

# Reading Assignment

- Read George and Appel's paper, "Iterated Register Coalescing." (Linked from Class Web page)
- Read Larus and Hilfinger's paper, "Register Allocation in the SPUR Lisp Compiler."

# Liveness Analysis

Just because a definition reaches a Basic Block,  $b$ , *does not* mean it must be allocated to a register at  $b$ .

We also require that the definition be *Live* at  $b$ . If the definition is dead, then it will no longer be used, and register allocation is unnecessary.

For a Basic Block  $b$  and Variable  $V$ :

$\text{LiveIn}(b) = \text{true}$  if  $V$  is Live (will be used before it is redefined) at the beginning of  $b$ .

$\text{LiveOut}(b) = \text{true}$  if  $V$  is Live (will be used before it is redefined) at the end of  $b$ .

LiveIn and LiveOut are computed, using the following rules:

1. If Basic Block  $b$  has no successors then  
     $\text{LiveOut}(b) = \text{false}$

2. For all Other Basic Blocks

$$\text{LiveOut}(b) = \bigvee_{s \in \text{Succ}(b)} \text{LiveIn}(s)$$

3.  $\text{LiveIn}(b) =$

    If  $V$  is used before it is defined in  
        Basic Block  $b$

    Then true

    Elsif  $V$  is defined before it is  
        used in Basic Block  $b$

    Then false

    Else  $\text{LiveOut}(b)$

# Merging Live Ranges

It is possible that each Basic Block that contains a definition of  $v$  creates a *distinct* Live Range of  $V$ .

$\forall$  Basic Blocks,  $b$ , that contain a definition of  $V$ :

$$\text{Range}(b) = \{b\} \cup \{k \mid b \in \text{Defsln}(k) \ \& \ \text{Liveln}(k)\}$$

This rule states that the Live Range of a definition to  $V$  in Basic Block  $b$  is  $b$  plus all other Basic Blocks that the definition of  $V$  reaches and in which  $V$  is live.

If two Live Ranges overlap (have one or more Basic Blocks in common), they *must* share the same register too. (Why?)

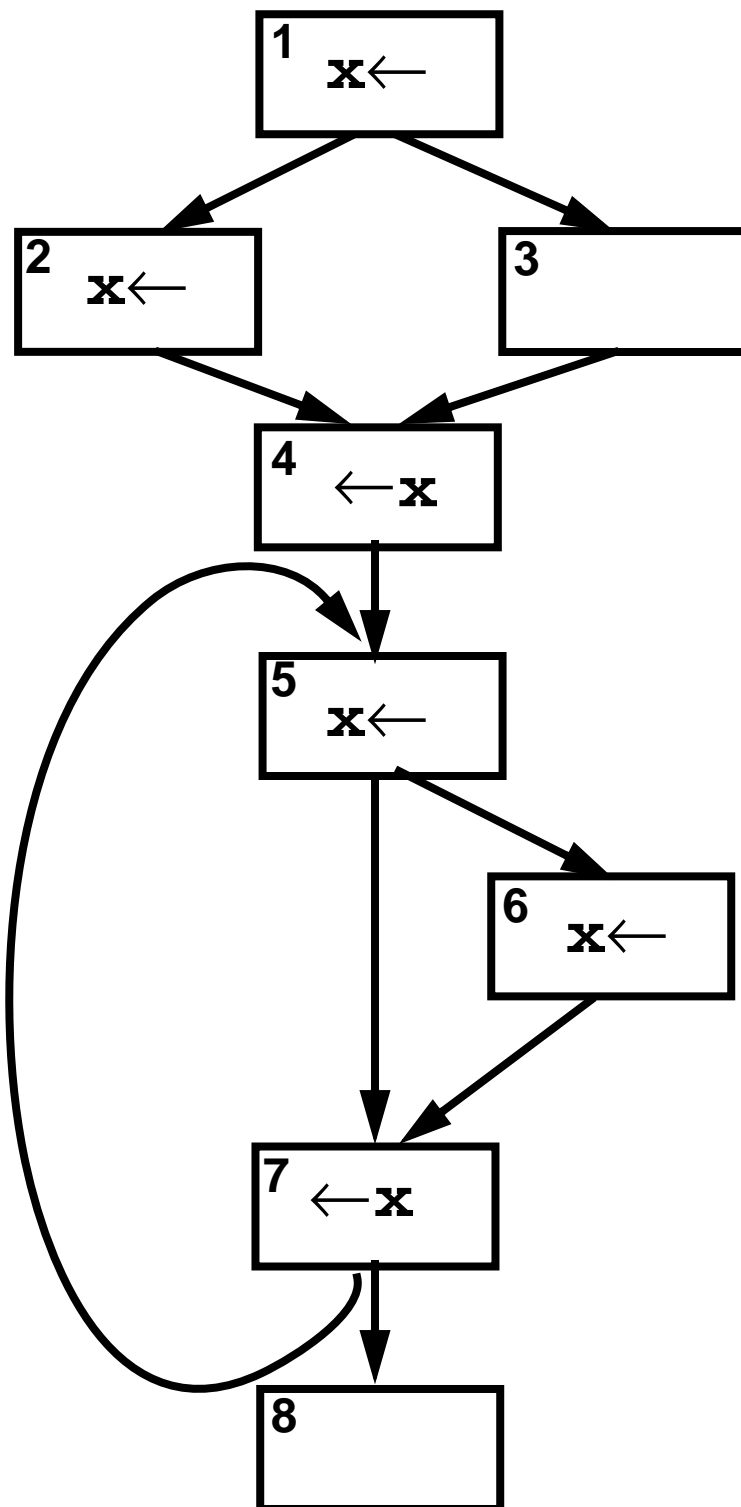
Therefore,

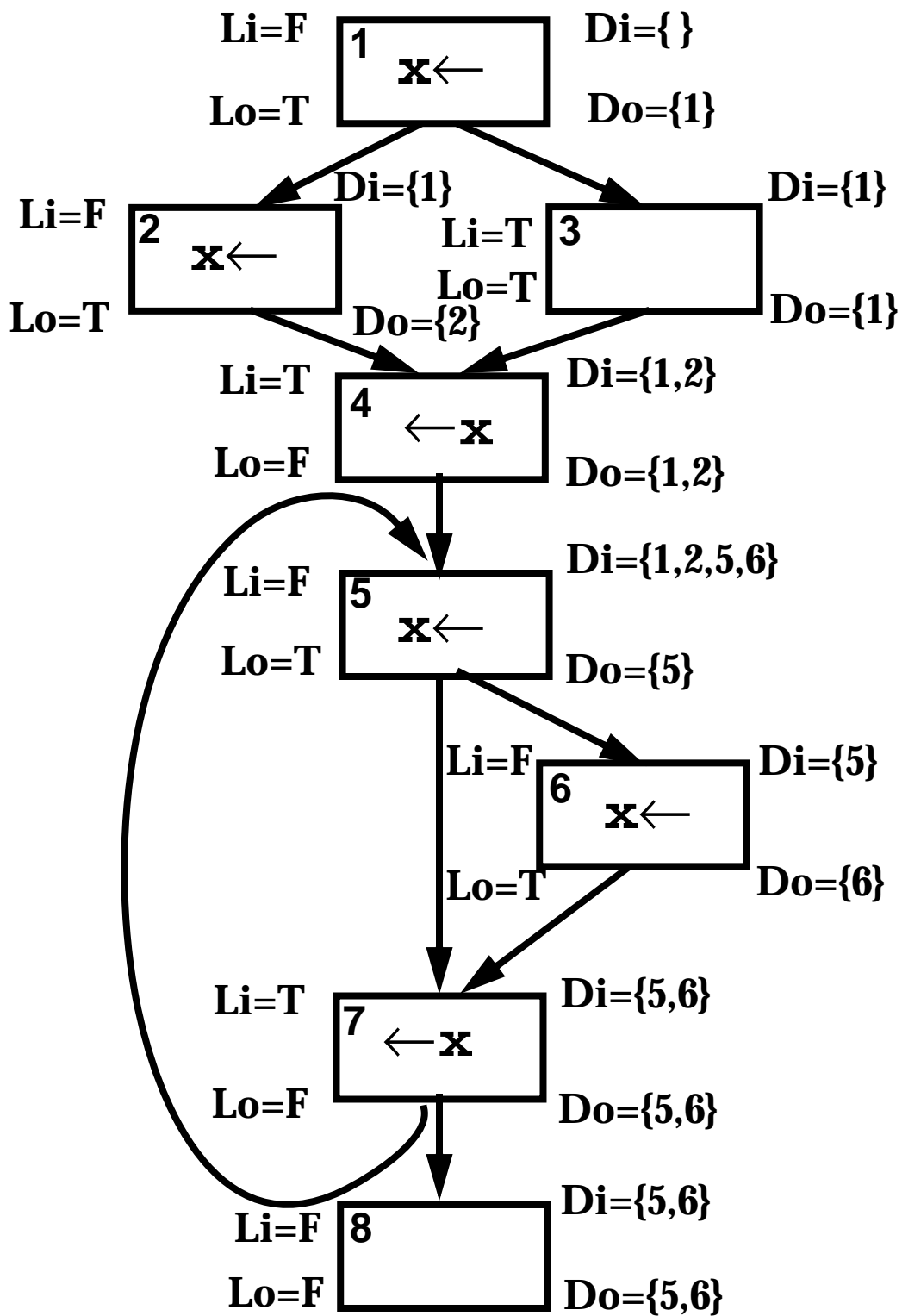
If  $\text{Range}(b_1) \cap \text{Range}(b_2) \neq \phi$

Then replace

$\text{Range}(b_1)$  and  $\text{Range}(b_2)$   
    with  $\text{Range}(b_1) \cup \text{Range}(b_2)$

# Example





## The Live Ranges we Compute are

$$\text{Range}(1) = \{1\} \cup \{3,4\} = \{1,3,4\}$$

$$\text{Range}(2) = \{2\} \cup \{4\} = \{2,4\}$$

$$\text{Range}(5) = \{5\} \cup \{7\} = \{5,7\}$$

$$\text{Range}(6) = \{6\} \cup \{7\} = \{6,7\}$$

Ranges 1 and 2 overlap, so

$$\text{Range}(1) = \text{Range}(2) = \{1,2,3,4\}$$

Ranges 5 and 6 overlap, so

$$\text{Range}(5) = \text{Range}(6) = \{5,6,7\}$$



# Interference Graph

An *Interference Graph* represents interferences between Live Ranges.

Two Live Ranges *interfere* if they share one or more Basic Blocks in common.

Live Ranges that interfere *must* be allocated different registers.

In an Interference Graph:

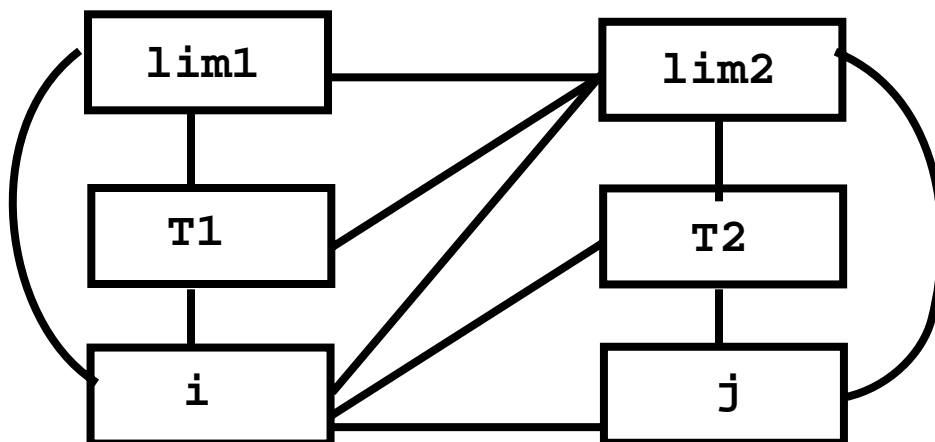
- Nodes are Live Ranges
- An undirected arc connects two Live Ranges if and only if they interfere

# Example

```
int p(int lim1, int lim2) {  
    for (i=0; i<lim1 && A[i]>0;i++){  
        for (j=0; j<lim2 && B[j]>0;j++){  
            return i+j;  
        }  
    }  
}
```

We optimize array accesses by placing `&A[0]` and `&B[0]` in temporaries:

```
int p(int lim1, int lim2) {  
    int *T1 = &A[0];  
    for (i=0; i<lim1 && *(T1+i)>0;i++){  
        int *T2 = &B[0];  
        for (j=0; j<lim2 && *(T2+j)>0;j++){  
            return i+j;  
        }  
    }  
}
```



# Register Allocation via Graph Coloring

We model global register allocation as a Coloring Problem on the Interference Graph

We wish to use the fewest possible colors (registers) subject to the rule that two connected nodes can't share the same color.

# Optimal Graph Coloring is NP-Complete

Reference:

"Computers and Intractability,"  
M. Garey and D. Johnson,  
W.H. Freeman, 1979.

We'll use a Heuristic Algorithm originally suggested by Chaitin et. al. and improved by Briggs et. al.

References:

"Register Allocation Via Coloring,"  
G. Chaitin et. al., Computer  
Languages, 1981.

"Improvement to Graph Coloring  
Register Allocation," P. Briggs et. al.,  
PLDI, 1989.

# Coloring Heuristic

To R-Color a Graph (where R is the number of registers available)

1. While any node,  $n$ , has  $< R$  neighbors:  
Remove  $n$  from the Graph.  
Push  $n$  onto a Stack.
2. If the remaining Graph is non-empty:  
Compute the Cost of each node.  
The Cost of a Node (a Live Range) is the number of extra instructions needed if the Node isn't assigned a register, scaled by  $10^{\text{loop\_depth}}$ .  
Let  $\text{NB}(n) =$   
    Number of Neighbors of  $n$ .  
Remove that node  $n$  that has the smallest  $\text{Cost}(n)/\text{NB}(n)$  value.  
Push  $n$  onto a Stack.  
Return to Step 1.

3. While Stack is non-empty:

    Pop  $n$  from the Stack.

    If  $n$ 's neighbors are assigned fewer  
        than  $R$  colors

    Then assign  $n$  any unassigned color  
    Else leave  $n$  uncolored.