

CS 839: Foundation Models In-Context Learning

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Announcements

•Logistics:

- •Homework 1 due in 5 days---hopefully you've gotten started ③
- •Class roadmap:

| Thursday Oct. 5 | In-Context Learning: Practice and Theory |
|------------------|--|
| Tuesday Oct. 10 | Fine-Tuning, Specialization, Adaptation |
| Thursday Oct. 12 | Training |
| Tuesday Oct. 17 | RLHF |
| Thursday Oct. 19 | Data |

Outline

Back to In-Context Learning

•Basic idea, two ways of thinking about ICL, metalearning

Analysis and Theory

•Setup, learning simple function classes, implicit training, existence, learning results

Prompting Review

• Everything we've talked about so far

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Reminder: In-context learning

Also called few-shot: but *sometimes* means fine-tune on this dataset, then prompt

In-context learning: do not finetune. Model weights unchanged.

• Everything happens in forward pass

Text: (lawrence bounces) all over the stage, dancing, Sentiment: positive

Text: despite all evidence to the contrary, this clun Sentiment: negative

Text: for the first time in years, de niro digs deep Sentiment: positive

Weng / SST



Dong et al, '23

ICL: Two ways to think about it

One way to think about few-shot is recovering some *fixed* model

- •I.e., sentiment analysis model
- •Here: goal of few-shot examples is to *activate* this model

Other way: be able to learn a function in *k Demonstration* T *Examples* Template *New Review:* [Text] *Query*

•Learn $w^T x$ for any w



Dong et al, '23

ICL: Various ways to think about it

Other way: be able to learn a function in a function class

- •Learn w^Tx for any w
- •Note: this is **metalearning**
 - Learn a transformers-based model that can then learn other functions
 - Traditionally a hard bilevel optimization problem



ICL: Various ways to think about it

Other way: be able to learn a function in a function class

- •Learn w^Tx for any w
- Metalearning approach
- •Q: How is this possible?
 - Note that we're not changing the trained model, so has to itself do a full training (inner-level) procedure in a forward pass
 - Perhaps doable with a big model?



Break & Questions

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What Can Transformers Learn?

Can study from theoretical or empirical points of view Theoretical setup:

$$\underset{\substack{\theta \in \mathbf{x}_{1}, \dots, \mathbf{x}_{n} \sim p(x) \\ f \sim p(f)}}{\operatorname{srgmin}} \left[\sum_{i=1}^{n} \mathcal{L}\left(f(\mathbf{x}_{i}), T_{\theta}\left([\mathbf{x}_{1}, f(\mathbf{x}_{1}) \dots, \mathbf{x}_{i}]\right)\right) \right]$$

Akyurek et al '23

Note: trained model T is the in-context learner: it's given a "dataset" in a prompt, plus a test point

What Can Transformers Learn?

Theoretical setup:

$$\underset{\substack{\theta \\ f \sim p(f)}}{\operatorname{arg\,min}} \underset{\substack{\boldsymbol{x}_1, \dots, \boldsymbol{x}_n \sim p(x) \\ f \sim p(f)}}{\mathbb{E}} \left[\sum_{i=1}^n \mathcal{L}\left(f(\boldsymbol{x}_i), T_{\theta}\left([\boldsymbol{x}_1, f(\boldsymbol{x}_1) \dots, \boldsymbol{x}_i]\right)\right) \right]$$

Akyurek et al '23

Here, during training we're not learning one function f

- •We're training an ICL to "learn" new functions!
 - At test time!
 - This is the metalearning idea

What Can Transformers Learn? Linear Case

Let's try learning linear functions

$$f(x) = w^T x$$

Loss function: squared loss

$$L(y, f(x)) = (w^T x - y)^2$$

Regularized empirical risk

$$\sum_{i} (w^{T} x_{i} - y_{i})^{2} + \lambda \|w\|_{2}^{2}$$

What Can Transformers Learn? Linear Case

Let's try learning linear functions $f(x) = w^T x$

How do we learn a function like f?

Two ways:

1. Closed-form:
$$\hat{w} = (X^T X + \lambda I)^{-1} X^T y$$

2. Gradient descent: $w_t = w_{t-1} - \alpha \frac{\partial}{\partial w} (\text{Loss})$

$$w_{t-1} - 2lpha(xw_{t-1}^Tx - yx + \lambda w)$$
 — Next iterate

What Can Transformers Learn? Implicit GD

Note: the ICL model can't learn some specific w

- Different for each input/prompt...
- But, what if it can learn the *procedure* that generates a solution?

How can we tell? Possibility result from Akyurek et al '23

Theorem 1. A transformer can compute Eq. (11) (i.e. the prediction resulting from single step of gradient descent on an in-context example) with constant number of layers and O(d) hidden space, where d is the problem dimension of the input x. Specifically, there exist transformer parameters θ such that, given an input matrix of the form:

$$H^{(0)} = \begin{bmatrix} \cdots & 0 & y_i & 0 \\ \mathbf{x}_i & 0 & \mathbf{x}_n & \cdots \end{bmatrix}, \qquad \text{Input Dataset}$$
(12)

the transformer's output matrix $H^{(L)}$ contains an entry equal to $w'^{\top} x_n$ (Eq. (11)) at the column index where x_n is input.

Prediction after next step of GD

See also Oswald et al

What Can Transformers Learn? Closed Form

What about the closed-form approach?

- Have to invert $X^T X + \lambda I$
- Note: these are sums of rank 1-terms + diagonal, can run it sequentially with Sherman-Morrison

$$ig(A+uv^{\mathsf{T}}ig)^{-1}=A^{-1}-rac{A^{-1}uv^{\mathsf{T}}A^{-1}}{1+v^{\mathsf{T}}A^{-1}u}$$

• Here too,

Theorem 2. A transformer can predict according to a single Sherman–Morrison update:

$$\boldsymbol{w}' = \left(\lambda I + \boldsymbol{x}_i \boldsymbol{x}_i^{\top}\right)^{-1} \boldsymbol{x}_i y_i = \left(\frac{I}{\lambda} - \frac{\frac{I}{\lambda} \boldsymbol{x}_i \boldsymbol{x}_i^{\top} \frac{I}{\lambda}}{1 + \boldsymbol{x}_i^{\top} \frac{I}{\lambda} \boldsymbol{x}_i}\right) \boldsymbol{x}_i y_i$$
(14)

with constant layers and $\mathcal{O}(d^2)$ hidden space. More precisely, there exists a set of transformer parameters θ such that, given an input matrix of the form in Eq. (12), the transformer's output matrix $H^{(L)}$ contains an entry equal to $w'^{\top}x_n$ (Eq. (14)) at the column index where x_n is input.

Does this Work?

These existence results show this is possible...

•I.e., there exist weights that produce this behavior But does training actually get us these?

•A: Yes



What About Learning?

Is it possible to show that **training** a transformer produces this behavior?

- •A: Yes: Ahn et al '23
 - Model choice: multi-layer linear self-attention

Theorem 4. Assume that $x^{(i)} \stackrel{iid}{\sim} \mathcal{N}(0, \Sigma)$ and $w_{\star} \sim \mathcal{N}(0, \Sigma^{-1})$, for i = 1...n, and for some $\Sigma \succ 0$. Consider the optimization of in-context loss for a k-layer transformer with the the parameter configuration in Eq. (9) given by:

$$\min_{\{A_i\}_{i=0}^k} f\left(\{A_i\}_{i=0}^k\right).$$

Let $S \subset \mathbb{R}^{(k+1) \times d \times d}$ be defined as follows: $A \in S$ if and only if for all $i \in \{0, \ldots, k\}$, there exists scalars $a_i \in \mathbb{R}$ such that $A_i = a_i \Sigma^{-1}$. Then

$$\inf_{A \in S} \sum_{i=0}^{k} \|\nabla_{A_i} f(A)\|_F^2 = 0,$$

where $\nabla_{A_i} f$ denotes derivative wrt the Frobenius norm $\|A_i\|_F$.



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Review: Few-Shot Choices

Examples/structure affect performance:

- 1. Prompt format (affects everything)
- 2. Choice of examples
- 3. Order of examples (permutation)



Review: Choice of Examples

How to pick appropriate examples in few-shot?

•Note: only a "small' number of examples can be shown, unlike in supervised learning.

Many options. Sampling:

- Liu et al, '21: kNN in embedding space (semantic similarity)
- Su et al, '22: Encourage diversity in embeddings
- Diao et al, '23: "Active prompting"



Diao et al '23

2. Choice of Examples

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Diao et al '23

Chain-of-Thought

Performing complex reasoning is hard. Help the model:



Chain-of-Thought: Generalizations

How do we really "reason"?

• Not really by sampling a bunch of chains...



Tools: Program-aided LMs

Use external tools:

• Python interpreter

- How? Interleave the text explanations in CoT steps with lines of Python code
- LMs can already output code
 - Just need to *prompt* the right way

Chain-of-Thought (Wei et al., 2022)

Q: Roger has 5 tennis balls. He buys 2 more cans of tennis balls. Each can has 3 tennis balls. How many tennis balls does he have now?

A: Roger started with 5 tennis balls. 2 cans of 3 tennis balls each is 6 tennis balls. 5 + 6 = 11. The answer is 11.

Q: The bakers at the Beverly Hills Bakery baked 200 loaves of bread on Monday morning. They sold 93 loaves in the morning and 39 loaves in the afternoon. A grocery store returned 6 unsold loaves. How many loaves of bread did they have left?

Model Output

A: The bakers started with 200 loaves. They sold 93 in the morning and 39 in the afternoon. So they sold 93 + 39 = 132 loaves. The grocery store returned 6 loaves. So they had 200 - 132 - 6 = 62 loaves left. The answer is 62.

Gao et al '23

Program-aided Language models (this work)

Q: Roger has 5 tennis balls. He buys 2 more cans of tennis balls. Each can has 3 tennis balls. How many tennis balls does he have now?

A: Roger started with 5 tennis balls. tennis_balls = 5 2 cans of 3 tennis balls each is bought_balls = 2 * 3 tennis balls. The answer is answer = tennis_balls + bought_balls

Q: The bakers at the Beverly Hills Bakery baked 200 loaves of bread on Monday morning. They sold 93 loaves in the morning and 39 loaves in the afternoon. A grocery store returned 6 unsold loaves. How many loaves of bread did they have left?

Model Output

A: The bakers started with 200 loaves loaves_baked = 200 They sold 93 in the morning and 39 in the afternoon loaves_sold_morning = 93 loaves_sold_afternoon = 39 The grocery store returned 6 loaves. loaves_returned = 6 The answer = loaves_baked - loaves_sold_morning - loaves_sold_afternoon + loaves_returned >>> orini(answer)



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Thank You!