

# MERGING LIVE RANGES

It is possible that each Basic Block that contains a definition of  $v$  creates a *distinct* Live Range of  $V$ .

∀ Basic Blocks,  $b$ , that contain a definition of  $V$ :

$$\text{Range}(b) = \{b\} \cup \{k \mid b \in \text{DefIn}(k) \ \& \ \text{LiveIn}(k)\}$$

This rule states that the Live Range of a definition to  $V$  in Basic Block  $b$  is  $b$  plus all other Basic Blocks that the definition of  $V$  reaches and in which  $V$  is live.

If two Live Ranges overlap (have one or more Basic Blocks in common), they *must* share the same register too. (Why?)

Therefore,

If  $\text{Range}(b_1) \cap \text{Range}(b_2) \neq \phi$

Then replace

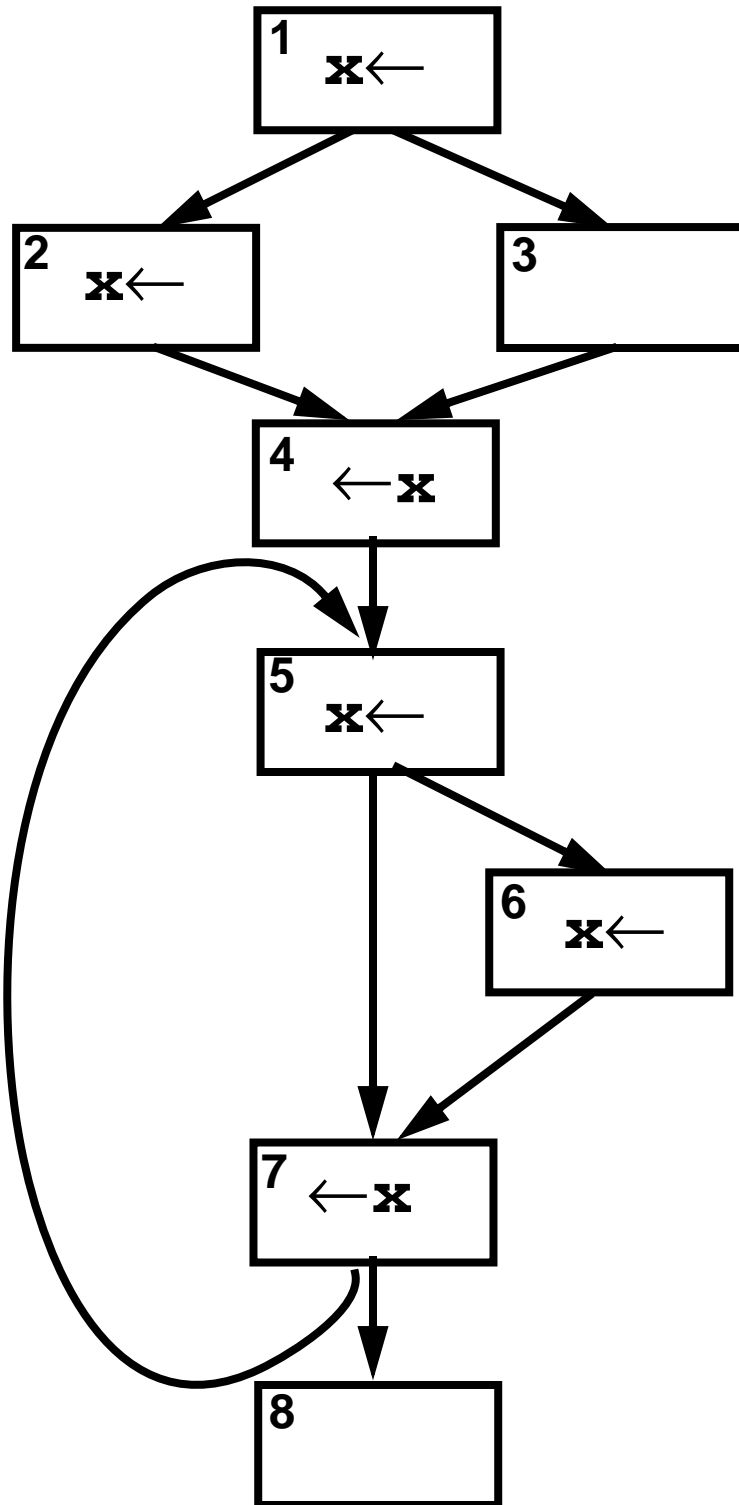
$\text{Range}(b_1)$  and  $\text{Range}(b_2)$

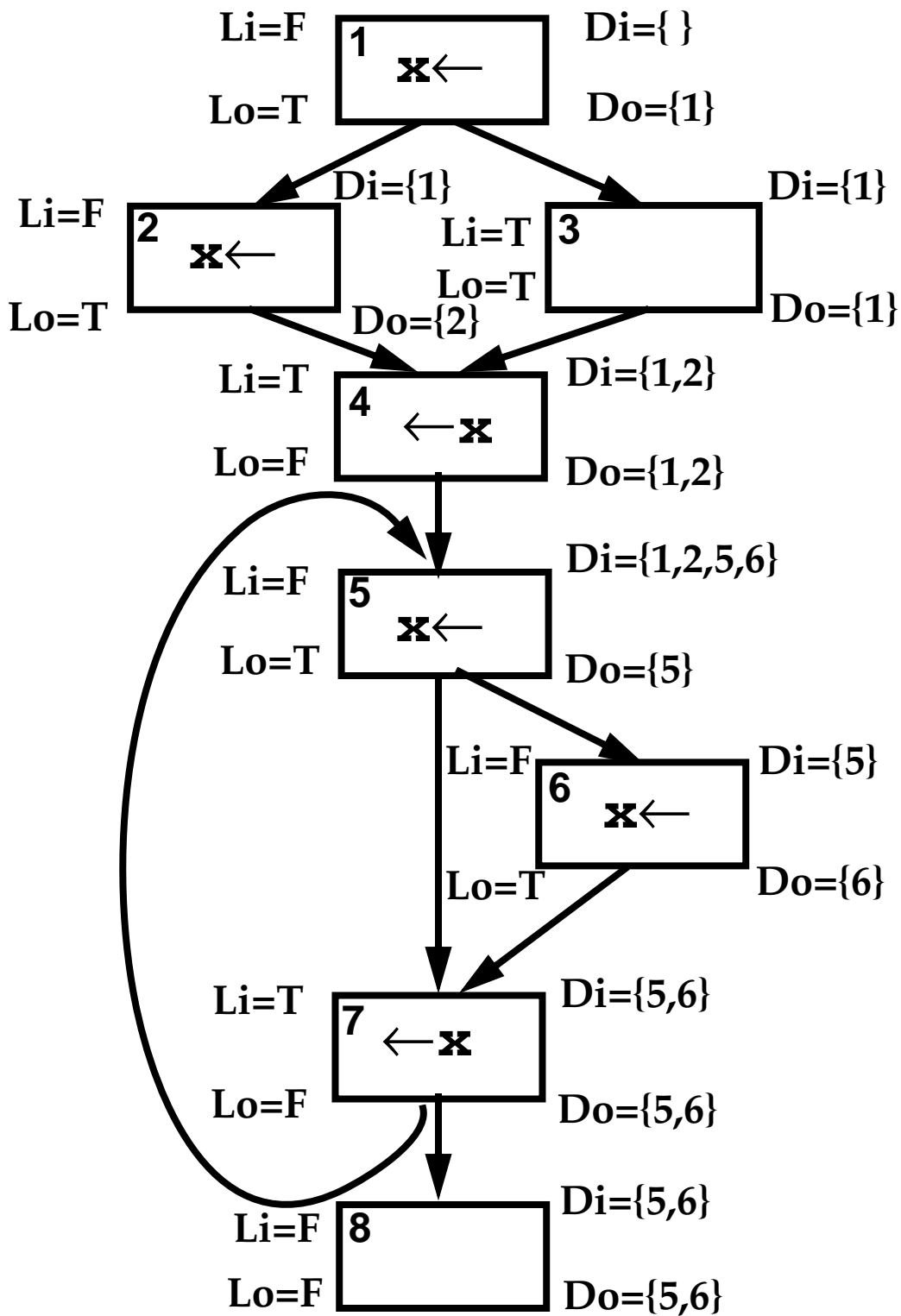
with  $\text{Range}(b_1) \cup \text{Range}(b_2)$

# READING ASSIGNMENT

- Read George and Appel's paper, "Iterated Register Coalescing." (Linked from Class Web page)
- Read Larus and Hilfinger's paper, "Register Allocation in the SPUR Lisp Compiler."

# Example





## The Live Ranges we Compute are

$$\text{Range}(1) = \{1\} \cup \{3,4\} = \{1,3,4\}$$

$$\text{Range}(2) = \{2\} \cup \{4\} = \{2,4\}$$

$$\text{Range}(5) = \{5\} \cup \{7\} = \{5,7\}$$

$$\text{Range}(6) = \{6\} \cup \{7\} = \{6,7\}$$

Ranges 1 and 2 overlap, so

$$\text{Range}(1) = \text{Range}(2) = \{1,2,3,4\}$$

Ranges 5 and 6 overlap, so

$$\text{Range}(5) = \text{Range}(6) = \{5,6,7\}$$

# INTERFERENCE GRAPH

An *Interference Graph* represents interferences between Live Ranges.

Two Live Ranges *interfere* if they share one or more Basic Blocks in common.

Live Ranges that interfere *must* be allocated different registers.

In an Interference Graph:

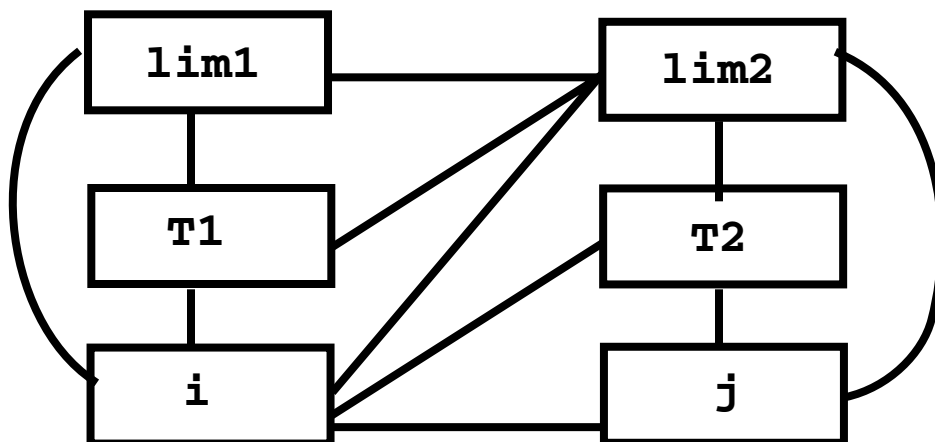
- Nodes are Live Ranges
- An undirected arc connects two Live Ranges if and only if they interfere

# Example

```
int p(int lim1, int lim2) {  
    for (i=0; i<lim1 && A[i]>0;i++){  
        for (j=0; j<lim2 && B[j]>0;j++){  
            return i+j;  
        }  
    }  
}
```

We optimize array accesses by placing `&A[0]` and `&B[0]` in temporaries:

```
int p(int lim1, int lim2) {  
    int *T1 = &A[0];  
    for (i=0; i<lim1 && *(T1+i)>0;i++){  
        int *T2 = &B[0];  
        for (j=0; j<lim2 && *(T2+j)>0;j++){  
            return i+j;  
        }  
    }  
}
```



# REGISTER ALLOCATION VIA GRAPH COLORING

We model global register allocation as a Coloring Problem on the Interference Graph

We wish to use the fewest possible colors (registers) subject to the rule that two connected nodes can't share the same color.

# **OPTIMAL GRAPH COLORING IS NP-COMPLETE**

Reference:

**"Computers and Intractability,"  
M. Garey and D. Johnson,  
W.H. Freeman, 1979.**

We'll use a Heuristic Algorithm originally suggested by Chaitin et. al. and improved by Briggs et. al.

References:

**"Register Allocation Via Coloring,"  
G. Chaitin et. al., Computer  
Languages, 1981.**

**"Improvement to Graph Coloring  
Register Allocation," P. Briggs et. al.,  
PLDI, 1989.**

# COLORING HEURISTIC

To R-Color a Graph (where R is the number of registers available)

1. While any node,  $n$ , has  $< R$  neighbors:  
Remove  $n$  from the Graph.  
Push  $n$  onto a Stack.
2. If the remaining Graph is non-empty:  
Compute the Cost of each node.  
The Cost of a Node (a Live Range) is the number of extra instructions needed if the Node isn't assigned a register, scaled by  $10^{\text{loop\_depth}}$ .  
Let  $NB(n) =$   
    Number of Neighbors of  $n$ .  
Remove that node  $n$  that has the smallest  $\text{Cost}(n)/NB(n)$  value.  
Push  $n$  onto a Stack.  
Return to Step 1.

**3. While Stack is non-empty:**

**Pop n from the Stack.**

**If n's neighbors are assigned fewer  
than R colors**

**Then assign n any unassigned color**

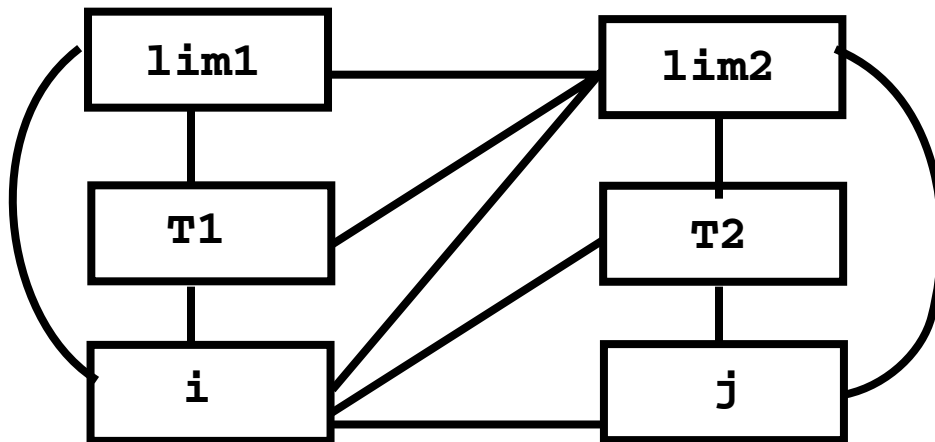
**Else leave n uncolored.**

# Example

```

int p(int lim1, int lim2) {
  int *T1 = &A[0];
  for (i=0; i<lim1 && *(T1+i)>0;i++){
  int *T2 = &B[0];
  for (j=0; j<lim2 && *(T2+j)>0;j++){
  return i+j;
  }
}

```



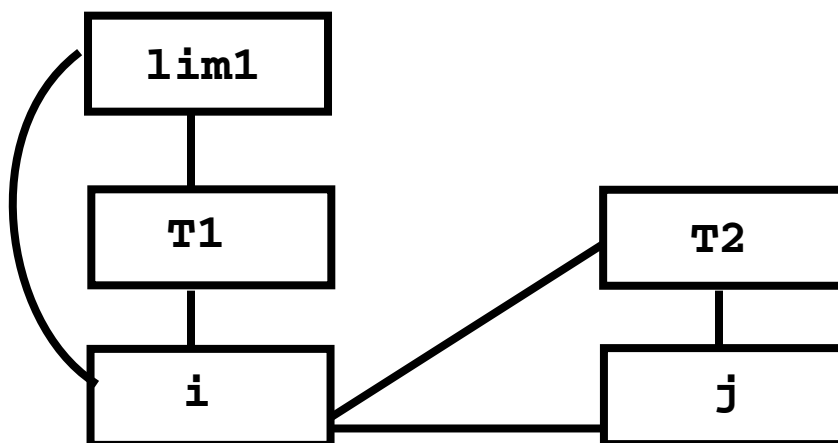
	lim1	lim2	T1	T2	i	j
Cost	11	11	11	11	42	42
Cost/ Neighbors	11/3	11/5	11/3	11/3	42/5	42/3

Do a 3 coloring

Since no node has fewer than 3 neighbors, we remove a node based on the minimum Cost/Neighbors value.

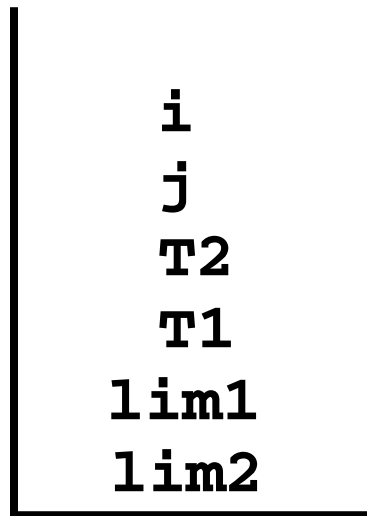
**lim2** is chosen.

We now have:



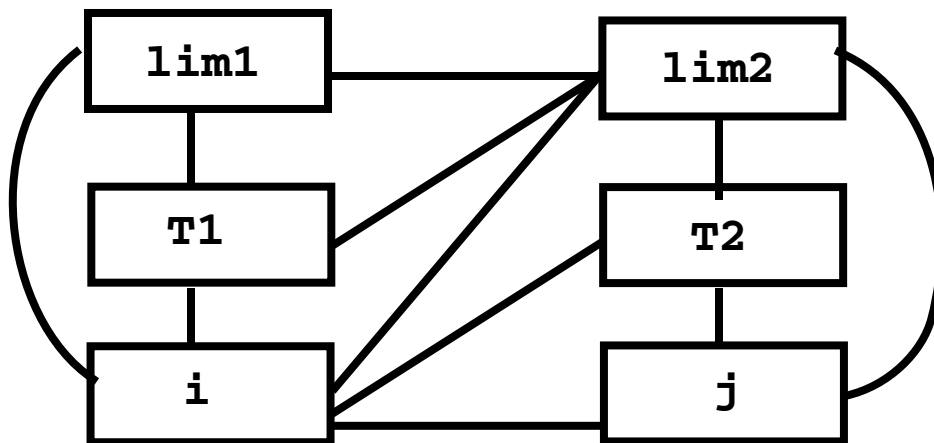
Remove (say) **lim1**, then **T1**, **T2**, **j** and **i** (order is arbitrary).

The Stack is:



Assuming the colors we have are R1, R2 and R3, the register assignment we choose is

`i`:R1, `j`:R2, `t2`:R3, `t1`:R2, `lim1`:R3, `lim2`:spill



# COLOR PREFERENCES

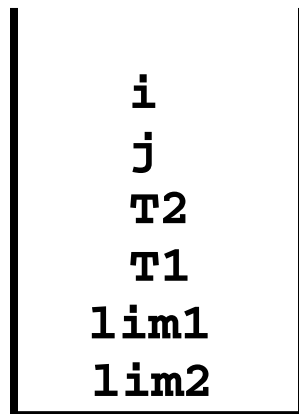
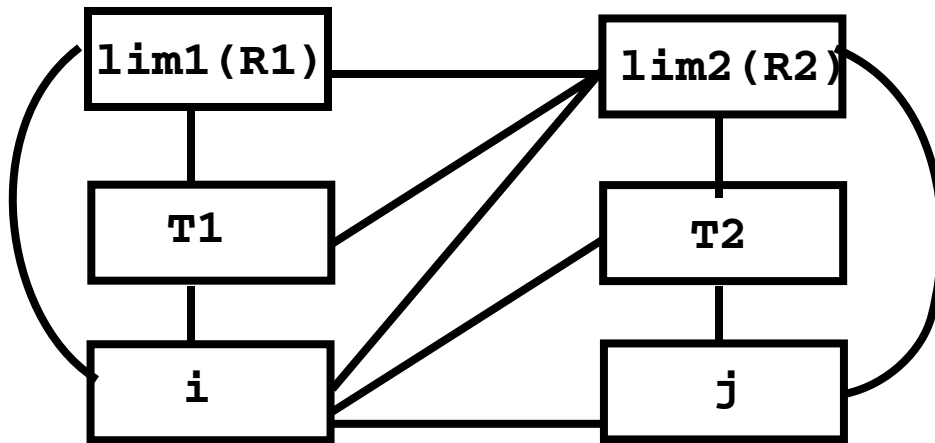
Sometimes we wish to assign a particular register (color) to a selected Live Range (e.g., a parameter or return value) *if possible*.

We can mark a node in the Interference Graph with a *Color Preference*.

When we unstack nodes and assign colors, we will avoid choosing color  $c$  if an uncolored neighbor has indicated a preference for it. If only color  $c$  is left, we take it (and ignore the preference).

# Example

Assume in our previous example that  
lim1 has requested register R1 and  
lim2 has requested register R2  
(because these are the registers the  
parameters are passed in).



Now when  $i$ ,  $j$  and  $T1$  are unstacked, they respect  $lim1$ 's and  $lim2$ 's preferences:

$i:R3, j:R1, T2:R2, T1:R2, lim1:R1, lim2:spill$

# Using Coloring to Optimize Register Moves

A nice "fringe benefit" of allocating registers via coloring is that we can often *optimize away* register to register moves by giving the source and target the *same color*.

Consider

Live in:  $a, b$

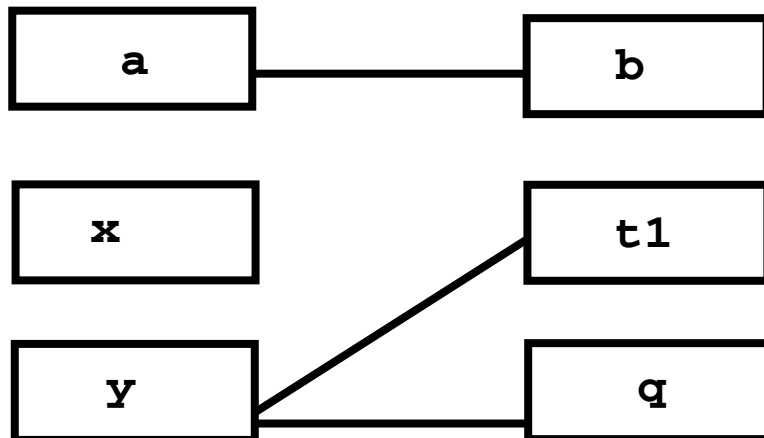
$t1 = a + b$

$x = t1$

$y = x + 1$

$q = t1$

Live out:  $y, q$



We'd like  $x$ ,  $t1$  and  $q$  to get the same color. How do we "force" this?

We can "merge"  $x$ ,  $t1$  and  $q$  together:

Live in:  $a, b$



$t1 = a + b$

$x = t1$



$y = x + 1$

$q = t1$

Live out:  $y, q$

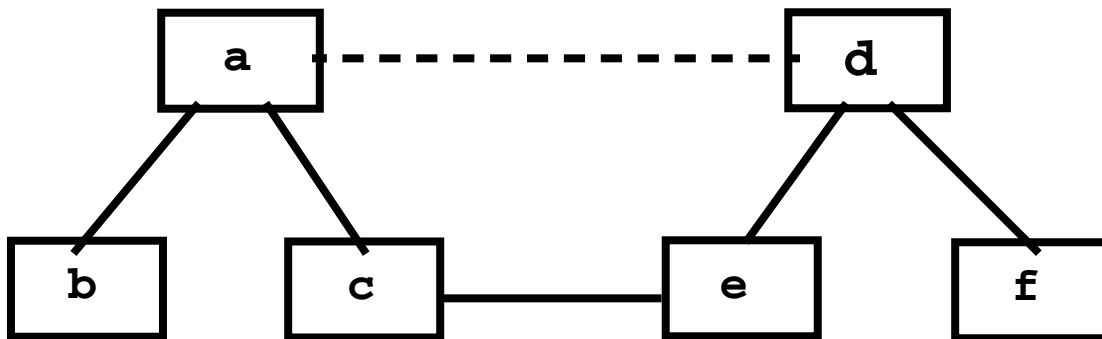
Now a 2-coloring that optimizes away both register to register moves is trivial.

# RECKLESS COALESCING

Originally, Chaitin suggested merging *all* move-related nodes that don't interfere.

This is *reckless*—the merged node may not be colorable!

(Is it worth a spill to save a move??)



This Graph is 2-colorable before the reckless merge, but *not* after.

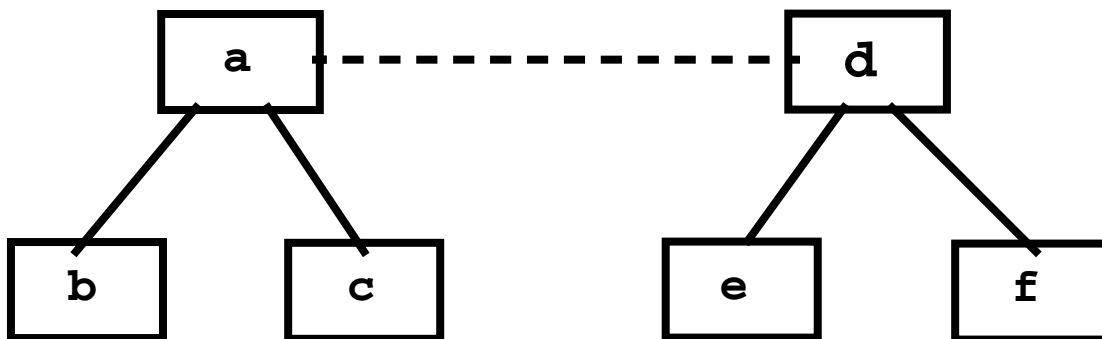
# CONSERVATIVE COALESCING

In response to Chaitin's reckless coalescing approach, Briggs suggested a *more conservative* approach.

See "Improvement to Graph Coloring Register Allocation," P. Briggs et. al., ACM Toplas, May 1994.

Briggs suggested that two move-related nodes should be merged *only if* the combined source and target node has fewer than  $R$  neighbors.

This *guarantees* that the combined node will be colorable, but may miss some optimization opportunities.



After a merge of nodes  $a$  and  $d$ , there will be four neighbors, but a 2-coloring is still possible.

# ITERATED COALESCING

This is an intermediate approach, that seeks to be safer than reckless coalescing and more effective than conservative coalescing. It was proposed by George and Appel.

## 1. Build:

Create an Interference Graph, as usual. Mark source–target pairs with a special move–related arc (denoted as a dashed line).

## 2. Simplify:

Remove and stack non–move–related nodes with  $< R$  neighbors.

## 3. Coalesce:

Combine move–related pairs that will have  $< R$  neighbors after coalescing.

Repeat steps 2 and 3 until only nodes with  $R$  or more neighbors or move–related nodes remain or the graph is empty.

#### 4. Freeze:

If the Interference Graph is  
non-empty:

Then If there exists a move-related  
node with  $< R$  neighbors

Then: "Freeze in" the move and  
make the node  
non-move-related.

Return to Steps 2 and 3.

Else: Use Chaitin's  
Cost/Neighbors criterion  
to remove and stack  
a node.

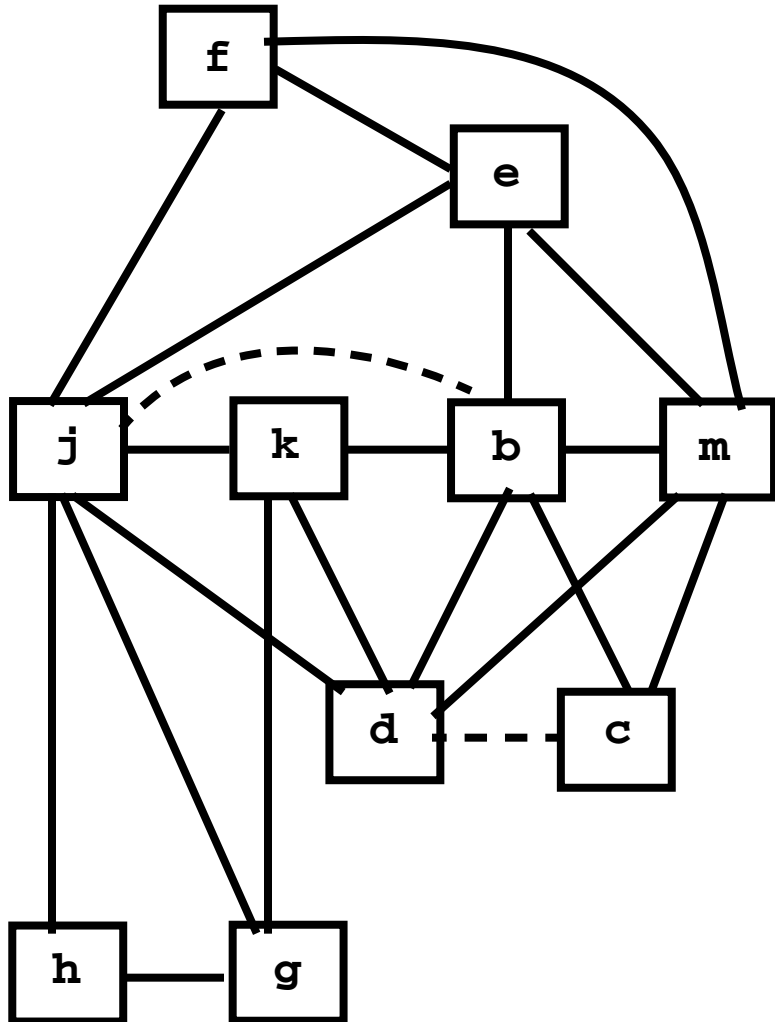
Return to Steps 2 and 3.

#### 5. Unstack:

Color nodes as they are unstacked as  
per Chaitin and Briggs.

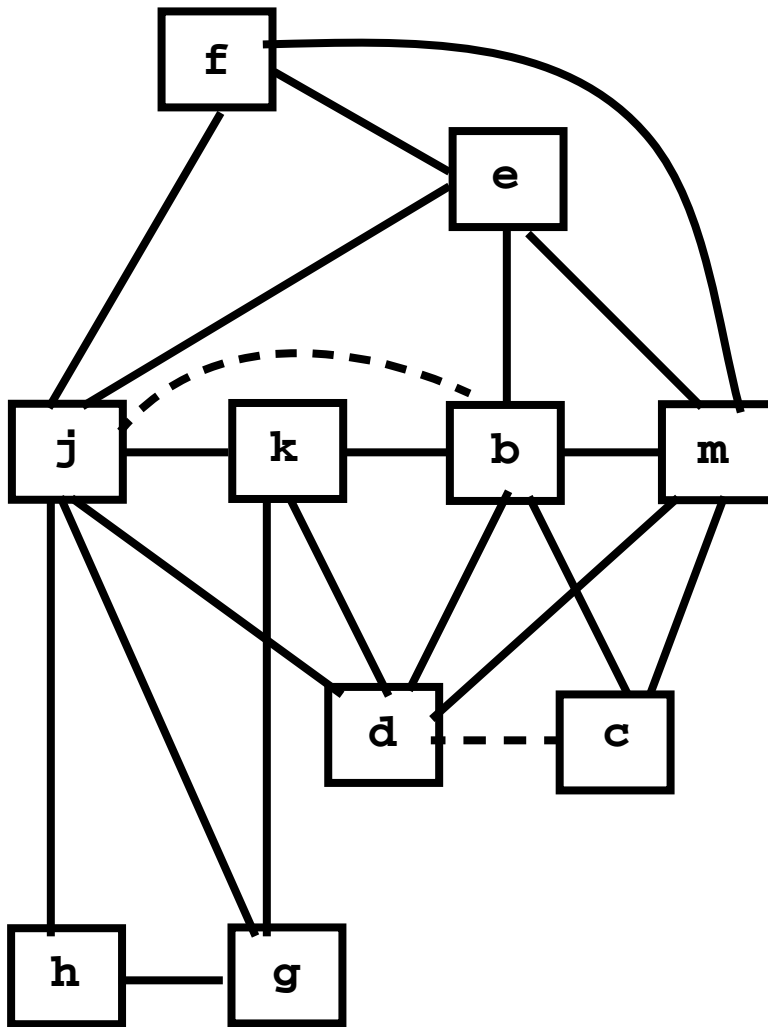
# Example

```
Live in: k, j
g = mem[j+12]
h = k-1
f = g*h
e = mem[j+8]
m = mem[j+16]
b = mem[f]
c = e+8
d = c
k = m+4
j = b
goto d
Live out: d, k, j
```



Assume we want a 4-coloring.

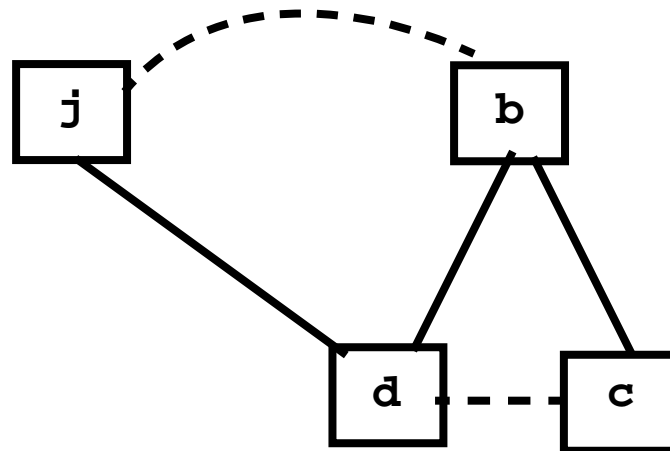
Note that neither  $j$  &  $b$  nor  $d$  &  $c$  can be conservatively colored.



We simplify by removing nodes with fewer than 4 neighbors.

We remove and stack: **g, h, k, f, e, m**

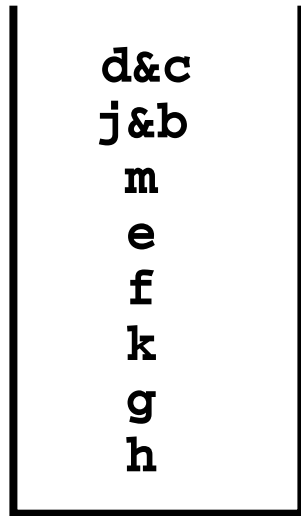
The remaining Interference Graph is



We can now conservatively coalesce the move-related pairs to obtain



These remaining nodes can now be removed and stacked.



We can now unstack and color:

**d&c:R1, j&b:R2, m:R3, e:R4, f:R1,  
k:R3, h:R1, g:R4**

No spills were required and both moves were optimized away.