; it is sometimes used with system implementation languages, that define operating systems or embedded applications (like a programmable controller). Pure code can execute on bare hardware without dependence on any other software.

Augmented Machine Code

Commonly, compilers generate code for a machine architecture *augmented* with operating system routines and run-time language support routines.

To use such a program, a particular operating system must be used and a collection of run-time support routines (I/O, storage allocation, mathematical functions, etc.) must be available. The combination of machine instruction and OS and run-time routines define a *virtual machine*—a computer that exists only as a hardware/software combination.

Virtual Machine Code

Generated code can consist *entirely* of virtual instructions (no native code at all). This allows code to run on a variety of computers.

Java, with its JVM (Java Virtual Machine) is a great example of this approach.

If the virtual machine is kept simple and clean, its interpreter can be easy to write. Machine interpretation slows execution by a factor of 3:1 to perhaps 10:1 over compiled code.

A “Just in Time” (*JIT*) compiler can translate “hot” portions of virtual code into native code to speed execution.

Advantages of Virtual Instructions

Virtual instructions serve a variety of purposes.

- They simplify a compiler by providing suitable primitives (such as method calls, string manipulation, and so on).
- They aid compiler transportability.
- They may decrease in the size of generated code since instructions are designed to match a particular programming language (for example, JVM code for Java).

Almost all compilers, to a greater or lesser extent, generate code for a virtual machine, some of whose operations must be interpreted.

FORMATS OF TRANSLATED PROGRAMS

Compilers differ in the format of the target code they generate. Target formats may be categorized as *assembly language*, *relocatable binary*, or *memory-image*.

- **Assembly Language (Symbolic) Format**

A text file containing assembler source code is produced. A number of code generation decisions (jump targets, long vs. short address forms, and so on) can be left for the assembler. This approach is good for instructional projects.

Generating assembler code supports *cross-compilation* (running a compiler on one computer, while its target is a second computer). Generating assembly language also simplifies debugging and understanding a compiler (since you can see the generated code).

C (rather than a specific assembly language) can be generated, treating C as a “universal assembly language.”

C is far more machine-independent than any particular assembly language. However, some aspects of a program (such as the run-time representations of program and data) are inaccessible using C code, but readily accessible in assembly language.

- **Relocatable Binary Format**

Target code may be generated in a *binary format* with external references and local instruction and data addresses are not yet bound. Instead, addresses are assigned relative to the beginning of the module or relative to symbolically named locations. A *linkage* step adds support libraries and other separately compiled routines and produces an absolute binary program format that is executable.

- **Memory-Image (Absolute Binary) Form**

Compiled code may be loaded into memory and immediately executed. This is faster than going through the intermediate step of link/editing. The ability to access library and precompiled routines may be limited. The program must be recompiled for each execution. Memory-image compilers are useful for student and debugging use, where frequent changes are the rule and compilation costs far exceed execution costs.

Java is designed to use and share classes designed and implemented at a variety of sites. Rather than use a fixed copy of a class (which may be outdated), the JVM supports *dynamic linking* of externally defined classes. When first referenced, a class definition may be remotely fetched, checked, and loaded during program execution. In this way “foreign code” can be guaranteed to be up-to-date and secure.

THE STRUCTURE OF A COMPILER

A compiler performs two major tasks:

- Analysis of the source program being compiled
- Synthesis of a target program

Almost all modern compilers are *syntax-directed*: The compilation process is driven by the syntactic structure of the source program.

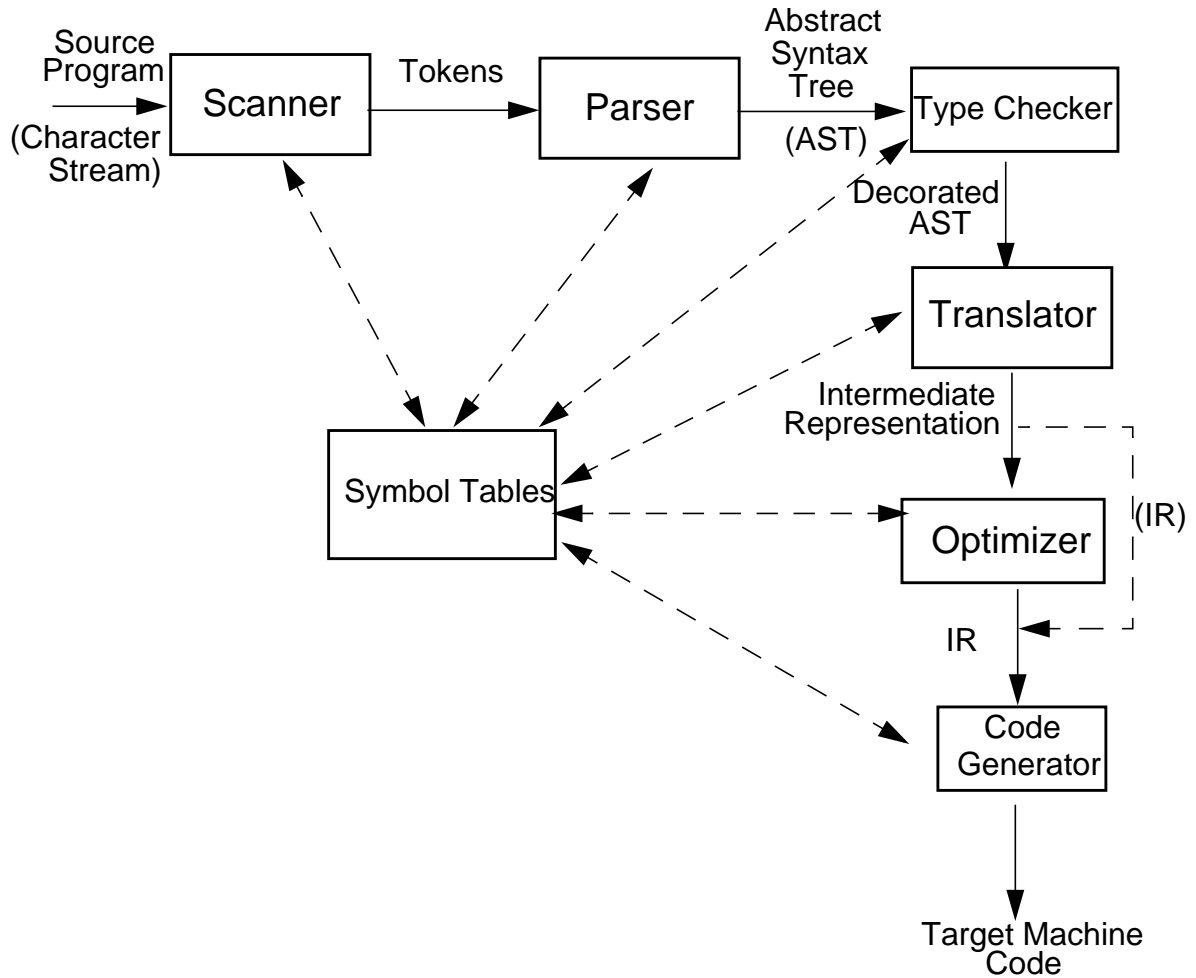
A parser builds semantic structure out of tokens, the elementary symbols of programming language syntax. Recognition of syntactic structure is a major part of the analysis task.

Semantic analysis examines the meaning (semantics) of the program. Semantic analysis plays a dual role.

It finishes the analysis task by performing a variety of correctness checks (for example, enforcing type and scope rules). Semantic analysis also begins the synthesis phase.

The synthesis phase may translate source programs into some intermediate representation (IR) or it may directly generate target code.

If an IR is generated, it then serves as input to a *code generator* component that produces the desired machine-language program. The IR may optionally be transformed by an *optimizer* so that a more efficient program may be generated.



The Structure of a Syntax-Directed Compiler

SCANNER

The scanner reads the source program, character by character. It groups individual characters into tokens (identifiers, integers, reserved words, delimiters, and so on). When necessary, the actual character string comprising the token is also passed along for use by the semantic phases.

The scanner:

- Puts the program into a compact and uniform format (a stream of tokens).
- Eliminates unneeded information (such as comments).
- Sometimes enters preliminary information into symbol tables (for

- example, to register the presence of a particular label or identifier).
- Optionally formats and lists the source program

Building tokens is driven by token descriptions defined using *regular expression* notation.

Regular expressions are a formal notation able to describe the tokens used in modern programming languages. Moreover, they can drive the *automatic generation* of working scanners given only a specification of the tokens. Scanner generators (like Lex, Flex and JLex) are valuable compiler-building tools.

PARSER

Given a syntax specification (as a context-free grammar, CFG), the parser reads tokens and groups them into language structures.

Parsers are typically created from a CFG using a parser generator (like Yacc, Bison or Java CUP).

The parser verifies correct syntax and may issue a syntax error message.

As syntactic structure is recognized, the parser usually builds an abstract syntax tree (AST), a concise representation of program structure, which guides semantic processing.

Type Checker (SEMANTIC ANALYSIS)

The type checker checks the *static semantics* of each AST node. It verifies that the construct is legal and meaningful (that all identifiers involved are declared, that types are correct, and so on).

If the construct is semantically correct, the type checker “decorates” the AST node, adding type or symbol table information to it. If a semantic error is discovered, a suitable error message is issued.

Type checking is purely dependent on the semantic rules of the source language. It is independent of the compiler’s target machine.

TRANSLATOR (PROGRAM SYNTHESIS)

If an AST node is semantically correct, it can be translated. Translation involves capturing the run-time “meaning” of a construct.

For example, an AST for a while loop contains two subtrees, one for the loop’s control expression, and the other for the loop’s body. *Nothing* in the AST shows that a while loop loops! This “meaning” is captured when a while loop’s AST is translated. In the IR, the notion of testing the value of the loop control expression,

and conditionally executing the loop body becomes explicit.

The translator is dictated by the semantics of the source language. Little of the nature of the target machine need be made evident. Detailed information on the nature of the target machine (operations available, addressing, register characteristics, etc.) is reserved for the code generation phase.

In simple non-optimizing compilers (like our class project), the translator generates target code directly, without using an IR.

More elaborate compilers may first generate a high-level IR

(that is source language oriented) and then subsequently translate it into a low-level IR (that is target machine oriented). This approach allows a cleaner separation of source and target dependencies.

OPTIMIZER

The IR code generated by the translator is analyzed and transformed into functionally equivalent but improved IR code by the optimizer.

The term optimization is misleading: we don't always produce the best possible translation of a program, even after optimization by the best of compilers.

Why?

Some optimizations are *impossible* to do in all circumstances because they involve an undecidable problem. Eliminating unreachable (“dead”) code is, in general, impossible.

Other optimizations are too expensive to do in all cases. These involve NP-complete problems, believed to be inherently exponential.

Assigning registers to variables is an example of an NP-complete problem.

Optimization can be complex; it may involve numerous subphases, which may need to be applied more than once.

Optimizations may be turned off to speed translation.

Nonetheless, a well designed optimizer can significantly speed program execution by simplifying, moving or eliminating unneeded computations.

Code Generator

IR code produced by the translator is mapped into target machine code by the code generator. This phase uses detailed information about the target machine and includes machine-specific optimizations like *register allocation* and *code scheduling*.

Code generators can be quite complex since good target code requires consideration of many special cases.

Automatic generation of code generators is possible. The basic approach is to match a low-level IR to target instruction templates, choosing

instructions which best match each IR instruction.

A well-known compiler using automatic code generation techniques is the GNU C compiler. GCC is a heavily optimizing compiler with machine description files for over ten popular computer architectures, and at least two language front ends (C and C++).

Symbol Tables

A symbol table allows information to be associated with identifiers and shared among compiler phases. Each time an identifier is used, a symbol table provides access to the information collected about the identifier when its declaration was processed.

Example

Our source language will be **CSX**, a blend of C, C++ and Java.

Our target language will be the Java JVM, using the Jasmin assembler.

- A simple source line is

a = bb+abs(c-7);

this is a sequence of ASCII characters in a text file.

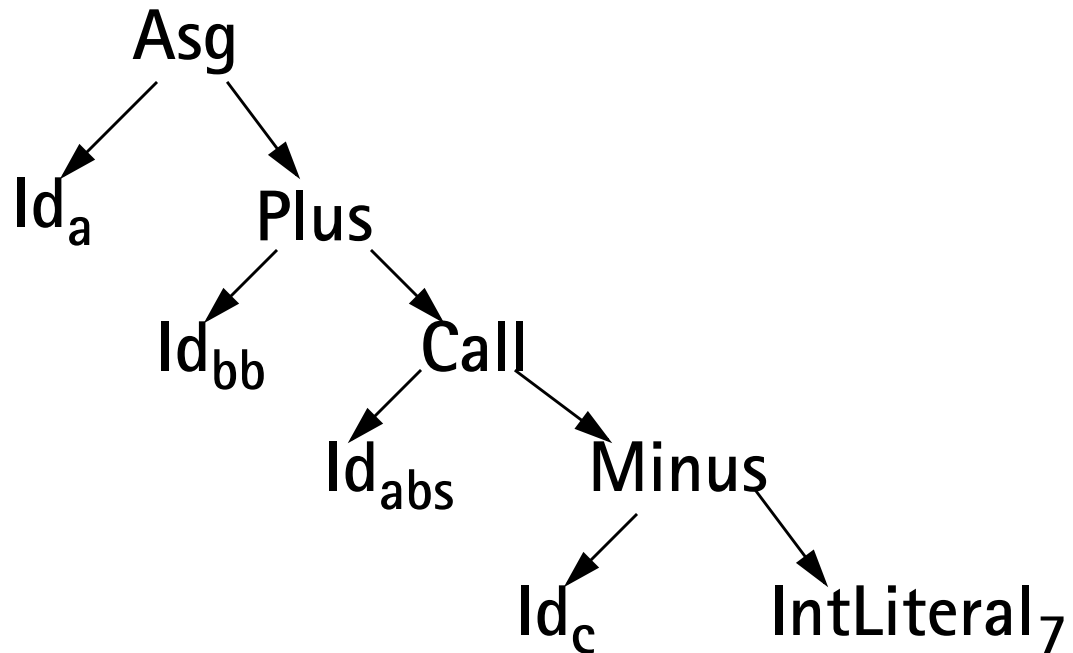
- The scanner groups characters into tokens, the basic units of a program.

a = bb+abs(c-7);

After scanning, we have the following token sequence:

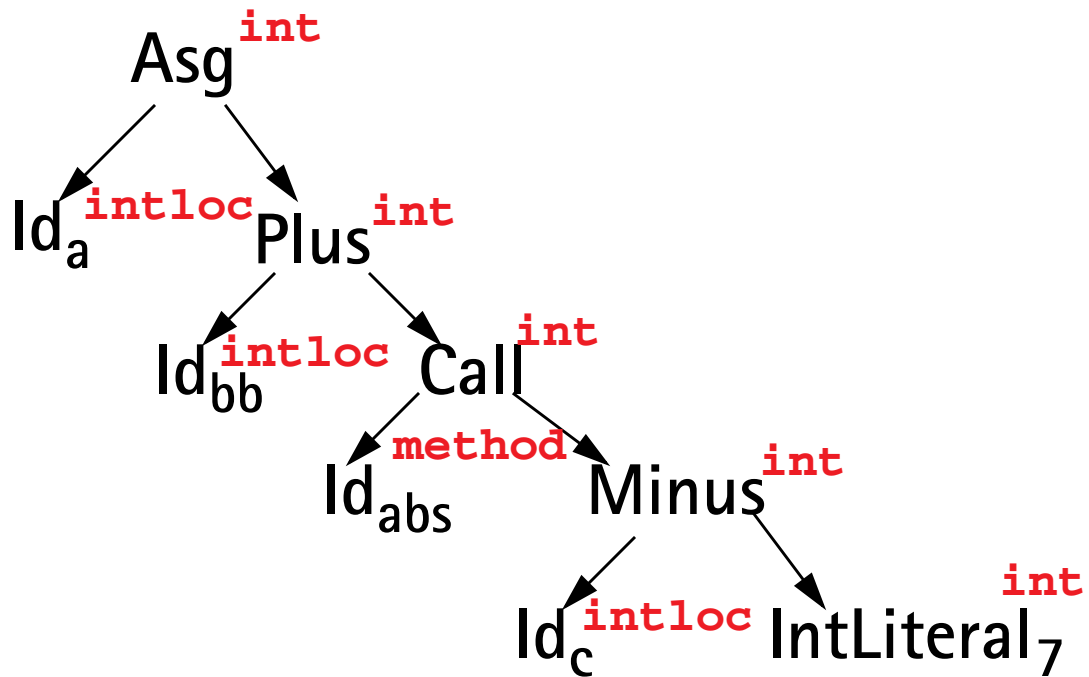
Id_a Asg Id_{bb} Plus Id_{abs} Lparen Id_c
Minus IntLiteral₇ Rparen Semi

- The parser groups these tokens into language constructs (expressions, statements, declarations, etc.) represented in tree form:



(What happened to the parentheses and the semicolon?)

- The type checker resolves types and binds declarations within scopes:



- Finally, JVM code is generated for each node in the tree (leaves first, then roots):

```
iload 3 ; push local 3 (bb)  
iload 2 ; push local 2 (c)  
ldc 7 ; Push literal 7  
isub ; compute c-7  
invokestatic java/lang/Math/  
abs(I)I  
iadd ; compute bb+abs(c-7)  
istore 1 ; store result into  
local 1(a)
```

Symbol Tables & Scoping

Programming languages use scopes to limit the range in which an identifier is active (and visible).

Within a scope a name may be defined only once (though overloading may be allowed).

A symbol table (or dictionary) is commonly used to collect all the definitions that appear within a scope.

At the start of a scope, the symbol table is empty. At the end of a scope, all declarations within that scope are available within the symbol table.

A language definition may or may not allow *forward references* to an identifier.

If forward references are allowed, you may use a name that is defined later in the scope (Java does this for field and method declarations within a class).

If forward references are not allowed, an identifier is visible only after its declaration. C, C++ and Java do this for variable declarations.

In CSX no forward references are allowed.

In terms of symbol tables, forward references require two passes over a scope. First all

declarations are gathered.
Next, all references are resolved using the complete set of declarations stored in the symbol table.

If forward references are disallowed, one pass through a scope suffices, processing declarations and uses of identifiers together.

Block STRUCTURED LANGUAGES

- Introduced by Algol 60, includes C, C++, CSX and Java.
- Identifiers may have a non-global scope. Declarations may be *local* to a class, subprogram or block.
- Scopes may *nest*, with declarations propagating to inner (contained) scopes.
- The lexically *nearest* declaration of an identifier is bound to uses of that identifier.

Example (drawn from C):

```
int x,z;
void A() {
    float x,y;
    print(x,y,z);
}
void B() {
    print(x,y,z)
}

```

The diagram illustrates the scope resolution for variables `x`, `y`, and `z` in the provided C code. Red arrows indicate the lookup path for each variable used in the `print` statements of `A()` and `B()`.

- For `A()`:
 - `x` and `y` are found in the local scope of `A()` (labeled `float`).
 - `z` is not found in `A()` and is found in the global scope (labeled `int`).
- For `B()`:
 - `x` and `y` are not found in `B()` and are found in the global scope (labeled `int`).
 - `z` is not found in `B()` and is found in the global scope (labeled `undeclared`).

Block STRUCTURE CONCEPTS

- Nested Visibility
No access to identifiers outside their scope.
- Nearest Declaration Applies
Using static nesting of scopes.
- Automatic Allocation and Deallocation of Locals
Lifetime of data objects is bound to the scope of the Identifiers that denote them.

Is CASE SIGNIFICANT?

In some languages (C, C++, Java and many others) case *is* significant in identifiers. This means **aa** and **AA** are different symbols that may have entirely different definitions.

In other languages (Pascal, Ada, Scheme, CSX) case *is not* significant. In such languages **aa** and **AA** are two alternative spellings of the same identifier.

Data structures commonly used to implement symbol tables usually treat different cases as different symbols. This is fine when case is significant in a language. When case is insignificant, you probably will

need to *strip case* before entering or looking up identifiers.

This just means that identifiers are converted to a uniform case before they are entered or looked up. Thus if we choose to use lower case uniformly, the identifiers `aaa`, `AAA`, and `AaA` are all converted to `aaa` for purposes of insertion or lookup.

BUT, inside the symbol table the identifier is stored in the form it was declared so that programmers see the form of identifier they expect in listings, error messages, etc.

HOW ARE SYMBOL TABLES IMPLEMENTED?

There are a number of data structures that can reasonably be used to implement a symbol table:

- An Ordered List
Symbols are stored in a linked list, sorted by the symbol's name. This is simple, but may be a bit too slow if many identifiers appear in a scope.
- A Binary Search Tree
Lookup is much faster than in linked lists, but rebalancing may be needed. (Entering identifiers in sorted order turns a search tree into a linked list.)
- Hash Tables
The most popular choice.

IMPLEMENTING BLOCK-STRUCTURED SYMBOL TABLES

To implement a block structured symbol table we need to be able to efficiently open and close individual scopes, and limit insertion to the innermost current scope.

This can be done using one symbol table structure if we tag individual entries with a “scope number.”

It is far easier (but more wasteful of space) to allocate one symbol table for each scope. Open scopes are stacked, pushing and popping tables as scopes are opened and closed.

Be careful though—many preprogrammed stack implementations don't allow you to “peek” at entries below the stack top. This is necessary to lookup an identifier in all open scopes.

If a suitable stack implementation (with a peek operation) isn't available, a linked list of symbol tables will suffice.