S. Kurlander, T. Proebsting and C.	
Fischer, "Efficient Instruction Scheduling for Delayed-Load Architectures," ACM Transactions on Programming Languages and Systems 1995. (Linked from class Web page)	

"On the Fly" Local Register Allocation Allocate registers as needed during

code generation.

Partition registers into 3 classes.

Allocatable

Explicitly allocated and freed; used to hold a variable, literal or temporary. On SPARC: Local registers & unused In registers.

Reserved

Reserved for specific purposes by OS or software conventions.

On SPARC: **%fp**, **%sp**, return address register, argument registers, return value register.

CS 701 Fall 2003®

• Work

Volatile—used in short code sequences that need to use a register. On SPARC: **%g1** to **%g4**, unused out registers.

Register Targeting

Allow "end user" of a value to state a register preference in AST or IR.

or

Use Peephole Optimization to eliminate unnecessary register moves.

or

Use *preferencing* in a graph coloring register allocator.

Register Tracking

Improve upon standard getReg/ freeReg allocator by *tracking* (remembering) register contents.

Remember the value(s) currently held within a register; store information in a *Register Association List.*

Mark each value as *Saved* (in memory) or *Unsaved* (in memory).

Each value in a register has a *Cost*. This is the cost (in instructions) to restore the value to a register.

53

The cost of allocating a register is the sum of the costs of the values it holds.
 0
 Dead Value

 Cost(register) =
$$\sum_{values \ e} cost(values)$$
 0
 Dead Value

 When we allocate a register, we will choose the cheapest one.
 0
 Saved Local Variable

 If 2 registers have the same cost, we choose that register whose values have the most distant next use.
 Unsaved Global Variable

 Why most distant?)
 0
 Dead Value

Register Tracking Allocator

```
reg getReg() {
  if ( \exists r \in regSet and cost(r) == 0)
      choose(r)
  else {
      c = 1;
      while(true) {
         if ( \exists r \in regSet and cost(r) == c){
             choose r with cost(r) == c and
                   most distant next use of
                   associated values;
             break;
         }
          c++;
      }
      Save contents of r as necessary;
  }
  return r;
}
```

- Once a value becomes dead, it may be purged from the register association list without any saves.
- Values no longer used, but unsaved, can be purged (and saved) at *zero* cost.
- Assignments of a register to a simple variable may be *delayed*—just add the variable to the Register's Association List entry as unsaved.

The assignment may be done later or made *unnecessary* (by a later assignment to the variable)

• At the end of a basic block all unsaved values are stored into memory.

Example

ir	nt	a,b,c,d;	11	Globals
a	=	5;		
b	=	a + d;		
С	=	b - 7;		
b	=	10;		

Naive Code

mov	5,%10
st	%10,[a]
ld	[a],%10
ld	[d],%11
add	%10,%11,%10
st	%10,[b]
ld	[b] , %10
sub	%10,7,%10
st	%10,[c]
mov	10,%10
st	%10,[b]
18 instruc	tions are needed (memory
references	take 2 instructions)

CS 701 Fall 2003

With Register Tracking

Instruction Generated	%10	%11
mov 5,%10	5(S)	
! Defer assignment to a	5(S), a(U)	
ld [d], %11	5(S), a(U)	d(S)
!d unused after next inst		
add %10,%11,%11	5(S), a(U)	b(U)
!b is dead after next inst		
sub %11,7,%11	5(S), a(U)	c(U)
! %ll has lower cost		
st %11, [c]	5(S), a(U)	
mov 10, %11	5(S), a(U)	b(U), 10(S)
! save unsaved values		
st %10, [a]		b(U), 10(S)
st %11,[b]		

12 instructions (rather than 18)

CS 701 Fall 2003®

60

Pointers, Arrays and Reference Parameters

When an array, reference parameter or pointed-to variable is read, all unsaved register values that might be aliased must be *stored*.

When an array, reference parameter or pointed-to variable is written, all unsaved register values that might be aliased must be *stored*, then *cleared* from the register association list.

Thus if a[3] is in a register and a[i] is assigned to, a[3] must be stored (if unsaved) and removed from the association list.

Optimal Expression Tree Translation—Sethi-Ullman Algorithm

Reference: R. Sethi & J. D. Ullman, "The generation of optimal code for arithmetic expressions," Journal of the ACM, 1970.

Goal: Translate an expression tree using the *fewest* possible registers.

Approach: Mark each tree node, N, with an *Estimate* of the minimum number of registers needed to translate the tree rooted by N.

Let RN(N) denote the Register Needs of node N.

61



Key Insight of SU Algorithm

Translate subtree that needs more registers *first*. Why?

After translating one subtree, we'll need a register to hold its value.

If we translate the more complex subtree first, we'll still have enough registers to translate the less complex expression (without *spilling* register values into memory).

CS 701 Fall 2003

Specification of SU Algorithm

TreeCG(tree *T, regList RL);

Operation:

- Translate expression tree T using only registers in RL.
- RL must contain at least 2 registers.
- Result of T will be computed into head(RL).

Summary of SU Algorithm

if T is a node (variable or literal) load T into R1 = head(RL)else (T is a binary operator) Let R1 = head(RL)Let R2 = second(RL)if RN(T.left) >= Size(RL) and RN(T.right) >= Size(RL)(A spill is unavoidable) TreeCG(T.left, RL) Store R1 into a memory temp TreeCG(T.right, RL) Load memory temp into R2 Generate (OP R2,R1,R1) elsif RN(T.left) >= RN(T.right)TreeCG(T.left, RL) TreeCG(T.right, tail(RL)) Generate (OP R1,R2,R1) else TreeCG(T.right, RL) TreeCG(T.left, tail(RL)) Generate (OP R2,R1,R1)

65



Assume 3 Registers; RL = [%10,%11,%12] Since right subtree is more complex, it is translated first.



70

CS 701 Fall 2003®



73

When more registers are used, there is often more potential for parallel evaluation:

A B C L

Here as many as *four* registers may be used to increase parallelism.