

## Reading Assignment

- Read Assignment #2.
- Read George and Appel's paper, "Iterated Register Coalescing." (Linked from Class Web page)
- Read Larus and Hilfinger's paper, "Register Allocation in the SPUR Lisp Compiler."

## Liveness Analysis

Just because a definition reaches a Basic Block,  $b$ , *does not* mean it must be allocated to a register at  $b$ .

We also require that the definition be *Live* at  $b$ . If the definition is dead, then it will no longer be used, and register allocation is unnecessary.

For a Basic Block  $b$  and Variable  $V$ :

$\text{LiveIn}(b)$  = true if  $V$  is Live (will be used before it is redefined) at the beginning of  $b$ .

$\text{LiveOut}(b)$  = true if  $V$  is Live (will be used before it is redefined) at the end of  $b$ .

$\text{LiveIn}$  and  $\text{LiveOut}$  are computed, using the following rules:

1. If Basic Block  $b$  has no successors then  
 $\text{LiveOut}(b) = \text{false}$

2. For all Other Basic Blocks

$$\text{LiveOut}(b) = \bigvee_{s \in \text{Succ}(b)} \text{LiveIn}(s)$$

3.  $\text{LiveIn}(b) =$

If  $V$  is used before it is defined in  
Basic Block  $b$

Then true

Elsif  $V$  is defined before it is  
used in Basic Block  $b$

Then false

Else  $\text{LiveOut}(b)$

## Merging Live Ranges

It is possible that each Basic Block that contains a definition of  $v$  creates a *distinct* Live Range of  $V$ .

$\forall$  Basic Blocks,  $b$ , that contain a definition of  $V$ :

$\text{Range}(b) =$

$$\{b\} \cup \{k \mid b \in \text{DefsIn}(k) \ \& \ \text{LiveIn}(k)\}$$

This rule states that the Live Range of a definition to  $V$  in Basic Block  $b$  is  $b$  plus all other Basic Blocks that the definition of  $V$  reaches and in which  $V$  is live.

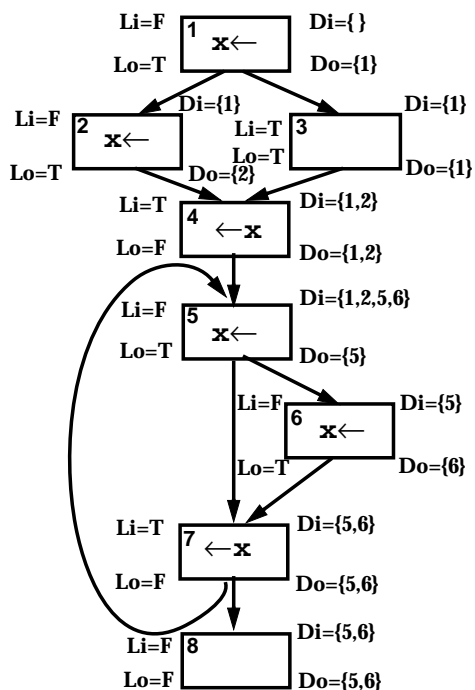
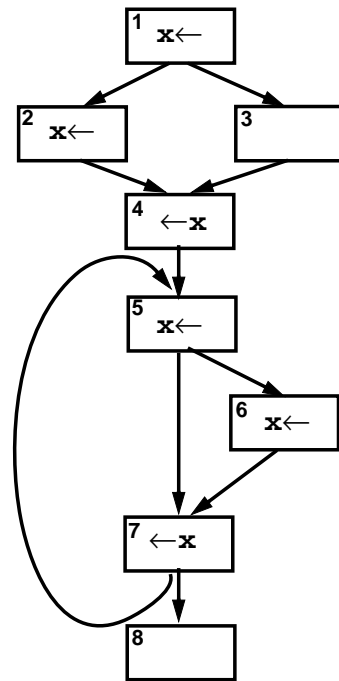
If two Live Ranges overlap (have one of more Basic Blocks in common), they *must* share the same register too. (Why?)

Therefore,

If  $\text{Range}(b_1) \cap \text{Range}(b_2) \neq \emptyset$

Then replace  
 $\text{Range}(b_1)$  and  $\text{Range}(b_2)$   
 with  $\text{Range}(b_1) \cup \text{Range}(b_2)$

## Example



The Live Ranges we Compute are

$$\text{Range}(1) = \{1\} \cup \{3,4\} = \{1,3,4\}$$

$$\text{Range}(2) = \{2\} \cup \{4\} = \{2,4\}$$

$$\text{Range}(5) = \{5\} \cup \{7\} = \{5,7\}$$

$$\text{Range}(6) = \{6\} \cup \{7\} = \{6,7\}$$

Ranges 1 and 2 overlap, so

$$\text{Range}(1) = \text{Range}(2) = \{1,2,3,4\}$$

Ranges 5 and 6 overlap, so

$$\text{Range}(5) = \text{Range}(6) = \{5,6,7\}$$

## Interference Graph

An *Interference Graph* represents interferences between Live Ranges.

Two Live Ranges *interfere* if they share one or more Basic Blocks in common.

Live Ranges that interfere *must* be allocated different registers.

In an Interference Graph:

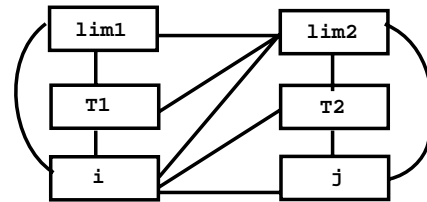
- Nodes are Live Ranges
- An undirected arc connects two Live Ranges if and only if they interfere

## Example

```
int p(int lim1, int lim2) {
  for (i=0; i<lim1 && A[i]>0;i++){
    for (j=0; j<lim2 && B[j]>0;j++){
      return i+j;
    }
}
```

We optimize array accesses by placing `&A[0]` and `&B[0]` in temporaries:

```
int p(int lim1, int lim2) {
  int *T1 = &A[0];
  for (i=0; i<lim1 && *(T1+i)>0;i++){
    int *T2 = &B[0];
    for (j=0; j<lim2 && *(T2+j)>0;j++){
      return i+j;
    }
}
```



## Register Allocation via Graph Coloring

We model global register allocation as a Coloring Problem on the Interference Graph

We wish to use the fewest possible colors (registers) subject to the rule that two connected nodes can't share the same color.

## Optimal Graph Coloring is NP-Complete

Reference:

"Computers and Intractability,"  
M. Garey and D. Johnson,  
W.H. Freeman, 1979.

We'll use a Heuristic Algorithm originally suggested by Chaitin et. al. and improved by Briggs et. al.

References:

"Register Allocation Via Coloring,"  
G. Chaitin et. al., Computer  
Languages, 1981.

"Improvement to Graph Coloring  
Register Allocation," P. Briggs et. al.,  
PLDI, 1989.

## Coloring Heuristic

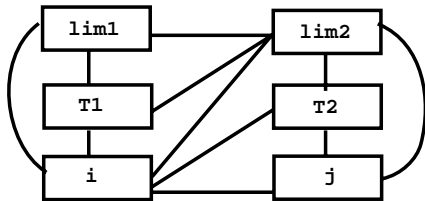
To R-Color a Graph (where R is the number of registers available)

1. While any node, n, has < R neighbors:  
Remove n from the Graph.  
Push n onto a Stack.
2. If the remaining Graph is non-empty:  
Compute the Cost of each node.  
The Cost of a Node (a Live Range)  
is the number of extra instructions  
needed if the Node isn't assigned a  
register, scaled by  $10^{\text{loop\_depth}}$ .  
Let  $NB(n) =$   
Number of Neighbors of n.  
Remove that node n that has the  
smallest  $\text{Cost}(n)/NB(n)$  value.  
Push n onto a Stack.  
Return to Step 1.

3. While Stack is non-empty:  
Pop n from the Stack.  
If n's neighbors are assigned fewer  
than R colors  
Then assign n any unassigned color  
Else leave n uncolored.

## Example

```
int p(int lim1, int lim2) {
  int *T1 = &A[0];
  for (i=0; i<lim1 && *(T1+i)>0;i++){
  int *T2 = &B[0];
  for (j=0; j<lim2 && *(T2+j)>0;j++){
    return i+j;
  }
}
```



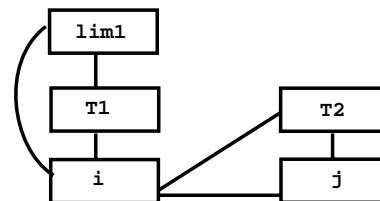
	lim1	lim2	T1	T2	i	j
Cost	11	11	11	11	42	42
Cost/ Neighbors	11/3	11/5	11/3	11/3	42/5	42/3

Do a 3 coloring

Since no node has fewer than 3 neighbors, we remove a node based on the minimum Cost/Neighbors value.

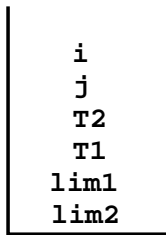
lim2 is chosen.

We now have:



Remove (say) lim1, then T1, T2, j and i (order is arbitrary).

The Stack is:



Assuming the colors we have are R1, R2 and R3, the register assignment we choose is

i:R1, j:R2, t2:R3, t1:R2, lim1:R3, lim2:spill

